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# Robotic and Sensor Technologies in Environmental Exploration and Monitoring

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### **Message from the Collection Editors**

Create a highly transdisciplinary discussion forum among scientists and engineers on robotic and technologies for the autonomous exploration, environmental monitoring, and in cursive manipulation of terrestrial and marine ecosystems. Applications can be presented in relation to different platform designs (including the biomimicking ones), energy systems (e.g., fuel cells), and navigation and data collection procedures (including storage, transmission, communication, and virtual-control interfaces). Fields of relevance can be the surveillance of maritime industrial activities, precision agriculture developments, exploration and assessment of and terrestrial georesources, exo-oceans exploration. and the spatiotemporally intensive measurements of ecosystems and their biodiversity or services (e.g., in cursive biological sampling and fisheryindependent stock assessment). Technologies for marine litter and microplastics quantification and removal are welcome. New sensor technologies of already existing ones (e.g., LiDAR, multispectral, and optoacoustic imaging) will be judged as interesting. Special preference will be given to new ecogenomic sensor applications.













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## **Message from the Editor-in-Chief**

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(Instrumentation)

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