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Smart Data Blending Framework to Enhance Precipitation Estimation through Interconnected Atmospheric, Satellite, and Surface Variables

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Abstract: Accurate precipitation estimation remains a challenge, though it is fundamental for most hydrological analyses. In this regard, this study aims to achieve two objectives. Firstly, we evaluate the performance of two precipitation products from the Integrated Multi-satellitE Retrievals for Global Precipitation Measurement (GPM-IMERG) for Sicily, Italy, from 2016 to 2020 by a set of categorical indicators and statistical indices. Analyses indicate the favorable performance of daily estimates, while half-hourly estimates exhibited poorer performance, revealing larger discrepancies between satellite and ground-based measurements at sub-hourly timescales. Secondly, we propose four multi-source merged models within Artificial Neural Network (ANN) and Multivariate Linear Regression (MLR) blending frameworks to seek potential improvement by exploiting different combinations of Soil Moisture (SM) measurements from the Soil Moisture Active Passive (SMAP) mission and atmospheric factor of Precipitable Water Vapor (PWV) estimations, from the Advanced Microwave Scanning Radiometer-2 (AMS2). Spatial distribution maps of some diagnostic indices used to quantitatively evaluate the quality of models reveal the best performance of ANNs over the entire domain. Assessing variable sensitivity reveals the importance of IMERG satellite precipitation and PWV in non-linear models such as ANNs, which outperform the MLR modeling framework and individual IMERG products.

Keywords: deep learning; satellite precipitation estimations; multi-source merging models; improving precision



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1. Introduction

The precise estimation of precipitation perhaps plays the most significant role in water-related studies [1] and in many hydrologic modeling and forecasting applications. For many years, the most reliable source of rainfall measurements has been represented by ground rain gauge networks [2,3], which have the great advantage of high accuracy in monitoring precipitation, even if measurements refer to a small area around the instrument. Rain gauge networks, on the other hand, are usually poorly distributed in plateaus, mountains, deserts, and other areas, and may not even be present in uninhabited areas, creating gaps in the data [2,3].

Currently, satellite-retrieved and atmospheric reanalysis precipitation are increasingly used in an attempt to bridge the spatiotemporal gaps of in-situ rain gauge networks, although estimation errors still limit their practical applications [4]. Among these products, the Integrated MultisatellitE Retrievals from Global Precipitation Measurement (GPM) constellation (IMERG; [5]) is widely used. Many studies have been devoted to validating and improving IMERG data with respect to ground-based data. Some of these studies have evaluated IMERG data on a global scale (e.g., [6]), while others have focused on some specific areas of the globe such as Europe [7–9], vast territories throughout Asia [10–15], and America [16–19]. Their investigations suggest the promising use of IMERG to estimate

spatiotemporal variability of rainfall across diverse rainfall patterns, climates, and geographical characteristics; nonetheless, they highlight the importance of regional calibration to improve IMERG reliability. In a comprehensive global review, [20] identified the lack of studies evaluating sub-daily scales for the latest version (V06) release of IMERG as an issue that should be addressed more, particularly for Europe, for which satellite precipitation products have been investigated less than those for Asian and American territories.

With reference to the Mediterranean basin, the area has been always subjected to high uncertainty in rainfall estimations due to its unique topography and complex climate [21]. According to the literature, the discrepancy between satellite and ground measurements in this area is higher in regions characterized by a complex morphology and influenced by land–sea transitions, especially when the finer temporal resolutions are considered [22–24]. Additionally, the Mediterranean region is one of the most vulnerable areas of the globe to the effects of climate change [25–27], which makes rainfall estimation from satellites difficult since the climate today is exposed to more frequent and severe extreme events, particularly at finer temporal resolutions (e.g., hourly and sub-hourly) [28], that the complexity becomes more evident than those modeled in the past [25,28–33].

Precipitation estimation over sub-hourly time scales plays a critical role for many sectors impacted by natural phenomena. Nevertheless, only a few studies have focused on evaluating satellite products with rain-gauge measurements at fine scales [20]. However, half-hourly rainfall estimates of IMERG are available to the public, and there are selected studies evaluating hourly and sub-hourly IMERG data. Some of these studies include an evaluation of IMERG V06 at an hourly scale over Canada [34], at 1, 6, and 24 h scales by [35] over Brazil, and at 1 and 3 h scales by [36]. Although these studies highlight the potential of IMERG at sub-hourly scales, they also suggest that there is still room for further improvement in product accuracy at fine sub-daily scales for practical aims. Impacts of temporal resolution on space-based precipitation estimates over Southern Italy are similarly construed to a few. To give an example, [37] set a 10-day threshold for stable performances of satellite estimates in terms of categorical indicators and statistical metrics, whereas [38] discovered a reasonable performance in remote-sensing estimates above a 6 h temporal resolution. Most recently, daily and 6 h data from IMERG V04, [22] suggested that the performance of GPM satellite data is primarily driven by temporal aggregation rather than orography.

Following these evaluations, many researchers have attempted to reduce the uncertainties involved in Satellite Rainfall Estimates (SRE) using different methods such as the mean correction factor method [39], quantile mapping [40], and the Bayesian approach [41]. However, these methods are often associated with various limitations and, for this reason, are often replaced by more advanced methods [42,43]. In some cases, the blending of ancillary variables to enhance precipitation estimates has been implemented to overcome these limitations [44]. These merging techniques have proven to be effective in improving the accuracy of precipitation estimates from satellites [45,46]. For instance, some authors blended SRE along with the topography and physical characteristics of a region through a linear parametric model [47], while others took advantage of atmospheric variables, specifically Precipitable Water Vapor (PWV), which is suggested to be highly interconnected to precipitation [48]. The authors of [4] improved rainfall estimates through a fusion of weather radars, satellite estimates, soil moisture data, and terrain elevations within two distinct model frameworks: Artificial Neural Network (ANN) and Geographically Weighted Regression (GWR). The authors of [49] blended four multisource precipitation estimates, including IMERG, CMORPH (CPC MORPHing technique), Climate Hazards Group Infrared Precipitation with station data (CHIRPS), and the Precipitation Estimation from Remotely Sensed Information using Artificial Neural Networks by Dynamic Infrared–Rain Rate (PERSIANN-PDIR), with PWV and land surface temperature.

Various strategies for combining satellite-based and ancillary data have been widely used to improve space-based estimates, including linear regression as the most common method with desirable outcomes [50,51]. In addition to scientific techniques, Machine

Learning (ML) techniques, such as ANNs, have been increasingly applied in rainfall studies due to their ability to extract a non-linear relationship between independent and dependent variables, without the need for predefined relationships; this has led to a significant improvement compared to traditional blending methods [46,49,52–55]. A summary of selected literature reviews in this field is reported in Table 1.

In this study, we develop a methodology to correct high-resolution satellite precipitation estimations over the Mediterranean island of Sicily, Italy, through blending atmospheric characteristics and land surface factors. The methodology is a two-phase process. During the first phase, the latest version of individual IMERG (V06) precipitation estimations, at a relatively high temporal resolution (i.e., half-hourly) and daily scale, is validated against observed data provided by the rain gauge network of the Agrometeorological Information Service of Sicily (Servizio Informativo Agrometeorologico Siciliano—SIAS) for the period 2016–2020. Upon gaining a deep insight into the satellite performance over the region, the second phase concentrates on enhancing the accuracy of space-based precipitation estimations through blending IMERG with ancillary data that describe interactions with atmospheric content and land surface properties. In this regard, two techniques are applied, namely, Multivariate Linear Regression (MLR) and ANN. Given that Surface Soil Moisture (SSM) retrievals are strongly associated with rainfall depth [56,57], successful blending approaches by [49,55] have inspired this study to include soil moisture in precipitation estimation models as a potential ancillary variable.

We believe that the framework developed within the study may offer a promising solution for generating more reliable inputs in hydrological studies, such as those aimed at assessing flow regime alteration [58], particularly in complex terrain areas that are prone to extreme events, such as the Mediterranean region. Moreover, its potential benefits could be extended to the catchment and regional scales, contributing to improving studies on hydrogeological risk assessment.

The manuscript is organized as follows. Section 2 describes the study area, dataset, and merging methods. The results are presented and discussed in Section 3. Section 4 concludes the paper.

Table 1. Summary of selected literature for review.

Author	Framework, Material, and Approach	Study Area Study Period	Result(s)
Moazemi et al., 2021 [34]	Evaluating different IMERG precipitation products with hourly resolution	Canada 2014–2018	<ol style="list-style-type: none"> 1. PrecipitationCal (PrCal) outperformed other precipitation products of IMERG. 2. Best seasonal performance in summer and dry seasons. 3. Capability of IMERG to capture spatiotemporal variation of rainfall.
Caracciolo et al., 2018 [22]	Examining the performance of IMERG-v06 SPEs over Mediterranean islands of Italy	Italy 2015–2016	<ol style="list-style-type: none"> 1. GPM SPEs performances were driven by temporal aggregation more than geographic context. 2. A stable performance was reached at approximately 10 days.
Brocca et al., 2013 [57]	SM2RAIN approach to space precipitation estimates based on soil moisture data from ASCAT	South Europe 2008–2011	<ol style="list-style-type: none"> 1. The method provided reasonable rainfall estimates using both in situ and satellite data. 2. Possibility of application to precipitation estimations on global scales.

Table 1. Cont.

Author	Framework, Material, and Approach	Study Area Study Period	Result(s)
Wehbe et al., 2020 [4]	Two fusion approaches based on ANN and GWR to merge satellite precipitation estimates, weather radars, and soil moisture	UAE 2015–2018	<ol style="list-style-type: none"> Both GWR and ANN estimations outperformed the original GPM and radar estimates. The weakest rainfall correction was obtained by GWR during the summer. The incorporation of SM led to improved corrections by the ANN model compared to GWR. The methodology is extendable to other arid and hyper-arid regions with poor gauge networks.
Beykhamadi et al., 2021 [48]	Improving the accuracy of daily and 6-hourly SPEs of IMERG through PWV and land surface elevation	Iran 2015–2017	<ol style="list-style-type: none"> There was no specific linear or nonlinear relation between SPEs and elevation. Blending SPEs with atmospheric PWV enhanced the rainfall estimates significantly in terms of both categorical and statistical metrics.
Nosratpour et al., 2022 [49]	Fusion model based on the integration of CMORPH, PDIR, CHIRPS, IMERG, PWV, and LST through MLR and ANN	Iran 2017–2021	<ol style="list-style-type: none"> General enhancement in SPEs with respect to evaluation indices compared to estimations from original products, with superiority of the ANN method. Best results achieved with the model developed by IMERG, PDIR, CMORPH, and CHIRPS along with PWL and LST. Superior seasonal performance of merged models in dry seasons.
Zhao et al., 2022 [59]	Integrate multi-source precipitation products (APHRODITE, ERA5, CHIRPS) with environmental factors (vegetation and soil moisture) through a ML model	China 1987–2017	<ol style="list-style-type: none"> Accuracy of precipitation estimates increased compared to individual satellite estimates. The more ancillary factors interconnected to precipitation merged, the more robust the model became. An ML framework for blending data corresponded to the strongest results.

2. Materials and Methods

2.1. Study Area

Sicily is the largest island in the Mediterranean Sea and is located at the southern end of Italy, between latitudes 36° N and 39° N and longitudes 12° E and 16° E (Figure 1). It is separated from the Italian Peninsula by the Strait of Messina and bordered by the Ionian Sea (eastward), the Tyrrhenian Sea (northward), and the Channel of Sicily (southward), which separates Sicily from Africa (Figure 1). The island covers an area of approximately 25,700 km², with orography ranging from 0 to 3320 m a.s.l. at the volcano Etna (Figure 1). The climate there is typical of that in Mediterranean regions. Because of its geographic position and morphology, Sicily is characterized by significant spatiotemporal variability in precipitation; the mean annual precipitation ranges between approximately 360 mm in the southeastern part of the island and approximately 1900 mm in the northeastern part of the island [60], with summers (i.e., from June through August) typically dry, with little or no rain, and the highest amount of rainfall occurring during the winter months [61,62].

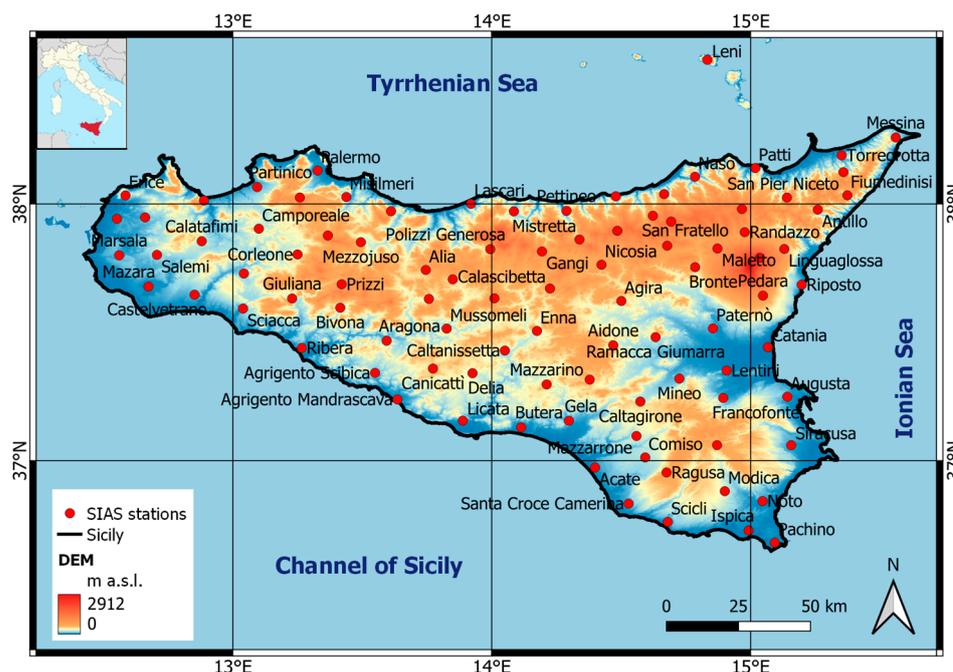


Figure 1. Digital Elevation Model (DEM) of Sicily and location of SIAS rain gauge stations.

Figure 1 shows the Digital Elevation Model (DEM) of Sicily and its location in the Mediterranean Sea (see inset in Figure 1). DEM has a 20×20 m resolution and is provided by the Italian National Geoportal (<http://www.pcn.minambiente.it/mattm/en/>; accessed on 15 January 2023).

2.2. Datasets

2.2.1. Precipitation Data: Ground and Satellite Observations

In this study, ground-based and satellite precipitation measurements were used. Ground-based data were provided by the SIAS, which manages a network of approximately 100 tipping bucket rain gauges distributed over the entire island (Figure 1) that collect data with a temporal resolution of 10 min and a rain resolution of 0.2 mm. For the comparison with the IMERG data, the original data were aggregated at both half-hourly and daily scales. For daily data, a wet day (or rainy day) was defined as a day in which a minimum rainfall of 1 mm/day occurred. In addition, an inter-event time was fixed equal to 1 h, which separated one rain event from the next [63,64].

Satellite data were obtained from IMERG, which is a unified algorithm that provides multi-satellite precipitation products to the U.S. GPM team. The current version of the dataset is the V06, with 0.1° spatial resolution (i.e., approximately 10×10 km at the latitudes of Sicily) and 30 min temporal resolution (GPM_3IMERGHH) [44]. This was used to obtain the dataset of the GPM Level 3 IMERG “Final” at the daily scale at the same spatial resolution (GPM_3IMERGDF).

IMERG combines retrievals from Passive Microwave (PMW) and Microwave-calibrated Infrared (IR) to produce a quasi-global (60° S– 60° N) precipitation product based only on satellite data. Raw data are processed and then gridded and merged with IR data to provide global, homogeneous precipitation measurements [65]. IMERG has three types of products based on latency and the processing method applied to observations: early (IMERG-E), late (IMERG-L), and final (IMERG-F). While early and late products are available 3 and 12 h after the observations, respectively, the final version is released 3.5 months later. An advantage of IMERG-F is the additional levels of data processing that are not considered in the first two products. The gridded data are available from mid-March 2014 to the present. The products used in this study were GPM_3IMERGHH-06 and GPM_3IMERGDF-06, corresponding to half-hourly and daily temporal resolutions, respectively.

For both the ground-based and satellite precipitation, data within the period of 2016 to 2020 were considered. Table 2 reports the main characteristics of the SIAS and IMERG rainfall datasets.

Table 2. Overview of the high-resolution ground and satellite-based products used in this study.

Product	Temporal Resolution	Spatial Resolution	Coverage	Version	Latency	Provider
SIAS	10 min	Point data	Regional Sicily	-	-	Servizio Informativo Agrometeorologico Siciliano (http://www.sias.regione.sicilia.it/ ; accessed on 2 May 2022)
IMERGHH	Half-hourly	~10 km	Global	6	Final (3.5 months)	NASA (https://gpm.nasa.gov/data/directory ; accessed on 2 May 2022)
IMERGDF	Daily	~10 km	Global	6	Final (3.5 months)	NASA
AMSR2-PWL	Daily	10 km	Global	1	1 day	JAXA (https://www.eorc.jaxa.jp/AMSR/index_en.html ; accessed on 2 May 2022)
SMAP-L3E	Daily	9 km	Global	3	50 days	NASA

2.2.2. Ancillary Data: Precipitable Water Vapor and Soil Moisture

In addition to precipitation data, some ancillary data coming from remote sensing measurements, namely, the precipitable water vapor and the soil moisture, were considered in this study.

The amount of vertically accumulated water vapor in the atmosphere is defined as the amount of water per unit area. Here, the Precipitable Water vapor over Land product (GCOM-W PWL Research Product— kg/m^2) was retrieved at the daily scale and on a spatial resolution of approximately 10 km from the Japan Aerospace Exploration Agency (JAXA) portal of Advanced Microwave Scanning Radiometer-2 (AMSR2), which was launched aboard the Global Change Observation Mission 1st-Water (GCOM-W1) satellite. Data were acquired in HDF format for the period 2016–2020 via ftp service through https://www.eorc.jaxa.jp/AMSR/index_en.html (accessed on 5 April 2023). AMSR2 provides data on global precipitation, ocean wind speed, water vapor, sea ice concentration, brightness, temperature, and soil moisture with the purpose of analyzing variations in water circulation [66]. Estimations of vertically integrated columns of water vapor over land are conducted using polarization differences of 18 and 23 GHz channels, respectively.

Data on soil moisture remotely sensed were obtained from the SMAP satellite available through the National Snow and Ice Data Center (NSIDC) (https://nsidc.org/data/sp13smp_e/versions/3 accessed on 5 April 2023). Soil moisture estimates using SMAP's passive microwave radiometer have been proven to outperform other satellite soil moisture datasets when compared to in-situ soil moisture data. Since 2015, the SMAP-L3E (Enhanced SMAP data from Level 3 of processing) dataset has been available at the spatial resolution of 9×9 km on a daily scale for free. Although the spatial resolution of the product is roughly close to 10 km, which is the common spatial resolution of all datasets, we implemented a bilinear interpolation method to rescale and adjust the product's spatial resolution. The SM data in the topmost layer were evaluated and discarded if the soil temperature was below $273 \text{ }^\circ\text{K}$ ($\sim 0 \text{ }^\circ\text{C}$). The investigated period was again from 2016 to 2020.

A summary of detailed information regarding the two ancillary datasets used in this study is listed in Table 2.

2.3. Methodology

With the growing volume and complexity of data, traditional statistical methods are often inadequate to handle very large datasets. Concerning this matter, data mining techniques have proven to be an essential part of the data analysis process. By leveraging a variety of methods, including machine learning and statistical modeling, data mining enables analysts to identify relationships within large, different, and independent variables. In the context of meteorology and climatology, data mining techniques have shown promising results in enhancing the accuracy and reliability of precipitation estimates, as discussed in the previous section. This technology is used for descriptive and predictive purposes, where the last one is mainly the core of meteorology and atmospheric science. In this study, both purposes have two distinct phases. Phase 1 evaluates and compares daily and half-hourly rainfall estimates in terms of some statistical and categorical indices that are discussed in Section 3.2. Thereafter, the effects of the variables originating from different sources, such as atmosphere or land, on precipitation estimations are examined by two methods (i.e., MLR and ANN) in phase 2, which are briefly discussed in the following section.

Machine learning models require both training (calibration) and testing (validation) procedures to ensure that they are accurate, reliable, and generalizable. While it is necessary that the training data is representative of the entire dataset, there is currently no precise mathematical guideline to determine the minimum size required for these subsets. Despite this, the present study followed suggestions from the literature and randomly assigned 75% of the dataset for training and the remaining subset for assessment.

2.3.1. Multivariant Linear Regression Model

Linear regression is heavily used in atmospheric science to decrease the complexity of relationships among variables and extract the level of their association. In this study, two MLR models were proposed to improve rainfall estimates by merging rainfall remote estimations with PWV and SM. Before applying the procedure to the data, each dataset was standardized using its mean and standard deviation [67] to ensure that all variables contributed at a common scale.

Following studies by [52,53,59], which used water vapor in the atmosphere and soil moisture as ancillary variables, this study merged two models based on an MLR framework, as defined below:

$$P_{MLR1} = c_1 Z_{IMERG} + c_2 Z_{PWV} + c_3 \quad (1)$$

$$P_{MLR2} = c_1 Z_{IMERG} + c_2 Z_{PWV} + c_3 Z_{SM} + c_4 \quad (2)$$

where P_{MLR_i} denotes the value of precipitation estimated by the i -th linear integration model ($i = 1, 2$), Z is the variable associated with its subscript, and c_i are the coefficients of the model variables. Equations (1) and (2) will be hereafter referred to as MLR_1 and MLR_2 , respectively. MLR_1 aims to mathematically interconnect the amount of IMERG precipitation estimates, Z_{IMERG} , to the amount of water vapor in the atmosphere, Z_{PWV} , which can potentially be converted into rain. MLR_2 performs similarly to MLR_1 , including the amount of water received by soil in terms of rain at the very first layer, Z_{SM} , as well. The coefficients for the proposed models were calculated using the Harmony Search (HS) algorithm, which is a meta-heuristic and self-learning algorithm that has recently been developed [63–67].

The HS algorithm is an optimization technique that combines existing harmonies to generate new ones using three hyperparameters: Pitch Adjustment Rate (PAR), Harmony Memory Considering Rate (HMCR), and BandWidth (BW). The initial population of harmonies is followed by the generation of new harmonies by means of a random combination of elements from the existing population. Harmonies that provide a higher level of fitting replace the previous ones until a stopping criterion is met. Optimal hyperparameter values have been recommended based on experiments, including $BW = 0.1$, $PAR = 0.1$, $HMCR = 0.7$, and a maximum number of iterations equal to 1500. The HS algorithm has

been implemented in MATLAB and further information can be found in [63–67]. Figure 2a shows a flowchart of the HS algorithm used in this study.

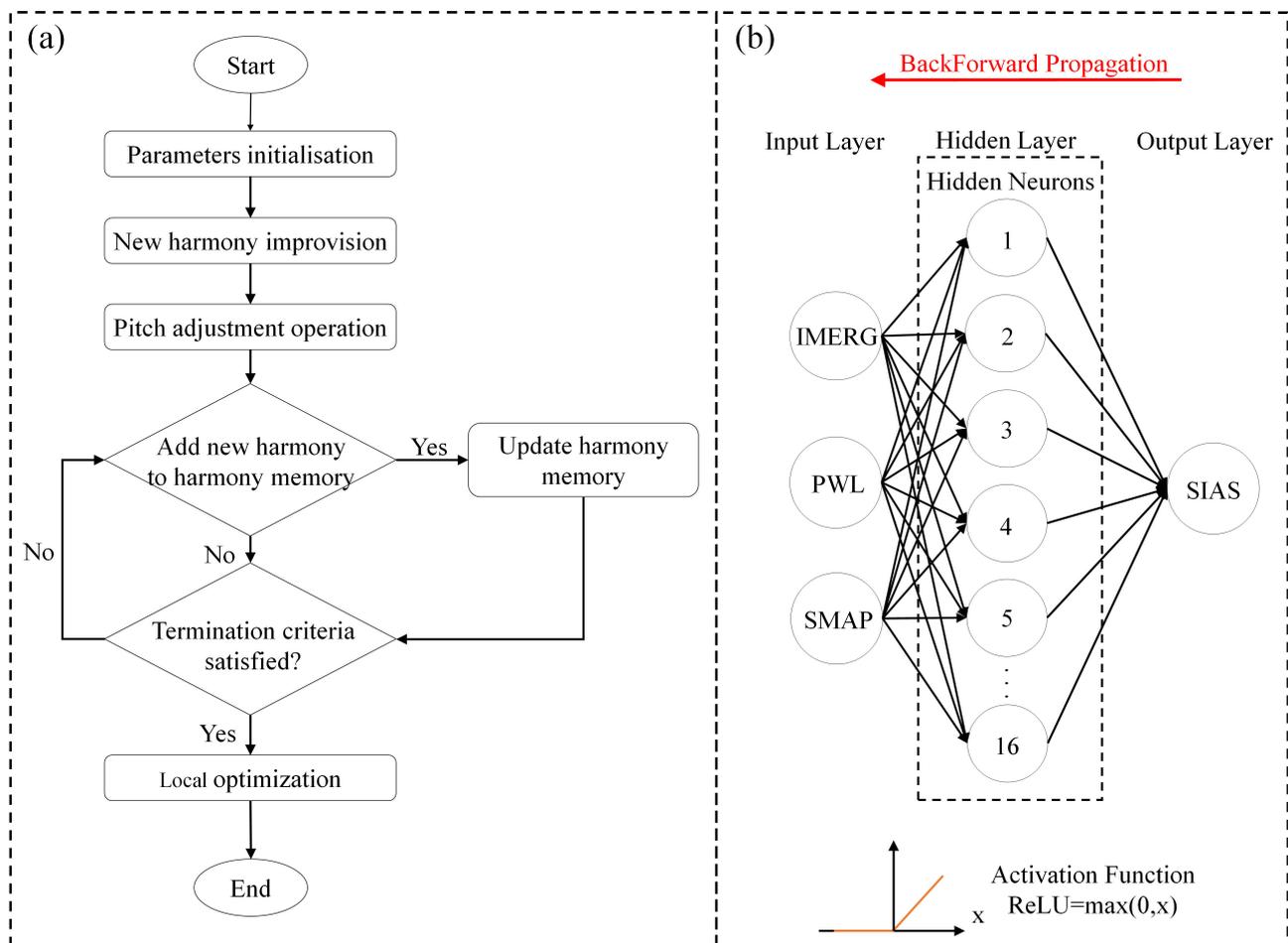


Figure 2. (a) Harmony search algorithm flowchart; (b) Schematic diagram of neural network architecture, input data, hidden layer, neurons, activation function, and output prediction.

2.3.2. Artificial Neural Networks

Artificial Neural Networks (ANNs) have been developed as generalizations of mathematical models of biological nervous systems [68] and today are used as useful alternatives to traditional statistical modeling techniques in many scientific disciplines.

The architecture of an ANN typically consists of three main types of layers: an input layer, which contains the independent variables, an output layer, which produces the desired output or dependent variable, and one or more hidden layers, which contain neurons that apply activation functions to compute complex relationships between the input and output layers.

The input layer receives the raw input data, while the output layer produces the final output or prediction. The hidden layers are instead responsible for transforming the input data into a format that is better suited for predicting the desired output. Each neuron in a hidden layer applies an activation function to the weighted sum of its inputs, which introduces nonlinearity into the network and allows it to model complex relationships between the input and output variables. Overall, the architecture of an ANN with its input, output, and hidden layers, along with the activation functions used in the hidden layers, play a crucial role in determining the network's ability to learn from data and, therefore, its performance. A schematic architecture of the neural network used in this work is illustrated in Figure 2b.

This study used a Multilayer Perceptron model with the backpropagation algorithm network; a growing number of papers in the atmospheric literature have demonstrated that MLP provides robust estimates within a fast, simple yet powerful algorithm [4,46,69] that is particularly suitable for mimicking what happens in the atmosphere. Indeed, unlike traditional statistical techniques, the MLP makes no prior assumptions concerning the data distribution and can model highly non-linear functions. Therefore, it has become an attractive alternative to numerical models, particularly in dynamic systems, including those studied by atmospheric science [70].

The MLP used in this study is defined as follows:

$$l_0 = Z \quad (3)$$

$$l_i = f(W_i \times l_{i-1}), i = 1, \dots, N_l - 1 \quad (4)$$

$$\text{Output}(Z) = l_{N_l} = W_{N_l} \times l_{N_l-1} \quad (5)$$

where l_0 represents the input layer, l_i represents the i -th hidden layer, W_i is the weight matrix of the i -th layer, and f is the transfer function of the N_l -layered neural network. $\text{Output}(Z)$ is the desired ANN output from the initial input layer, Z . As for the MLP case, two integrated ANN models were defined to estimate rainfall as below:

$$P_{ANN_j} = \text{Output}(Z_j) \quad j = 1, 2 \quad (6)$$

$$Z_1 = [Z_{PWV}, Z_{IMERG}] \quad (7)$$

$$Z_2 = [Z_{PWV}, Z_{IMERG}, Z_{SM}] \quad (8)$$

where P_{ANN_j} represents the precipitation estimated from merging initial input layers j , as defined in vectors (7) and (8).

An ANN was trained using the backpropagation algorithm or backward propagation of errors, which is a generalized extension of the Least Mean Squared rule [71]. It works by propagating the error from the output layer back through the network, adjusting the weights of the connections between neurons in order to minimize the difference between the predicted output and the target output. The objective function used to train the MLP is defined as below:

$$\text{SquareError} = \sum_{i=1}^N (P_{obs}(i) - P_{Model}(i))^2 \quad (9)$$

where $P_{obs}(i)$ and $P_{Model}(i)$ indicate the i -th observed and estimated precipitation, respectively. Applying the backpropagation error algorithm to developed models, the number of layers and neurons was computed by a trial-and-error procedure during the calibration process. Table 3 provides an overview of the details of the parameters and ANN configuration network.

Table 3. Overview of selected configuration and parameter values for the proposed ANN models.

Network Attribute	Value/Selection
No. of hidden layers	1
No. of hidden neurons	16
Epochs	150
Hidden and output layer activation functions	Rectified Linear Unit (ReLU)
Optimizer	ADAM
Training algorithm	Backpropagation Error Algorithm

2.3.3. Performance Analyses

The performances of 3IMERGHH and 3IMERGDF products were evaluated against SIAS ground observations using a pixel-to-pixel comparison. To achieve this, ground station data were interpolated using the Inverse Distance Weighting (IDW) technique to create a raster with a spatial resolution of 10 km, which is the same as that for the IMERG products. In addition to the individual IMERG products, the performances of the MLR and ANN merged models were also evaluated.

Several diagnostic indices were used to quantitatively evaluate the quality of the models and products by quantifying the error within the satellite data and models using ground observations as a reference. These indices included the Pearson Correlation Coefficient (CC), which measures the linear correlation between two datasets, Relative Bias (RBias), which indicates the systematic bias of datasets, Root Mean Square Error (RMSE), which measures the average error magnitude weighting it towards larger errors, Nash-Sutcliffe Efficiency (NSE), which is used to assess the predictive skill of hydrological models, and Willmott Index (WIA), which is used to evaluate the accuracy of model estimations.

In addition to statistical metrics, categorical metrics including Probability Of Detection (POD), Critical Success Index (CSI), and False Alarm Ratio (FAR) were used to analyze the detection capability of the satellite products or simulated models [72] by setting the cut-off value to the 5th percentile of the resampled SIAS rainfall empirical distribution in each grid cell and considering rainfall events exceeding 1 mm per day. Using a contingency table, POD deals with the question of what fraction of the observed events was correctly estimated. FAR represents events identified by the simulation but not confirmed by observations, while CSI describes the overall skill of the simulation relative to reference observations [73]. Table 4 summarizes the statistical and categorical metrics used for the evaluation of individual IMERG products and merged models, where P_{obs_i} is the observed gauge data of order i , P_{est_i} is the estimated data of order i , \bar{P} is the average of dataset, *Hits* are the days when both satellites and stations recorded the event as rainy, *FalseAlarm* are the days when satellites recorded rain but the gauges did not, and *Misses* are the days when satellites did not register rain but the gauges did.

Table 4. Summary of statistical/categorical indices used to evaluate the satellite precipitation products and the performance of the MLR and ANN models. Bold values indicate a perfect agreement between satellite (or modeled) data and reference data (i.e., SIAS data).

Index	Unit	Equation	Range of Values
Correlation Coefficient (CC)	-	$CC = \frac{\sum_{i=1}^N (p_{est_i} - \bar{p}_{est})(p_{obs_i} - \bar{p}_{obs})}{\sqrt{\sum_{i=1}^N (p_{est_i} - \bar{p}_{est})^2} \sqrt{\sum_{i=1}^N (p_{obs_i} - \bar{p}_{obs})^2}}$	-1 to 1
Relative Bias (RBias)	-	$Rbias = \frac{\sum_{i=1}^N (p_{est_i} - p_{obs_i})}{\sum_{i=1}^N p_{obs_i}}$	-inf to +inf 0
Root of the Mean Square Error (RMSE)	mm	$RMSE = \sqrt{\frac{1}{N} \sum_{i=1}^N (P_{obs_i} - P_{est_i})^2}$	-inf to +inf 0
Nash-Sutcliffe Efficiency (NSE)	mm	$NSE = 1 - \frac{\sum_{i=1}^N (P_{obs_i} - P_{est_i})^2}{\sum_{i=1}^N (P_{obs_i} - \bar{P}_{obs})^2}$	-inf to 1 0.36 < Satisfactory < 0.75 Good > 0.75
Willmott Index (WIA)	-	$WIA = 1 - \frac{\sum_{i=1}^N (P_{obs_i} - P_{est_i})^2}{\sum_{i=1}^N (P_{obs_i} - \bar{P}_{obs} + P_{est_i} - \bar{P}_{obs})^2}$	0–1
Probability Of Detection (POD)	-	$POD = \frac{Hits}{Hits + Misses}$	0–1
Critical Success Index (CSI)	-	$CSI = \frac{Hits}{Hits + Misses + FalseAlarm}$	0–1
False Alarm Ratio (FAR)	-	$FAR = \frac{FalseAlarm}{Hits + FalseAlarm}$	0–1

3. Results and Discussion

3.1. Evaluation across Temporal Scales

This section presents the assessment of individual IMERG products with ground reference data, reported in Table 5. Starting with half-hourly data, it is worth noting that this is the first time that this IMERG product has been evaluated against ground-based data at this relatively high temporal resolution over the largest island of the Mediterranean Sea. Over the entire period here investigated (2016–2020), CC = 0.22 along with RMSE = 0.86 mm was achieved, thus denoting a weak correlation between satellite products and observed data. Moreover, negative values of RBias (−1.1) and NSE (−0.4) suggested an underestimation and unsatisfactory estimates for rainfall, respectively, at the half-hourly scale. With reference to categorical indices, a POD with an average value of 0.66 depicted an acceptable detection power of estimate on rainfall/non-rainfall events at such a resolution. This was followed by an adequate value of CSI, equal to 0.64, which indicated that the half-hourly data performed satisfactorily in distinguishing correct warned events out of all warnings issued and unwarned events. Moreover, IMERG half-hourly data provided many false rainfall events occurrences, as reported by FAR equal to 0.41. Whenever the FAR and POD are both relatively high, it is safe to assume that over-warnings occurred [74]. It is noteworthy that the results at this time scale are in accordance with those of previous studies on hourly IMERG precipitation estimates for Sicily [22].

Table 5. Summary of the spatially averaged evaluation metrics at half-hourly and daily time scales for Sicily.

	2016 HH *	2017 HH	2018 HH	2019 HH	2020 HH	2016–2020 HH	Daily
CC	0.27	0.25	0.2	0.21	0.22	0.22	0.63
RBias	−1.26	−1.02	−1.14	−1.92	−1.05	−1.1	1.92
RMSE [mm]	0.86	0.77	0.87	0.86	0.75	0.86	3.3
NSE	−0.22	−0.34	−0.3	−0.11	−0.26	−0.4	0.38
POD	0.63	0.62	0.66	0.65	0.68	0.66	0.85
FAR	0.41	0.42	0.4	0.41	0.4	0.41	0.22
CSI	0.68	0.61	0.62	0.65	0.66	0.64	0.89

* HH refers to half-hourly estimates.

As expected, switching to daily data improved the performance in terms of both statistical and categorical indices compared to those obtained with half-hourly data. For instance, on average, CC equal to 0.63 indicated a stronger correlation with SIAS measurements compared to half-hourly data. Considering RBias, daily estimations showed a positive value, thus indicating an overestimation of ground-based data. As expected, errors within satellite estimates were larger in terms of RMSE at the daily scale than at the half-hourly scale, with values of 3.3 mm and 0.86 mm, respectively. This was mainly because the daily scale retrieval averaged out some of the short-term variability (including half-hourly estimates) and could be more robust to noise and errors, but it could also result in the loss of important information or a cumulation of errors within sub-daily retrievals. In contrast, the higher temporal resolution of the half-hourly scale captured more short-term variability in rainfall, but this also made the estimates more sensitive to noise and errors in the data, as well as to errors in the processing algorithms. On the other hand, NSE had a notable improvement from negative values to 0.34, indicating preferable estimations and better-matched ground measurements. Considering categorical indices, daily estimates generally exhibited less error in detecting precipitation compared to half-hourly ones, with decreasing FAR values and increasing values of POD and CSI. In this case, it is noteworthy that the results agree with those previously found over the same region by [22]. As these results have been previously proven by many authors [34,75–77] across the world and, more specifically, by [22] for Sicily, such an analysis confirms that an aggregating time scale has a significantly positive impact on satellite estimates.

In conclusion, the poor sub-hourly metrics and still improvable daily performances here obtained reveal the need for IMERG products to be corrected with ground observations across regions with complex terrain or improved with other methods such as the blending techniques discussed in Section 3.2.

3.2. Fusion Models Performance Analysis

3.2.1. Primary Results

This section presents the results obtained from applying two blending techniques. As previously mentioned, the main goal of such techniques is to improve the performance of IMERG precipitation estimates by optimally combining them with ancillary datasets that represent atmospheric and land surface characteristics. Half-hourly IMERG data show poor performance for the study area, as discussed in Section 3.1, and, therefore, there is a critical need to improve precipitation estimates at sub-daily/hourly time scales; however, the improvement techniques presented here were applied only to daily scale precipitation. This is mainly because the spatial and temporal resolutions of the ancillary data used here (SM and PWV) were lower than those of the IMERG data; in this case, the only temporal scale that matches with all ancillary data is the daily one.

With reference to the application of the Harmony Search algorithm, the coefficients of integrated multi-linear variant models (Equations (1) and (2)) were determined and are represented in Table 6.

Table 6. Summary of the coefficients related to the calibration of MLR models.

	Number of Parameters	C ₁	C ₂	C ₃	C ₄
P_{MLR_1}	3	2.041	0.167	0.152	-
P_{MLR_2}	4	1.719	0.178	0.091	0.138

According to [78], the importance of the predictor variables depends on the weights of the coefficients within a linear regression. In this case, as expected, IMERG had the heaviest weight among all datasets, while PWV had a stronger impact than SM on the regression procedure, unlike the results obtained by [79] for the Iberian Peninsula.

Figure 3 contains the spatial mean of the temporally averaged values for statistic and categoric metrics for daily rainfall events for the period 2016–2020. To facilitate visual comparison, all metrics were transformed into a scale that ranged between 0 and 1, with 1 representing the ideal value. Thus, a larger area on the spider plot indicates better model performance. This was also applied to RBias, which was converted to normalized bias (hereafter referred to as NBias) simply dividing by the total sample size.

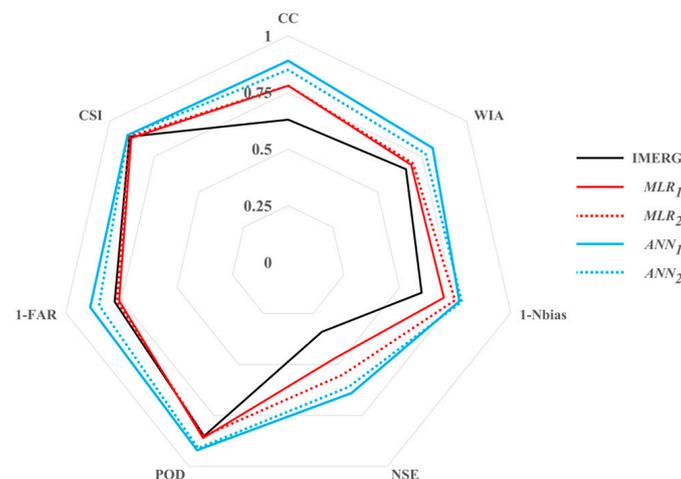


Figure 3. Spider plot showing the results of the general comparison of satellite precipitation estimates and the MLR and ANN models with observed data from SIAS rain gauge networks.

As the evaluation metrics reported in Figure 3 suggest, ANN_2 outperformed other models and the individual IMERG product. More generally, CC indicated a very high degree of agreement with reference to precipitation when passing from individual IMERG estimates to merged models, as shown in Figure 3. The values of NSE of the merged models imply an overall modest improvement compared to individual satellite products. Indeed, ranging from 0.55 to 0.64, NSE fell within the ideal range commonly defined for a model [80] and showed satisfactory estimates of merged models. Comparing the two methods of blending data, i.e., ANN and MLR, the use of ANNs led to a decrease in the magnitude of errors, as demonstrated by the highest values of WIA (0.81) and 1-NBias (0.77), indicating less overestimated data. MLR_1 produced a marginal improvement in the wetness index anomaly (WIA) to 0.70 compared to IMERG's WIA of 0.66. Conversely, MLR_2 's total increase in WIA of 0.3 was even less than the improvement attained by MLR_1 . This adverse performance of MLR_2 compared to MLR_1 may have been due to a nonlinear relation between rainfall and ancillary variables that made the WIA unsuitable to describe such a relationship. In addition, except for MLR_1 and MLR_2 , a general slight improvement was achieved in terms of POD and FAR when compared to IMERG estimates; higher values were reached for ANN_2 (i.e., 7% and 11%, respectively), which was recognized as the best estimator among all. From one point of view, improvements in categorical indicators were less considerable compared to improvements in statistical indices. This was a clear sign that improvements due to the blending techniques used were mainly reflected in estimations of rainfall intensity, volume, and overall trends rather than in the detection ability.

3.2.2. Spatial Analysis

To further evaluate the performance of the merged models for the study region, Figures 4 and 5 show the spatial distribution of selected statistical and categorical metrics, respectively, for Sicily for the period 2016–2020. Metrics were calculated using equations previously defined in Section 2.3, considering daily values as estimated from IMERG products and measured by the SIAS network.

With reference to Figures 4 and 5, the first row (panels a and b) shows the spatial distribution of the CC and RMSE calculated using IMERG daily estimations and SIAS reference data. To better highlight improvements due to the application of blending models and their possible spatial patterns, rows 2 through 5 (including panels c to j) instead show the percentage variation between the metrics obtained from the estimates of the blending model and the IMERG product, here used as a term of comparison, for each pixel. The difference was calculated using the following formula: $[(\text{Model Value} - \text{IMERG Value}) / \text{IMERG Value}] \times 100$.

Figure 4a,b depict the spatial distribution of the CC for IMERG, revealing that a vast majority of pixels exhibited good agreement with SIAS measurements (e.g., orange to red pixels), particularly in the central and southern regions. On the contrary, regions with complex orography on the east and northeast sides and the coastlines on the north and east sides of the island show less significant correlations. The spatial distribution of errors, as demonstrated by the RMSE map in Figure 4b, follows a similar pattern, with an average RMSE below 3.5 mm observed across the left-half side of the island, but increasing to over 7 mm in the south-eastern corner. This distinct spatial pattern of error distribution is aligned with patterns previously detected by [22,37]. Expectedly, CC and RMSE spatial distribution maps by IMERG V06 for 2016–2020 were quite similar to those of version 03 by [22] in 2015–2016 for Sicily. The worst performances along the coastlines are likely due to the weakness of the IMERG retrieval techniques in distinguishing the different radiative characteristics of hydrometeors over the land and ocean [14,25].

The spatial maps of differences depicted in Figure 4 reveal that all the blending models successfully improved precipitation estimations in terms of statistical metrics. Specifically, the MLR models improved the CC, especially on the east side and in the southern regions, despite some negative results indicated by dark grey pixels in Figure 4. Greater improvements were reached with the ANN models. Specifically, the ANN_2 model

improved pixels with previously weak values of CC that were not improved by the MLR models. The ANN models showed an increase in the level of agreement across the island, characterized by a pattern that included a 5–25% improvement along the coastline. Over 25% of the increase in agreement was concentrated in the eastern corners of the island, where the highest values of disagreement were observed. Conversely, there were either zero or minimal changes in the central parts of the island, where the level of agreement was already high. This improvement pattern was further accentuated by the use of the model ANN_2 .

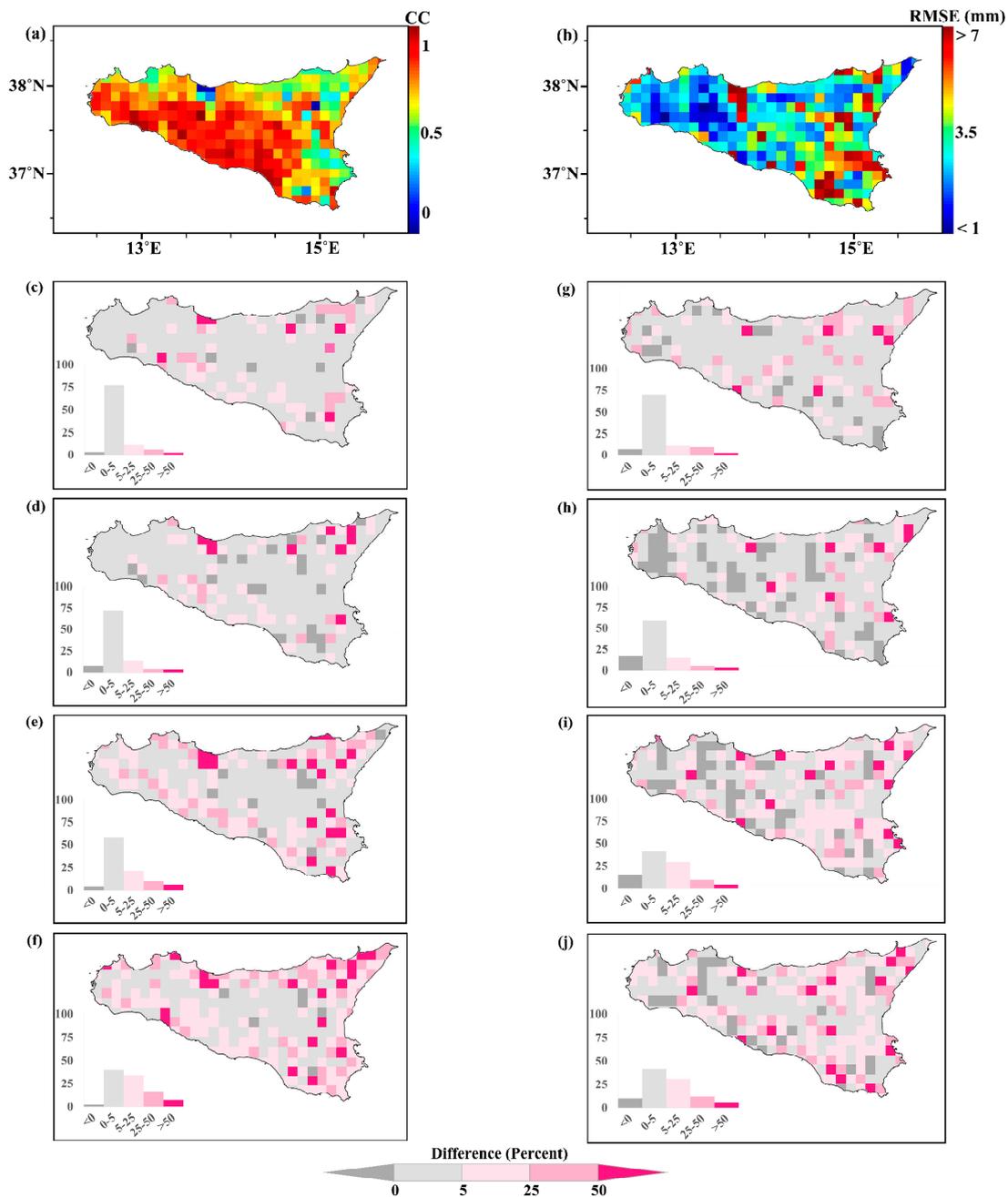


Figure 4. Comparison of IMERG data and model estimates. Panels on the first row (a,b) show the spatial distribution of CC and RMSE for IMERG individual products with reference to SIAS data, while the subsequent panels (c–j) illustrate the relative deviations of each blending model’s estimates from the IMERG data. The relative frequency function (percentage) of pixels falling within different classes is displayed inside each panel.

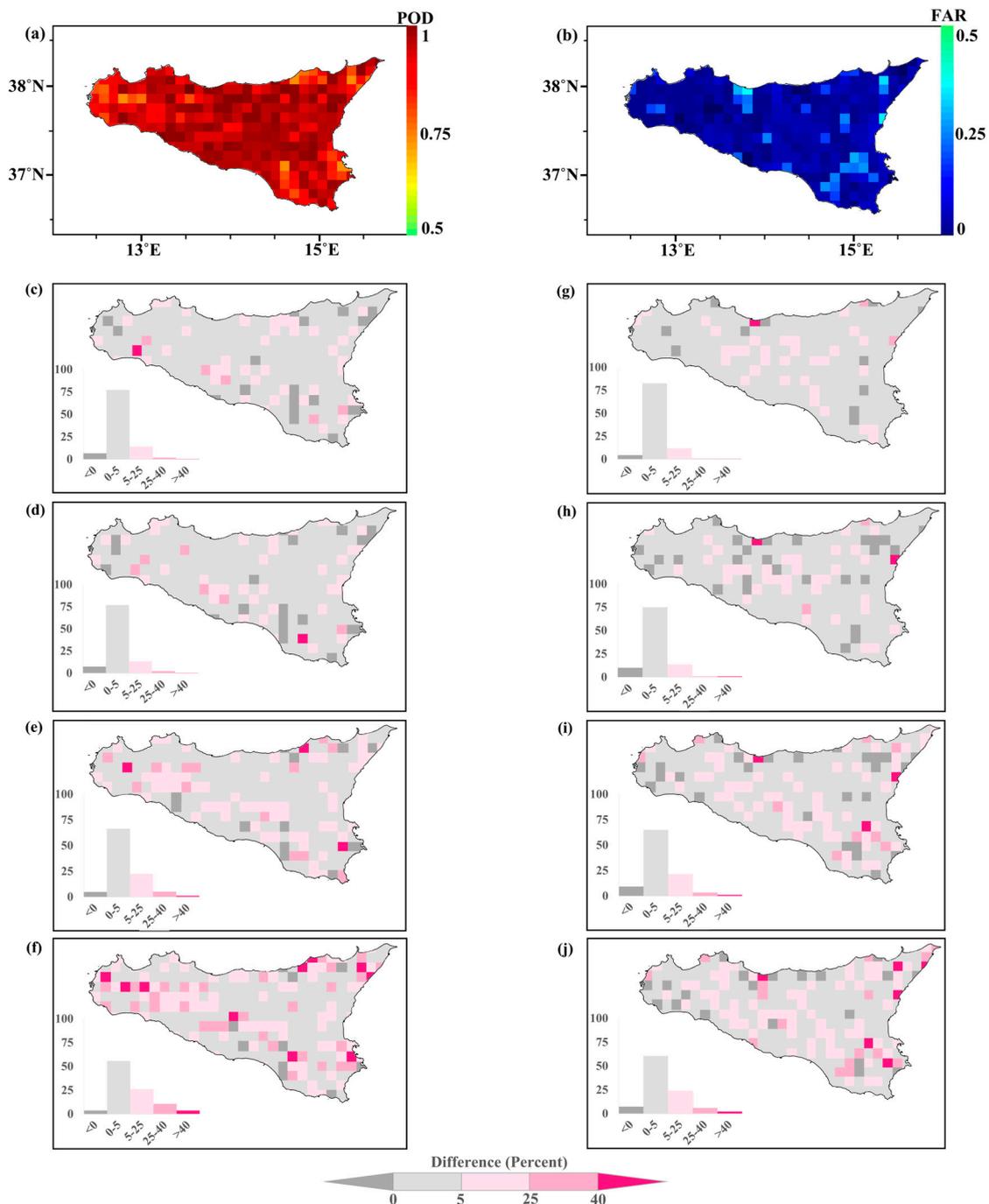


Figure 5. Same as Figure 4 but for categorical metrics (i.e., POD and FAR). Scale bars are modified to the ranges where the POD and FAR fell, i.e., 0.5–1 and 0–0.5, respectively. Panels on the first row (a,b) show the spatial distribution of POD and FAR for IMERG individual products with reference to SIAS data, while the subsequent panels (c–j) illustrate the relative deviations of each blending model’s estimates from the IMERG data. The relative frequency function (percentage) of pixels falling within different classes is displayed inside each panel.

Regarding the RMSE, the relative frequency function indicated that the number of pixels with worsened rainfall estimations decreased from MLRs to ANNs. Most pixels in MLR_1 exhibited negligible changes or remained unchanged, while the number of pixels with reduced RMSE increased in MLR_2 , even though this was compensated by many worsened estimations, especially in the west corner of the island, where the accuracy of remote

sensing instruments was adversely affected by complex oceanic streams. Consequently, no significant spatial improvements in RMSE were observed in MLR_1 or MLR_2 . However, as for the CC, ANNs not only followed a pattern of error reduction along the coastline of a 5–25% reduction in RMSE but also demonstrated a significant increase in the frequency of pixels that were improved by over 50% on the frequency function, with a concentration of pixels improved by over 25% on the right-half side of the island. Furthermore, in addition to the aforementioned improvement pattern, there was a reduction of over 50% in the high values of RMSE observed in a few individual pixels scattered throughout the island. Taken together, these findings suggest that the ANN models, specifically ANN_2 , yielded notable improvements in estimating precipitation patterns across the island, with an ability to capture the complex spatial variability of precipitation.

The findings from the analysis of the two categorical indices, POD and FAR, are presented in Figure 5a,b along with the deviation spatial maps of the proposed models (Figure 5c–j). The maps of POD and FAR illustrate the ability of IMERG to effectively distinguish daily rainfall events from non-rainfall events at various locations with a 95% probability of detection above the threshold of 1 mm. Overall, IMERG showed promising detection ability, with values approaching perfection for both POD and FAR, which is aligned with the spatiotemporally averaged values for IMERG reported in Figure 3 (POD = 0.85, FAR = 0.22). Nevertheless, some errors persisted, particularly in the three corners of the island. The spatial maps of categorical indices are aligned with the results of IMERG V03 by [22] and the Tropical Rainfall Measuring Mission (TRMM) Multisatellite Precipitation Analysis (TMPA) product by [37] for the region, as well as the spatial maps of CC and RMSE. Most pixels remained unchanged or experienced less than 5% improvement with all models, particularly MLRs. Conversely, ANN models, particularly ANN_2 , effectively improved detection capability in the poorly detected regions on the east and west corners, as demonstrated by the increase in dark pink pixels, while also substantially reducing the number of worsened pixels. Overall, the ANN_2 blending model was the most effective approach for improving detection in pixels that were frequently associated with inaccurate detections.

Examining in detail the major inconsistencies and errors between the gauge measurements, IMERG daily products, and daily estimations corrected by applying blending models, it is possible to notice worse performances over the eastern region, which is poorly gauged (especially in the southeast corner) and characterized by high intensity and depth of rainfall [28] and diverse mechanisms of precipitation (i.e., orographic rather than cyclonic) that can be challenging to estimate accurately due to interactions with complex orography causing large spatial variations [81–83].

A distinct spatial pattern of errors was observed repeatedly for Sicily when using TMPA product by [37], as well as with different old versions of IMERG products by [22], which was also identified in the present study using the latest version of an IMERG individual product. Hopefully, this pattern of errors was efficiently detected and addressed by the ANN models to obtain a more consistent spatial map of evaluation metrics. This additionally demonstrates the ANN_2 model's capability of integrating the response of soil moisture and precipitable water vapor of the atmosphere into the precipitation correction process more effectively than the MLR process.

3.2.3. Seasonality Analysis

To further diagnose the models' inter-comparison, Figure 6 illustrates the spatially averaged monthly time series of rainfall records from SIAS, along with generated estimates by IMERG, MLR, and ANN, for the period 2016–2020.

As shown in Figure 6, all rainfall products generally showed high agreement with the recorded rainfall pattern of the region, with wet autumn and spring seasons and dry summers. Considering NBias in Figure 3, a tendency towards overestimation was visible within all series, particularly during the wet seasons, which was significantly reduced by the ANN models. Generally, the blending models, particularly the ANNs, resulted

in substantial increases in agreement with ground records compared to the individual IMERG product.

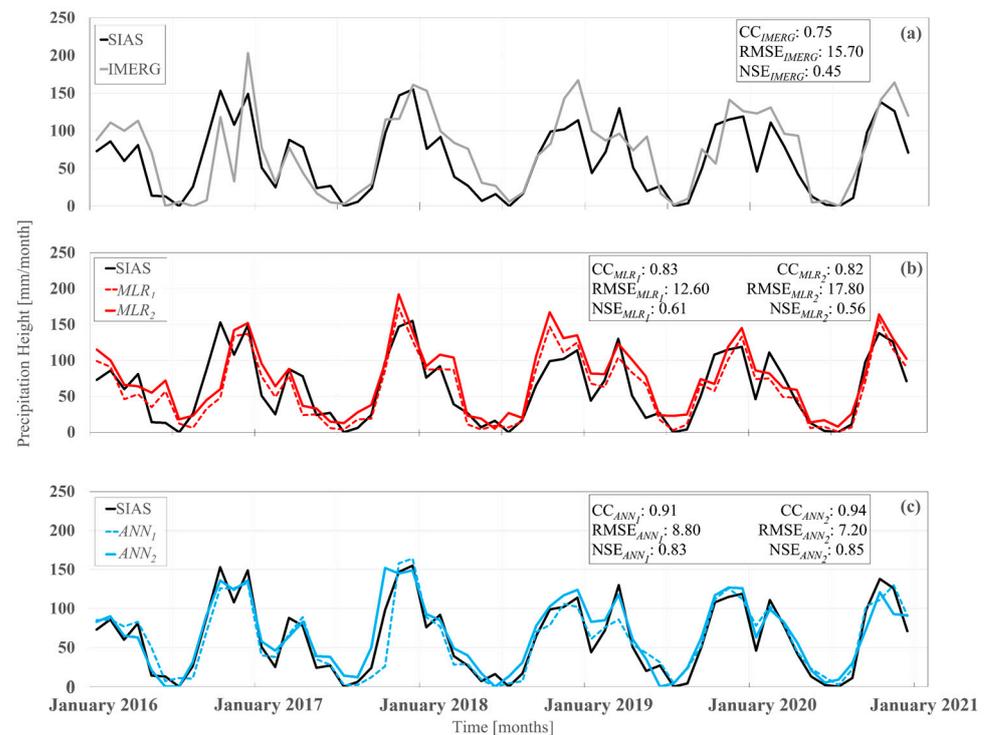


Figure 6. Monthly average rainfall series from 2016 to 2020 for SIAS (black line) compared to IMERG (grey line) in panel (a), generated MLR models (solid and dashed red lines) in panel (b), and generated ANN models (solid and dashed blue lines) in panel (c).

From Figure 6, a strong agreement between MLR_1 and SIAS records ($CC = 0.83$) at the monthly scale can be observed. After incorporating the SM variable into MLR_2 , a relative improvement compared to IMERG individual estimations was observed. However, it was outweighed by an increase in RMSE and a decrease in NSE values from 12.6 to 17.8 mm and from 0.61 to 0.56, respectively, when compared to MLR_1 . This indicated that either SM was highly correlated with the PWV, leading to redundant information being included in the model, or a simple linear model was not able to extract the relationships among variables, which ANN models do efficiently.

ANN models provided a time series close to the reference data, as shown by the NSE over 0.83 and CC over 0.91, with the magnitude of errors almost halved from 15.7 mm in IMERG to 7.2 mm in the ANN_2 model. After the analysis of the wet and dry seasons, the merged models appeared to be more consistent with SIAS measurements during dry months. Conversely, estimations showed more deviation from the reference data in wet seasons, mostly with reference to winter peaks, when the average depth of rainfall exceeded 100 mm rainfall. Comparing ANN_2 and ANN_1 for some wet months (e.g., October and December 2018, March and December 2019, and January and October 2020, to name a few), it is possible to observe that the SM variable contributed to improving the accuracy of precipitation estimates in wet months, as expected. On the other hand, in dry months, only negligible improvements were observed. Among all blending models, once again, ANN_2 appeared to be more aligned with the SIAS ground data and outperformed other models in terms of seasonality agreement.

3.2.4. Sensitivity Analysis

When blending independent variables to improve rainfall estimates, it is important to assess the sensitivity of the results to each input ancillary variable. One common approach

is to perform a sensitivity analysis by systematically removing one variable at a time from a model that includes all variables and quantifying the impact of that change on the accuracy of the estimations. The sensitivity of a model to the removal of individual input variables can be measured by computing the increase in the Mean Squared Error (MSE) of the model after the variable is removed while keeping the other input variables constant. The larger the increase in MSE, the more sensitive the model is to the removal of the variable, thus indicating the importance of that variable for the model performance.

The variable importance methodology first introduced by [78] helps to recognize influential variables and the relative contribution of each in improving the capability of a model in reproducing precipitation. The first step in such an analysis is to fit a model to a dataset using a chosen set of input variables. The baseline MSE of the model is then calculated using the chosen set of input variables. For each input variable, the variable is removed from the model, and the model is refitted to the data using the remaining variables. The new MSE for the model with the variable removed is then calculated. The percentage increase in MSE for each variable, hereafter named %IncMSE, was calculated by taking the difference between the baseline MSE and the new MSE after removing the variable and dividing the result by the baseline MSE. The input variables were then ranked based on their %IncMSE values, with larger values indicating greater importance. The results obtained by applying the variable importance test for the three explanatory variables (i.e., SM, PWV, and IMERG products) are presented in Figure 7.

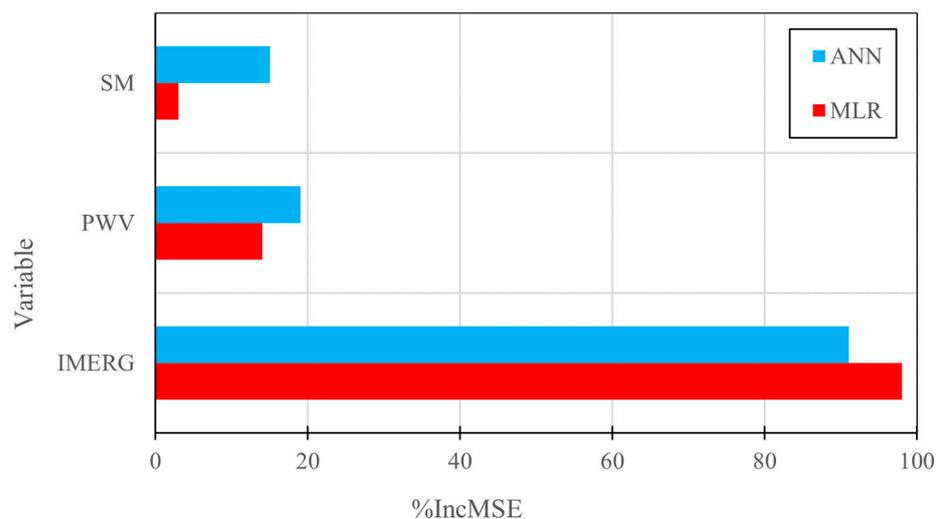


Figure 7. Variable importance plot for IMERG, PWV, and SM: %IncMSE is the percentage increase in mean square error.

As expected, IMERG satellite precipitation was ranked as the most important estimator variable, showing its strong impact in model estimations by producing the highest values of %IncMSE, i.e., 91% and 98% for MLR and ANN, respectively. Moreover, PWV was ranked as the next most significant variable by showing high %IncMSE, i.e., 14% and 19% for MLR and ANN, respectively. This meant that when including the PWV variable in the blending models, the mean square error between reference records and generated models decreased by an average of 14–19%. Comparing the values of WIA in Figure 3 for IMERG (0.69) to those of MLR_1 (0.69) and ANN_1 (0.77) suggested similar improvements in terms of reducing the magnitude of errors. Moreover, as previously observed in Figure 3, SM played a minor role in MLR by slightly improving the performance of the model. Here, the removal of the SM variable also caused negligible changes, with the lowest value of %IncMSE (i.e., 3%) observed in MLR_2 . This supports our previous observations that SM did not contribute to a considerable improvement within the linear regression blending model. Conversely, in a non-linear model such as ANN, the removal of the SM variable led to an increase in error, with a %IncMSE equal to approximately 15% observed in ANN_2 . This

finding is consistent with our previous observations from Figure 3, where the inclusion of SM and PWV within the ANN model led to a decrease in WIA from 0.70 to 0.69. These corroborate the findings reported in Section 3.2.1, which suggested that the ANN model outperformed the MLR model in accurately reconstructing precipitation estimates through the merging of IMERG products with PWV and SM variables.

4. Conclusions

Accurate and reliable precipitation data are a crucial input variable used in many hydrologic and hydraulic modeling frameworks, particularly in the context of climate change-induced sustainability and risk management policies. This study explored, for the first time in Sicily, the performance of half-hourly rainfall estimates and daily IMERG estimates in reproducing observed precipitation for the period 2016–2020. While the daily IMERG estimates provided satisfactory results for the investigated region, the half-hourly assessment revealed potential weaknesses, such as an inability to accurately distinguish between rainfall and non-rainfall events or represent precise values for rainfall depth.

Four merging models were developed within a multivariate regression and a neural network framework. To evaluate the improvement in detection power due to the application of the merged models, different statistical (i.e., CC, NBias, and RMSE) and categorical (i.e., POD, FAR, and CSI) indicators were used. The results show that exploiting SM and PWV data for the assessment of daily precipitation leads to improvements in the estimation of precipitation provided by IMERG products. Furthermore, the artificial neural networks and multiple linear regression fusion techniques improved the accuracy compared to the original IMERG product. Consistent with the findings reported by [4], who reported the failure of linear regression approaches in capturing the intricate and spatiotemporal nonlinear relationships between precipitation and other land/atmospheric variables compared with ANN approaches, this study showed significant improvements in precipitation estimation when using neural network models to merge SM and PWV with IMERG data compared to multivariate linear regression models. As the sensitivity analysis suggested, SM and PWV contributed efficiently and almost equally to enhancing rainfall estimates within an ANN framework. Despite the considerable improvement due to the blending models, a minority of errors still existed, especially in the west and northwest regions where the rainfall depth and intensity were both high.

In conclusion, the suggested ANN-based correction framework offers a promising solution for generating more reliable inputs in hydrological studies, particularly in complex terrain areas that are prone to extreme events such as the Mediterranean region. Its potential benefits extend to various scales, including catchment-level assessments and macro- and regional-level evaluations, which can contribute to water-related risk reduction efforts. To further refine the physically based ANN representation, it might be worthwhile to incorporate additional interconnected variables from the surface or atmosphere, such as land surface temperature, humidity, and wind, in future research.

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