



# Article Study on Propulsion Performance by Varying Rake Distribution at the Propeller Tip

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**Abstract:** This study provides a comparison of propulsion performance, with a particular focus on efficiency, by varying rake distribution at the tips of propellers. Owing to increased attention to environmental pollution, there is a significant interest in reducing the energy efficiency design index (EEDI) and SO<sub>x</sub> emissions by improving the performance in the field of shipbuilding. The forward (Kappel) and backward tip rake propellers have been widely used to improve efficiency, as well as to reduce fluctuating pressure from the tip vortex cavitation. As there is almost no parametric and design research on tip rake propellers, this systematic parametric study was conducted to identify the optimal configuration by the potential code. For this performance comparison the KP505 (KCS propeller) was chosen as the reference propeller as the tips of that propeller have no rake. The model test and computational fluid dynamics (CFD) calculation confirmed the result by comparing the open water performances for the three optimally selected propellers (forward, backward, KP505). The differences of efficiency obtained from the potential analysis and the model test exhibit similar tendencies, but the result for the CFD is different. The difference would be investigated by changing the grid system around the tip as well as the turbulence model in the CFD analysis. An analysis of self-propulsion and pressure fluctuation is also expected to be conducted in the near future.

Keywords: tip rake propeller; EEDI; Energy saving device

## 1. Introduction

Interest in fossil energy depletion and global warming has increased in recent years. The International Maritime Organization (IMO) has been applying indicators for energy efficiency to ships constructed after 2013. In particular, the energy efficiency design index (EEDI) represents the amount of carbon dioxide emitted during the transportation of 1ton of cargo per mile. Emissions will need to be reduced 30% by 2025, beginning with a 10% reduction in January 2013. As a result, research is continuing to improve hull form and propulsion systems to reduce EEDI worldwide. Propulsion system performance has been greatly improved by developing a compound propulsion system. The Compound propulsion system can be classified as pre device, main device, and post device. The pre-swirl stator and Mewis ducts are known to be more effective in pre device, and high performance special propellers, contra rotating propellers, and duct propellers are known to be effective as main devices. Although the performance varies depending on the ship types, the approximate energy reduction effect is about 3%–4%. In addition, twisted rudders, rudder bulbs, and fins are effective post devices. The performance of the rudder has been improved by modifying the shape of the rudder or by installing an additive such as a fin or bulb.

This study addresses the Kappel [1] propeller (forward type) and backward tip rake propeller, which are recently developed propeller concepts. Figure 1 shows the shape of Kappel and CLT propeller. The backward tip rake propeller is popularly being used with Korean ship companies.

(Lee, et al., 2017) [2]. The present design concept of both forward and backward tip rake propellers came from the contracted loaded tip (CLT) propeller. The CLT idea originally came from winglets, which are widely used in aircraft. Winglets reduce the induced drag by weakening the vortex at the wing, leading to greater efficiency (Ha, et al., 2014) [3]. In other words, both propellers prevent the three-dimensional vortex effect by reducing fluctuating pressure changes at the wing tips. It should be noted that in the CLT propeller, contrary to the tip rake propeller, the end plates are unloaded and operate as barriers, preventing the cross flow of the pressure and suction side of the blades, with the finite load at the tip of the blade (G. Gennaro, et al., 2012) [4]. Although the CLT's effect of weakening the tip vortex is probably better than that of the tip rake propeller, the Kappel and tip rake propellers have been more widely used than the CLTs due to the risk of cavitation in the corners and also loss with the end plate drag at high speeds.



Figure 1. (a) Kappel propeller, (b) Contracted Loaded Tip (CLT) Propeller.

While the Kappel and tip rake propellers have been widely used for more than 15 years, their performance and design is not well understood (Yamasaki, et al., 2013) [5]. A parametric study for optimal rake shape has been conducted here. The performance of the optimized propellers was verified by computational fluid dynamics (CFD) and model tests.

Pressure fluctuation issues from the propeller should also be investigated and compared to verify the performance of the tip rake propeller because it is more effectively used to reduce the aft hull surface pressure fluctuation induced by propellers. These studies are expected to be conducted in the near future.

## 2. Study Methods of Tip Rake Propellers

#### 2.1. Design Based on Potential Analysis

The KP505 propeller, which was designed for the Korea Research Institute of Ships & Ocean engineering (KRISO) Container ship (KCS), was selected as the reference propeller. This propeller is widely used for academic and comparative purposes as its performance and geometry are readily available. The KP505 is appropriate for this comparative study because no radial rake was applied. Rake was applied to the reference propeller by altering the starting radii, the maximum rake size, and the rake application (backward and forward).

The starting points of the rake distribution were set as 0.4 R, 0.5 R, 0.6 R, and continuously increased by 0.1 R to the blade tip. If the starting point is less than 0.4 R or greater than 0.7 R, it is difficult to introduce the rake effect. The maximum rake variation was 1%–10% of the propeller diameter. If the rake variation is greater than 10%, the propeller acquires excessive curvature and very difficult to be smooth along radii. Figure 2 represents the radial distribution of the rake applied to a forward and backward propeller, respectively. The rake shape along the radius was designed as a sine curve. The side view of tip rake propellers is shown in Figure 3.



Figure 2. Rake distribution variability with radius: (a) Forward type, (b) Backward type.



Figure 3. The side view of tip rake propellers.

Numerical analysis of the propeller's open water performance was performed using KPA4, a potential-based numerical analysis is commonly used in the study of open water propeller performance (Kim, et al., 1993; Kim and Lee, 2005) [6,7]. The KPA4 package was developed based on the vortex lattice method (VLM). The diameter of the model propeller for the propeller open water (POW) analysis was 250 mm and the propeller rotation speed was 16rps. The analysis was performed with J = 0.05 to J = 1.00 at an interval of 0.05. Finally, the geometry of the propellers is as shown in Table 1.

r/R	P/D	Rake (xG/D)		Skew(°)	C/D	fo/C	T <sub>e</sub> /D
1/1C	1/2	Forward	Backward	SRew()	СĮВ	10/0	10/10
0.18	0.8347	0.0000	0.0000	-4.72	0.2313	0.0284	0.0459
0.25	0.8912	0.0000	0.0000	-6.98	0.2618	0.0296	0.0407
0.30	0.9269	0.0004	0.0000	-7.82	0.2809	0.0295	0.0371
0.40	0.9783	0.0031	-0.0017	-7.74	0.3138	0.0268	0.0305
0.50	1.0079	0.0101	-0.0082	-5.56	0.3403	0.0220	0.0246
0.60	1.0130	0.0174	-0.0206	-1.50	0.3573	0.0173	0.0195
0.70	0.9967	0.0200	-0.0285	4.11	0.3590	0.0140	0.0149
0.80	0.9566	0.0180	-0.0285	10.48	0.3376	0.0120	0.0107
0.90	0.9006	0.0119	-0.0189	17.17	0.2797	0.0104	0.0069
0.95	0.8683	0.0070	-0.0113	20.63	0.2225	0.0101	0.0053
1.00	0.8331	0.0000	0.0000	24.18	0.0001	8.7000	0.0037

Table 1. Propeller geometry of forward- and backward-type propellers.

The computed POW efficiency was compared at  $K_T/J^2 = 0.4725$  as shown in Figure 4. Based on these results, an optimal shape was selected for forward and backward propellers. The optimal rake for the backward propeller was STP = 0.4R and xG/D = 0.02 and was 2.15% greater than the reference propeller. The optimal rake for the forward propeller was STP = 0.5 R and xG/D = 0.03, and it was 3.35% greater than the reference propeller. After the optimal rake had been applied to the propeller, there were non-smooth surfaces during 3-D modeling. The observed discontinuity is shown in Figure 5. Therefore, the rake distribution was smoothed as shown in Figure 6. After the final modifications to the rake were applied, improvements of 1.9% and 2.2% by the forward and backward propellers, respectively, were obtained compared to the reference propeller, which is shown in Table 2.



**Figure 4.** Comparison of open water propeller efficiency based on potential. (**a**) Forward propeller; (**b**) backward propeller.



Figure 5. Discontinuity of the 3-dimensional configuration.



Figure 6. Modified rake distribution variability with radius.

 Table 2. Comparison of open water propeller efficiency based on potential.

the Type of Propellers	PP016 (KP505)	PP033 (Forward)	PP034 (Backward)
J	0.659	0.662	0.661
$\eta_0$	0.614	0.626	0.627
Diff.(%)	-	1.934	2.207

## 2.2. Tip Rake Propeller Model Test

The aluminum model of the reference propeller (PP016, KP505) and the optimally designed forward (PP033), and backward propellers (PP034) were manufactured for the model test shown in Figure 7. The propeller's diameter is 0.2m. The propeller open water test was performed at intervals of 0.05 from J = 0.05–1.00. According to the International Towing Tank Conference (ITTC), the minimum Reynolds number for the POW test is  $2 \times 10^5$ , however some cases, that may not be large enough (Kim, et al., 1985) [8]. In this study, the minimum Reynolds number is more than  $5 \times 10^5$  as shown in the Figure 8. The results of the self-propulsion test at the speed of 24 knots, which was conducted in the PNU towing tank, the target  $K_T/J^2=0.4725$  was identified (Kwon, 2013) [9]. The open water efficiency of the three propellers is compared in Table 3 where the backward propeller is 1.28% greater and the forward propeller is 0.264% greater than the reference propeller (KP505) at the same point of  $K_T/J^2$ . The tendency of the efficiency gain is similar to the potential computation although there is little quantitative difference. Figure 9 shows a comparison with KP505 open water test results conducted by KRISO to verify reliability of PNU model test results. In the low J area, there was some difference

in thrust and torque coefficients, but not much difference in open water efficiency with the KRISO results. The open water efficiency near target J (approximately 0.6) was almost identical to each other. Figure 10 shows the results of comparison of open water propeller efficiency based on experiments.



Figure 7. Model propellers.



Figure 8. Reynolds number of J during experimental tests.

Table 3. Comparison of open water propeller efficiency based on experiments.

the Type of Propellers	PP016 (KP505)	PP033 (Forward)	PP034 (Backward)
J	0.646	0.651	0.651
$\eta_0$	0.607	0.608	0.614
Diff.(%)	-	0.264	1.280



Figure 9. Comparison of model test results vs. KRISO.



Figure 10. Comparison of open water propeller efficiency based on experiments.

## 2.3. Numerical Analysis of Propeller Open Water Performance by Computational Fluid Dynamics (CFD)

Numerical analysis has been performed for the reference propeller PP016 (KP505) and the optimized forward and backward propellers, PP033 and PP034, respectively. The configurations of the propellers are shown in Figure 11. Local flow analysis of wing tip vortices was also carried out to investigate the hydrodynamic phenomena manifested by the application of rake at the wing

tip (Park, et al., 2011; Baek, et al., 2014) [10,11]. For all propellers, the revolution speed was 16 rps, the same as the potential analysis case. An interval of 0.2 from J = 0.1-0.9 was used, and local flow investigation was performed at J = 0.7. Table 4 shows the POW performance of the 3 propellers in CFD analysis.



Figure 11. Three-dimensional modeling of the three selected propellers.

J	KT	10KQ	ETAO		
0.1	0.479	0.672	0.113		
0.3	0.386	0.558	0.330		
0.5	0.279	0.431	0.516		
0.7	0.173	0.303	0.637		
0.9	0.066	0.160	0.596		
	(a) Reference	e propeller (KPS	505)		
J	KT	10KQ	ETAO		
0.1	0.472	0.668	0.112		
0.3	0.384	0.561	0.327		
0.5	0.281	0.436	0.512		
0.7	0.175	0.308	0.635		
0.9	0.068	0.164	0.597		
(b) Forward propeller					
J	KT	10KQ	ETAO		
0.1	0.480	0.672	0.114		
0.3	0.385	0.557	0.330		
0.5	0.278	0.429	0.515		
0.7	0.172	0.302	0.633		
0.9	0.065	0.158	0.586		
(c) Backward propeller					

Table 4. The propeller open water (POW) performance of the 3 propellers.

The analysis was performed using STAR CCM+, which is a commercial CFD program developed by CD-adapco. In the following equations,

$$\frac{\partial u_i}{\partial x_i} = 0 \tag{1}$$

$$\frac{\partial(\rho u_i)}{\partial t} + \frac{\partial(\rho u_i u_j)}{\partial x_i} = -\frac{\partial p}{\partial x_i} + \frac{\partial}{\partial x_i} \left(-\rho \overline{u_i' u_j'}\right) + \frac{\partial}{\partial x_i} \left[\mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i}\right)\right]$$
(2)

 $x_i$ ,  $u_i$ ,  $\rho$ , and  $\mu$  denote the rectangular coordinate system, the velocity component, pressure, density, and viscosity, respectively. The Reynolds stress term in Equation (2) is analyzed using a  $\kappa$ - $\varepsilon$  model. The Semi-Implicit Method for Pressure Linked Equations (SIMPLE) was used for velocity, pressure,

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and ductility, and a second order differential method was applied for calculating convection and diffusion. The computation domain and boundary conditions considered in this study are shown in Figure 12. The motion of the flow analysis area was analyzed by the sliding mesh method, which is the same method used for the local flow analysis. The analysis conditions used for CFD are shown in Table 5.



Figure 12. Computational domain and boundary conditions.

Program	Star CCM+ (Ver. 9.04)	
Governing equation	Reynolds Averaged Navier Stokes (RANS) equation	
Discretization	Cell centered FVM	
Turbulence model	Realizable κ-ε model	
Velocity-pressure coupling	SIMPLE algorithm	
Rotation method	Sliding interface moving mesh	
Cell number	1,600,000	

Table 5. Computational fluid dynamics (CFD) analysis conditions.

The open water propeller efficiency of each propeller was compared at the same  $K_T/J^2 = 0.4725$  as in the potential analysis study. The difference in open water propeller efficiency was 0.2% for the forward propeller (PP033) and 0.6% for the backward propeller (PP034) compared to the reference propeller (PP016, KP505). The results are summarized in Table 6 and Figure 13. The tendency of the computed results of the efficiency gain is different from the potential analysis and the experimental results. There is almost no quantitative difference among them. The results of the model test and potential analysis are thought to be more reliable, so it is necessary to investigate the reason for the different results. The denser grid around the tip might be necessary for capturing the tip vortex more accurately, and a parameter study of turbulence modeling might be also necessary. However, it might still be necessary to improve the present CFD analysis, the comparison of the tip vortices of the three propellers has been completed.

Table 6. Comparison of open water propeller efficiency based on CFD.

The Type of Propellers	PP016 (KP505)	PP033 (Forward)	PP034 (Backward)
J	0.669	0.670	0.668
$\eta_0$	0.618	0.617	0.614
Diff.(%)	-	-0.2	-0.6



Figure 13. Comparison of open water propeller efficiency based on CFD.

The vorticity magnitude is shown in Figure 14 where the backward propeller is a little weaker than the other two propellers. Although the total efficiency of the tip rake propeller is slightly worse, the backward tip rake might locally work better than the others.



**Figure 14.** Vorticity magnitude (J = 0.7).

### 3. Conclusions and Discussion

A parametric study on tip rake propellers has been completed based on the KP505, the KCS propeller, by varying the maximum size and starting rake radius. A potential based analysis code was used for the present parametric study. The optimally designed forward and backward propellers had an efficiency gain of 1.9% and 2.2%, respectively, over the reference propeller (KP505) in POW conditions. The three propellers (reference, backward, and forward) were tested in POW conditions to confirm their performances experimentally. The results are similar to the potential analysis where the propellers performed 1.3% (backward) and 0.3% (forward) better than the reference propeller, although the efficiency gain is somewhat less than during the potential analysis.

Lastly, the CFD analysis was applied to validate the performance of the three propellers. The computed results are different from the previous two cases (potential analysis and experimental test). There was efficiency loss compared to the reference propeller of -0.2% (forward) and -0.6% (backward). While there is some discrepancy in efficiency by the CFD analysis, the tip vortex flow was also investigated CFD. The tip vortex strength of the backward propeller was slightly less than those of the other two propellers (Figure 15), which is a similar result to the potential based analysis and the experimental test. More investigation into CFD analysis is expected by varying the grid system and turbulence modelling. Table 7 shows the open water propeller efficiency difference according to analysis method.



**Figure 15.** Comparison of results according to analysis method. (**a**) Reference propeller (KP505); (**b**) backward propeller; (**c**) forward propeller.

	Potential Analysis	Model Test	CFD Analysis
Forward	+1.9%	+0.3%	-0.2%
Backward	+2.2%	+1.3%	-0.6%

**Table 7.** Open water propeller efficiency difference according to analysis method compared to the results of the reference propeller.

Future work extending from this study is expected to include the study of pressure fluctuations and noise from the tip vortex by changing the configuration of the tip shape so that tip rake is more effectively applied to reduce hull pressure fluctuations, especially for container ships.

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