



Article Off-State Performance Characterization of an AlGaN/GaN Device via Artificial Neural Networks

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Abstract: Due to the complexity of the 2D coupling effects in AlGaN/GaN HEMTs, the characterization of a device's off-state performance remains the main obstacle to exploring the device's breakdown characteristics. To predict the off-state performance of AlGaN/GaN HEMTs with efficiency and veracity, an artificial neural network-based methodology is proposed in this paper. Given the structure parameters, the off-state current–voltage (I–V) curve can therefore be obtained along with the essential performance index, such as breakdown voltage (BV) and saturation leakage current, without any physics domain requirement. The trained neural network is verified by the good agreement between predictions and simulated data. The proposed tool can achieve a low average error of the off-state I–V curve prediction (Ave. Error < 5%) and consumes less than 0.001‰ of average computing time than in TCAD simulation. Meanwhile, the convergence issue of TCAD simulation is avoided using the proposed method.

Keywords: artificial neural network; off-state I-V curve; breakdown performance; AlGaN/GaN HEMT

1. Introduction

AlGaN/GaN devices have gained successful application in high-power fields due to their better than silicon performance [1,2]. One of the most essential performance parameters for a GaN-based power device is its capability to handle a high voltage in its off state [3]. The success of the designing and exploration of Si-based power devices in the past few decades has mainly relied on the mature combination of technology computeraided design (TCAD) tools and analytical models. This combined tool is currently not that applicable in the exploration of AlGaN/GaN HEMTs, who have much more complicated device physics. The simulations using commercial TCAD tools not only require the users for their abundant experience in physics and simulations. These time difference (TD) methodor Monte Carlo (MC) method-based simulations are also time-consuming and poor in convergence. Moreover, due to the complicated coupling effects resulting from the stacked structure and 2D distribution of charges, considering the influence of background carriers, traps, and interface states in AlGaN/GaN HEMT, such a defect of the conventional TCAD method is therefore amplified [4,5]. For the same reason, the physical analytical models which are expected to be capable of effectively characterizing the correlation between structure parameters and off-state performance are yet to be presented, demonstrating the difficulty of characterizing the off-state performance.

However, the machine learning (ML) techniques that have emerged in recent years provide a potential means to effectively predict these devices' performance without using physical-based models [6–8]. By using an artificial neural network (ANN), the ML-based methods can explore the latent relationship between input and output data via training



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Copyright: © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). a neural network that is constructed by several hidden-layer. Once the neural network is trained adequately by using enough valid data, the output data can therefore be predicted correctly and efficiently [9,10]. In this case, one group of input data consists of a set of device structure parameters and bias conditions. Nowadays, ML-based methods are employed to predict one or several core parameters such as breakdown voltage (BV) and on-resistance (Ron) [11]. Yet, the answer to the more complicated question of how the structure parameters of an AlGaN/GaN HEMT affect the off-state I–V curve and breakdown performance remains unclear.

In this paper, an efficient numerical method using a multi-layer ANN framework is proposed to characterize the off-state performance of AlGaN/GaN HEMTs. The proposed method features its capability to predict the complicated off-state performance of AlGaN/GaN HEMTs swiftly. The effectiveness and veracity of the ANN-based numerical methodology are effectively verified by their good agreement with calibrated TCAD simulations. The average error of the off-state I–V curve between the predictions and simulations is less than 5%. Meanwhile, since no physical models are employed in the proposed numerical approach, the average computing time using the proposed method is only 10^{-6} of that using the TCAD tool.

2. Off State Performance Prediction

As shown in Figure 1, an AlGaN/GaN HEMT is composed of a stacked structure of the AlGaN barrier layer, GaN channel layer, GaN buffer layer. Among them, a 2D layer of high-density polarization charge is formed at the AlGaN/GaN interface. This twodimensional electron gas (2DEG) not only determines the on-state characteristic but also plays an important part in off-state behavior. Table 1 gives the basic material properties of GaN for the simulation. Meanwhile, unlike the conventional Si-based lateral power devices, the GaN-based power devices' off-state breakdown performance is influenced by multiple 2D effects simultaneously. Such a collective 2D coupling effect is not only determined by the value of the devices' structure parameters, but also the unusual/unclear 2D physical mechanism, thus resulting in a distinctive off-state characteristic of the AlGaN/GaN HEMT.



Figure 1. Schematic diagram of AlGaN/GaN HEMT structure.

Table 1. The basic material properties of GaN.

Property	GaN	
Bandage (eV)	3.4	
Critical electric field (MV/cm)	3.3	
Thermal conductivity $(W/(cm \cdot K))$	1.3	
Electron carrier mobility $(cm^2/(V \cdot s))$	2000	
Electron saturation velocity (10^7 cm/s)	2.5	

In particular, as shown in Figure 2, the simulated off-state I–V curve indicates that the analysis of the off-state characteristics on the device is quite complicated. The three

plots in Figure 2 are exported from the commercial TCAD tool Sentaurus. The breakdown can occur under various states, such as partially depleted breakdown and fully depleted breakdown. When the breakdown occurs, the depletion region may be at different depletion stages, and the current trend will also occur differently. In particular, the condition can be ascribed to three different types according to the changing trend of leakage current with drain voltage [12,13]. Especially for the case of type 2, as shown in Figure 2, there are five different stages in the trend of leakage current, which also demonstrate the superior difficulty of the off-state characteristics analysis. Yet, the prediction of the off-state performance is essential to a power device such as an AlGaN/GaN HEMT. Hence, we propose the ANN-based method to characterize off-state characteristics. The proposed approach is expected to provide an efficient and accurate prediction tool by using the data to explore the latent relationship between the device and its off-state performance without physical requirements.



Figure 2. The off-state I-V curve of AlGaN/GaN HEMT.

For the ANN architecture used in this paper, the input neurons represent the applied voltage (i.e., V_{gs} , V_{ds}) and structure parameter (i.e., t_1 , t_2 , t_{bar} et al.). Figure 3 shows the overall flow of the proposed framework for off-state performance characterization. The number of hidden layers and the neurons are the training hyperparameters (i.e., weight, bias), which are subject to the tuning process to realize the optimal solution according to the complexity of the prediction task. The neurons of the output layer represent the current-related features, which are used as the input of the conversion function. As for the configurations for the proposed ANN, first, ReLU is employed as the nonlinear activation function [14]. Then, Adam optimizer is used to perform the error backpropagation process by updating the training parameters [15]. In addition, an adaptive learning rate is utilized to control the optimization process [16]. Moreover, the error between the output layer and the targets can be evaluated as the mean square error (*MSE*) [17], which can be formulated as:

$$MSE = \frac{1}{N} \sum_{i=0}^{N} (I_i - I_i^t)^2$$
(1)

where *N* is the total training data number and I_i and I_i^t are the predicted feature and target value of the *i*th sample, respectively.



Figure 3. The overall flow of the proposed framework for off-state performance characterization.

When the device is under the off-state condition, as the applied drain voltage V_d increases, the span of the current change will cover several orders of magnitude (i.e., from 10^{-16} to 10^{-9}), which will hinder the fitting ability between the training dataset and the neural network. Thus, to optimize the fitting capability, a conversion function (CF) is introduced. Mathematically, the conversion function in this work can be expressed as:

$$I_{\rm ds} = I_0 \cdot 10^{-l_i} \tag{2}$$

where I_0 denotes the standardization factor and I_i represents the output features of the output layer. The components of the conversion function can effectively guarantee that the range of output features I_i lie within a small range. It can not only eliminate the adverse effects caused by singular sample data, but also can accelerate the speed of gradient descent to find the optimal solution, which will improve the prediction accuracy. The dataset for the model training was generated by TCAD simulation. A total of 950 groups of devices were collected for off-state characteristics; 80% of the dataset was used to train the model, while the remaining part was used to evaluate the model. Table 2 shows the variation range of structural parameters. By combining the applied voltage (i.e., V_{gs} , V_{ds}) and structure parameters (i.e., t_1 , t_2 , t_{bar} et al.), the dataset for off-state performance characterization contains 78,595 samples. In addition, the ANN algorithm is established by using the available algorithms in the standard package Tensorflow and then utilized to characterize the off-state performance of AlGaN/GaN HEMT.

Table 2. AlGaN/GaN HEMTs structural parameters and their variation ranges.

Structural Parameters	Range
GaN channel thickness t_1 , (µm)	[0.2, 0.8]
GaN buffer thickness t_2 , (µm)	[0.6, 5.4]
AlGaN barrier thickness t _{bar} , (µm)	[0.005, 0.02]
The length of Gate to Drain, L_{GD} (µm)	[5, 25]
Al composition, Al	[0.15, 0.25]

3. Results and Discussion

3.1. ANN Model Prediction for Off-State I–V Curve

Figure 4 shows the comparison between the predicted results from the ANN-based framework and targets simulated by TCAD simulation. As shown in Figure 4, clearly, with the increase in the drain voltage, the different structures will go through different states to achieve breakdown. The three different types of off-state I–V curves corresponding to Figure 2 are given. The red round point line represents the off-state performance obtained by TCAD simulation, and the blue square point results, representing the predictions of the proposed ANN-based method, are almost in good agreement with the target simulation results, demonstrating the capability of the proposed approach. Moreover, all of these I–V curves can be effectively characterized by the ANN-based framework without physics domain knowledge.



Figure 4. The predicted off-state I–V curve of the ANN-based framework.

Figure 5 shows the off-state I–V curve prediction error changes under different training epochs. In the initial stage of the training process, the prediction error is relatively large, so the error drastically changes to optimize the loss function by updating the training weights and bias. As the training epoch increases, the error changes tend to converge, validating the effectiveness of the model optimization process. In addition, since the ANN-based model optimization is a dynamic tuning process by updating the training parameters, it is reasonable to have small fluctuations accompanying the training process. Meanwhile, the similar changes in training and testing errors indicate that no overfitting occurs during the model generalization process.



Figure 5. Off-state I–V curve prediction error changes corresponding to different training epochs.

3.2. The Effectiveness of Introducing Conversion Function

To examine the effectiveness of introducing the conversion function, we explore the prediction results without considering the conversion function (CF). Figure 6 gives the results by only using the ANN framework with and without the conversion function. The results represent the absolute error between the ANN-based predictions and TCAD simulation. The closer to zero, the better the results. As the figure shows, the absolute error between the prediction are close to zero. However, those results without CF fail to capture the relationship between the input features (i.e., V_{ds} , t_1 , t_2 , t_{bar} , etc.) and the drain current. Since the drain current covers a wide range of dimensional units, such a case will severely affect the convergence behavior of the ANN framework, thereby leading to training failure. However, by utilizing the conversion function to exponentially process the output results, the magnitude range of the data can be narrowed to a small range, making the network training more accurate and efficient.



Figure 6. The predicted results with and without the conversion function (CF).

Moreover, Figure 7 shows the results considering the conversion function without the standardization factor I_0 , as in Equation (1). The red circular points represent the results considering the standardization factor, while the purple square ones represent the result when the standardization factor is not considered. It can be observed that a better agreement between the targets and predictions can be achieved with the standardization factor. Obviously, especially for the case of type 2, compared to the results with the standardization factor, there is still a slight diversion from the target using the ANN-based prediction without the standardization factor. Thus, to further improve the prediction ability, the standardization factor I_0 is introduced to narrow the range of the output features, thereby optimizing the model training process.



Figure 7. The predicted results consider the conversion function without the standardization factor.

3.3. Breakdown Voltage Extraction

Figure 8 shows the breakdown voltage prediction results from the off-state I–V curve. The points represent the results obtained by the various machine learning algorithms, including support vector regression (SVR), Gaussian process regression (GPR), and the proposed ANN-based method. The solid black line represents the results where the targets are equal to the predictions. The closer the points are to the line, the higher the prediction accuracy of the results is. It is important to note that almost all predicted points

representing breakdown voltage are located on the target line with these machine learning approaches. Yet, by means of the numerical calculation, the use of the proposed ANN method allows an average prediction error of around 5%, which shows superior capability for the prediction task.



Figure 8. The breakdown voltage prediction results from the off-state I–V curve.

3.4. Time Comparison

To exhibit the efficiency of the proposed method, the time taken to predict the off-state I–V curve is also analyzed. By using the simulation tool to obtain the off-state performance, the average time for the various collected test structures is about 8 h or even longer due to convergence issues. However, for all different device structures, the time to predict such performance remains at 0.01 s with the ANN-based method. The computing time speeds up by more than 10^6 times compared to the TCAD tools. Moreover, the convergence issue which is associated with the TCAD tools is totally avoided by the proposed method.

4. Conclusions

In this paper, we propose an ANN-based predictive framework to predict the off-state curve of AlGaN/GaN HEMTs. By employing the proposed method, the complicated off-state performance can be accurately predicted without utilizing time-consuming TCAD simulation tools. The numerical results show that the proposed method is not only capable of tracing off-state I–V curves, but also appliable for predicting the critical parameter based on the structural parameters. Significantly, the average error of off-state I–V curve prediction is less than 5%. Moreover, since no physical equations and models are employed in the proposed approach, the convergence issue that easily occurs in TCAD tools is absolutely avoided. Meanwhile, by using the proposed method, the average computing time is only 10^{-6} of that using the TCAD tool.

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