



Article Artificial Neural Network Model to Estimate the Viscosity of Polymer Solutions for Enhanced Oil Recovery[†]

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Abstract: Polymer flooding is now considered a technically- and commercially-proven method for enhanced oil recovery (EOR). The viscosity of the injected polymer solution is the key property for successful polymer flooding. Given that the viscosity of a polymer solution has a non-linear relationship with various influential parameters (molecular weight, degree of hydrolysis, polymer concentration, cation concentration of polymer solution, shear rate, temperature) and that measurement of viscosity based on these parameters is a time-consuming process, the range of solution samples and the measurement conditions need to be limited and precise. Viscosity estimation of the polymer solution is effective for these purposes. An artificial neural network (ANN) was applied to the viscosity estimation of FlopaamTM 3330S, FlopaamTM 3630S and AN-125 solutions, three commonly-used EOR polymers. The viscosities measured and estimated by ANN and the Carreau model using Lee's correlation, which has been widely used for accuracy evaluated by the average absolute relative deviation, which has been widely used for accuracy evaluation of the results of ANN models. In all conditions, the accuracy of the ANN model is higher than that of the Carreau model using Lee's correlation.

Keywords: enhanced oil recovery; polymer flood; artificial neural network; viscosity

1. Introduction

In the primary recovery stage, oil can be mainly produced using natural energy sources, such as reservoir pressure. As oil production progresses, reservoir pressure decreases, and economical oil production is no longer feasible. To reduce the decline of reservoir pressure and push the oil in the reservoir to the production well, water flooding (secondary recovery), which is the process of injecting water into the reservoir, has been commonly applied to most oil fields. The primary and water flooding methods typically extract no more than 10%–40% of the original-oil-in-place [1]. One of the main reasons for oil to remain after water flooding is the high mobility of the injected water induced by its low viscosity. Mobility is defined as the effective permeability of the reservoir divided by the viscosity of the phase, which is water in this case [2]. The high mobility of injected water compared to oil results in low volumetric sweep efficiency and a large amount of remaining oil. Volumetric sweep efficiency is the volume of oil in contact with the displacing agent divided by the volume of the original-oil-in-place [3]. One of the effective methods for increasing volumetric sweep efficiency and

oil production is the injection of viscous fluids. Polymer flooding, which is a technique for enhanced oil recovery (EOR), is the process of injecting a viscous polymer solution into the reservoir. Polymer flooding is now considered to be a technically- and commercially-proven EOR method, especially since its large-scale application at Daqing oil field in northern China, which produced about 300,000 barrels of incremental oil per day [4]. The viscosity of the polymer solution is the key property for the successful application of polymer flooding. The required viscosity of the polymer solution, which can effectively push viscous oil from the pores of the reservoir rock to the production well, can be calculated using water saturation in the reservoir, the relative permeability of each phase (oil and water) and oil viscosity [2]. To ascertain whether the viscosity of the available polymer solution can reach the required viscosity given the injection and reservoir conditions, the apparent viscosity (also known as in situ viscosity), which is the viscosity of the polymer solution in a porous medium, such as the reservoir, needs to be calculated. Apparent viscosity cannot be measured directly. Instead, it is calculated according to Darcy's equation using data from core flood experiments. However, core flood experiments require much time and specialized expertise. The apparent viscosity of polymer solutions has usually been calculated using the viscosity in a bulk solution; this viscosity of a polymer solution in the bulk state can be measured or estimated. Experimental measurement using a rheometer is the most reliable method, but it is a time-consuming process. The measurement requires experience and skill with a special apparatus for the preparation of a homogeneous polymer solution. Generally, the time required for mixing with an EOR polymer is 2-4 days per solution sample. The molecular chain of an EOR polymer can be easily agglomerated and generates a micro-gel; therefore, identifying the homogeneity of the polymer solution through filtration testing is required. Furthermore, the viscosity of a polymer solution is affected by various parameters at the same time in a complex way. Many researchers [5–21] found that the viscosity of polymer solutions for EOR has a non-linear relationship with the molecular weight, degree of hydrolysis, concentration of polymer, cation concentration of polymer solution, shear rate and temperature. Considering the relatively long time required for measurement and the large number of samples induced by various influential parameters, the range of samples and the measurement conditions need to be narrow and focused. Viscosity estimation of the polymer solution is effective for these purposes. The artificial neural network (ANN), which is inspired by the structural and functional aspects of the biological neuron in the human brain, provides a powerful tool for performing non-linear, multi-dimensional interpolations. ANN has been applied to viscosity estimation in a variety of areas to consider the non-linear relationship between various influential parameters and viscosity [22–26]. For EOR polymers, Kang and Lim [27] used ANN to estimate the viscosity of pH-sensitive polymers. ANN's ability to process data in parallel, which allows the processing of a large number of data in a short period of time, makes it attractive for estimating the viscosity of polymer solutions [28]. In this study, ANN was applied to estimate the viscosity of the bulk solution for general EOR polymers.

2. Types of EOR Polymers

Polyacrylamide (PAM) was applied to polymer flooding, but its usage for enhanced oil recovery has significantly decreased. PAM tends to adsorb strongly on the mineral surfaces of reservoir rock and induces high polymer retention in the reservoir. High polymer adsorption increases the required amount of polymer and decreases injectivity; therefore, the usage of PAM has been avoided for polymer flooding. To reduce polymer adsorption, hydrolyzed polyacrylamide (HPAM) has been applied in the fields. According to Manrique et al. [29], HPAM is the most widely used polymer in EOR applications; it is used in 92% of EOR cases worldwide [30]. HPAM is a copolymer of acrylamide and sodium acrylate and a synthetic, water-soluble straight chain polymer of acrylamide monomers (Figure 1a). It has negative charges along its chain, and the repulsion between the negative charges contributes to the chain extension, thereby resulting in high viscosity. In addition, the availability and low cost of HPAM promotes its wide use in the oil recovery business [31]. HPAM cannot be applied in all reservoir conditions mainly due to its thermal degradation at high temperatures and

its high sensitivity to cation concentrations. New polymers that are stable in harsh environments (high temperatures and high cation concentrations) attract attention because of the need for polymer flooding in oil reservoirs with these conditions [32–37]. 2-Acrylamido-2-methylpropane-sulfonate copolymer (AMPS) can be effectively applied to high-temperature or high-cation concentration conditions. AMPS has water-soluble anionic sulfonate, shielding acrylamide and unsaturated double bonds (Figure 1b). Sulfonate has high resistance to cations. Rigid side chains, large chains or chains of the ring structure provide high resistance to thermal degradation [2]. Parker and Lezzi [38] reported that the AMPS moiety itself is susceptible to thermal degradation at temperatures above roughly 100 °C. Zhao et al. [39] reported that the viscosity of AMPS/AM was about twice than that of HPAM at the same conditions when salinity was increased. After aging at 90 °C for 16 days, the viscosity of AMPS/AM was almost unchanged [2].



Figure 1. Molecular structure of each polymer type. (**a**) HPAM: hydrolyzed polyacrylamide; (**b**) AMPS: 2-acrylamido-2-methylpropane-sulfonate copolymer.

The polymers investigated in this study consist of two HPAMs with different molecular weights and one copolymer of AMPS and acrylamide, referred to as poly(AM-co-AMPS), which are the most widely-used EOR polymers [40], as shown in Table 1.

| Fable 1. Polymers tested | in | this | study |
|---------------------------------|----|------|-------|
|---------------------------------|----|------|-------|

| Polymer | Туре | Molecular weight (million) | Degree of hydrolysis (%) | Manufacturer |
|-----------------------------|------------------|-------------------------------|-----------------------------|---------------------------|
| Flopaam TM 3330S | HPAM | 8 | 25-30 | |
| Flopaam TM 3630S | HPAM | 20 | 25-30 | SNF Floerger [®] |
| AN-125 | Poly(AM-co-AMPS) | 8 | 25-30 * | 0 |

Degree of hydrolysis: mole % of amide groups that are converted by hydrolysis; * Indicates mole % of AMPS. HPAM: hydrolyzed polyacrylamide; AM: acrylamide; AMPS: 2-Acrylamido-2-methylpropane -sulfonate copolymer.

3. Rheological Characteristics of EOR Polymers

An EOR polymer solution in the bulk state generally behaves like a shear-thinning fluid. The decrease in the viscosity of polymer solution as a function of shear rate can be described using the power-law model [41], as shown in Equation (1). The power-law model can only describe the shear-thinning region, as shown in Figure 2.

$$\eta = K \dot{\gamma}^{(n-1)} \tag{1}$$



Figure 2. Shear-thinning behavior by the power-law and Carreau models.

At low and high shear rate conditions, an EOR polymer solution behaves similarly to a Newtonian fluid, which cannot be described by the power-law model. In other words, the viscosity of a polymer solution that is lower than the viscosity of the solvent (water) at the same conditions of flow and temperature is not physically reasonable. Empirical constants (K and n) vary with the conditions of the polymer solution; thus, the power-law model cannot estimate unmeasured viscosity without using empirical correlations between the empirical constants and influential parameters.

The Carreau model [42,43] can depict shear-thinning behavior, including Newtonian behavior at low and high shear rates, as shown in Figure 2 and Equation (2).

$$\eta - \eta_{\infty} = (\eta_0 - \eta_{\infty}) \left[1 + (\lambda \dot{\gamma})^{\alpha} \right]^{(n-1)/\alpha}$$
⁽²⁾

Model parameters (η_0 , n, λ) vary with the conditions of the polymer solution; therefore, the empirical correlations of these parameters are needed for the estimation of the unmeasured viscosity of the polymer solution. Lee et al. [44] used the Martin equation [45] in Equation (3) and proposed empirical correlations, as shown in Equations (4)–(8). These correlations were the only methods for estimating the unmeasured viscosity of a polymer solution. However, Lee [46] reported that the accuracy of this correlation is low in cases of low salinity conditions or FlopaamTM 3630S.

$$\ln\left(\frac{\eta_0 - \eta_\infty}{\eta_\infty C_p}\right) = K'' \left|\eta\right| C_p + \ln\left|\eta\right|$$
(3)

$$K'' = \exp\left[\left(a_1 \exp\left(a_2 C_1\right) + a_3 \exp\left(a_4 C_1\right)\right) \left(\frac{C_1 + (a_5 C_2)^{a_6}}{C_1}\right)^{a_7}\right] / |\eta|$$
(4)

$$|\eta| = \exp\left[\left(\frac{b_1C_1 + b_2}{C_1 + b_3}\right) \left(\frac{C_1 + (b_4C_2)^{b_5}}{C_1}\right)^{b_6}\right]$$
(5)

$$n = 1 - 0.075 \ln\left(\frac{\eta_0}{\eta_\infty}\right) \tag{6}$$

$$\lambda = \left[d_1 \ln \left(\frac{\eta_0 - \eta_\infty}{\eta_\infty C_p} \right) \right]^{d_2} \tag{7}$$

$$\frac{|\eta|(T)}{|\eta|(T_{\text{ref}})} = \frac{T_{\text{ref}}}{T}$$
(8)

4. Development of ANN Models

ANNs generally consist of input, hidden and output layers. Each layer is composed of interconnected neurons. Every signal from each neuron in a layer is summed up by the neuron in the next layer. Then, bias and weights, which are adjusted by the training process, are applied to this summed-up value. Every signal from each neuron is calculated by the activation function. ANN models are of different types according to their structure, training method or method of processing data through the network. The feed-forward neural network, which comprises neurons in the input layer connected to only one succeeding layer, is the most common type of ANN [47–49]. Previous research [27] proved that a feed-forward neural network with two hidden layers is effective for viscosity estimation of pH-sensitive polymers for enhanced oil recovery.

The parameters that are influential on the viscosity of the polymer solution need to be included in the input layer; therefore, polymer physics and oil field conditions should be considered in the selection of neurons for the input layer. A polymer solution for enhanced oil recovery is a non-Newtonian fluid, and the shear rate was included in the input layer. The viscosity of a polymer solution increases as the polymer concentration increases. The increased number of polymer molecules induces more interactions between polymer chains and results in more frictional effects that increase viscosity. Various monocations and divalent cations are found in the reservoir and can neutralize the charge in the polymer side chains. The viscosity of a polymer solution decreases when a cation is added. Na⁺ is one of the most common cations in injection water and formation water that is directly in contact with the polymer. Previous studies [11,15] reported that Ca²⁺ causes greater viscosity reduction than other common divalent cations, such as Mg²⁺. An increase in temperature results in enhanced activity of polymer molecules and reduced friction between molecules, which decreases viscosity. In this study, the input layer consists of five neurons, namely, shear rate, polymer concentration, NaCl concentration, Ca²⁺ concentration and temperature. This study proposes three ANN models, one each for FlopaamTM 3330S, FlopaamTM 3630S and AN-125. Thus, the molecular weight and the degree of hydrolysis, which are polymer properties, were not included in the input layer.

For training, validating and testing of the ANN model, the measured viscosity data for each polymer from the literature [46] based on shear rate, polymer concentration, NaCl concentration, Ca²⁺ concentration and temperature were used as shown in Table 2. These data were randomly divided into training (70%), validation (15%) and test (15%) sets. For training the ANN model, the Levenberg-Marquardt method [50,51] was applied as shown in Appendix. This method has been used for viscosity estimation effectively [23,25–27].

| Flopaam TM 3330S, Flopaam TM 3630S, AN-125 | | | | | |
|--|----------------------------------|------------------------------|------------------------------|--|---------------------|
| Case (#) | Shear rate (s ⁻¹) | Polymer concentration (wt %) | NaCl concentration (wt %) | Ca ²⁺ concentration (wt %) | Temperature (°C) |
| 1 | | | 0.1 | 0 | 25 |
| 2 | | 0.05, 0.1, 0.2, 0.3 | 1 | 0 | 25 |
| 3 | 0.01–1000 | | 4 | 0 | 25 |
| 4 | | 0.1 | | 0 | 25 |
| 5 | | 0.2 | 0.1, 0.5, 1, 2, 4 | 0 | 25 |
| 6 | | 0.3 | | 0 | 25 |
| 7 | | 0.3 | 0.1 | | 25 |
| 8 | | 0.3 | 1 | 0, 0.05, 0.1, 0.15 | 25 |
| 9 | | 0.3 | 4 | | 25 |
| 10 | | 0.2 | 1 | 0 | 25, 50, 70, 90 |

Table 2. Conditions of polymer solutions.

To identify the appropriate structure of the ANN model, a trial-and-error process was applied based on the number of neurons in the hidden layer and the activation function with data processing. An exceedingly large number of neurons tends to induce over-fitting phenomena, whereas too small a number of neurons tends to decrease accuracy. To identify the appropriate activation function between layers, the log sigmoid function (logsig), the hyperbolic tangent sigmoid transfer function (tansig) and the linear transfer function (purelin) were examined as shown in Figure 3.



Figure 3. Types of activation functions. (a) Logsig. (b) Tansig. (c) Purelin.

After the examination of thousands of structures of ANN models for FlopaamTM 3330S, FlopaamTM 3630S and AN-125, the feed-forward neural network with two hidden layers, including five neurons in each layer was selected (Figure 4). Only the ANN model with a tangent sigmoid transfer function in the hidden layers and a linear transfer function in the output layer showed well-matched results for all cases in this study.



Figure 4. Structure of the artificial neural network (ANN) model.

Figures 5–7 show the comparison of measured data with the training, validating and testing results of the estimated data using the ANN model. The estimated data using each ANN model in this study show good agreement with the measured data based on shear rate, polymer concentration, NaCl concentration, Ca²⁺ concentration and temperature. It is interesting to note that the same structure of the ANN model resulted in estimates that are well matched with measured viscosity for all three polymers (FlopaamTM 3330S, FlopaamTM 3630S and AN-125).



Figure 5. Comparison of the measured and estimated data for FlopaamTM 3330S, cp is centi-poise. (a) Training. (b) Validation. (c) Test.



Figure 6. Comparison of the measured and estimated data for FlopaamTM 3630S. (a) Training. (b) Validation. (c) Test.



Figure 7. Comparison of the measured and estimated data for AN-125. (**a**) Training. (**b**) Validation. (**c**) Test.

5. Results of Viscosity Estimation Using ANN Models

The proposed ANN models were applied to the viscosity estimation of polymer solutions as shown in Table 2. The measured viscosity, viscosity estimated by the ANN model and viscosity estimated by the Carreau model using Lee's correlation [44] were compared, as shown in Figures 8–10. The viscosity estimate from the Carreau model using Lee's correlation did not match well with the measured viscosity in the case of low salinity conditions (0.1 wt % NaCl), as shown in Case #1 of FlopaamTM 3330S and FlopaamTM 3360S. The viscosity estimate from the ANN model was in good

agreement with the measured viscosity overall. The accuracy of the estimated viscosity was evaluated using the average absolute relative deviation (AARD), as shown in Equation (9).

$$AARD (\%) = \frac{100}{n_A} \sum_{i=1}^{N} \left| \frac{y_i - x_i}{x_i} \right|$$
(9)



Figure 8. Comparison between the measured and estimated viscosities of FlopaamTM 3330S. Line, viscosity estimated by the ANN model; dot, measured viscosity; dotted line, viscosity estimated by the Carreau model using Lee's correlation.



Figure 9. Comparison between the measured and estimated viscosities of FlopaamTM 3630S. Line, viscosity estimated by the ANN model; dot, measured viscosity; dotted line, viscosity estimated by the Carreau model using Lee's correlation.



Figure 10. Comparison between the measured and estimated viscosities of AN-125. Line, viscosity estimated by the ANN model; dot, measured viscosity; dotted line, viscosity estimated by the Carreau model using Lee's correlation.

AARD, which is also known as the maximum average error percentage, average absolute percentage error or average absolute relative error (fraction form), has been widely used for evaluating the accuracy of the results by ANN models [22–27]. The calculated AARD is shown in Figure 11.



Figure 11. Average absolute relative deviation (AARD) of the viscosity estimated by the ANN model and by the Carreau model using Lee's correlation. (**a**) FlopaamTM 3330S. (**b**) FlopaamTM 3630S. (**c**) AN-125.

In all cases, the AARD of the viscosity estimate from the ANN model was lower than that of the Carreau model using Lee's correlation, which means that the ANN model tends to estimate the viscosity of the polymer solution more closely to the measured viscosity than does the Lee correlation. If the ANN model cannot recognize the relationship between influential parameters and viscosity, it cannot estimate viscosity accurately for some conditions of polymer solutions. For high accuracy of the Lee correlation, a strong linear relationship between polymer concentration and ln $((\eta_0 - \eta_\infty) / \eta_\infty C_p)$ needs to exist. According to Lee [46], this relationship in low salinity conditions is not linear, unlike that in higher salinity conditions, which is one of the possible reasons for the low accuracy of the Lee correlation. Another possible reason is that the measured λ of FlopaamTM 3630S did not match well with the λ estimated by the Lee correlation, unlike FlopaamTM 3330S and AN-125 [46]. In certain conditions, the relationships between the influential parameters and viscosity can change.

6. Conclusions and Discussions

- In this study, ANN was applied to estimate the viscosity of various bulk solutions of the most widely-used EOR polymers (FlopaamTM 3330S, FlopaamTM 3630S and AN-125) based on shear rate, polymer concentration, NaCl concentration, Ca²⁺ concentration and temperature. As a result, three ANN models, one for each of the EOR polymers, were presented.
- 2. The viscosity estimated using the ANN models is in good agreement with the measured viscosity. Based on the AARD calculations, the ANN models show higher accuracy than the Carreau model using Lee's correlation, which is the only method to estimate the unmeasured viscosity of a polymer solution for enhanced oil recovery.

- 3. In some conditions (low salinity or FlopaamTM 3630S), the viscosity estimation by the Carreau model using Lee's correlation is not accurate. It is possible that the relationship between the influential parameters and viscosity can change under certain conditions, such as low salinity (0.1 wt % NaCl) or high molecular weight polymers (20 million). The ANN models proposed in this study are less affected by this effect than the Carreau model using Lee's correlation considering the higher accuracy for all conditions of polymer solutions.
- 4. It is concluded that the ANN models proposed in this study can be utilized for quick estimation of the viscosity of the bulk polymer solution prior to experimental measurement, which is a time-consuming process.
- 5. One interesting finding is that the same structure of the ANN model can provide accurate estimation despite the different polymer structures of HPAM and poly(AM-co-AMPS). Considering that ANN can easily be expanded to include other factors, such as polymer characteristics (polymer structure and degree of hydrolysis, among others), it would be possible to develop an ANN model to estimate the viscosity of other EOR polymers if a method for the quantification of polymer structures can be established.

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Conflicts of Interest: The authors declare no conflict of interest.

Nomenclature

| α | empirical constant, generally two |
|--------------------------------|---|
| a ₁ –a ₇ | empirical constants |
| b ₁ -b ₆ | empirical constants |
| C ₁ | Na ⁺ concentration |
| c ₁ | empirical constant |
| C ₂ | Ca ²⁺ concentration |
| Cp | polymer concentration |
| $d_1 - d_2$ | empirical constants |
| Κ | flow consistency index |
| К// | empirical constant |
| n | power-law index |
| n _A | total number of viscosity data |
| Т | temperature |
| T _{ref} | temperature at reference condition |
| x _i | measured viscosity |
| y _i | estimated viscosity |
| $\dot{\gamma}$ | shear rate |
| η | viscosity |
| $ \eta $ | intrinsic viscosity |
| η_{∞} | Newtonian viscosity at a high shear rate, generally solvent (water) viscosity |
| η_0 | Newtonian viscosity at a low shear rate |
| λ | empirical constant |

Appendix

The Levenberg–Marquardt algorithm was designed to approach the second-order training speed without having to compute the Hessian matrix. When the performance function has the form of a sum of squares (as is typical in training feed-forward networks), then the Hessian matrix can be approximated as:

$$\mathbf{H} = \mathbf{J}^T \mathbf{J},\tag{A1}$$

and the gradient can be computed as:

$$\mathbf{g} = \mathbf{J}^T \boldsymbol{e},\tag{A2}$$

where J is the Jacobian matrix that contains the first derivatives of the network errors with respect to the weights and biases, and *e* is a vector of network errors. The Jacobian matrix can be computed through a standard back-propagation technique. The Levenberg-Marquardt algorithm uses this approximation to the Hessian matrix in the following Newton-like update:

$$X_{k+1} = X_k - \left[\mathbf{J}^T \mathbf{J} + \mu \mathbf{I}\right]^{-1} \mathbf{J}^T e$$
(A3)

When the scalar μ is zero, this is Newton's method using the approximate Hessian matrix. When μ is large, this becomes a gradient descent with a small step size. Newton's method is faster and more accurate near an error minimum; therefore, the aim is to shift toward Newton's method as quickly as possible.

Thus, μ is decreased after each successful step (reduction in the performance function) and is increased only when a tentative step would increase the performance function. In this way, the performance function is always reduced at each iteration of the algorithm.

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