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Establishment of a Reference Evapotranspiration Forecasting Model Based on Machine Learning

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Abstract: Water scarcity is a global problem. Deficit irrigation (DI) reduces evapotranspiration, improving water efficiency in agriculture. Reference evapotranspiration ET_0 is an important factor in determining DI. ET_0 forecasting predicts field water consumption and enables proactive irrigation decisions, offering guidance for water resource management. However, implementation of ET_0 forecasting faces challenges due to complex calculations and extensive meteorological data requirements. This project aims to develop a machine learning system for ET_0 forecasting. The project involves studying ET_0 methods and identifying required meteorological parameters. Historical meteorological data and weather forecasts were obtained from meteorological websites and analyzed for accuracy after preprocessing. A machine learning-based model was created to forecast reference crop evapotranspiration. The model's input parameters were selected through path analysis before it was optimized using Bayesian optimization to reduce overfitting and improve accuracy. Three forecasting models were developed: one based on historical meteorological data, one based on weather forecasts, and one that corrects the weather forecasts. All three models achieved good accuracy, with root mean square errors ranging from 0.52 to 0.81 mm/day. Among them, the model based on weather forecast had the highest accuracy; the RMSE six days before the forecast period was between 0.52 and 0.75 mm/day, and the RMSE on the seventh day of the forecast period was 1.12 mm/day. In summary, this project has established a mathematical model of ET_0 prediction based on machine learning, which can achieve more accurate predictions for within a few days.

Keywords: water resources; deficit irrigation; machine learning; agricultural irrigation forecasting; water resource management



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1. Introduction

In 2020, China's agricultural water consumption was 361.24 billion cubic meters, accounting for 62% of the country's total water use. The water-saving irrigation area is 37,795.99 thousand hectares, accounting for about 50% of the total irrigation area, and the effective utilization coefficient of farmland irrigation water is only 0.565 [1]. The development of agriculture largely depends on the rational use of water resources, but there are widespread problems of low water efficiency and serious water waste in agriculture at present. Much of the water is consumed by plants through transpiration, and crops use only 66% of the water used for irrigation [2]. This is a huge waste, and the application of defect irrigation can solve this problem, but there is a lack of an available scientifically and mathematically based guiding model. It is the goal of this article to address this lack.

With the further development of modern economy and society, the strategic position of water resources is becoming increasingly important, which also makes the development of water-saving agriculture become urgent, and water-saving science urgently needs reliable and convenient methods to promote.

As a kind of water-saving science, deficit irrigation (DI) is designed to stabilize yields and obtain maximum crop water productivity, not maximum yield [3]. As the most important factor of DI, it is very important to consider how the value of reference evapotranspiration (ET_0) can be obtained effectively and accurately. Traditional methods of measuring evapotranspiration rely on precision instruments like lysimeters. However, these methods have high equipment requirements and lack predictive capabilities. They cannot forecast future evapotranspiration. The Food and Agriculture Organization of the United Nations (FAO) provides a method to calculate evapotranspiration of reference crops using meteorological information. The evapotranspiration of reference crops is multiplied by the crop coefficient to obtain the evapotranspiration of specific crops [4].

With the maturity of computer technology, scholars at home and abroad have begun to use machine learning to forecast evapotranspiration in reference crops. Reference crop evapotranspiration forecasting is the key to realizing irrigation forecasting. The ET_0 forecasting model is trained by using past meteorological data as input. For example, Yin et al. [5]. Used the Mixed Bidirectional Long and Short Memory Network (Bi-LSTM) model to conduct ET_0 short-term forecasting. E Lucas et al. [6] used integrated convolutional neural networks for ET_0 prediction.

In this paper, a prediction model capable of predicting for the next seven days was constructed by using machine learning and meteorological data, additionally combining the crop coefficient method, soil water stress coefficient, and farmland water balance equation. This approach calculates the ET_0 and forecasts irrigation needs for the next seven days.

2. Materials and Methods

2.1. Experimental Data Source

The experimental data in this paper were divided into historical meteorological data and weather forecast data.

2.1.1. Sources of Historical Meteorological Data

MERRA-2 is a dataset of atmospheric reanalysis data provided by NASA. It combines historical observation data and numerical prediction to generate complete and stable historical weather data. The dataset includes temperature, relative humidity, wind speed, and net radiation data. Because these factors are strongly related to the weather, they have also been used in the establishment of various weather forecast models [7].

The nc4 file containing historical meteorological data for Haidian District In Beijing (116.25, 40.0) was downloaded from the official MERRA website (<https://gmao.gsfc.nasa.gov/reanalysis/MERRA-2>, accessed on 3 June 2023). The data covered a 10-year period from 1 December 2012 to 30 November 2022, with hourly intervals. The specific variables available in the dataset were temperature, specific humidity, wind speed, net short-wave radiation, and net long-wave radiation.

The parameters and units of hourly meteorological data are shown in Table 1.

Table 1. Historical meteorological data parameters and units.

Historical Meteorological Data	Units of Measure
Date	UTC
Air temperature	K
Specific humidity	g/kg
Average wind speed at 10 m	m/s
Average net short-wave radiation	W/m ²
Average net long-wave radiation	W/m ²

2.1.2. Sources of Meteorological Forecast Data

Choi Wan (<https://api.caiyunapp.com/>, accessed on 3 June 2023) has been a strategic partner of the China Meteorological Administration for many years, providing authoritative cloud weather forecast data since September 2014. To automatically crawl daily data, a

Python crawler was developed. The target area for data acquisition was Haidian District, Beijing (116.25, 40.0). The data required were from 21 October 2021 to 25 November 2021. Additionally, a total of 2870 daily forecast datasets were needed for the period of 23 December to 31 December 2022. The daily forecast data included maximum temperature, minimum temperature, maximum relative humidity, minimum relative humidity, 10 m wind speed, average solar radiation, maximum solar radiation, minimum solar radiation, and precipitation.

The weather forecast data and units obtained are detailed in Table 2.

Table 2. Meteorological forecast data parameters and units.

Historical Meteorological Data	Units of Measure
Date	UTC+ 8:00
Air temperature	°C
Relative humidity	%
Average wind speed at 10 m	m/s
Solar radiation	W/m ²

2.2. Prediction Methods of ET_0

FAO's PM Formula

Since the PM formula comprehensively considers the influence of various weather factors on ET_0 , and other alternative methods have their own limitations, such as the Hargreaves–Samani method [8] based on temperature calculation and the Priestley–Taylor method [9] based on radiation calculation, FAO defines the PM formula as the standard formula for calculating ET_0 . This paper also includes calculations according to the PM formula. This method defines a reference crop as a well-irrigated grassland with a height of 0.12 m, which is fully mulched, like a large, well-grown grassland. The reference crop is an imaginary crop with a surface resistance of 70 and a reflectance of 0.23. The PM formula considers both the physical evapotranspiration process of plants and meteorological parameters, making it effective at combining these variables. ET_0 represents the atmospheric evaporation capacity at a specific location over a certain period, and is not affected by actual crops or soil. Instead, it is calculated solely based on meteorological factors.

The PM formula for calculating ET_0 is as follows:

$$ET_0 = \frac{0.408\Delta(R_n - G) + \gamma \frac{900}{T+273} u_2 (e_s - e_a)}{\Delta + \gamma(1 + 0.34u_2)} \quad (1)$$

where ET_0 is the reference crop evapotranspiration calculated by day step, mm/day; Δ is the slope of saturated water vapor pressure curve at temperature T , kPa/°C; R_n is the net radiation of crop surface, MJ/(m²·day); G is soil heat flux, MJ/(m²·day); γ is the hygrometer constant, kPa/°C; T is the average daily temperature at 2 m altitude, °C; u_2 is the daily average wind speed at a height of 2 m, m/s; e_s is the daily average saturated vapor pressure, kPa; e_a is the daily average actual vapor pressure, kPa. The calculation formulas of these parameters are also provided in the FAO document. The meteorological factors can be solved according to the following formula, to calculate the reference crop evapotranspiration ET_0 :

1. Average daily temperature at 2 m altitude T_{mean} :

$$T_{mean} = \frac{T_{max} + T_{min}}{2} \quad (2)$$

where T_{mean} is the daily average temperature at a height of 2 m, °C; T_{max} is the daily maximum temperature at 2 m altitude, °C; T_{min} is the daily minimum temperature at 2 m altitude, °C. To standardize, the T_{mean} definition is the average daily highest temperature T_{max} and minimum temperature T_{min} , not average temperature per hour;

2. Daily mean saturated vapor pressure e_s :

$$e_s = \frac{e^0(T_{max}) + e^0(T_{min})}{2} \quad (3)$$

$$e^0(T) = 0.6108 \times \exp\left(\frac{17.27T}{T + 237.3}\right) \quad (4)$$

where e_s is the daily average saturated vapor pressure, kPa; $e^0(T)$ is the water vapor pressure at the air temperature T , kPa; T_{max} is the daily maximum temperature, °C; T_{min} is the daily minimum temperature in °C;

3. Daily mean actual vapor pressure e_a :

$$e_a = \frac{e^0(T_{max}) \frac{RH_{min}}{100} + e^0(T_{min}) \frac{RH_{max}}{100}}{2} \quad (5)$$

where e_a is the daily average actual water vapor pressure, kPa; RH_{max} is the daily maximum relative humidity, %; RH_{min} is the daily minimum relative humidity, %;

4. Slope of saturated vapor pressure curve Δ at temperature T :

$$\Delta = \frac{4098 \times 0.6108 \times \exp\left(\frac{17.27T}{T+237.3}\right)}{(T + 237.3)^2} = \frac{4098 \times e^0(T)}{(T + 237.3)^2} \quad (6)$$

where Δ is the slope of saturated water vapor pressure curve at temperature T (kPa/°C);

5. Hygrometer constant γ :

$$\gamma = 0.665 \times 10^{-3} P \quad (7)$$

$$P = 101.3 \left(\frac{293 - 0.0065z}{293} \right)^{5.26} \quad (8)$$

where γ is the hygrometer constant, kPa/°C; P is the atmospheric pressure, kPa; z is the altitude, m;

6. Daily average wind speed u_2 :

$$u_2 = u_h \frac{4.87}{\ln(67.82h - 5.42)} \quad (9)$$

where u_2 is the daily average wind speed at a height of 2 m, m/s; u_h is the average wind speed at h m, m/s; h is the height of the measured wind speed, m;

7. Net radiation from crop surface R_n :

$$R_n = R_{ns} - R_{nl} \quad (10)$$

where R_n is the net radiation of crop surface, MJ/(m²·day); R_{ns} is net shortwave radiation, MJ/(m²·day); R_{nl} is the net long-wave radiation, MJ/(m²·day).

2.3. Path Analysis

Path analysis refers to a statistical method that uses the path coefficient to analyze the correlation between variables. Path analysis provides a reliable basis for statistical decision making. Since it was first proposed by American scholar Sewall Wright [10], it has been widely used in many fields [11,12].

This study used path analysis to calculate the direct and indirect coefficients of each dependent variable in relation to the independent variable. This allowed the analysis of how each dependent variable determined the independent variable and contributed to its regression equation's R^2 . Based on the results, we selected the combination of dependent

variables that had the greatest impact on the independent variables to develop a more effective machine learning model with a simpler input.

The path analysis calculation process was as follows. Python was used in this study to write a program to achieve the calculation process.

1. Correlation analysis

The Pearson coefficient between the pairwise independent variables was calculated, and the calculation formula is shown in Equation (11). The Pearson coefficient between the independent variable and the dependent variable was calculated, as shown in Equation (12):

$$r_{i,j} = \frac{\sum_{i=1}^n (X_i - \bar{X}_i)(X_j - \bar{X}_j)}{\sqrt{\sum_{i=1}^n (X_i - \bar{X}_i)^2} \sqrt{\sum_{j=1}^n (X_j - \bar{X}_j)^2}} \quad (11)$$

$$r_{i,y} = \frac{\sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})}{\sqrt{\sum_{i=1}^n (X_i - \bar{X})^2} \sqrt{\sum_{i=1}^n (Y_i - \bar{Y})^2}} \quad (12)$$

2. Path coefficient

The relationship between the correlation coefficient and path coefficient is shown in Equation (13):

$$r_{i,y} = p_{i,y} + \sum_{i \neq j}^n r_{i,j} p_{j,y} \quad (13)$$

where $r_{i,y}$ is the Pearson coefficient between the independent variable X_i and the dependent variable Y ; $p_{i,y}$ is the direct path coefficient of the independent variable X_i to the dependent variable Y , indicating the direct effect of X_i on Y ; $r_{i,j}$ $p_{j,y}$ for independent variables X_i through independent variable X_j and the indirect path coefficient of dependent variable Y have indirect effects on Y . The path coefficient can be solved using Equation (13) to list n -element equations in one order, as shown in Equation (14):

$$\begin{cases} r_{1,y} = p_{1,y} + r_{1,1}p_{1,y} + \dots + r_{1,n}p_{n,y} \\ r_{2,y} = p_{2,y} + r_{2,1}p_{1,y} + \dots + r_{2,n}p_{n,y} \\ \vdots \\ r_{n,y} = p_{n,y} + r_{n,1}p_{1,y} + \dots + r_{n,n}p_{n,y} \end{cases} \quad (14)$$

3. Decision coefficient

The path coefficient defines the concept of coefficient of determination. However, the coefficient of determination of the dependent variable by multiple independent variables cannot determine the independent variable that has the greatest influence on the dependent variable. Therefore, Yuan et al. [13] proposed the concept of decision coefficient index based on the decision coefficient, reflecting the comprehensive determining effect of dependent variable X_i on independent variable Y through the network of other dependent variables. Since the decision coefficient index was proposed, most of the literature using the path analysis method has used it for decision analysis [14].

The calculation process of the decision coefficient is as follows:

1. R_i is the direct determinant of the independent variable X_i with respect to the dependent variable Y , as shown in Equation (15):

$$R_i^2 = p_{i,y}^2 \quad (15)$$

2. $R_{i,j}$ is the indirect determinant of the independent variable X_i with respect to the dependent variable Y , as shown in Equation (16):

$$R_{i,j}^2 = 2r_{i,j}p_{i,y}p_{j,y} \quad (16)$$

3. R is the coefficient of determination of all independent variables over dependent variables, as shown in Equation (17):

$$R^2 = \sum_{i=1}^n p_{i,y} r_{i,y} \quad (17)$$

4. $R_{(i)}$ is the decision coefficient of the independent variable X_i over the dependent variable Y , as shown in Equation (18):

$$R_{(i)}^2 = R_i^2 + \sum_{i \neq j} R_{i,j}^2 = p_{i,y}^2 + \sum_{i \neq j} 2r_{i,j} p_{i,y} p_{j,y} \quad (18)$$

2.4. Introduction to the Model

Meteorological data are tabular data, which are large in quantity and highly coupled. It is difficult to build predictive models through mathematics, and the advantages of machine learning techniques are just right for this scenario [15]. The author selected four suitable machine learning models, Random Forest, XGBoost and LightGBM, for data processing and compared the performance to select the most suitable model.

2.4.1. Random Forest

Random forest is a machine learning algorithm proposed by Breiman [16]. It integrates multiple decision trees through ensemble learning. Decision trees, first proposed by Morgan and Sonquist [17], consist of nodes and directed edges, with internal nodes representing features or attributes, and leaf nodes representing values. In regression tasks, the decision tree divides the feature space and recursively assigns test data to specific units, ultimately providing output values [18]. A random forest is constructed using sample perturbation and feature selection randomness, allowing each decision tree to use different datasets and select the best features for node splitting.

2.4.2. MLP

A multilayer perceptron (MLP) is a simple artificial neural network with a forward structure, which simulates and simplifies a structure like that of biological neurons. The basic structure of an MLP consists of an input layer, output layer, and several fully connected hidden layers. During training, input values are linearly transformed using weights and biases for each layer (except the input layer) then undergo nonlinear changes through an activation function before moving to the next layer [19].

2.4.3. XGBoost

A gradient boosting decision tree (GBDT) is an ensemble model based on the idea of boosting, while XGBoost (eXtreme Gradient Boosting) is a newer algorithm proposed by Chen and Guestrin [20] that builds upon GBDT. XGBoost follows the core principles of GBDT but improves upon them in several aspects:

1. Flexibility: XGBoost supports not only the CART algorithm used by GBDT but also linear classifiers and allows for custom loss functions, providing increased flexibility;
2. Improved Accuracy: XGBoost utilizes the second-order Taylor expansion to optimize the loss function, enhancing calculation accuracy;
3. Regularization: by incorporating regularization terms, XGBoost simplifies the model and avoids overfitting by removing constant terms;
4. Parallel Computation: XGBoost employs a block storage structure, enabling parallel computation for improved performance;
5. Column Sampling: inspired by random forests, XGBoost supports column sampling to reduce overfitting and computational overhead.

The XGBoost algorithm continuously adds new CART trees, making it an additive model composed of k base learning models [21]. During training, XGBoost predicts the

value for sample i after the t -th iteration based on the previous predictions and the t -th tree's model using Equation (19):

$$\hat{y}_i^{(t)} = \sum_{k=1}^t f_k(x_i) = \hat{y}_i^{(t-1)} + f_t(x_i) \quad (19)$$

In the training process, XGBoost pre-sorts features numerically and uses a greedy and approximate algorithm to find optimal split points for leaf nodes. Once the best split point for a feature is found, the data are divided into left and right child nodes.

2.4.4. LightGBM

LightGBM is also a GBDT-based algorithm, which was proposed by Microsoft Research Asia (MSRA) [22]. LightGBM optimizes the framework based on XGBoost, which greatly improves the running speed. The specific optimizations of LightGBM compared with XGBoost are as follows:

1. To transform traversal samples into traversal histograms, the histogram algorithm is employed. The process involves discretizing continuous eigenvalues into integers and establishing a histogram. As the data are traversed, statistics are accumulated in the histogram based on the discretized values. Once the traversal is complete, the histogram contains the necessary statistics. Finally, the optimal segmentation point is determined by traversing the histogram using its discrete values [23].
2. Single-side gradient sampling (GOSS) filters out many small-gradient data samples. This allows focusing on the remaining high-gradient data when calculating information gain. Compared with XGBoost traversing all eigenvalues, it saves a lot of time and space overhead.

2.4.5. Bayesian Optimization

Bayesian optimization is a popular method for adjusting model parameters. Unlike grid search and random search, Bayesian optimization leverages information from previous parameter combinations to efficiently seek the optimal combination. It is considered more reliable and efficient in the parameter adjustment process.

To implement Bayesian optimization in Python, we utilized the `bayes_opt` library and its `BayesianOptimization` function [24]. The implementation steps included:

1. Writing a custom model evaluation function that defined the model, parameters, and evaluation metrics targeted for Bayesian optimization;
2. Creating a Bayesian optimizer function that set the number of initial points and iterations;
3. Setting the parameter ranges to be optimized in the main function, calling the Bayesian optimizer function, providing the custom model evaluation function, and initiating the optimization process.

3. Results

To facilitate organization, this chapter is based on different data sources (historical meteorological data, weather forecast data, and corrected forecast data) to carry out the reference crop evapotranspiration forecast.

Each specific forecast result was subject to:

1. Path analysis: several inputs that have the greatest influence on ET_0 were selected;
2. Model selection: the algorithm model described in Section 2.4 was used for calculation, and the algorithm model with the best fitting effect was selected after comparing the fitting effect of the results;
3. Bayesian optimization: finally, Bayesian optimization was used to improve data performance;
4. Presentation of results.

Finally, the results of the three data sources are compared to select the best evapotranspiration forecast model.

Due to the repeatability of the processing of the three data sources, to ensure the simplicity of the results, the processing of historical meteorological data and weather forecast data is briefly introduced, while the processing of the corrected forecast data is fully described.

3.1. Forecast Reference Crop Evapotranspiration Based on Historical Meteorological Data

A direct method for predicting reference crop evapotranspiration based on historical meteorological data was implemented. First, historical meteorological data were used to calculate the reference crop evapotranspiration according to the FAO-PM formula mentioned in Section 2.2, and the result is then used as the output of the machine learning model. Historical meteorological data were used as input to train reference crop evapotranspiration forecast model based on historical meteorological data. Finally, weather forecast data were used as input to test the forecast accuracy of the model.

The forecast results using MLP and BO-MLP on the historical meteorological data test set are shown in Figure 1.

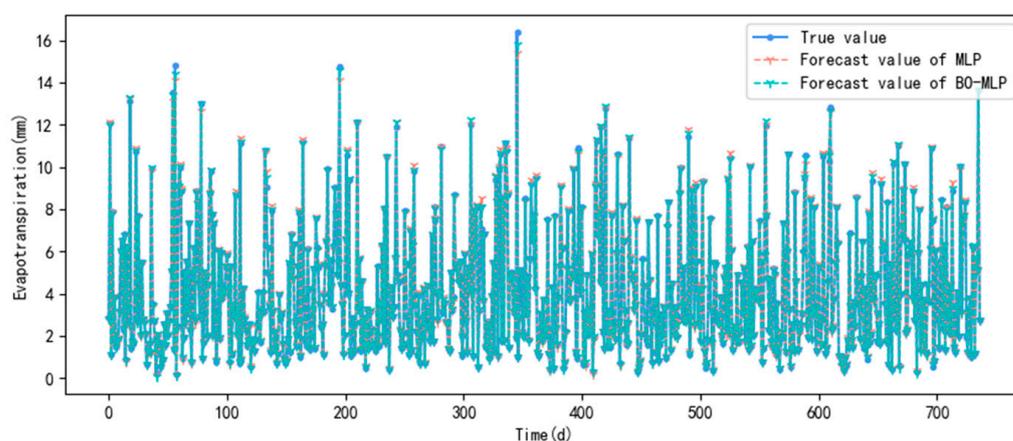


Figure 1. MLP and BO-MLP forecast results on the historical weather data test set.

Because of the complete historical meteorological data, the prediction accuracy of MLP using the historical meteorological data test set is very high. Before tuning, RMSE, R^2 , and MAE were 0.12 mm/d, 0.9986, and 0.08, respectively. After tuning, the accuracy of the model was further improved, with RMSE as low as 0.07 mm/d, R^2 as high as 0.9996, and MAE of 0.04.

The forecast results using the BO-MLP model with the weather forecast dataset are shown in Figure 2.

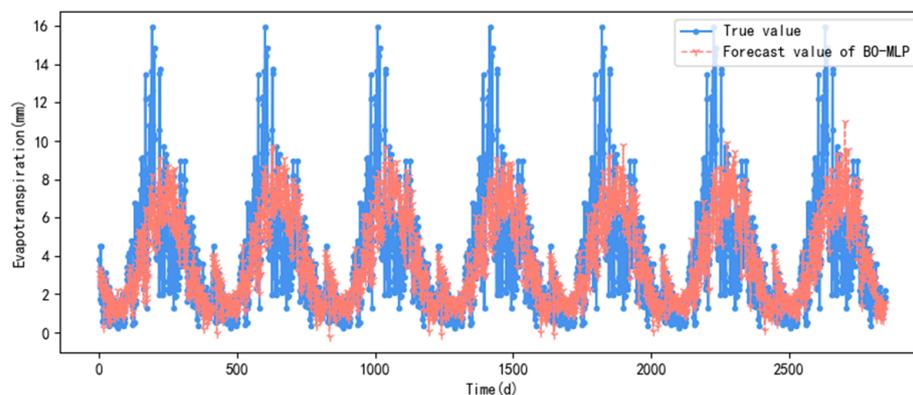


Figure 2. BO-MLP forecast results using weather forecast dataset.

3.2. Forecast Reference Crop Evapotranspiration Based on Weather Forecast Data

In this section, the indirect method of forecasting reference crop evapotranspiration based on weather forecast data is considered. Weather forecast data were taken as input and historical meteorological data ET_0 calculated by the PM formula were used as output to train the reference crop evapotranspiration model. Finally, the weather forecast test set was used to verify the model accuracy.

After path analysis and comparison of the above experiments, the BO-LGB model was used to construct the ET_0 forecast model based on weather forecasts using Combination 4 of meteorological factors as input. The forecast results using the test set are shown in Figure 3.

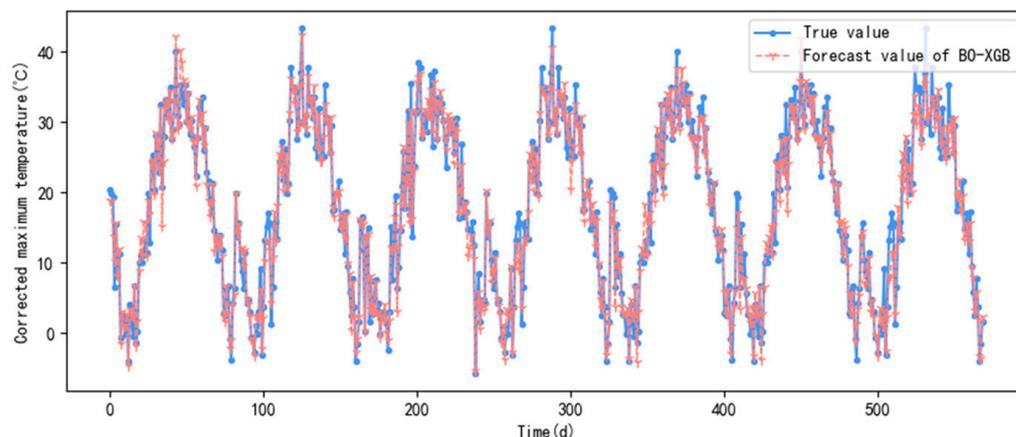


Figure 3. BO-LGB4 forecast results.

The RMSE values of the forecast results were calculated according to different forecast periods, as shown in Figure 4.

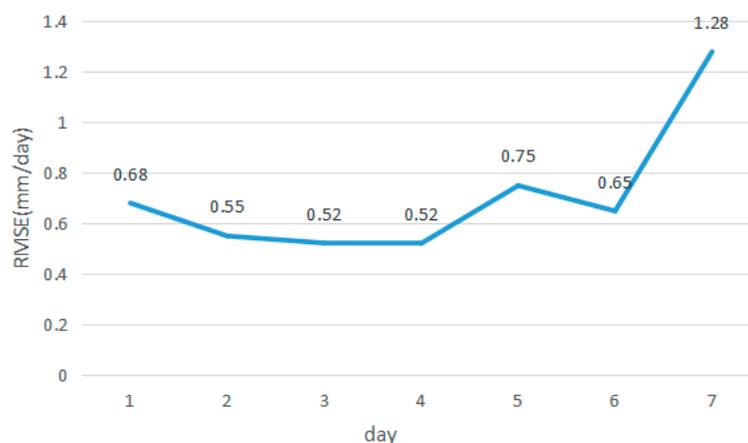


Figure 4. BO-LGB4 RMSE for different forecast periods.

The BO-LGB4 model based on weather forecast data was used to forecast ET_0 . The R^2 value using the test set was 0.996, the MAE was 0.47, and the RMSE was 0.74 mm/day.

3.3. Forecast Reference Crop Evapotranspiration Based on Corrected Forecast Data

This section assesses weather forecast data as input and corresponding meteorological data in the historical meteorological data as output, using machine learning to complete the correction of weather forecast.

After the comparison of the above experiments, the weather Combination 2 selected via path analysis was finally used as the input, and the forecast factor correction model was constructed using BO-LGB and BO-XGB models. The forecast results using the test set were shown in Figure 5.

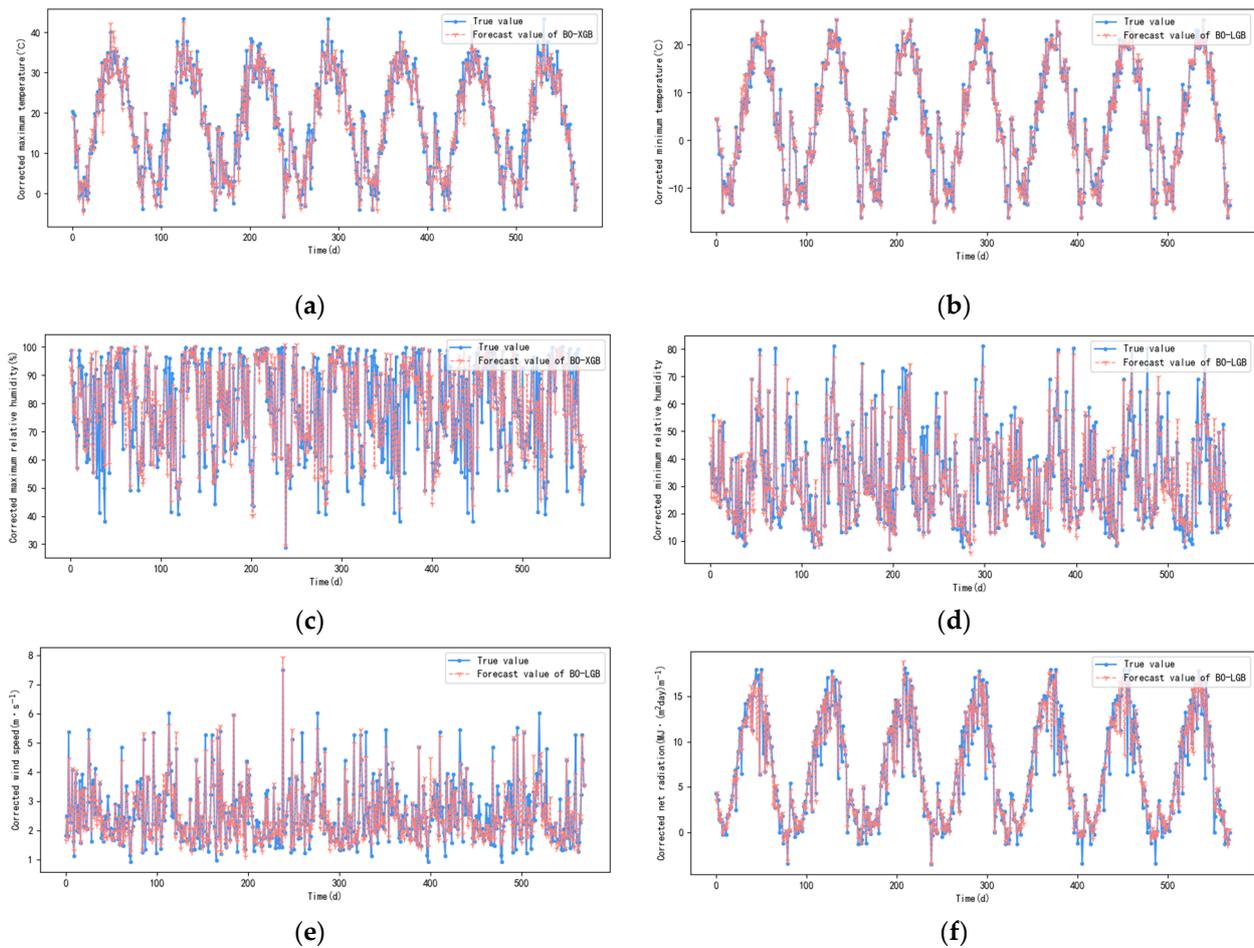


Figure 5. Predictor correction results (a) BO-XGB model corrects T_{max} results; (b) The BO-LGB model corrects T_{min} results; (c) BO-XGB corrects RH_{max} results; (d) BO-XGB corrects RH_{min} results; (e) BO-LGB corrects U_2 results; (f) BO-LGB corrects R_n results.

For the test set, the RMSE for the correction of the maximum temperature was $1.49\text{ }^{\circ}\text{C}$, the RMSE for the correction of the minimum temperature was $1.03\text{ }^{\circ}\text{C}$, the RMSE for the correction of the maximum relative humidity was 6.63% , the RMSE for the correction of the minimum relative humidity was 5.38% , and the RMSE for the correction of the wind speed was 0.39 m/s . The RMSE of the corrected net radiation was $1.22\text{ MJ}/(\text{m}^2\cdot\text{day})$. Using the corrected data and bringing it into the PM formula, the obtained prediction result of ET_0 is shown in Figure 6. R^2 was 0.93 , MAE was 0.44 mm/day , and RMSE was 0.76 mm/day .

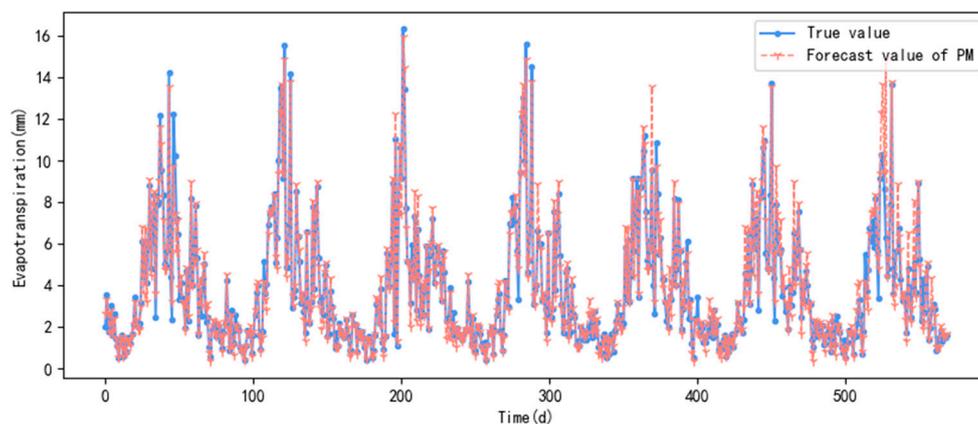


Figure 6. Correction of forecast data using the PM formula forecast results.

Using the corrected data, the BO-MLP model of Section 2.4.2 was brought in, and the result of forecasting ET_0 is shown in Figure 7. R^2 was 0.93, MAE was 0.51 mm/day, and RMSE was 0.81 mm/day.

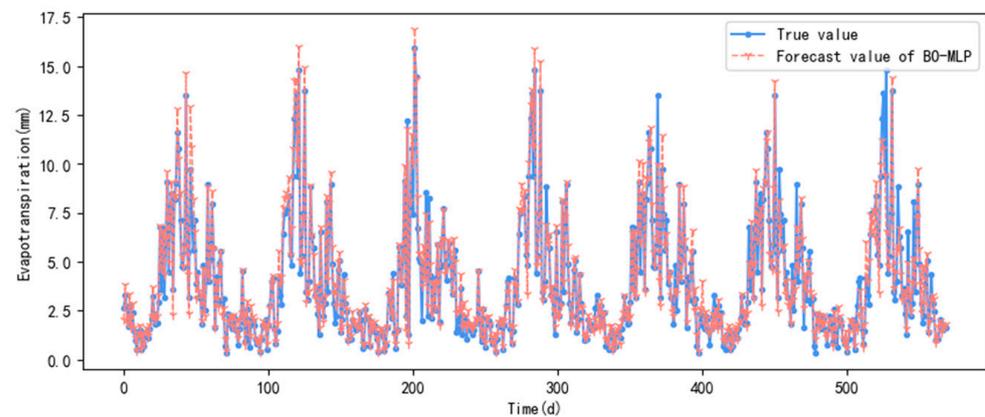


Figure 7. Correction of forecast data using BO-MLP forecasts.

4. Discussion

First, the results of the three data sources were analyzed around parameters such as RMSE.

4.1. ET_0 Forecast Model Based on Historical Meteorological Data

In the evaluation of model performance, historical weather data and corrected weather forecast data were used to compare the RMSE data size of the system. With the weather forecast dataset, the forecast accuracy of BO-MLP was greatly reduced, the forecast effect was not good, and the RMSE was 2.34 mm/d, which cannot meet practical application requirements. The reason for this analysis may be that the forecast accuracy is low and there is a prediction accuracy error, which makes the difference between the weather forecast data and the historical meteorological data large. Therefore, the weather forecast data cannot be used directly. So, it is necessary to correct the weather forecast data to obtain better accuracy and serve as the test data for the forecast model.

4.2. ET_0 Forecast Model Based on Weather Forecast

The BO-LGB4 model based on weather forecast data was used to forecast ET_0 . The R^2 value on the test set was 0.996, the MAE was 0.47, and the RMSE was 0.74 mm/day. The forecast accuracy was high, which met the application requirements. At the same time, the model was less affected by the forecast period. Except for the prediction period 7, the forecast accuracy significantly decreased, and the RMSE in other forecast periods was maintained between 0.520 and 0.748 mm/day.

4.3. ET_0 Forecast Model Based on Corrected Weather Forecast

The BO-MLP model based on the corrected weather forecast data performed well for ET_0 prediction. R^2 was 0.93, MAE was 0.51 mm/day, and RMSE was 0.81 mm/day. All of these reached the required accuracy range, but compared with the BO-LGB4 model based on weather forecast data, the level of optimization is not obvious. Since the weather forecast data must be corrected first before input, which increases the time consumption and computing power required, the authors believe that the use of corrected weather forecast data does not show enough advantage and practical value after consuming more computing power.

The authors think that the model based on weather forecast data has more application value.

Because changes in the weather are the result of the interaction of various factors, it is reasonable that the RMSE should increase with the increase of time. Moreover, due to

the cumulative error in evapotranspiration forecasting, RMSE increases with time, but the error within seven days is still within the acceptable range, so the model can be defined as successfully established.

5. Conclusions

The purpose of this study is to propose a machine learning-based ET_0 prediction model to serve precision irrigation scenarios and promote the application of DI. This paper attempts to compare the performance of historical meteorological data, weather forecasts, and corrected weather forecast data after processing by deep learning models such as MLP and random forest, and finally selects models and data sources that meet the accuracy expectations, exploring the possibility of applying machine learning methods in the field of precision agriculture. It provides a scientific basis for promoting agricultural water saving. Ultimately, the study created a forecast model based on weather forecast data that can predict irrigation demand over the next seven days with ideal accuracy.

5.1. ET_0 Forecast Model Based on Historical Meteorological Data

Firstly, the path analysis between historical meteorological data and ET_0 was carried out, and the conclusion drawn that the maximum temperature, radiation, and relative humidity have a great influence on ET_0 , so the forecast accuracy of these meteorological parameters is related to the result accuracy of method 1. After model selection and Bayesian optimization, the ET_0 forecast model based on historical meteorological data was obtained using MLP. The RMSE of the model on the historical meteorological data test set was 0.07 mm/day, and the RMSE on the weather forecast data set was 2.34 mm/day. The RMSE on the corrected weather forecast data test set was 0.81 mm/day. Due to the error of forecast accuracy in weather forecast and historical meteorological data, this method cannot be used between them, and better accuracy could be obtained only after the weather forecast was corrected.

The following are detailed descriptions of the three model processing steps:

5.2. ET_0 Forecast Model Based on Weather Forecast

Firstly, path analysis was conducted on the weather forecast data and ET_0 , and several meteorological factors with significant impact on ET_0 were identified. These factors were combined into six different input combinations of meteorological factors. After model selection, it was determined that the model with J' , T_{max} , T_{min} , and RH_{min} as inputs had the highest accuracy. This indicates that path analysis can effectively identify input factors with a significant impact, thereby improving model accuracy and reducing overfitting. Through the comparison of random forest, LightGBM, and XGBoost models, it was found that the BO-LGB model had the highest accuracy, and the RMSE on the weather forecast test set was 0.74 mm/day.

5.3. ET_0 Forecast Model Based on Corrected Weather Forecast

Firstly, path analysis was conducted between weather forecast data and corresponding historical meteorological data. This identified several meteorological factors that significantly impact the historical data, which were then divided into three input combinations. Combination 1 represents full factor correction, combination 2 involves multi-factor correction following path analysis selection, and combination 3 focuses on single-factor correction. Results reveal that combinations 1 and 2 exhibited higher accuracy compared with combination 3, with combination 2 showing lower overfitting than combination 1. Consequently, combination 2 was selected for weather forecasting factor correction. After comparing and optimizing the random forest, LightGBM, and XGBoost models, the corrected maximum temperature demonstrated an RMSE of 1.49 °C, the corrected minimum temperature had an RMSE of 1.03 °C, and the corrected maximum relative humidity exhibited an RMSE of 6.63%. The RMSE for minimum relative humidity correction was 5.38%, the RMSE for wind speed correction was 0.39 m/s, and the RMSE for net radiation correction was

1.22 MJ/(m²·day). Incorporating the corrected weather forecast data into the PM formula, the RMSE for the ET_0 forecast was 0.76 mm/day.

All three machine learning-based reference crop evapotranspiration prediction models achieved good accuracy, with the model based on weather forecast and the model based on corrected weather forecast demonstrating slightly higher accuracy, but with minimal difference. Considering the time cost, the direct use of weather forecast data is more suitable for practical applications. Analyzing the variation in model accuracy with the forecast period for the weather forecast-based ET_0 forecast model reveals a general decrease in accuracy with longer forecast periods. However, the RMSE in the first six days showed little difference, ranging from 0.52 to 0.75 mm/day, while the prediction accuracy for the seventh day was slightly worse at 1.12 mm/day.

The limitation of this study is that the time span of the weather forecast data set was limited, the amount of data was small, and the accuracy of the model needs to be improved. Secondly, the time that can be predicted is relatively limited, and good accuracy can only be achieved for up to seven days. Finally, the prediction model has not been verified by experiments in actual scenarios.

Further attempts can be made to increase the time span, which should lead to stronger forecast accuracy, and then attempts to forecast a longer time horizon in the future to verify the accuracy. It is hoped that this experiment can be verified on a global scale to confirm the feasibility of the theory. It is also possible to try more deep learning models to optimize the speed of computation and improve the accuracy of computation.

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