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Solutions to Increase PV Hosting Capacity and Provision of Services from Flexible Energy Resources

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Received: 9 June 2020; Accepted: 22 July 2020; Published: 27 July 2020



Abstract: Future smart grids will be more dynamic with many variabilities related to generation, inertia, and topology changes. Therefore, more flexibility in form of several active and reactive power related technical services from different distributed energy resources (DER) will be needed for local (distribution network) and whole system (transmission network) needs. However, traditional distribution network operation and control principles are limiting the Photovoltaic (PV) hosting capacity of LV networks and the DER capability to provide system-wide technical services in certain situations. New active and adaptive control principles are needed in order to overcome these limitations. This paper studies and proposes solutions for adaptive settings and management schemes to increase PV hosting capacity and improve provision of frequency support related services by flexible energy resources. The studies show that unwanted interactions between different DER units and their control functions can be avoided with the proposed adaptive control methods. Simultaneously, also better distribution network PV hosting capacity and flexibility services provision from DER units even during very low load situations can be achieved.

Keywords: distributed energy resources; flexibility services; active network management; frequency control

1. Introduction

The potential of active (*P*) and reactive power (*Q*) control of distributed energy resources (DER) connected at distribution networks (MV and LV) is expected to be utilized increasingly in the future power systems to manage different renewable energy sources (RES) variabilities related challenges. These challenges related to larger share of RES based generation [1], concern (a) power generation fluctuations and (b) higher variability in power system inertia and fault levels. Moreover, network topologies need to be adapted by active network management (ANM) functionalities including occasionally intended island operation. DER consisting of distributed generation (DG), energy storages (ESs), demand response, or electric vehicles (EVs) can provide flexibility and resiliency for local (distribution system operator, DSO) and system-wide (transmission system operator, TSO) needs. Flexibility can also enable larger scale integration of RES and EVs and minimize the system and societal costs. The effective utilization of flexibilities requires combination and coordination of different types and sizes of resources from all voltage levels (LV, MV, and HV).

Traditionally used fixed on-load-tap-changer's (OLTC's) setting value is rather high because it considers only the existence of customer loads. Additionally, the same OLTC setting value is typically used during the whole year. These traditional OLTC's settings, together with fixed and uncoordinated

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DER units' droop control settings limit the PV hosting capacity of distribution networks and DER ability to provide power system frequency control support during very low load situations. In order to overcome these limitations, more active and adaptive distribution network operation and control principles are needed. Flexibility services provision must be enabled by DER management schemes, regulation, market structures, and business models. DER participation requires new distribution and transmission network operation and planning principles based on active utilization of flexibilities [2].

P and Q related flexibility services by DER can be realized by various inverter local control modes or functions. Inverter control functions such as constant power factor $(\cos\varphi)$, fixed Q, Q(P), $\cos\varphi(P)$, QU, PU, and Pf, where f is frequency and U is voltage, are already required by different network connection and operation codes. QU-droop control seems to be the preferred and most effective inverter-based DG units' voltage control method in distribution networks [3,4]. In order to increase DG hosting capacity and avoid curtailment of PV active power P, QU-droop is used as a primary voltage control method and P curtailment by PU-droop control as a secondary method. In order to achieve the best possible voltage level control in both MV and LV networks simultaneously, the control settings of distribution grid connected DER need to be coordinated with the HV/MV substation's OLTC settings. This improves further DER hosting capacity in distribution networks and reduces network losses [5–7]. Different DER unit control modes, settings, and coordination with OLTC settings should be increasingly considered in the planning stage to obtain the most benefits from the coordinated operation.

Amongst the various DER, battery energy storage systems (BESSs) are expected to play an important role in future smart grids due to their fast and controllable dynamics and potential to provide multiple different flexibility services in stationary applications. In many cases the use of BESS for only one purpose, for example, for (i) improving electricity supply reliability (in case of intended islanding or microgrid operation) or for (ii) increasing distribution network/PV hosting capacity [8,9] may not be an economically viable solution. Therefore, multi-purpose use cases are normally needed for the distribution network connected BESSs. In general, DER control can be roughly divided into local, distributed, and centralized control methods [10–12]. The management scheme can be also a hybrid i.e., combination of centralized and distributed control features. In the literature, different BESS control schemes and sizing principles have been proposed in [13–35]. Different control methods have been also proposed to improve the BESS dynamic inertial response [36]. It can be noted that some of the proposals, such as [10,36], consider only the use of active power P control and do not use the reactive power Q control for local voltage control. It has been shown however that more effective voltage control can be achieved by using both P and Q control capabilities of BESS [8,32]. Due to their rapid response and dynamics, BESSs are also capable of providing system-wide (TSO level) frequency control related services. These services can be realized by an individual large-scale BESS or by aggregating multiple small-scale BESSs [37,38]. The optimization of BESS for multi-purpose use in order to provide different local (DSO) and system level (TSO) services should be also taken into account [37].

This paper studies and proposes new solutions and adaptive settings and management schemes in order to increase DER (PV) hosting capacity and the capability of distribution network connected DER to provide flexibility services, predominantly frequency support for system-wide (TSO) needs. In particular, this paper deals with problems such as (1) the coordination between DER units functions and OLTC settings, (2) interactions between different DER units and their control functions, and (3) multi-purpose use of BESS to increase their short- and long-term viability for grid integration (stationary applications). Simulations focus mainly on studying the potential DER (PV and BESS) units QU-, PU-, and Pf-control interactions in different situations. Based on the case studies results, the paper proposes frequency adaptive PU-droops and role of PU-droops implementation logic with different DER configurations. The way unwanted interactions between DER units and their control functions can be avoided is shown. In addition, novel real-time adaptive management of DER PU-and QU-droops and PV-droops substation transformer's OLTC settings is proposed.

Section 2 of the paper presents the simulated case studies and explains the differences with previous research, the DER droop control settings, and the simulation sequence. Section 3 shows the

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PSCAD simulation results from the main study cases, presents simulation results by utilizing real-life frequency data, and proposes new frequency adaptive *PU*-droops for PVs and BESSs. In Section 4 new real-time adaptive management schemes for *PU*-droops, *PQ*-flow dependent OLTC settings, and OLTC setting dependent *QU*-droops are proposed. Finally, conclusions are drawn in Section 5.

2. Simulation Model and Study Cases

2.1. Simulated Study System

The initial choices made for this paper were based on conclusions from previous research in [39]. Paper [39] studied new multi-objective ANM scheme by simulating local smart grid pilot Sundom Smart Grid (SSG) with different future potential DER scenarios. Currently there are two DG units connected to SSG [39]. One 3.6 MW full-power-converter based wind turbine (WT) connected to MV network with own MV feeder J08 (Figure 1) and another LV network connected inverter based PV unit (33 kW) at MV/LV substation TR4318 (not included in Figure 1).

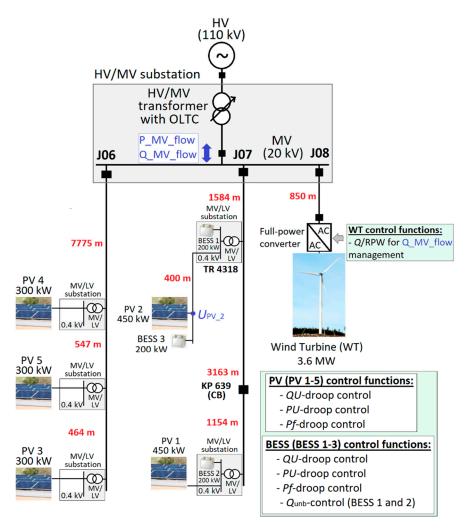


Figure 1. One-line diagram of the studied SSG in future scenario with more PV and BESS units in LV network, as well as with control functions applied in WT, PVs, and BESSs.

However, in the study cases of this paper also future scenarios with higher amount of PV units as well as with BESSs connected in LV network of SSG (Figure 1) are evaluated. As shown in Figure 1, in the studied future scenario there are two 450 kW PV units (PV 1 and PV 2) at MV feeder J07 and three 300 kW PV units (PV 3–5) at MV feeder J06. Respectively, three 200 kW BESS units (BESSs 1–3)

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were added to MV feeder J07 in different locations (Figure 1). Figure 1 also shows what type of control functions are applied in the studies of this paper for WT, PVs, and BESSs. Differences to the previous studies in [39] can be also seen in Table 1.

Table 1. Main focus areas of previous studies [39] and research work done in this paper.

Previous Studies [39] Research Work in the Paper 0. Initial choices (based on [39] findings) No QU- and PU-droops on WT Only Fingrid RPW-limits used which are fulfilled by the control of WT reactive power 1. Type of DER units 1. Type of DER units PV units (300 and 450 kW), BESS units (200 kW) PV units (300 kW) and WT (3.6 MW) and WT (3.6 MW), see Figure 1 and Table 2 Average models with controlled voltage sources Average models with controlled voltage sources 2. Droops and control functions of DER units Utilization of WT or PVs to fulfill RPW-limits 2. Droops and control functions of DER units QU- and PU-droop also on WT See Figure 1 Different QU- (seasonal) and PU-droops for PVs One *Pf*-droop for PVs 3. Focus on Solutions to increase PV hosting capacity in LV network as well as provision of services from LV 3. Focus on network connected DER Multi-objective ANM scheme Coordination between DER unit functions and Different RPW-limits (Fingrid and ENTSO-E) **OLTC** settings and control of reactive power flow between HV Multi-purpose use of BESS and MV networks Potential DER (PV and BESS) unit Pf- and Effect of different OLTC setting values *PU*-control interactions in different situations (20.7 or 20.0 kV) New frequency adaptive *PU*-droops (Section 3.2) Mutual/conflicting requirements between WT Role of PU-droops implementation logic with control functions) (QU-droop 2 and Q-control to different DER configurations fulfill RPW-limits) Very low and high load situations For example, effect of PU-blocking with PVs (only) and with PVs + BESSs Very low load situations 4. In addition, this paper presents new real-time adaptive management schemes (Section 4) for DER units' PU-droops, HV/MV substation transformer's OLTC setting \bigcirc value and DER units' QU-droops

In this paper, the studies were undertaken by utilizing Fingrid's (Finnish TSO) Reactive Power Window (RPW)-limits (see [39]) in scenarios with more PVs and BESSs (Figure 1) than in [39]. In the studied cases, WT alone is responsible for fulfilling the Fingrid's RPW-limits (Figure 1). In addition, during normal operation WT close to HV/MV substation does not need to have *QU*- or *PU*-droops. This also prevents potential mutual effects between control functions, which were reported in [39]. However, if WT would be connected to network in some back-up feeding configuration (e.g., during Sundom HV/MV primary transformer maintenance), then suitable *QU*- and *PU*-droops could be used. The main focus areas of previous studies in [39] and research work in this paper are summarized in Table 1.

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2.2. Droop Control of the DER Units

Figure 1 in Section 1 presented the type of control functions applied in the studies for WT, PVs, and BESSs. Voltage control of MV and LV distribution network is managed by HV/MV substation OLTC setting as well as by QU- and PU-droop control of PV and BESS units. In the simulations QU-droop control of the DER units is used as the primary local voltage control method and PU-droop control as the secondary method in order to avoid unnecessary P curtailment of PV units.

Increased reactive power *Q* production (Equation (1)) of cables during very high voltages and very low load currents can potentially lead to local overvoltage situations in the distribution network and therefore seasonal OLTC setting values could be used to improve DER hosting capacity of the network.

$$Q_{cable} = Q_{production} - Q_{consumption} = \omega C U^2 - 3\omega L I^2, \tag{1}$$

where

 ω = angular frequency,

C = cable capacitance,

U = cable voltage,

L = inductance/phase,

I = cable current.

In order to improve distribution network PV hosting capacity, the OLTC setting during very high load (winter season, total load 6548 kW, 283 kVAr) was chosen to be 20.3 kV (1.015 pu). Reactive power Q produced by cables is dependent on voltage (Equation (1)) and therefore lower OLTC setting is more suitable during summer time when cable load current I dependent reactive power consumption is also smaller. In the simulations during very-low load (summer season, total load 970 kW, -660 kVAr) the set value of OLTC was 20.0 kV (1.0 pu) with dead-zone \pm 0.3 kV/0.015 pu and 7.0 s operation time delay (due to short simulation time t = 110 s). Total load includes also P losses and Q produced/consumed by cables and overhead lines.

Respectively, seasonal *QU*- and *PU*-droops should be utilized for DER units in order to improve the DER hosting capacity of the distribution network. In addition, the seasonal *QU*- and *PU*-droops should be compatible with the seasonal OLTC setting values as well as coordinated between different type of units. This means that, for example, *PU*-droop settings of PV and BESS units at the same connection point should be coordinated so that unnecessary active power curtailment of PV unit due to local overvoltage can be avoided by simultaneous charging of the BESS unit.

The used QU-droops, PU-droops, and Pf-droop of PV and BESS units are shown in Figure 2. It can be noted that BESSs 1 and 2 (Figure 1) have also the $Q_{\rm unb}$ -control responsibility in order to enable correct operation of passive islanding detection methods [40–42]. In many grid codes, like in ENTSO-E NC RfG [43], the required reactive power feeding/absorbing capability of the DER units is defined to be range $\cos(\varphi) = 0.95_{\rm ind/cap}$ and that has been also used in this paper for defining the reactive power limits of the DER unit (PV and BESS) QU-droops (Figure 2a,b). The basis for dimensioning the DC/AC converter of the PV unit can be found e.g., from [44]. However, in order to reduce the needed simulation time with multiple connected DER units (PVs, BESSs, and WT), average models with controlled voltage sources are used instead of actual power-electronics switches in PSCAD models utilized in the studies of this paper.

In the simulation studies of this paper, PV and BESS units had different chosen *QU*-droops for winter (PV/BESS *QU*-droop 2, Figure 2a,b) and summer time (PV/BESS *QU*-droop 1, Figure 2a,b). Dead-zone of *QU*-droops during summer time was chosen to be smaller in order to compensate more reactive power produced by cables during very low load. In the studies, coordinated *PU*-droop settings of PV and BESS units were also used (Figure 2c).

In addition, PV and BESS units have *Pf*-droop functions (Figures 1 and 2d) in order to participate in frequency control during over-/under-frequency situations. In the simulations, two different *Pf*-droops

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for PVs and BESSs with smaller and larger dead-zones were utilized (Figure 2d). The *Pf*-droops smaller dead-zones are used during summer time (PV/BESS *Pf*-droop 1, Figure 2d) when there is typically also less inertia in the power system and need for more rapid response from DER units to support the power system frequency. The used *Pf*-droops are also more sensitive than those required by the grid codes, because the idea is that the PV and BESS units could offer participation in frequency control as a flexibility service, for example, through a flexibility marketplace.

The implementation of PV unit's active and reactive power droop control functions in the used PSCAD model is shown in Figure 3 (see also Figures 1 and 2). From Figure 3 it can be seen how the active and reactive power controllers with respective droop functions (QU-, PU-, and Pf-droops) will create the active and reactive power references (P-ref, Q-ref) which are further processed in order to have current reference values (I_{d} -ref) for the current controller. The current controller (Figure 3) then gives the voltage reference values (V-ref) for the controlled voltage sources in the PSCAD model. In the simulations it was also found out that the mutual effects of Pf- and PU-control functions on PV 2 (Figure 1) during over-frequency support participation need additional blocking logic (PU-blocking in Figure 3) in the control system. Otherwise, the active power of PV unit PV 2 needs to be curtailed and it cannot participate in frequency control due to mutual interaction of Pf- and PU-control functionalities. In the PSCAD simulations, the control functionality of BESS units was very similar when compared to the PVs (Figure 3).

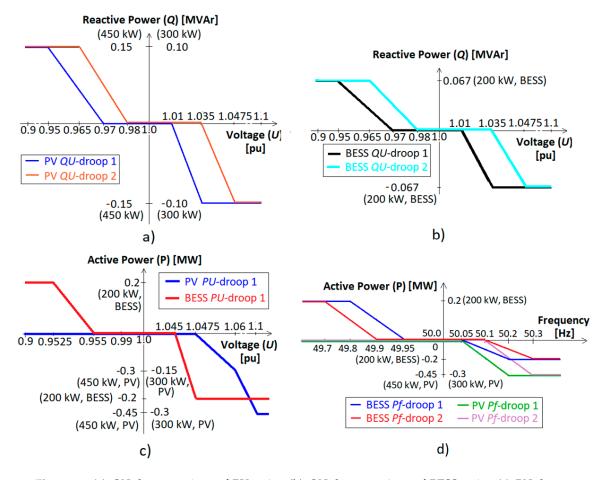


Figure 2. (a) *QU*-droop settings of PV units, (b) *QU*-droop settings of BESS units, (c) *PU*-droop settings of PV and BESS units, and (d) *Pf*-droop settings of BESS units which were used in the PSCAD simulations (see also Figures 1 and 3).

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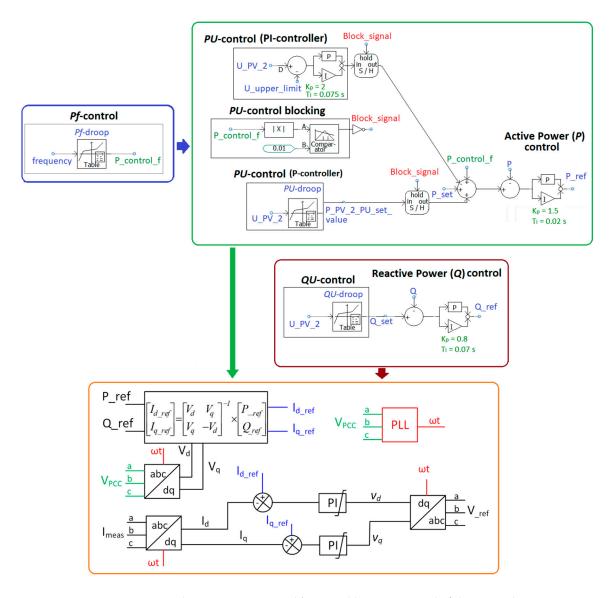


Figure 3. PV unit's active and reactive power control functions like *QU-*, *PU-*, and *Pf-*droops implementation in PSCAD model (see also Figures 1 and 2).

2.3. Study Cases and Simulation Sequence

Table 2 shows the study cases presented in this paper and used QU-, PU-, and Pf-droops for the PV and BESS units (Figure 2). In all cases (Table 2), over- and under-voltage limits were 1.05 and 0.95 pu and OLTC dead-zone was \pm 0.3 kV/0.015 pu. In order to highlight the effect of adapting the OLTC setting during very low load situations, simulations with OLTC setting value 20.7 kV (1.035 pu) were also included in the simulation results (Table 2). Voltage limits of 0.95 and 1.05 pu were chosen as steady-state operation target limits in order to guarantee stable voltage level and high power quality in LV network. In addition, all simulation cases presented in the following were simulated with only P-controllers on PVs and BESSs for PU-control (see Table 2 and Figure 3). In Table 3, the used simulation sequence and other issues regarding study cases (Table 2) are presented.

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Case	WTs **)	PVs **)	BESSs **)	QU-Droop of PVs/BESSs	PU-Droop of PVs/BESSs	Pf-Droop of PVs/BESSs	PU-Blocking with PVs/BESSs	OLTC Set Value (kV)/(pu)
1a	1	5	0	1/-	1/-	1/-	No	20.7/1.035
1b	1	5	0	1/-	1/-	1/-	No	20.0/1.0
2a	1	5	0	1/-	1/-	1/-	Yes	20.7/1.035
2b	1	5	0	1/-	1/-	1/-	Yes	20.0/1.0
3a	1	5	0	2/-	1/-	2/-	Yes	20.7/1.035
3b	1	5	0	2/-	1/-	2/-	Yes	20.0/1.0
4a	1	5	2	1/1	1/1	1/1	Yes	20.0/1.0
4b *)	1	5	2	1/1	1/1	1/1	Yes	20.0/1.0
5a	1	5	3	1/1	1/1	1/1	No	20.0/1.0
5b	1	5	3	1/1	1/1	1/1	Yes	20.0/1.0

Table 2. Simulation study cases, very low load in all cases (see Figure 2).

WT is wind turbine, PV is photovoltaic unit, BESS is battery energy storage unit, *) remote voltage (U_PV_2) measurement from PV 2 connection point to BESS 1 control through communication, **) number of units.

Table 3. Simulation sequence actions and other issues in study cases (see Table 2 and Figure 1). Total simulation time t = 110 s.

Time (s)	Initial Condition/Action
t = 0-110	PV unit active power (P_{PV}) is at nominal *) i.e., 300 or 450 kW
t = 10.5	WT active power (P_{WT}) increases from initial 0.5 to 1.5 MW *)
t = 15.0	WT active power (P_{WT}) increases from 1.5 to 2.5 MW *)
t = 19.0	WT active power (<i>P</i> _{WT}) increases from 2.5 to 3.6 MW *)
t = 30-40	Over-frequency situation (50.07 Hz) **)
t = 50-60	Over-frequency situation (50.25 Hz) **)
t = 70-80	Under-frequency situation (49.9 or 49.4 Hz) **)
t = 90-100	Under-frequency situation (49.8 or 49.4 Hz) **) Part of the load participates in demand response and disconnects from the LV network
Other issues	In all study cases of Table 2 PVs <i>QU</i> -droop is primary and <i>PU</i> -droop secondary local voltage control method

^{*)} If voltage at PV or WT connection point is between min. and max. limits, **) Pf-control of PVs/BESSs participates in frequency control according to their Pf-droops.

3. Simulation Results and New Frequency Adaptive PU-Droop

In this section, the main simulation results regarding potential solutions which could increase LV distribution networks' PV hosting capacity and provision of flexibility services from small-scale DER are presented. In Section 3.1, the focus of the simulations was in the following issues (Table 2):

- Effect of BESSs utilization (Cases 4a–5b), two or three BESSs (with default PU-droops on BESSs).
- Potential DER (PV and BESS) unit *Pf* and *PU*-control interactions during future scenarios with very high PV penetration and very low load in (i) steady-state, (ii) over-frequency, and (iii) under-frequency situations to study the effect of:
 - additional PU-control blocking logic (Cases 2a–4b and 5b);
 - odifferent *Pf* and *QU*-droop settings (Cases 3a–3b).
- Effect of remote LV voltage measurement from PV (further in LV network) connection point to BESS at closest MV/LV secondary substation in order to maximize PV production during very low loads (Case 4b).
- Effect of adapting the OLTC setting during very low load situations (Cases 1b, 2b, 3b, and 4a–5b).

After that, Section 3.1 presents simulation results by utilizing measured 30 min real-life frequency data from SSG (Case 6). Finally, in Section 3.2. frequency adaptive *PU*-droops for PVs and BESSs during larger under- and over-frequency situations are proposed (Cases 7a–7b).

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3.1. Simulations to Study Different Potential Solutions for Increasing LV Network PV Hosting Capacity and Provision of Flexibility Services from DER

In the following, simulation results from different very low load cases (Tables 2 and 3) with only P-controllers for PU-control in PVs and BESSs (Figure 3) are explained in detail. At first, Table 4 presents PV 2 unit's (Figure 1) active (P_{PV_2}) and reactive (Q_{PV_2}) power as well as PV 2 connection point voltage (U_{PV_2}) during over- and under-frequency events in different cases. After that, Tables 5 and 6 show the active and reactive power of BESS 1 and 3 during over- and under-frequency events in different cases. In order to highlight the PV hosting capacity in PV 2 connection point, Figure 4 presents the active power (P_{PV_2}) values of PV 2 during steady-state, over- and under-frequency events in different cases.

From Table 4 and Figure 4 it can be seen that the PV hosting capacity in PV 2 connection point (Figure 1) without BESSs in Cases 1a–3b during steady-state operation ($t=25.0\,\mathrm{s}$) can be increased with lower (20.0 kV) OLTC setting (Cases 1b, 2b, 3b). During over-frequency event 50.07 Hz ($t=25.0\,\mathrm{s}$) in Cases 1a–3b without BESSs one can see that best frequency support (frequency control participation) can be achieved in Cases 2a and 2b with utilization of PU-control blocking logic (Figure 3) and Pf-droop 1 (Figure 2) on PVs. On the other hand, during under-frequency event 49.8 Hz ($t=95.0\,\mathrm{s}$) in Cases 1a–3b without BESSs it can be seen from Table 4 and Figure 4c that due to load demand response participation to frequency support by disconnecting part of the load at PV 2 connection point, also the PV 2 active power needs to be curtailed in order to avoid local over-voltages. However, this PV curtailment during under-frequency event is not feasible from system-wide perspective and reduces the effect of load demand response to frequency control. Table 4 results also show that, due to used P-controllers for PU-control in PV 2 and BESS 3 without any PI-controllers (Figure 3), small voltage limit violations at the PV 2 connection point voltage (U_{PV-2}) can be possible.

Table 4. PV 2 active (P_{PV_2}) and reactive (Q_{PV_2}) power as well as PV 2 connection point voltage
(U_{PV_2}) during over- and under-frequency events in different cases (Figures 1 and 2, Tables 2 and 3).

Case	Load Level	$P_{\text{PV}_2}, Q_{\text{PV}_2}, U_{\text{PV}_2}$ Steady-State, $t = 25 \text{ s}$ (kW, kVAr, pu)	P_{PV_2} , Q_{PV_2} , U_{PV_2} 50.07 Hz, $t = 35 \text{ s}$ (kW, kVAr, pu)	$P_{PV_2}, Q_{PV_2}, U_{PV_2}$ 50.25 Hz, $t = 55 \text{ s}$ (kW, kVAr, pu)	P_{PV_2} , Q_{PV_2} , U_{PV_2} 49.8 Hz, $t = 95 \text{ s}^{*}$ (kW, kVAr, pu)
1a	Low	243, -150, 1.056	236, -150, 1.054	0, 0, 1.006	213, -150, 1.057
1b	Low	316, -150, 1.053	310, -150, 1.051	0, 0, 0.976	286, -150, 1.054
2a	Low	243, -150, 1.056	190, -150, 1.038	0, 0, 1.006	213, -150, 1.057
2b	Low	316, -150, 1.053	264, -150, 1.035	0, 0, 0.976	286, -150, 1.054
3a	Low	241, -150, 1.056	242, -150, 1.056	0, 0, 1.006	210, -150, 1.057
3b	Low	316, -150, 1.053	317, -150, 1.053	0, 10, 0.979	286, -150, 1.054
4a	Low	316, -150, 1.053	264, -150, 1.035	0, 0, 0.974	281, -150, 1.055
4b	Low	334, -150, 1.052	282, -149, 1.035	0, 0, 0.974	298, -150, 1.054
5a	Low	450, -150, 1.046	390, -150, 1.039	0, 140, 0.950	363, -150, 1.051
5b	Low	450, -150, 1.046	390, -139, 1.033	0, 150, 0.935	245, -150, 1.056

^{*)} Part of the load also at PV_2 connection point participates in demand response and disconnects from the LV network.

Table 5. BESS 1 active ($P_{\text{BESS_1}}$) and reactive ($Q_{\text{BESS_1}}$) power during over- and under-frequency events in different cases (Figures 1 and 2, Tables 2 and 3).

Case	Load Level	$P_{\text{BESS_1}}$, $Q_{\text{BESS_1}}$ Steady-State, $t = 25 \text{ s}$ (kW, kVAr)	$P_{\rm BESS_1}, Q_{\rm BESS_1}$ 50.07 Hz, $t = 35 \text{ s}$ (kW, kVAr)	$P_{\text{BESS}_1}, Q_{\text{BESS}_1}$ 50.25 Hz, $t = 55 \text{ s}$ (kW, kVAr)	P _{BESS_1} , Q _{BESS_1} 49.8 Hz, t = 95 s (kW, kVAr)
4a	Low	0, 0	-27, 0	-200, 0	200, 0
4b	Low	-200, -67	-200, 0	-200, -67	0, -67
5a	Low	0, 0	-27, 0	-200, 0	200, 0
5b	Low	0,0	-27, 0	-200, 0	200, 0

Table 6. BESS 3 active (P_{BESS_3}) and reactive (Q_{BESS_3}) power during over- and under-frequency events
in different cases (Figures 1 and 2, Tables 2 and 3).

Case	Load Level	P_{BESS_3} , Q_{BESS_3} Steady-State, $t = 25 \text{ s}$ (kW, kVAr)	P_{BESS_3} , Q_{BESS_3} 50.07 Hz, $t = 35 \text{ s}$ (kW, kVAr)	P_{BESS_3} , Q_{BESS_3} 50.25 Hz, $t = 55 \text{ s}$ (kW, kVAr)	P_{BESS_3} , Q_{BESS_3} 49.8 Hz, $t = 95 \text{ s}$ (kW, kVAr)
5a	Low	-93, -67	-52, -67	-165, 62	-25, -67
5b	Low	-93, -67	-84, -62	-200, 67	108, -67

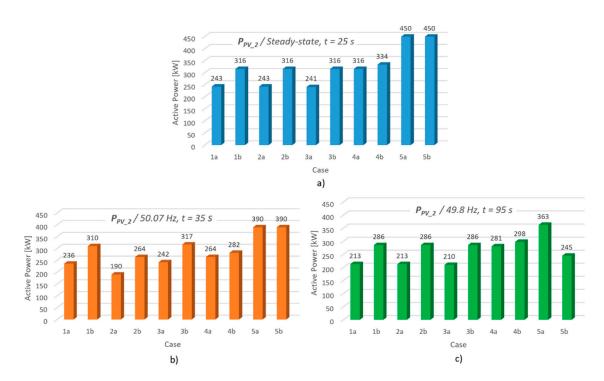


Figure 4. PV 2's active power (P_{PV_2}) values in different cases with very low load during (**a**) steady-state, (**b**) over- and (**c**) under-frequency events (see also (Figures 1 and 2, Tables 2–6)).

The effect of BESS 1 and 3 (Figure 1) on the PV hosting capacity in PV 2 connection point can be seen from Cases 4a–5b (Tables 4–6, Figure 4). When comparing Cases 4a and 4b with BESS 1 during steady-state operation (t = 25.0 s) one can see that PV 2 hosting capacity can be only be increased in Case 4b in which remote LV voltage measurement from PV 2 connection point to BESS 1 (Figure 1) control is utilized through communication. In Cases 5a and 5b with BESS 3 at the PV 2 connection point however, the PV hosting capacity during steady-state operation (t = 25.0 s, Figure 4a) can be maximized by simultaneously charging BESS 3 (Table 6) in order to avoid local over-voltages. By comparing the simulation results of Cases 5a and 5b (Tables 4–6) during over-frequency event 50.25 Hz (t = 55.0 s) the effect of PU-control blocking logic of PVs and BESSs can be seen. The PU-blocking maximizes the BESS 3 participation in frequency support in Case 5b (Table 6), but simultaneously leads to local under-voltage at PV 2 connection point (Table 4). During under-frequency event 49.8 Hz (t = 95.0 s) in Cases 5a and 5b with BESS 3 it can be seen from Tables 4 and 6 that in Case 5a without PU-blocking total active power change (PV2 + BESS 3) is $\Delta P_{5a_49.8Hz} = \Delta P_{PV2}(-87 \text{ kW}) + \Delta P_{BESS3}(68 \text{ kW}) = -19 \text{ kW}$ and in Case 5b with PU-blocking $\Delta P_{5b_49.8Hz} = \Delta P_{PV 2}(-205 \text{ kW}) + \Delta P_{BESS 3}(201 \text{ kW}) = -4 \text{ kW}$. The total active power change is quite similar in Cases 5a and 5b, but it seems that in cases with PV and BESS at the same connection point, the PU-blocking (Case 5b) may lead to unnecessary large PV curtailment during under-frequency events if BESS unit participates in frequency control. This issue is further studied in Section 3.2.

Simulations with Real-Life Measurement Data

In this Section, the aim was to study PV 2 and BESS 3 unit's (Figure 1) active (P_{PV_2}) and reactive (Q_{PV_2}) power as well as PV 2 connection point voltage (U_{PV_2}) in Case 5 by utilizing measured real-life frequency data from SSG (Figure 5). Measured 30 min frequency data (Figure 5) was modified for PSCAD simulations to 240 s input data and was utilized in the new simulation Case 6 during t = 10-250 s (Figure 6a).

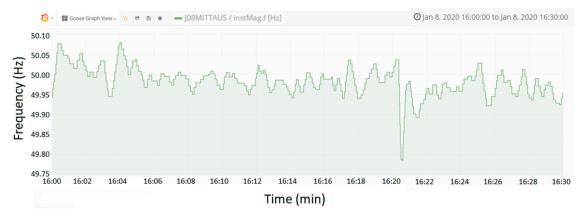


Figure 5. Measured 30 min real-life frequency data from SSG (which is modified for PSCAD simulations to 240 s frequency input data between t = 10–250 s, see Figure 6a).

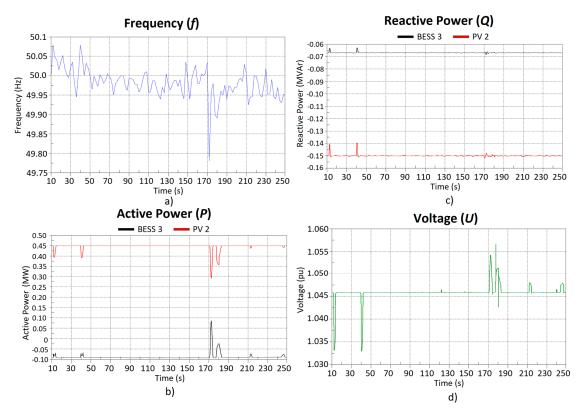


Figure 6. (a) Input frequency (*f*) data modified from real-life SSG measurements (Figure 5), PV 2 and BESS 3 (b) active (*P*) and (c) reactive power (*Q*), as well as (d) local voltage (*U*) behavior at PV 2 connection point during simulated Case 6 (similar to Case 5, see also Figures 1 and 2, Tables 2–6).

From simulation results of Figure 6 it can be seen how PV 2 and BESS 3 units participate in frequency control when frequency exceeds 50.05 Hz. In a similar manner, BESS 3 participates in frequency

control during under-frequencies (i.e., when frequency is smaller than 49.95 Hz). In addition, during t = 178.0–180.5 s also load demand response participates in frequency support by load disconnection when under-frequency limit 49.90 Hz is exceeded. Due to local voltage rise at PV 2 connection point during under-frequency events also PV 2 active power needs to be simultaneously curtailed as shown in Figure 6.

- 3.2. Frequency Adaptive PU-Droops for PVs and BESSs During Larger Under- and Over-Frequency Situations Based on the simulations results of Section 3.1. it can be concluded that
- Use of *PU*-blocking is needed from system-wide perspective in order to enable feasible operation of PV 2 (without BESS 3) in Cases 2a and 2b during 50.07 Hz over-frequency situation.
- With BESS 3 in Case 5b during 49.8 Hz under-frequency situation however, PV 2 output needs to be curtailed more with *PU*-blocking due to BESS 3 unit's more rapid and extensive participation in system frequency support.
 - Therefore, use of *PU*-blocking is not recommended from PV curtailment viewpoint when there are both PV and BESS at the same network connection point. On the other hand, simultaneous BESS frequency support with *PU*-blocking logic is higher.
 - One potential option to avoid PV 2 curtailment could be disabling *Pf*-control of BESS 3 during under-frequency events. On the other hand, that is not optimal from whole-system perspective especially if frequency deviation is large and frequency support is needed.

By considering above conclusions there is a need for development of PU-droops in order to avoid the mentioned shortcomings and challenges. Therefore, in this section 'frequency adaptive PU-droops' are proposed. The idea, settings, and PSCAD implementation of the frequency adaptive PU-droop are presented in Figure 7. For example with PV 2 and BESS 3 the adaption of frequency adaptive PU-droops would mean that when frequency is e.g., $\geq \pm 0.2$ –0.5 Hz and between over-voltage limits 1.05–1.15 pu or under-voltage limits 0.85–0.95 pu then active PU-droops would be changed from PU-droop 1 (Figure 2) to PU-droop 2 or 3 (Figure 7).

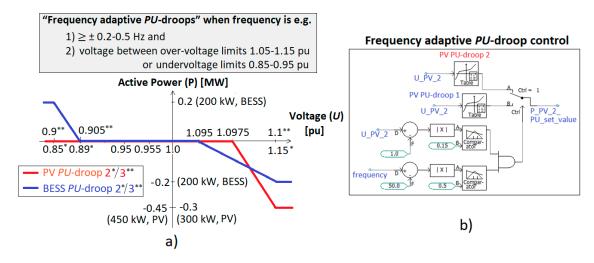


Figure 7. 'Frequency adaptive *PU*-droops' (**a**) idea and settings for PVs and BESSs during larger under and over-frequency situations and (**b**) PSCAD implementation of the PV and BESS droops 2.

Standard EN 50160 [45] defines that LV network supply voltage variations under normal operation should not exceed \pm 10% of nominal voltage $U_{\rm n}$ (99% of the 10-min mean RMS value over one week) and none of the 10-min mean RMS values shall exceed \pm 15% of $U_{\rm n}$. When comparing these frequency

adaptive *PU*-droop settings (Figure 7) to standard EN 50160 [45] requirements regarding supply voltage variation in LV network, it can be stated that standard requirements are respected.

Frequency adaptive PU-droops should be used without PU-blocking in cases with PV + BESS at the same connection point in order to enable PV or BESS unit participation in frequency control markets as well as to maximize smaller LV network connected demand (loads) participation in frequency control.

In Tables 7 and 8, active and reactive power of PV 2 and BESS 3 (Figure 1) as well as PV 2/BESS 3 connection point voltage (U_PV_2 , Figure 1) values during larger under-frequencies (49.4 Hz) in Cases 7a and 7b are presented.

Table 7. PV 2 active (P_{PV_2}) and reactive (Q_{PV_2}) power as well as PV 2 connection point voltage (U_{PV_2}) during larger under-frequencies (49.4 Hz) (Figures 1 and 2, Tables 2–6).

Case	PV Droop	Load Level	$P_{\text{PV}_2}, Q_{\text{PV}_2}, U_{\text{PV}_2}$ Steady-State, $t = 25 \text{ s}$ (kW, kVAr, pu)	$P_{\text{PV}_2}, Q_{\text{PV}_2}, U_{\text{PV}_2}$ 49.4 Hz, $t = 75 \text{ s}$ (kW, kVAr, pu)	P_{PV_2} , Q_{PV_2} , U_{PV_2} 49.4 Hz, $t = 95 \text{ s}^{*}$ (kW, kVAr, pu)
2b	1	Low	316, -150, 1.053	319, -150, 1.053	285, -150, 1.054
7a	2	Low	316, -150, 1.053	450, -150, 1.095	426, -150, 1.100
7a	3	Low	316, -150, 1.053	450, -150, 1.095	416, -150, 1.098
5a	1	Low	450, -150, 1.046	395, -150, 1.050	362, -150, 1.051
7b	2	Low	450, -150, 1.046	400, -150, 1.103	376, -150, 1.106
7b	3	Low	450, -150, 1.046	448, -150, 1.097	406, -150, 1.098

^{*)} Part of the load also at PV_2 connection point participates in demand response and disconnects from the LV network.

Table 8. BESS 3 active (P_{BESS_3}) and reactive (Q_{BESS_3}) during larger under-frequencies (49.4 Hz) (Figures 1 and 2, Tables 2–6).

Case	BESS Droop	Load Level	P_{BESS_3} , Q_{BESS_3} Steady-state, $t = 25 \text{ s}$ (kW, kVAr)	P_{BESS_3} , Q_{BESS_3} 49.4 Hz, $t = 75 \text{ s}$ (kW, kVAr)	P_{BESS_3} , Q_{BESS_3} 49.4 Hz, $t = 95 \text{ s}$ (kW, kVAr)
5a	1	Low	-93, -67	-25, -67	-25, -67
7b	2	Low	-93, -67	144, -67	135, -67
7b	3	Low	-93, -67	76, –67	76, –67

In both cases OLTC set value is 20.0 kV. Case 7a is similar to 2b and Case 7b is same as 5a (Table 2). The under-frequencies (49.4 Hz) however, are larger (Table 3) and both Cases 7a and 7b are done without *PU*-blocking in PV 2/BESS 3 due to their 'frequency adaptive *PU*-droops' (Figure 7).

From Tables 7 and 8 it can be seen that during larger under-frequencies (49.4 Hz) in Case 7a with only PVs (no BESSs), the frequency adaptive PU-droop enables larger PV 2 output and power system frequency support also during simultaneous demand response at t=95 s (see Case 7a $\Delta P_{\rm TOTAL_75s}$ and $\Delta P_{\rm TOTAL_95s}$ values in Table 9 when compared to Case 2b). Respectively, in Case 7b with PVs and BESSs during 49.4 Hz under-frequency events the combined frequency support of PV 2 and BESS 3 is increased (see Case 7b $\Delta P_{\rm TOTAL_75s}$ and $\Delta P_{\rm TOTAL_95s}$ values in Table 9 when compared to Case 5a) and their total effect due to 'frequency adaptive PU-droops' is much better from the whole system point of view.

Figure 8 shows the active power behavior of PV 2 and BESS as well as voltage behavior at PV 2 connection point during simulated under-frequency (49.4 Hz) events in Cases 5a, 7b (with different PU-droops, Figure 7 and Tables 7 and 8). From Figure 8 and Tables 7 and 8 it can be seen that PV 2 active power $P_{\rm PV}$ is much less curtailed during under-frequency events in Case 7b with PU-droop 2 than with PU-droop 3. In addition, simultaneous change and increase in BESS 3 active power $P_{\rm BESS}$ is smaller in Case 7b with PU-droop 3 than with PU-droop 2. These differences in $P_{\rm PV}$ and $P_{\rm BESS}$ behavior during under-frequencies are affected by different PU-droops as well as the PSCAD implementation logic presented in Figure 7b.

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Case	ΔP_{PV_2} $49.4 \text{ Hz},$ $t = 75 \text{ s (kW)}$	ΔP_{PV_2} 49.4 Hz, $t = 95 \text{ s}^{*}$ (kW)	ΔP_{BESS_3} $49.4 \text{ Hz},$ $t = 75 \text{ s (kW)}$	ΔP_{BESS_3} 49.4 Hz, $t = 95 \text{ s}^{*)} \text{ (kW)}$	$\Delta P_{\text{TOTAL}_{-75s}}$ **) 49.4 Hz, $t = 75 \text{ s (kW)}$	$\Delta P_{\text{TOTAL}_{95s}}^{***}$ 49.4 Hz, $t = 95 \text{ s}^{*} \text{ (kW)}$
2b	+3	-31	_	_	+3	-31
7a	+134	+110	_	_	+134	+110
7a	+134	+100	_	_	+134	+100
5a	-55	-88	+68	+68	+13	-20
7b	-50	-74	+237	+228	+187	+154
7b	-2	-44	+169	+169	+167	+125

Table 9. Provided frequency support by PV 2 and BESS 3 in different cases during simulated under-frequency (49.4 Hz) events (see also Tables 7 and 8).

^{*)} Part of the load also at PV_2 connection point participates in demand response and disconnects from the LV network, **) $\Delta P_{\text{TOTAL 75s}} = \Delta P_{\text{PV 2}} + \Delta P_{\text{BESS 3}}$ at t = 75 s, ***) $\Delta P_{\text{TOTAL 95s}} = \Delta P_{\text{PV 2}} + \Delta P_{\text{BESS 3}}$ at t = 95 s.

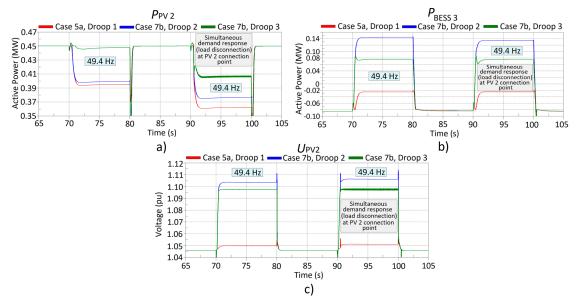


Figure 8. (a) PV 2 active power P_{PV_2} , (b) BESS 3 active power P_{BESS_3} , and (c) local voltage U_{PV_2} behavior at PV 2 connection point during simulated under-frequency (49.4 Hz) events in Cases 5a (PU-droop 1), 7b (PU-droop 2), and 7b (PU-droop 3), see also Figures 2 and 7.

4. New Real-Time Adaptive Management Schemes

In the following, new real-time adaptive management schemes are proposed based on the previous studies and simulation results presented in Section 3.

4.1. Real-Time Frequency Adaptive PU-Droop

In Section 3.2. the idea of frequency adaptive PU-droops for PVs and BESSs was presented. The implementation could be smoother without exact frequency ($\geq \pm 0.2$ -0.5 Hz) and voltage limits for the activation of the frequency adaptive functionality. Therefore, in Figure 9 new 'real-time frequency adaptive PU-droop' for PV and BESS units is proposed when frequency deviation is between ± 1.0 Hz from the nominal frequency f_n . If frequency deviation is larger, then similar settings will be used as if the deviation would be 1.0 Hz from f_n . This approach enables constant and smoother frequency adaptive response from the DER units which is also more dependent on the real-time magnitude of frequency change. It should be noted from Figure 9 that different equations will be used for calculation of the PU-droop set-points X_1 , X_2 , X_3 , and X_4 depending on the situation (i.e., under- or over-frequency, $f < f_n$ or $f > f_n$). In these Figure 9 equations for X_1 , X_2 , X_3 , and X_4 :

f = measured frequency (Hz) f_n = nominal frequency (Hz) Appl. Sci. 2020, 10, 5146 15 of 21

 $U_{\min_i ni}$ = chosen initial minimum voltage set-point value when $f = f_n$ (pu) $U_{\max_i ni}$ = chosen initial maximum voltage set-point value when $f = f_n$ (pu) P_n = nominal active power (MW).

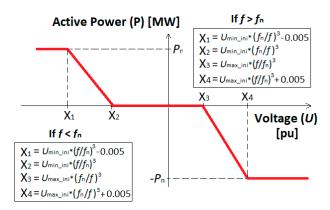


Figure 9. Real-time smooth frequency adaptive *PU*-droop without specific frequency and voltage limits for activation e.g., for BESS unit.

Figure 10 shows example about calculated real-time frequency adaptive PU-droop values X_1 , X_2 , X_3 , and X_4 (Figure 9) for 200 kW BESS with different frequency values when $f_n = 50$ Hz, $P_n = 0.2$ MW, $U_{\min_i ni} = 0.955$ pu, and $U_{\max_i ni} = 1.045$ pu.

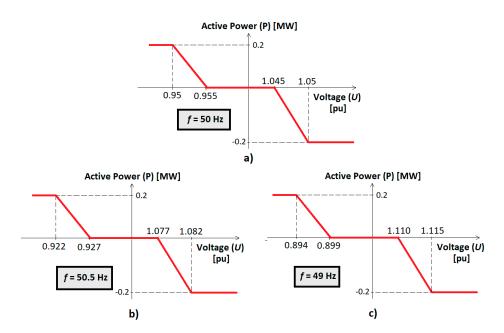


Figure 10. Example of real-time frequency adaptive PU-droop values for 200 kW BESS with (a) f = 50 Hz, (b) f = 50.5 Hz, and (c) f = 49 Hz ($f_n = 50$ Hz, $P_n = 0.2$ MW, $U_{min_ini} = 0.955$ pu, and $U_{max_ini} = 1.045$ pu, Figure 9).

4.2. Real-Time HV/MV Substation PQ-Flow Dependent OLTC Setting Value

Instead of seasonal OLTC settings the OLTC setting value could be based on locally measured real-time active and reactive power flow levels (5 min average $P_{\rm HV}$ and $Q_{\rm HV}$ values) between HV and MV networks at the HV/MV substation as shown in Figure 11. The example in Figure 11 is based on SSG RPW-limits [39]. This proposed new PQ-flow dependent OLTC setting value calculation could enable increased DER and PV hosting capacity in distribution networks, less reactive power produced

by cables (see Equation (1), Section 2.2), and therefore decreased need for voltage control support in MV and LV networks by the flexible energy resources. In addition, simultaneously the availability of, for example, demand response, for provision of system-wide frequency support could be increased.

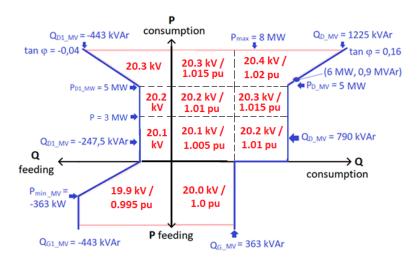


Figure 11. Real-time HV/MV substation PQ-flow dependent OLTC setting value with SSG (RPW)-limits.

The proposed *PQ*-flow dependent OLTC setting value (Figure 11) is based on local measurements only and does not require knowledge about minimum and maximum voltages in the corresponding distribution network. Therefore, this approach could be further improved in the future with the real-time measurements based data in order to achieve even more optimized and coordinated determination of OLTC set value and compatible settings for the adaptive *QU*-droops of the DER units (Section 4.3).

4.3. Real-Time Adaptive QU-Droop Based on OLTC Setting Value

If seasonal OLTC settings are utilized, then also *QU*-droop settings of DER units should be adapted accordingly when OLTC seasonal setting value is changed. This could be done, for example, based on date if also OLTC set value is changed based on the same schedule. This approach was also used as a hypothesis in the simulations presented in Section 3. If the real-time OLTC setting value (e.g., as defined in Section 4.2) however, can be communicated to the DER unit then it could be used as an input to adapt the DER unit *QU*-droop settings as shown in Figure 12. Regarding the *QU*-droop settings (Figure 12), the dead-zone size could be modified based on chosen constant B value (from 0.02 to 0.06 pu) depending on the location of the DER unit in MV or LV network. In addition, if participation of the DER unit to compensate fast voltage variations is emphasized then a smaller constant A value in Figure 12 (e.g., 0.005 pu) could be used instead of a larger one (e.g., 0.015 pu) in *QU*-droop settings.

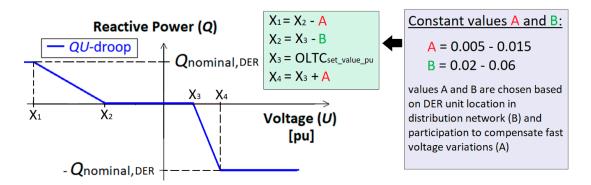


Figure 12. Real-time adaptive DER unit QU-droop based on OLTC set value and constants A and B.

5. Conclusions

In this paper solutions for increasing PV hosting capacity and distribution network connected flexible energy resources improved utilization for local (DSO) and system-wide (TSO) services were studied by PSCAD simulations during very low load situations. The focus was on the potential momentary mutual effects and simultaneous interaction between different functions. Based on the simulation results, it can be concluded that

- PV hosting capacity in LV network can be increased with lower OLTC setting value.
- Feasible and coordinated *QU-*, *PU-*, and *Pf-*droop settings (with dead-zones) of PVs and BESSs are essential in maximizing the provision of their flexibility services.
- During an over-frequency event without BESS, the best frequency support can be achieved by using *PU*-control blocking logic on PVs.
- PV hosting capacity can be increased to some extent by remote LV voltage measurement from PV connection point to MV/LV substation connected BESS.
- With BESS at the PV connection point however, the PV hosting capacity during steady-state operation can be maximized by simultaneously charging BESS in order to avoid local over-voltages.
- During larger frequency deviations frequency adaptive *PU*-droops can enable larger PV and BESS power system frequency support as well as maximize smaller LV network connected demand (loads) participation in frequency control.
- Actual implementation logic (e.g., PU-blocking or change of active PU-droop with frequency adaptive PU-droops) affects the PV and BESS frequency support contribution and the extent of PV curtailment (Table 10).

Table 10. Summary about effect of functionalities implementation logic during simulated very low load situations.

DER Unit(s)	Without PU-Blocking	With PU-Blocking	Frequency Adaptive PU-Droops (Without PU-Blocking)
PV (only)	Over-frequency support can be limited	Better over-frequency support	No difference depending on the PU-droop settings and over-voltage limits in the logic (during under-frequencies)
PV + BESS (at the same connection point)	During under-frequency events small PV curtailment + smaller BESS contribution	During under-frequencies PV curtailment larger + BESS contribution larger	Smaller PV curtailment + smaller BESS contribution with lower over-voltage limit on the PU-droop and implementation logic (during under-frequencies)

In general, it can be stated that the dead-zones in BESS and PV unit *QU-*, *PU-*, and *Pf*-droops are required in order to enable multi-use of active (*P*) and/or reactive (*Q*) power for different purposes. In the future, new adaptive management schemes to enable maximum availability of all types and sizes of flexibilities for different local and system level services are needed. New management and DER control methods must be also compatible with other flexibility service options and platforms like flexibility markets. Therefore, in the near future flexible *QU-*, *PU-*, and *Pf-*droop functions for DER units are required. Flexible droop functions could also enable local operation optimization at DSO level by updating droop functions setting values and activation limits in a seasonal/monthly/weekly/daily/hourly manner. The adaptation of these droops to the changing network situations, however, should be increasingly done in the future based on the available local and/or remote measurements information. Therefore, in Section 4 new real-time adaptive management schemes for DER units' *PU*-droops, HV/MV substation transformer's OLTC setting value (dependent on the *PQ-*flow through the transformer), and DER units' *QU*-droops (dependent on OLTC setting value) were also proposed.

It was shown by simulations that with BESS at the PV connection point the PV hosting capacity during steady-state operation and very low load situation can be maximized by simultaneously

charging BESS. In reality this is only possible if State-of-Charge (SOC) of the BESS is at a suitable level. BESS's SOC naturally has an effect on its capabilities to be used for different control purposes and the ability to provide different flexibility services. In real-life, the SOC-dependency of the BESS *PU*-droops would be feasible to be implemented as part of the control system in order to be able to maximize benefits to the owner of the assets/flexibility resources. Real-time SOC-level defines the actual BESS ability to provide the different flexibility services. These issues will be considered in the future research.

Author Contributions: Conceptualization, methodology, investigation, H.L.; writing—original draft preparation, H.L., C.P., H.H., M.S.-k., H.K.; writing—review and editing, C.P., H.H., M.S.-k., H.K., N.H. All authors have read and agreed to the published version of the manuscript.

Funding: This work was done as part of FLEXIMAR-project (Novel marketplace for energy flexibility) which is funded by Business Finland and Finnish companies (https://www.univaasa.fi/en/research/projects/fleximar/).

Conflicts of Interest: The authors declare no conflict of interest.

Nomenclature

AC Alternating Current

ANM Active Network Management BESS Battery Energy Storage System

CB Circuit Breaker DC Direct Current

DG Distributed Generation
DER Distributed Energy Resources
DSO Distribution System Operator

ENTSO-E European Network of Transmission System Operators for Electricity

ES Energy Storage
EU European Union
EV Electric Vehicle
HV High Voltage

J06, J07, J08 MV feeders in the study case

LV Low Voltage
MV Medium Voltage
NC Network Code
OLTC On-Load Tap Changer

PSCAD Power System Simulation Software

P-controller Proportional controller

PI-controller Proportional-Integral controller

PV Photovoltaic

RES Renewable Energy Sources
RfG Requirements for Generators

RMS Root Mean Square RPW Reactive Power Window

SOC State-of-Charge SSG Sundom Smart Grid

TSO Transmission System Operator

WT Wind Turbine ω Angular frequency C Capacitance $\cos \varphi$ Power factor

 $cos \varphi(P)$ Active Power dependent power factor

f Frequency

f_n Nominal frequency (Hz)

I Current

I_{meas} Measured Current

I_d Current direct (d) component

I_{d ref} Current direct (d) component reference value

I_q Current quadrature (q) component

 I_{q_ref} Current quadrature (q) component reference value

L Inductance P Active Power

Pf or P(f) Active Power—Frequency
PU or P(U) Active Power—Voltage

 ΔP_{BESS_3} Active Power change of BESS unit 3 ΔP_{PV_2} Active Power change of PV unit 2

 $\begin{array}{ll} \Delta P_{TOTAL_75s} & \quad \text{Total Active Power change during simulation at } t = 75 \text{ s} \\ \Delta P_{TOTAL_95s} & \quad \text{Total Active Power change during simulation at } t = 95 \text{ s} \\ \end{array}$

 $\begin{array}{ll} P_{BESS_1} & Active \ Power \ of \ BESS \ unit \ 1 \\ P_{BESS_3} & Active \ Power \ of \ BESS \ unit \ 3 \\ P_n & Nominal \ active \ power \\ P_{PV} & Active \ Power \ of \ PV \ unit \ P_{PV \ 2} & Active \ Power \ of \ PV \ unit \ 2 \\ \end{array}$

P_{WT} Active Power of Wind Turbine (WT)
P_ref Active Power reference value
PQ Active Power—Reactive Power

Q Reactive Power

Q_MV_flow Reactive Power flow between HV and MV networks

 $\begin{array}{ll} Q_{cable} & Total \ Reactive \ Power \ of \ a \ cable \\ Q_{consumption} & Reactive \ Power \ consumed \ by \ a \ cable \\ Q_{production} & Reactive \ Power \ produced \ by \ a \ cable \end{array}$

 $\begin{array}{lll} Q_{unb} & Reactive \ Power \ unbalance \\ Q(P) & Reactive \ Power—Active \ Power \\ QU \ or \ Q(U) & Reactive \ Power—Voltage \\ Q_{BESS_1} & Reactive \ Power \ of \ BESS \ unit \ 1 \\ Q_{BESS_3} & Reactive \ Power \ of \ BESS \ unit \ 3 \\ Q_{PV_2} & Reactive \ Power \ of \ PV \ unit \ 2 \\ Q_ref & Reactive \ Power \ reference \ value \end{array}$

t Time U Voltage

U_n Nominal Voltage

 U_{min_ini} Chosen initial minimum voltage set-point value U_{max_ini} Chosen initial maximum voltage set-point value

U_{PV_2} Connection point voltage of PV unit 2

 $\begin{array}{lll} V_d & & \text{Voltage direct (d) component} \\ V_q & & \text{Voltage quadrature (q) component} \\ V_{PCC} & & \text{Voltage at the point of common coupling} \end{array}$

V_ref Voltage reference value

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