# Supplementary material for "The mechanisms for within-host influenza virus control affect model-based assessment and prediction of antiviral treatment"

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The supplementary material contains the following:

- 1. Supplementary figures (S1–S5)
- 2. MATLAB code for solving the TIV model
- 3. MATLAB code for solving the IR model

## **1** Supplementary figures



FIGURE S1: A solution of the TIV model with parameters given in Table S1 (no treatment).



FIGURE S2: A solution of the IR model with parameters given in Table S1 (no treatment).



Figure S3: Dependence of viral load profile on drug efficacy for the TIV model. The time course of plasma OC concentration is shown in the lower panel. For  $EC_{50}$  varying from 10 ng/mL to 300 ng/mL, corresponding viral load solutions are shown in the upper panel with different colours. The solution with no drug applied is shown in dashed black curve. In this simulation, target cell regrowth is not allowed by setting  $g_T = 0$ .



Figure S4: Dependence of infection-related quantities on drug efficacy for the TIV model with no target cell regrowth. As drug efficacy  $EC_{50}$  varies from 10 ng/mL to 800 ng/mL, infection-related quantities, AUC (**A** and **B**), peak viral load (**C**) and duration of infection (**D**), are shown in different panels. AUC<sub>8</sub>, AUC<sub>4</sub> and peak viral load are normalised to their corresponding quantities in the no-drug control. Insets show sub-parts of the plots. For duration of infection longer than 30 days, we truncate the duration at 30 days in panel **D**. The duration of infection without antiviral treatment is indicated by the dotted red line in panel **D**.



Figure S5: Dependence of infection-related quantities on drug efficacy for the IR model with no target cell regrowth. As drug efficacy  $EC_{50}$  varies from 10 ng/mL to 800 ng/mL, infection-related quantities, AUC (**A** and **B**), peak viral load (**C**) and duration of infection (**D**), are shown in different panels. AUC<sub>8</sub>, AUC<sub>4</sub> and peak viral load are normalised to their corresponding quantities in the no-drug control. The duration of infection without antiviral treatment is indicated by the dotted red line in panel **D**.

#### 2 MATLAB code for solving the TIV model

```
dt=0.01; % time step size
1
  time=0: dt:20; % simulation time
2
3
  % viral dynamic model parameters
4
  pV = 210:
5
  beta=5e-7;
6
  betap=3e-8;
7
  V0=1e+4;
8
  T0=7e+7;
9
  gT = 0.8;
10
  deltaV = 5;
11
  deltaI = 2;
12
13
  % PK parameters
14
  ka = 11.04; \% per day
15
  ke = 2.64; \% per day
16
  EC50=30; % ng/mL (varied)
17
  emax=0.98; % epsilon_max
18
  omega=4.63; % a factor converting mg to ng/mL
19
20
  % variable vectors and initial conditions
21
  V=zeros(1,length(time));
22
  V(1)=V0; T=V; T(1)=7e+7; I=T; I(1)=0; De=I; D=I;
23
24
  Dadmin=75; % applied NAI dose every 12 hours
25
  % set Dadmin = 0 for no-drug case
26
27
  Td0=28/24; % start of treatment (day)
28
  % vary Td0 to change the drug administration time
29
  Td=12/24; % period of dosage (one dose per 12 hours)
30
  Td_ind=round((Td0:Td:time(end))./dt+1);
31
32
  Tadmin=zeros (size (De));
33
  Tadmin(Td_ind)=Dadmin;
34
35
  init = [V(1), T(1), I(1), De(1), D(1)]'; % initial condition
36
37
  options = odeset('RelTol', 1e-3, 'AbsTol', 1e-6);
38
39
  for i=2:length(time)
40
       [~,Y] = ode15s (@TIVmodel,[0 dt], init, options, gT, pV, beta,
41
          betap, deltaV, deltaI, T0, ka, ke, EC50, emax, omega);
       V(i)=Y(end, 1); T(i)=Y(end, 2); I(i)=Y(end, 3);
42
       De(i)=Y(end, 4)+Tadmin(i);
43
      D(i) = Y(end, 5);
44
      % initial condition for next iteration
45
```

 $_{46} | init = [V(i), T(i), I(i), De(i), D(i)]';$ 

47 end

where the function "TIVmodel" appearing in the command of *ode15s* is given by

```
function ynew=TIVmodel (~, y, gT, pV, beta, betap, deltaV, deltaI, T0,
1
     ka, ke, EC50, emax, omega)
2
  ynew=zeros(5,1);
3
4
  %viral dynamic model
5
  ynew (1) = (1 - emax + y(5) / (y(5) + EC50)) + pV + y(3) - deltaV + y(1) - beta + y
6
     (1)*y(2); % equation of dV/dt
  ynew(2)=gT*y(2)*(1-(y(2)+y(3))/T0)-betap*y(1)*y(2); \% equation
7
      of dT/dt
  ynew(3)=betap*y(1)*y(2)-deltaI*y(3); % equation of dI/dt
8
9
  %PK model
10
  ynew(4)=-ka * y(4);
11
  ynew(5)=omega*ka*y(4)-ke*y(5); % equation of dD/dt
12
```

### **3** MATLAB code for solving the IR model

```
dt=0.01; % time step size
1
  time = 0: dt : 20;
2
3
  % PD parameters
4
  pV=210; beta=5e-7; betap=3e-8; kappaE=5e-5; pF=1e-5; kappaS=0.8;
5
  kappaL = 0.4; betaBn = 0.03; deltaP = 0.5; deltaS = 2; pS = 12; pL = 4;
6
  deltaL = 0.015; V0=1e+4; hC=1e+4; hB=1e+4; T0=7e+7; gT=0.8;
7
  deltaV = 5; deltaI = 2; kappaN = 2.5; pB = 20.8; pC = 7.2; phi = 0.33;
8
  rho = 2.6; deltaF = 2; betaCn = 1; deltaE = 0.57; tauC = 6; tauB = 4;
9
10
  % PK parameters
11
  ka = 11.04; \% per day
12
  ke=2.64; % per day
13
  EC50=30; % ng/mL (varied)
14
  emax=0.98; % epsilon_max
15
  omega=4.63; % a factor converting mg to ng/mL
16
17
  % index indicating when delayed process starts
18
  indC=round(tauC/dt+1); \% for tauC
19
  indB=round(tauB/dt+1); % for tauB
20
21
  % variable vectors and initial conditions
22
  V=zeros(1, length(time));
23
  V(1) = V0; T = V; T(1) = 7e + 7;
24
  I=T; I(1)=0; R=I; F=I;
25
  Cn=100*ones(1, length(time));
26
  Bn=100*ones(1, length(time));
27
_{28} | E=zeros (1, indC+length (time));
  P=I; AS=zeros(1, indB+length(time));
29
  AL=AS; De=I; D=I;
30
31
  Dadmin=75; % applied NAI dose every 12 hours
32
  \% set Dadmin = 0 for no-drug case
33
34
  Td0=28/24; % start of treatment (day)
35
  % vary Td0 to change the drug administration time
36
  Td=12/24; % period of dosage (one dose per 12 hours)
37
  Td_ind=round((Td0:Td:time(end))./dt+1);
38
39
  Tadmin=zeros (size (De));
40
  Tadmin(Td_ind)=Dadmin;
41
42
  init = [V(1), T(1), I(1), R(1), F(1), Cn(1), E(1), Bn(1), P(1), AS(1), AL
43
      (1),De(1),D(1)]'; % initial condition
44
_{45} options = odeset('RelTol', 1e-3, 'AbsTol', 1e-6);
```

46 for i=2:length(time) 47 [,Y] = ode15s(@IRmodel,[0 dt],init,options,E(i),AL(i),AS(48 i), phi, rho, deltaF, gT, pF, pV, beta, betap, kappaN, deltaV, deltaI, betaCn, betaBn, kappaE, kappaS, pL, pS, deltaL, deltaS, deltaP, deltaE, pC, pB, kappaL, hC, hB, TO, ka, ke, EC50, emax, omega); V(i) = Y(end, 1); T(i) = Y(end, 2); I(i) = Y(end, 3); R(i) = Y(end, 4);49 F(i)=Y(end,5); Cn(i)=Y(end,6); Bn(i)=Y(end,8); P(i)=Y(end,9); 50 E(indC+i)=Y(end,7);51 AS(indB+i)=Y(end, 10);52 AL(indB+i)=Y(end, 11);53 De(i)=Y(end, 12)+Tadmin(i);54 D(i) = Y(end, 13);55 % initial condition for next iteration 56 init = [V(i), T(i), I(i), R(i), F(i), Cn(i), E(indC+i), Bn(i), P(i),57 AS(indB+i), AL(indB+i), De(i), D(i)]';end 58

where the function "IRmodel" appearing in the command of ode15s is given by

```
function ynew=IRmodel (~, y, E, AL, AS, phi, rho, deltaF, gT, pF, pV, beta
 1
              , betap, kappaN, deltaV, deltaI, betaCn, betaBn, kappaE, kappaS, pL,
              pS, deltaL, deltaS, deltaP, deltaE, pC, pB, kappaL, hC, hB, TO, ka, ke,
              EC50, emax, omega)
 2
     ynew=zeros(13,1);
 3
     %viral dynamic model
 4
      ynew (1) = (1 - emax * y(13) / (y(13) + EC50)) * pV * y(3) - deltaV * y(1) - kappaS
 5
              *y(1)*AS-kappaL*y(1)*AL-beta*y(1)*y(2); \% equation of dV/dt
      y_{new}(2) = gT * (y(2) + y(4)) * (1 - (y(2) + y(3) + y(4)) / T0) - betap * y(1) * y(2)
 6
              +(rho*y(4)-phi*y(2)*y(5)); % equation of dT/dt
      ynew (3) = betap * y(1) * y(2) - deltaI * y(3) - kappaN * y(3) * y(5) - kappaE * y(3) + y(3) * y(5) - kappaE * y(3) + y(3) * y(3) + y
 7
              (3) * E; % equation of dI/dt
      ynew(4) = (phi*y(2)*y(5)-rho*y(4)); % equation of dR/dt
 8
      ynew(5)=pF*y(3)-deltaF*y(5); % equation of dF/dt
 9
      ynew(6)=-betaCn*y(1)./(y(1)+hC)*y(6); % equation of dC_n/dt
10
      ynew(7)=betaCn*y(1)./(y(1)+hC)*y(6)*exp(pC)-deltaE*y(7); %
11
              equation of dE/dt
      ynew(8)=-betaBn*y(1)./(y(1)+hB)*y(8); % equation of dB_n/dt
12
      ynew (9) = betaBn * y(1) . / (y(1) + hB) * y(8) * exp(pB) - deltaP * y(9); %
13
              equation of dP/dt
      y_{new}(10) = pS * y(9) - deltaS * y(10); \% equation of dA_S/dt
14
      ynew(11)=pL*y(9)-deltaL*y(11); % equation of dA_L/dt
15
16
     %PK model
17
     ynew (12) = -ka * y (12);
18
     ynew(13)=omega*ka*y(12)-ke*y(13); % equation of dD/dt
19
```