



Supplementary Material

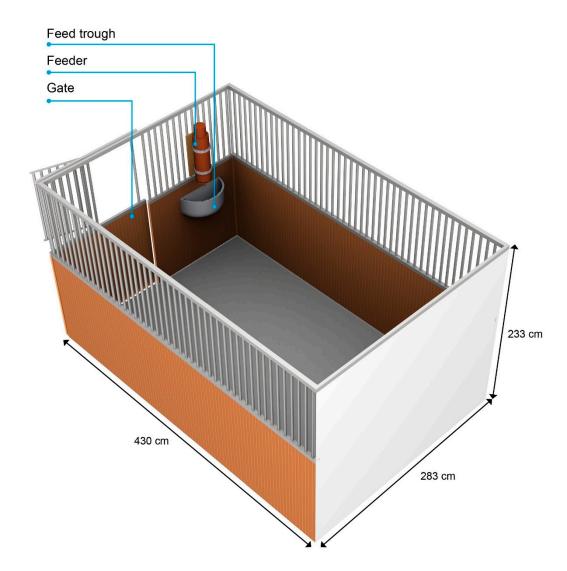
## The horses' (Equus caballus) laterality, stress hormones and task 2

## related behavior in innovative problem-solving 3

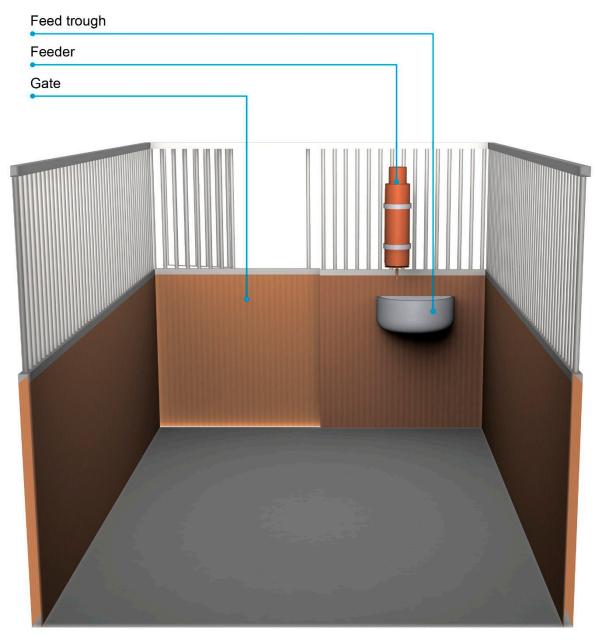
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- 13 Figure S1. Overview of the experimental area, the horse's box, type B. The horses were tested
- 14 in their own boxes. The boxes were closed on four sides and were made of wood up to a height of
- 15 130 cm and of lattice bars up to the height of 233 cm.

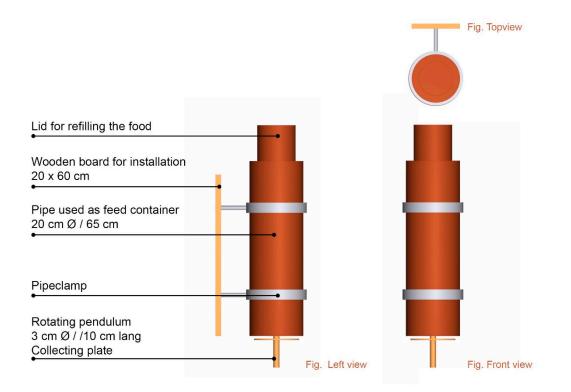


- 17 **Figure S2.** Inside the test area, the horses' box, type B. The feeder was installed above the feeding
- 18 trough. The feeding troughs were either on the left or the right side of the box and the entrance to the
- 19 box was on the opposite side from the feeding trough.



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- 23 Figure S3. Construction of the feeder. The feeder was similar to a casing tube with a
- 24 pendulum. When a horse moved the rod with the muzzle, a crossbar was rotated inside the
- 25 feeder, and small quantities of feed trickled onto the collection plate, and with further
- 26 rotation of the rod the feed fell from the collection plate in the feeding trough.



- 27 Figure S4. Criteria for evaluating the horses' sensory laterality. An approach of the horse to
- 28 the feeder was counted when a contact with the feeder followed the approach. A lateral
- 29 approach was counted when the horse twisted its head or body more than 10° to the left or
- 30 to the right to approach and contact the feeder
- 31
- 32 Figure S5. Horse lateral approach with a) the left eye, b) the right eye or c) in a neutral
- 33 position. The sensory laterality of the horses was analyzed from the video recordings by
- 34 noting the side of the head the horse turned towards the novel feeder for their first approach,
- 35 when contacting the feeder.



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58 Table S1. Horse motor laterality data. The motor laterality of the test horses was analysed 59 while they were grazing on the pasture in the weeks before the experiment was started. The 60 front leg that was placed forward was recorded every ten seconds until we had 200 61 recordings. These observations were distributed over three consecutive days for each horse. 62 A sensory and motor laterality index (Austin rogers 2012, 2014) was calculated for each 63 horse by applying the formula LI = (R - L) / (R + L). Where L stands for number of left scores 64 and R for the number of right scores. The index assigns a value between -1 and 1, in which 65 the range -1 to less than 0 stands for a preference for the left sensory organs or legs, while a 66 result between greater than 0 and +1 indicates a preference for the right ones and a result 67 equal to 0 means an ambilateral use of the right and left side. The absolute value of the 68 laterality index (|LI|) is a measurement of the strength of lateral bias irrespective of the 69 direction of the bias. To determine whether a preference of an individual horse was 70 significant Z scores  $(L - (L + R/2))/\sqrt{((L + R)/4)}$  were calculated. A z-score  $\ge 1.96$  or  $\le -1.96$ 71 indicates a lateral bias, a value between these two scores indicates no lateral bias 72 (ambilateral). Values of % left bias, calculated as L/(L + R) × 100, are also stated as a

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- 73 descriptive statistic to give an indication of the degree of bias but these were not used in any
- 74 of the calculations.
- 75 We categorized the horses to the following groups: innovative problem-solvers (ips), by chance
- 76 problem-solvers (cps) and non-problem-solvers (nps).
- 77

							laterality
Horse	group left	right	i	index	% left bias	z-score	group
Jana	cps	137	63	-0,37	68,50	5,23	left
Mirella	nps	197	3	-0,97	98,50	13,72	left
Kalinka	ips	146	54	-0,46	73,00	6,51	left
Floh	nps	94	106	0,06	47,00	-0,85	ambilateral
Melody	nps	78	112	0,18	41,05	-2,47	right
Filou	nps	94	106	0,06	47,00	-0,85	ambilateral
Tessa	nps	173	27	-0,73	86,50	10,32	left
Rimma	cps	121	79	-0,21	60,50	2,97	left
Sam	cps	89	111	0,11	44,50	-1,56	ambilateral
Szölo	cps	184	16	-0,84	92,00	11,88	left
Filly	nps	6	194	0,94	3,00	-13,29	right
Eloisa	ips	182	18	-0,82	91,00	11,60	left
Rio	cps	91	109	0,09	54,50	-1,27	ambilateral
Casuro	cps	184	16	-0,84	92,00	11,88	left
River	ips	179	21	-0,79	89.50	11,17	left
Quiso	ips	136	64	-0,36	68,00	5,09	left

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79

80	Table S2. Horse sensory laterality data. A new approach and contact were counted when
81	the interaction with the feeder was interrupted for more than ten seconds. Sensory laterality
82	was determined on the basis of the number of occurrences within the time period of the test.
83	A sensory and motor laterality index was calculated for each horse by applying the formula
84	LI = (R - L) / (R + L). Where L stands for number of left scores and R for the number of right
85	scores. The index assigns a value between -1 and 1, in which the range -1 to less than 0 stands
86	for a preference for the left sensory organs or legs, while a result between greater than 0 and
87	+1 indicates a preference for the right ones and a result equal to 0 means an ambilateral use
88	of the right and left side. The absolute value of the laterality index ( $ $ LI $ $ ) is a measurement of
89	the strength of lateral bias irrespective of the direction of the bias. To determine whether a
90	preference of an individual horse was significant Z scores (L – (L + R/2)/ $\sqrt{((L + R)/4)}$ were
91	calculated. A z-score $\ge$ 1.96 or $\le$ -1.96 indicates a lateral bias, a value between these two
92	scores indicates no lateral bias (ambilateral). Values of % left bias, calculated as L/(L + R) $\times$
93	100, are also stated as a descriptive statistic to give an indication of the degree of bias but

- 94 these were not used in any of the calculations. We categorized the horses to the following groups:
- 95 innovative problem-solvers (ips), by chance problem-solvers (cps) and non-problem-solvers (nps).

Horse	group	left	right	index	% left bias		laterality group
Jana	cps	15	44	0,49	25,42	-3,78	right
Mirella	nps	16	26	0,24	38,10	-1,54	ambilatera
Kalinka	ips	66	6	-0,83	91,67	7,07	lef
Melody	nps	5	9	0,29	35,71	-1,07	ambilatera
Floh	nps	78	135	0,27	36,62	-3,91	right
Filou	nps	18	1	-0,89	94,74	3,90	lef
Tessa	nps	8	7	-0,07	53,33	0,26	ambilateral
Rimma	cps	10	6	-0,25	62,50	1,00	ambilatera
Sam	cps	20	5	-0,60	80,00	3,00	lef
Szölo	cps	22	10	-0,38	68,75	2,12	lef
Filly	nps	17	10	-0,26	62,96	1,35	ambilateral
Eloisa	ips	6	5	-0,10	54,55	0,30	ambilatera
Rio	cps	14	2	-0,75	87,50	3,00	lef
River	ips	65	12	-0,69	84,42	6,04	lef
Casuro	cps	19	12	-0,23	61,29	1,26	ambilatera
Quiso	ips	59	20	-0,50	74,68	4,39	lef
generalized	omplete and linear mixed m food consumed	odels for cons	sidering rando	om and fixe	d effects on tl	ne depend	lent variable

115 metabolites, activity, latency, persistency, food motivation and tenacity as fixed factors.

**Consumption:** amount of consumed feed from the feeder; given in gram

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118
       Activity: sum of the duration of the video sequences is equal to the sum of the horses'
119
       being in motion, e.g. active; time is given in minutes
120
       Age: given in years
121
       B.ng.g: basal value (mean of 3 consecutive days) of the glucocorticoid metabolites in ng/g
122
       Food motivation: time needed to consume the feed in the pretrial, time is given in minutes
123
       Latency: time duration until first contact is the latency, time is given in minutes
124
       Motor laterality: laterality index
125
       Persistency: number of each test horse's contact with the feeder is the persistency
126
       Sensory laterality: laterality index
127
       Through position: Type B = right (1) or Type A = left (2)
128
       Sex: mare (1) or gelding (2)
129
       Size: measured at wither's height, given in meters
130
       T.ng.g: test value of the glucocorticoid metabolites in ng/g
131
       Tenacity: time spent with the feeder in relation to the agility, given as a percentage
132
133
134
       Including all factors
135
136
       Call:
137
       glm(formula = consumption ~ (activity + age + B.ng.g + food.motivation + latency
138
       + motor.laterality + persistency + (sensory.laterality/through.position) + sex +
139
       size + T.ng.g + tenacity)/ID, family = gaussian(identity),data = Dataset)
140
141
       Deviance Residuals:
142
              1
                         2
                                    3
                                               4
                                                          5
                                                                    6
                                                                               7
                                                                                          8
143
         86.145
                -151.377
                                1.265
                                         58.570
                                                   -27.156
                                                               33,607
                                                                         192.137
                                                                                     86.371
144
              9
                                                                   14
                        10
                                   11
                                              12
                                                         13
                                                                              15
                                                                                         16
145
       -197.804
                    -5.734 -112.043 -161.069
                                                   130.767
                                                                7.362
                                                                         -80.303
                                                                                    139.262
146
147
       Coefficients:
148
149
                                                                      Estimate
150
       (Intercept)
                                                                      3.445e+02
151
       activity
                                                                      3.003e+00
152
                                                                      4.314e+01
       age
153
                                                                      2.165e+00
       B.ng.g
154
       food.motivation
                                                                     -1.352e+02
155
                                                                      5.935e+00
       latency
156
       motor.laterality
                                                                    -5.550e+02
157
                                                                    -6.661e+00
       persistency
158
       sensory.laterality
                                                                    -2.455e+03
159
       sex
                                                                     -3.413e+02
160
       size
                                                                     -2.628e+03
161
                                                                      8.679e-01
       T.ng.g
```

162	tenacity	1.243e+02					
163	sensory.laterality:through.position	1.870e+03					
164	<pre>activity:age:B.ng.g:food.motivation:latency:motor.laterality:persistency:sensory.</pre>						
165	laterality:through.position:sex:size:T.ng.g:tenacity:ID	-1.392e-13					
166							
167		Std. Error					
168	(Intercept)	7.135e+03					
169	activity	2.730e+00					
170	age	1.533e+02					
171	B.ng.g	1.214e+01					
172	food.motivation	1.418e+03					
173	latency	3.125e+00					
174	motor.laterality	8.272e+02					
175	persistency	7.686e+00					
176	sensory.laterality	4.931e+03					
177	sex	1.638e+03					
178	size	6.094e+03					
179	T.ng.g	4.866e+00					
180	tenacity	6.230e+01					
181	sensory.laterality:through.position	3.845e+03					
182	<pre>activity:age:B.ng.g:food.motivation:latency:motor.latera</pre>	lity:persistency:sensory.					
183	laterality:through.position:sex:size:T.ng.g:tenacity:ID	1.970e-13					
184							
185		t value					
186	(Intercept)	0.048					
187	activity	1.100					
188	age	0.281					
189	B.ng.g	0.178					
190	food.motivation	-0.095					
191	latency	1.899					
192	motor.laterality	-0.671					
193	persistency	-0.867					
194	sensory.laterality	-0.498					
195	sex	-0.208					
196	size	-0.431					
197	T.ng.g	0.178					
198	tenacity	1.996					
199	sensory.laterality:through.position	0.486					
200	<pre>activity:age:B.ng.g:food.motivation:latency:motor.latera</pre>	lity:persistency:sensory.					
201	laterality:through.position:sex:size:T.ng.g:tenacity:ID	-0.707					
202							
203		Pr(> t )					
204	(Intercept)	0.969					
205	activity	0.470					

206	age				0	. 825	
200	B.ng.g					. 888	
207	food.motivation	0.939					
208							
	latency					. 309	
210	motor.laterality					.624	
211	persistency					. 545	
212	sensory.laterality					.706	
213	sex					.869	
214	size					.741	
215	T.ng.g					.888	
216	tenacity				0	.296	
217	sensory.laterality:t	hrough.po	sition		0	.712	
218	activity:age:B.ng.g:	food.moti	vation:late	ency:motor.	laterality	y:persister	ncy:sensory.
219	laterality:through.p	osition:s	ex:size:T.u	ng.g:tenaci	ty:ID 0	. 608	
220							
221	(Dispersion paramete	er for gau	ssian fami <sup>.</sup>	ly taken to	be 200664	4.3)	
222	Null deviance: 24443	8000 on 1	5 degrees	of freedom			
223	Residual deviance:	200664	on 1 deg	rees of fre	edom		
224	AIC: 228.39						
225							
226	Number of Fisher Sco	oring iter	ations: 2				
227							
228	After stepwise remo	val of fac	tors:				
229	Call:						
230	glm(formula = consumption ~ (activity + B.ng.g + food.motivation +						
231	latency + motor.	lateralit	y + persis <sup>.</sup>	tency + (se	nsory.late	erality/th	rough.positi
232	on) +						
233	sex + size + ter	nacity)/ID	, family =	gaussian(i	dentity),	data = Dat	taset)
234							
235	Deviance Residuals:						
236	1 2	3	4	5	6	7	8
237	85.680 -163.420	-12.157	38.217	-15.463	13.607	137.214	136.568
238	9 10	11	12	13	14	15	16
239	-195.507 6.973	-87.439	-134.663	109.683	12.632	-27.953	96.028
240							
241	Coefficients:						
242							
243				Est	imate		
244	(Intercept)				42e+03		
245	activity 2.575e+00						
246	B.ng.g 4.435e+00						
247	food.motivation 3.121e+02						
248	latency 5.292e+00						
249	motor.laterality -4.819e+02						
	motor raterally			-4.0	T)C+07		

250	persistency	-5.817e+00
251	sensory.laterality	-1.346e+03
252	sex	-8.359e+02
253	size	-8.364e+02
254	tenacity	1.099e+02
255	sensory.laterality:through.position	8.907e+02
256	<pre>activity:B.ng.g:food.motivation:latency:motor</pre>	
257	rality:through.position:sex:size:tenacity:ID	
258		
259		Std. Error
260	(Intercept)	1.186e+03
261	activity	6.692e-01
262	B.ng.g	1.845e+00
263	food.motivation	2.027e+02
264	latency	7.412e-01
265	motor.laterality	2.336e+02
266	persistency	3.368e+00
267	sensory.laterality	5.941e+02
268	sex	2.976e+02
269	size	8.018e+02
270	tenacity	1.425e+01
271	sensory.laterality:through.position	3.610e+02
272	<pre>activity:B.ng.g:food.motivation:latency:motor</pre>	.laterality:persistency:sensory.late
273	rality:through.position:sex:size:tenacity:ID	2.675e-10
274		
275		t value
276	(Intercept)	-1.554
277	activity	3.847
278	B.ng.g	2.404
279	food.motivation	1.539
280	latency	7.141
281	motor.laterality	-2.063
282	persistency	-1.727
283	sensory.laterality	-2.265
284	sex	-2.809
285	size	-1.043
286	tenacity	7.714
287	sensory.laterality:through.position	2.467
288	<pre>activity:B.ng.g:food.motivation:latency:motor</pre>	.laterality:persistency:sensory.late
289	rality:through.position:sex:size:tenacity:ID	-3.726
290		
291		Pr(> t )
292	(Intercept)	0.21808
293	activity	0.03099*

294	B.ng.g	0.09556'			
295	food.motivation	0.22139			
296	latency	0.00565**			
297	motor.laterality	0.13115			
298	persistency	0.18261			
299	sensory.laterality	0.10841			
300	sex	0.06734'			
301	size	0.37355			
302	tenacity	0.00453**			
303	sensory.laterality:through.position	0.09027'			
304	<pre>activity:B.ng.g:food.motivation:latency:motor.l</pre>	aterality:persistency:sensory.late			
305	rality:through.position:sex:size:tenacity:ID	0.03368*			
306					
307	Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.0	05 '.' 0.1 ' ' 1			
308					
309	(Dispersion parameter for gaussian family taker	n to be 53267.29)			
310	Null deviance: 24443000 on 15 degrees of freedom				
311	Residual deviance: 159802 on 3 degrees of freedom				
312	AIC: 220.75				
313					
314	Number of Fisher Scoring iterations: 2				
315					