

Article

No Pain Device: Empowering Personal Safety with an Artificial Intelligence-Based Nonviolence Embedded System

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Abstract: This paper presents the development of a novel anti-violence device titled “no pAIIn” (an acronym for Never Oppressed Protected by Artificial Intelligence Nonviolence system), which harnesses the power of artificial intelligence (AI). Primarily designed to combat violence against women, the device offers personal safety benefits for individuals across diverse demographics. Operating autonomously, it necessitates no user interaction post-activation. The AI engine conducts real-time speech recognition and effectively discerns genuine instances of aggression from non-violent disputes or conversations. Facilitated by its Internet connectivity, in the event of detected aggression, the device promptly issues assistance requests with real-time precise geolocation tracking to predetermined recipients for immediate assistance. Its compact size enables discreet concealment within commonplace items like candy wrappers, purpose-built casings, or wearable accessories. The device is battery-operated. The prototype was developed using a microcontroller board (Arduino Nano RP2040 Connect), incorporating an omnidirectional microphone and Wi-Fi module, all at a remarkably low cost. Subsequent functionality testing, performed in debug mode using the Arduino IDE serial monitor, yielded successful results. The AI engine exhibited exceptional accuracy in word recognition, complemented by a robust logic implementation, rendering the device highly reliable in discerning genuine instances of aggression from non-violent scenarios.

Keywords: personal safety; health; microcontrollers; Arduino; Internet of Things; artificial intelligence; Tiny Machine Learning



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1. Introduction

This paper presents an innovative device driven by artificial intelligence (AI), designed to prevent gender-based violence. The device operates in a completely automatic manner, requiring no user intervention beyond the initial power-up. It incorporates cutting-edge technologies including AI, Internet connectivity, GPS, and embedded systems (ES) while showcasing distinctive operational features designed for violence prevention.

Gender-based violence refers to acts of violence directed at individuals due to their gender, with women and girls comprising the predominant victims. This issue remains a significant challenge within our societies and is deeply entrenched in gender disparities, representing a violation of human rights and the most severe form of discrimination based on gender. According to a survey carried out by the EU Fundamental Rights Agency in 2014 [1], one in three women in the EU have been victims of violence in their lifetimes, and one in twenty women have been raped.

The statistics provide chilling data on femicides in Italy and globally over the last four years [1–11]. In 2020, there were 116 female victims of intentional homicide in Italy, accounting for 0.38 per 100,000 women. In 2021, 104 femicides were reported, with 70% of the victims being women killed by their partners or ex-partners. In 2022, the number of female victims increased to 196 compared to 2021. In 2023, 120 female victims of intentional homicide were recorded in Italy.

Globally, in 2020, more than 5 women and girls were killed every hour, totaling 45,000 victims. Shockingly, 56% of the 81,100 homicides worldwide that year involved women and girls killed by their husbands, partners, or other relatives. The actual number of femicides is likely higher, as at least 4 out of 10 deaths in 2020 were not officially classified as femicides due to insufficient data. In 2022, almost 89,000 women and girls were intentionally killed worldwide, marking the highest annual total in the last two decades. This is an increase from 81,100 victims in 2021. Of these, 55% (48,800) were committed by family members or partners.

The impact of violence on victims, even if not killed, is profound, significantly hindering their ability to fully engage in societal activities.

While the human costs are immense, the economic implications of gender-based violence are also staggering. According to estimates by the European Institute for Gender Equality (EIGE), the annual cost of gender-based violence in the European Union amounts to EUR 366 billion. Of this total, violence against women constitutes 79%, equivalent to EUR 289 billion.

These statistics underscore the severity of the gender-based violence issue in Italy and globally, thus elucidating why the author has chosen to address it from a technological standpoint. Indeed, one of the most effective ways to mitigate the severity of this phenomenon is undoubtedly prevention. The author, in this paper, delineates a technological solution aimed at substantially mitigating the prevalence of gender-based violence.

Currently, two main strategies are utilized to address this issue: traditional hand gestures signaling for assistance and the use of electronic bracelets, which are required in specific cases for individuals considered potentially violent. These approaches are then examined and compared with the innovative solution proposed by the author.

The first solution is a universally recognized hand gesture established to signal a request for help from a woman (or a person, in general) in danger. Unfortunately, there may be instances where the gesture goes unnoticed, or the victim may be unable to mimic it or there are no individuals nearby who can observe the plea for help. Often, gender violence takes place within the home, in the absence of other people. Furthermore, there is a risk of too much precious time elapsing between the moment when a person in danger signals for help through a gesture and the point at which someone noticing the gesture can effectively alert emergency services.

Hence, the author of this paper has conceptualized, designed, prototyped, and tested a fully automated, miniaturized, electronic device powered by AI that is a sort of electronic gesture of a plea for help. It operates in a totally automated mode and with the further advantage of notifying the plea even to people who are physically far from the place of violence and, therefore, would not be able to see the gesture if made by hand. It is named “no pAI” (which stands for: Never Oppressed Protected by Artificial Intelligence Nonviolence system). The “no pAI” device is an ES designed using the most advanced digital, geolocation and communication technologies available but unique for its behavior and operating mode. It is miniaturized and can be easily incorporated into a bracelet or concealed within a bag or other accessory used by persons at risk of violence who wish to carry it. It promptly discerns situations of serious danger in real-time and, when such situations arise, automatically dispatches requests for help along with geolocation data. This fully automated device obviates the necessity for any explicit gesture or plea for assistance from the victim, who may find themselves incapacitated to do so. Moreover, it transmits requests for help autonomously regardless of the presence or awareness of other individuals in proximity to the victim, dispatching real-time alerts for assistance in the form of messages, notifications, and emails to multiple remote recipients equipped to offer or coordinate immediate aid.

At present, there is not such a device in commerce. There exists an electronic bracelet mandated for potentially dangerous individuals, which prevents them from approaching a woman. This is the second solution currently adopted to prevent gender violence. In contrast, the “no pAI” device is intended for use by potential victims, rather than

potential assailants. The existing bracelet, mandated for dangerous individuals, can be likened to a “leash” that keeps them away from the person in danger. Conversely, the new device presented in this article, used by the person in danger, can be likened to a shield or bodyguard, offering protection against aggression. Furthermore, the existing bracelet requires a complaint from the victim and a judicial sentence (in Italy) for a dangerous individual to be obligated to wear it, necessitating that the individual has already been reported and a court has issued an order for the bracelet’s usage. However, this legal process is not always effective, as women may not always report aggressive partners and serious threats can arise suddenly from unfamiliar or completely unknown individuals. In contrast, the new device can be freely utilized by potential victims (without the need for a court order or authorization, as it is the individual’s voluntary choice whether to use the new device or not). Additionally, it provides protection against aggression that may originate from occasional perpetrators who have not been reported and therefore do not wear the electronic bracelet. Furthermore, leveraging AI, it enables early identification of risk conditions, even within domestic settings. Many women do not report their violent partners, who consequently are not mandated to wear the electronic bracelet and may even reside in the same household as their victim. In such cases, the use of this new device offers protection, whereas the electronic bracelet does not.

Hence, the novelty and unique benefits of the “no pAIIn” device are that it offers greater safety and reliability, functioning without the necessity of obtaining any authorization but instead operating in a completely free and voluntary manner. It is a personal device, managed privately, as the potential victim utilizes it directly, akin to an invisible bodyguard—a perpetually vigilant yet unseen sentinel safeguarding their health and life. It is fully automated: the AI detects dangerous situations and remotely sends requests for help with geolocation coordinates. No user intervention is needed. Finally, very importantly, an essential benefit of the “no pAIIn” device is that it allows a situation of gender violence to be identified at the very first signs and therefore to effectively prevent harmful consequences. Of course, the existing bracelet and the new “no pAIIn” device can be used in conjunction with each other, respectively, from the assailant and from the victim; one does not preclude the other.

The aim of this paper is to describe the “no pAIIn” device and its project and operation. Hence, Section 2 provides an overview of widely recognized devices useful for surveillance purposes, demonstrating the originality of the new one; Section 3 delves into the device’s architecture and design; Section 4 demonstrates the device in action, and finally, Section 5 presents conclusions and potential avenues for further project development.

2. Literature Survey

In the scientific literature, there are several works discussing projects and devices utilizing artificial intelligence (AI) for home automation and surveillance purposes.

The review in [12] explores intelligent audio surveillance for public safety, emphasizing the role of artificial intelligence in enhancing security through sound analysis.

The authors in [13] investigate wearable devices for personal safety, providing insights into the integration of AI for enhancing safety features in wearable technologies.

A focus on voice-based emotion recognition using deep learning, offering potential applications in systems emphasizing personal safety can be found in [14].

The work in [15] provides a survey of IoT-based personal safety systems, with a focus on AI integration for effective monitoring and response.

Cloud-based emergency response systems are examined in [16], highlighting the use of AI for efficient communication and coordination during emergencies.

In [17], there is a review of wireless sensor networks-based health monitoring systems, offering insights into the potential integration of AI for personalized safety monitoring.

Paper [18] investigates machine learning applications in public safety and emergency management, presenting a broad view of AI implementations in safety-related contexts.

A survey about mobile-based solutions for personal safety, including AI-enhanced features in mobile applications dedicated to individual security, is in [19].

A comprehensive review of voice emotion recognition, providing potential applications in systems focused on personal safety, can be found in [20].

A discussion about wearable technology in personal safety applications, examining the role of AI in enhancing the capabilities of wearable safety devices, is in [21].

The design of a smart home system utilizing voice control and deep learning for enhanced automation is in [22].

The article [23] focuses on a home automation system employing speech recognition with a deep learning approach.

The paper [24] discusses a home automation system integrating speech-based controls with AI.

The paper [25] presents a smart home system incorporating speech recognition and IoT technology for efficient control and communication.

The authors in [26] detail an intelligent home automation system utilizing voice control and Raspberry Pi technology.

The article [27] discusses a real-time home automation system employing voice control with a focus on deep learning techniques.

The paper [28] introduces an IoT-based home automation system integrating intelligent voice control through Amazon Alexa.

The authors in [29] present a smart home automation system utilizing voice recognition and deep learning techniques for improved functionality.

The paper [30] discusses a smart home system incorporating voice recognition and deep learning technologies for advanced automation.

The authors in [31] introduce a speech-based intelligent personal assistant designed for real-time control of home automation tasks.

Despite the extensive existing literature on intelligent devices, the author found no device in the literature review conducted that combines the functionalities of the new device. None resemble the “no pAIIn” device due to its distinct characteristics. The most well-known and widely used devices are those designed for remotely monitoring the health and condition of sick or elderly individuals. However, devices and smartphone applications with this functionality are not relevant to the operational specifications of the new device. These known devices and applications focus on monitoring vital signs and providing assistance in case of illness. In contrast, the new device relies on AI-based speech recognition and intervenes to aid perfectly healthy individuals with normal vital signs who are at risk of dying within minutes due to an assault.

3. Project Method, Device Operation and Architecture

The “no pAIIn” device is an ES with a microcontroller (μC) as the core of the hardware part, which also has a firmware part. The design method employed is rooted in the Arduino approach, commonly known as a “platform-based” design methodology, which presents notable advantages over conventional ES design approaches. Unlike traditional methods characterized by complex hardware setups, proprietary platforms, high licensing costs, intricate programming interfaces, and protracted development timelines, Arduino stands out for its open-source hardware and software platform, providing a straightforward and accessible alternative. Key advantages of the Arduino approach include:

- Simplified Development Workflow. Arduino streamlines the ES design process, reducing the learning curve and enabling rapid prototyping and iteration.
- Extensive Hardware Selection. Arduino offers a wide range of boards catering to diverse application needs, allowing for flexible hardware selection.
- Rich Library Ecosystem. It provides pre-written code modules for common tasks, accelerating development and ensuring reliability.

- **Modular Architecture.** It facilitates seamless integration with various sensors, actuators, and communication protocols, enabling rapid customization to meet project requirements.
- **Plug-and-Play Compatibility.** Arduino's plug-and-play hardware ecosystem simplifies prototyping, eliminating the need for intricate wiring and soldering, and fostering rapid iteration.
- **Interoperability.** Arduino is compatible with numerous software frameworks and development tools, ensuring interoperability with existing ecosystems and facilitating integration into complex projects.

This is why the Arduino approach has been chosen to design the “no pAIIn” device.

The project begins with the device behavior specifications, serving as its foundation. Functioning as a virtual “sentinel”, it employs AI for speech recognition, enabling real-time interpretation of scenarios with remarkable reliability. The device distinguishes high-risk violence situations from ordinary disagreements, intervening discreetly to protect the user when necessary. This intervention involves automatically sending geolocation-based requests for help, ensuring swift assistance without human intervention, and discreetly alerting pre-defined recipients via messages and emails.

To fulfill these tasks, the device includes a low-power μC capable of accommodating an AI engine for speech recognition, alongside management logic and operational instructions outlined in the behavioral specifications. Additionally, it features an omnidirectional microphone, an Internet connectivity module for remote communication, and geolocation capabilities, optionally supplemented with a physical GPS module. The consequent architecture of the “no pAIIn” device is as in Figure 1, which also delineates the dataflow and, consequently, the overall behavior of the device.

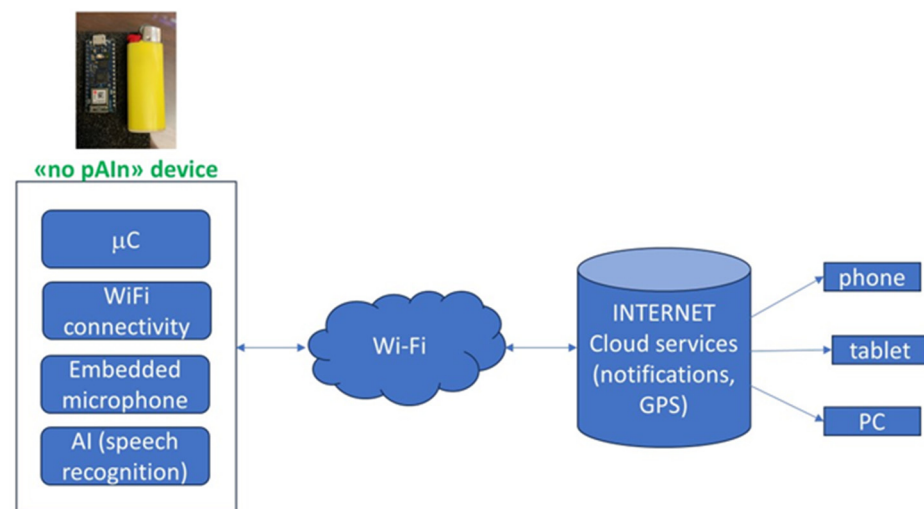


Figure 1. System architecture.

The hardware components of the device are compact, comprising only a μC , a microphone, and an Internet connectivity module. The inclusion of a GPS module is optional, as it is not essential for providing geolocation capabilities to the device, a topic that will be elaborated on in the paper's section on geolocation methodologies. The firmware, responsible for managing the device and Internet operations, is executed by the hardware components, completing the device architecture.

After defining the behavioral specifications and the resulting block architecture of the device, the next phase of the project involves formalizing the behavioral specifications as a flowchart. This flowchart is instrumental in developing the code (referred to as a “sketch” in the Arduino development environment) during the final stage of the project—implementing the design. The flowchart is illustrated in Figure 2.

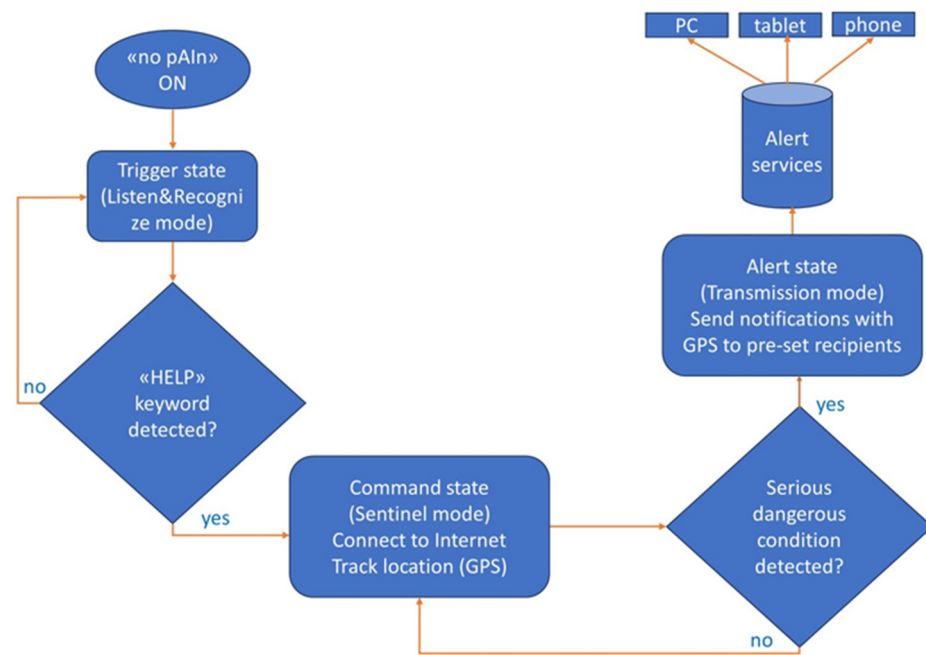


Figure 2. Flow chart of the firmware of the “no pAI” embedded device behavior.

We can describe it by envisioning the “no pAI” device as a finite state machine, comprising precisely three states. Each state corresponds to a specific operational mode. The first state is referred to as “Trigger”, and its operational mode is labeled as “Listen&Recognize”. The second state is termed “Command”, with its corresponding operational mode named “Sentinel”. The third state is labeled “Alert”, and its respective operational mode is named “Transmission”. The direction of the arrows in Figure 2 indicates the progression of state transitions. Subsequently, we examine the device’s behavior in each state and the conditions under which state transitions occur.

Upon powering on, the device enters the “Trigger” state, initiating the activation of AI which utilizes the device’s built-in microphone to listen and recognize the words heard (“Listen&Recognize” operational mode). All audio data are processed without storage, ensuring compliance with privacy laws. However, incorporating data storage into the firmware code would be straightforward, utilizing either a microSD card or a flash memory integrated into the device board. This would enable the “no pAI” device to store voice recordings of several minutes on board.

Upon detection of the keyword “help” (or an alternative keyword, customizable based on user preference), the device transitions from the “Trigger” state to the “Command” state, thereby activating the “Sentinel” mode, prepared to detect and respond appropriately to serious danger conditions. In fact, in the “Command” state (“Sentinel” mode), the device establishes an Internet connection and retrieves GPS coordinates.

Upon identification of a situation deemed as a serious danger, based on the subsequent words heard and recognized, the device transitions from the “Command” state (“Sentinel” mode) to the “Alert” state (“Transmission” mode). During the “Transmission” mode, the device autonomously sends a sequence of notifications to pre-defined recipients equipped with smartphones, tablets, or PCs. These notifications may consist of emails, Telegram messages, Discord messages, and in-app alerts, containing messages such as “Request for help” or “Likely need for rescue” or any other customizable help request message, accompanied by the geolocation coordinates of the victim.

The “no pAI” device operates with the utmost respect for privacy, abstaining from storing or disseminating any sensitive data, as already stated, except for geolocation information. Nonetheless, the sharing of geolocation data for personal safety with preferred individuals (the recipients of help request notifications) is governed by the implicit consent

of users who choose to utilize the device. For this reason, the use of the device raises no ethical questions of any kind, and there are no doubts about the legitimacy of its use.

The device requires a “one-off” configuration to set, for example, the recipients of emergency notifications and to perform other possible customizations. Aside from the initial setup, the firmware has been engineered so that the device operates entirely autonomously, requiring nothing more than powering it on.

Let us proceed with the project description by detailing each of the modules composing the architecture of the “no pAI_n” device (refer to Figure 1) and then the techniques implemented for Internet connectivity, geolocation, and sending alarm notifications.

3.1. Microcontroller

The μ C must demonstrate high performance to accommodate the required AI within its microprogram memory and manage all device operations across different states, including Internet connectivity and geolocation capabilities. Additionally, it must consume minimal power due to the device being battery-powered and intended for extended usage periods. Hence, the 32-bit ARM Cortex-M0+ was selected owing to its low power consumption, rendering it suitable for portable, battery-powered applications, alongside its commendable performance aligned with the device’s intended functionalities. Furthermore, its capabilities are apt for the integration of speech recognition AI.

For prototyping purposes, the Nano RP2040 Connect board, powered by Arduino, and depicted in Figure 1, emerges as the optimal selection. It is noticeable that the dimensions of the prototyping board are very small, about 20 mm \times 45 mm, smaller than a mini lighter. The Arduino Nano RP2040 Connect board represents a feature-rich development board in “nano” format, harnessing the capabilities of the RP2040 microcontroller. Noteworthy features of this board are outlined below [32–34]:

- Microcontroller: it uses Raspberry Pi’s new silicon, the RP2040, which is a dual-core 32-bit Arm[®] Cortex[®]-M0+ running @ 133 MHz.
- Memory: it has 264 KB of SRAM, and the 16 MB of flash memory is off-chip to give the designer extra storage.
- Connectivity: it supports Internet of Things projects with Bluetooth[®] and Wi-Fi connectivity, thanks to the U-blox[®] Nina W102 module.
- Sensors: it comes with an onboard accelerometer, gyroscope (6-axis IMU), temperature sensor, and an omnidirectional microphone.
- LED: it has a built-in RGB LED.
- Machine Learning: it supports machine learning using TinyML, TensorFlow Lite or EdgeImpulse, thanks to the high-performance energy-efficient microprocessor.
- Python[®] Support: This board can be programmed using MicroPython and Arduino IDE.

Hence, this board is suitable for developing robust embedded AI and IoT solutions with minimal effort. It is notable that the Nano RP2040 Connect board is equipped with an embedded MP34DT06JTR omnidirectional microphone, enabling real-time capture and analysis of sound for a wide range of applications.

These features make the Nano RP2040 Connect board particularly suitable for the “no pAI_n” project prototyping.

3.2. Internet Connectivity

The “no pAI_n” device can connect to the Internet in two ways.

Indeed, it can be outfitted with either its own SIM card and corresponding host module or it can establish a Wi-Fi connection to the Internet with a hotspot via a Wi-Fi module.

The Arduino Nano RP2040 Connect board used for prototyping is equipped with the U-blox[®] Nina W102 module. Certainly, both modules—the SIM and the Wi-Fi—may be present concurrently.

The μ C manages the connectivity modules (either SIM or Wi-Fi), activating the Internet connection as needed with simple dedicated instructions. Specifically, the Internet

connection is established only when the device switches from the “Listen&Recognize” mode to the “Sentinel” mode, to optimize the power consumption.

In the Wi-Fi connectivity scenario, implemented in the device prototype, there are two further options. One is that the device is programmed to connect to the user’s router (if at home) or to the user’s smartphone hotspot, both having a known SSID name and password. The second option is for the μ C to scan the surrounding Wi-Fi networks (many public places currently offer free Wi-Fi connections without a password) and connect to the nearest open hotspot. Both options have been successfully assessed in the “no pAI” device prototype.

The μ C initially checks for the presence of an encrypted connection with the router or with the user’s smartphone hotspot. If such a connection is not detected, it proceeds to search for the closest non-encrypted Wi-Fi network to establish a connection with. The credentials (SSID and password) required for connecting to the user’s encrypted network are preconfigured during the device setup phase.

From a programming standpoint, the Wi-Fi management libraries provided for Arduino streamline the procedure of scanning for available networks, identifying the SSID, assessing signal strength, determining encryption type, and allowing automatic connection. Functions of the Wi-Fi library (WiFiNINA for the U-blox® Nina W102 module on the RP2040 Connect board) such as

```
WiFi.scanNetworks(); //scanning available networks
WiFi.RSSI(); // measure the strength
WiFi.SSID(); //determine the SSID
WiFi.encryptionType(); // determine encryption type
WiFi.begin(<NetworkSSID>); //connect
```

are suitable for implementing the appropriate logic and corresponding code, which is useful for this purpose.

3.3. Artificial Intelligence Engine

The use of AI by μ C-based ES can occur in two modes: cloud-based and on-board.

The strategy that entails the deployment and utilization of AI directly on the device is known as Tiny Machine Learning (TinyML) for edge computing.

Both approaches offer distinct advantages and disadvantages.

Specifically, the benefits of the on-board implementation are as follows.

Data are processed directly on the device, reducing the need to transfer data over the network. As AI runs locally, response times are faster compared to sending data to a remote server for processing and waiting for the outcome of the processing in response. Sensitive data need not be shared over the network, reducing the risk of privacy breaches and unauthorized access. A constant Internet connection is not required, thereby reducing the power consumption of the device.

On the contrary, the disadvantages are as follows.

Microcontroller devices may have limited resources such as memory and computing power, limiting the complexity and size of AI models that can be run. AI model updates need to be manually distributed to devices, making software management and updates more complex. Integrating on-board AI models may require investments in more advanced hardware, which can be more expensive compared to devices relying solely on cloud services.

Cloud-based AI services offer numerous benefits. They are capable of processing vast amounts of data and provide scalable computing resources for handling AI processing requests. Furthermore, AI model updates can be centrally distributed to devices, streamlining software management, and guaranteeing consistent access to the latest model versions. Cloud data processing can provide access to external resources such as large datasets and pre-trained models, improving AI performance. Finally, there is no need to invest in advanced hardware to run AI, as processing occurs in the cloud.

On the contrary, the disadvantages of cloud-based AI services are as follows.

Device operation relies on Internet connectivity, which can pose issues in case of unstable or absent connectivity. Sending data to a remote server may raise concerns about security and privacy, especially for sensitive data. The time required to transmit data to the cloud server and receive a response can cause delays in AI system responses, especially in situations where speed is critical.

In summary, on-board AI usage (AI embedded) offers advantages such as increased speed, privacy, and reliability, but may be constrained by available hardware resources. On the other hand, cloud service usage offers scalability, ease of update, and access to external resources, but may be affected by network connectivity and raise concerns about security and privacy.

The choice between the two approaches will depend on the specific project requirements and technical limitations. Given the features and objectives of the “no pAIIn” project, an on-board approach has been selected, primarily due to its distinct advantages in terms of privacy and speed. Furthermore, the implemented on-board AI engine, which will now be described, meets the exceptionally high accuracy requirements, rendering the utilization of a cloud-based AI service unnecessary and potentially detrimental to the device’s operational speed.

Various techniques exist for implementing AI in ES; very interesting details can be found in [35,36]. Certain μC can be programmed with machine learning (ML) models, such as artificial neural networks, decision trees, or support vector machines, to make intelligent decisions. This approach, well known also as TinyML (short for Tiny Machine Learning), involves deploying models trained on large datasets to perform tasks like image recognition, speech recognition, time series forecasting, etc. It is a cutting-edge field focused on equipping extremely resource-constrained devices, including μC and ES, with ML capabilities. So, these devices can execute inference tasks locally without relying on external servers or cloud computing resources. Typically, TinyML models undergo optimization techniques like quantization to enable storage and execution on resource-limited like μC . Moreover, specialized software companies develop readily deployable libraries tailored for specific μC , a practice prevalent in the Arduino ecosystem.

Leveraging compact and efficient ML models, TinyML facilitates the integration of intelligent functionalities across diverse applications, encompassing IoT devices, wearables, and edge computing systems. This technology holds significant promise for enabling intelligent, autonomous operations in devices functioning at the network edge, particularly in scenarios where connectivity may be restricted or latency sensitive. The approach employed for speech recognition in the “no pAIIn” project falls within the realm of TinyML inference.

Currently, there are various methods for creating TinyML algorithms, including using the Google Colab platform to develop TensorFlow Lite models, utilizing Python libraries [37], employing MATLAB environment [35,38], and utilizing the Edgeimpulse platform [39], which is highly efficient.

Developing a bespoke AI system with exceptional classification accuracy necessitates the initial creation of a training dataset of significant size, followed by AI training durations proportional to the dataset’s magnitude. Therefore, where feasible, it is advisable to utilize pre-existing libraries, meticulously developed and readily accessible to designers for expedited implementation. In the specific context of the “no pAIIn” project, a library was searched that precisely aligned with the device’s specifications, ensuring both accuracy and functionality.

Therefore, since the “no pAIIn” device is prototyped on the Arduino Nano RP2040 Connect board, it was deemed that the most efficient way to implement the AI on-board was using the Arduino Speech Recognition Engine library [40], which boasts exceptionally high accuracy and other very interesting characteristics, as described in the following.

The Speech Recognition Engine is an extensive software library that allows anyone to interact with devices and machines quickly and easily by talking. It was developed by Cyberon to be part of Arduino Pro’s growing ecosystem of advanced professional solutions. It can be applied to different industrial and professional fields, from speech

dictation to voice-command controllers, health monitoring, robotics, and accessibility, among many others.

The Speech Recognition Engine is compatible with multiple Arduino boards, including the RP2040 Connect, and integrates seamlessly with the Arduino IDE, requiring no additional hardware, software, or Internet connectivity. It operates entirely on-board.

This engine comprehends commands specified through text input in over 40 languages, irrespective of the speaker's voice, intonation, or accent. Consequently, multiple wake-up words and sequences can be swiftly configured without the necessity for retraining for different users. Therefore, in addition to its high accuracy, the primary advantage lies in its inherent lack of requirement for training. In fact, this engine utilizes pre-trained models or ML algorithms to interpret and understand human language, allowing the system to analyze audio data in real-time and make decisions based on the information acquired through speech recognition. Furthermore, it possesses the capability to discern the speaker's voice amidst background noise, rendering it suitable for deployment in busy or crowded environments. The ability to accurately recognize speech even in noisy environments is a crucial feature for the "no pAIIn" project because the device must operate reliably in various contexts. Additionally, the capability to accurately classify speech regardless of emotions, accents, and voice tone makes the speech engine the perfect solution for the "no pAIIn" device.

In summary, key benefits include the following [40]:

- Recognition of multiple words and sequences of commands by phoneme-based modeling.
- No vocal training is required; words to be recognized are configurable through text input (text-to-speech, TTS, technology).
- Support for over 40 languages, independent from accent variations.
- One configuration for one language with multiple speakers, without retraining.
- Recognition on the edge, with no need for additional HW/SW or connectivity.
- Suitability for noisy environments.
- Compatibility with multiple Arduino Nano and Portenta products.
- Compatibility with Arduino IDE.

The Speech Recognition Engine is offered in both free and paid versions. While the paid version incurs a nominal cost (approximately USD 9 as of today), the free version includes limitations that do not compromise the performance criteria specified for the design of the "no pAIIn" device described herein. Therefore, the utilization of the free version is deemed acceptable.

Following the integration of the Speech Recognition Engine into the device, it becomes feasible to develop the Arduino sketch to execute customized tasks in response to recognized speech.

The process of embedding the Speech Recognition Engine into the "no pAIIn" prototype to enable the recognition of custom words/commands is outlined as follows.

First, it is necessary to complete a series of steps to register the board and activate the trial and free-of-charge license, as detailed in [40]. Subsequently, custom voice commands can be created. To accomplish this, it is essential to utilize the Cyberon Model Configuration webpage [41] to establish a new project with custom voice commands, following the provided procedure. After completing the required fields, a new project must be created, and the desired language for speech recognition selected. Next, the command list needs to be defined. Upon completion of the model configuration process, the model header file (model_ID.h) and the license file (CybLicense_ID.h) created must be incorporated into the Arduino sketch using the #include directive. So, the AI engine is embedded into the device.

3.4. Geolocation Methods

Several geolocation methods can be employed to track a device equipped with an Internet-connected μ C. Employing a dedicated GPS module managed by the μ C is the most conventional and accurate approach, enabling the reception of signals from GPS satellites to determine accurately latitude, longitude, and altitude. However, alternative

geolocation methods exist beyond the direct utilization of a GPS hardware module. In selecting the optimal method for implementing device tracking for the “no pAIn” project, various solutions have been implemented and evaluated.

The direct use of a hardware GPS module connected to the μC of the “no pAIn” device has been implemented and tested using the Adafruit Mini GPS PA1010D module [42], as depicted in Figure 3.



Figure 3. GPS module.

This module is particularly beneficial for the “no pAIn” device project due to its specific features. The Adafruit Mini GPS PA1010D is a compact module ($\sim 25\text{ mm} \times 25\text{ mm}$) equipped with both I2C and UART interfaces, providing flexibility for the designer to select the interface that best aligns with their requirements. The module supports GPS, GLONASS, GALILEO, and QZSS. It has a sensitivity of -165 dBm and can provide up to 10 location updates per second. It can handle up to 210 PRN channels with 99 search channels and 33 simultaneous tracking channels. The design is 5 V friendly and only draws 30 mA of current. It is breadboardable, with four mounting holes. The module has a battery-compatible RTC, a PPS output on a fixed $\pm 20\text{ ns}$ jitter, an internal patch antenna, and a low-power and standby mode with a WAKE pin. In the “no pAIn” project, the I2C interface has been used. The library “TinyGPSPlus” makes very simple the Arduino code to obtain all satellite signals and information.

The test shows that the device swiftly establishes connections with satellites and commences receiving data within a matter of seconds or less. It is the best solution in terms of the accuracy of the geolocation for outdoor applications. However, there are some drawbacks.

The primary limitation persists due to the requirement for unobstructed visibility of satellites, which poses challenges in reliably acquiring data within indoor environments. Furthermore, although the miniaturization of the Adafruit Mini GPS PA1010D module eliminates the need for an external antenna, its inclusion still enlarges the device, counteracting the necessity for compactness to ensure discreet concealment. Finally, the addition of a hardware module increases the cost of the “no pAIn” device.

Hence, alternative approaches for geolocation have been evaluated, solely leveraging the Wi-Fi module to circumvent the need for supplementary hardware like a physical GPS module. This strategy aims particularly at achieving optimal performance in indoor environments while concurrently reducing both the cost and dimensions of the “no pAIn” device. These solutions are based on the usage of cellular networks, Wi-Fi networks, hotspots and access points (APs), and Bluetooth Low Energy (BLE) beacon information [43–45].

Cellular Network-Based Positioning (GSM, LTE, 5G) utilizes cellular networks for location estimation. It measures the signal strength from nearby cellular towers. This method is reliable for both indoor and outdoor scenarios, but the device to be tracked must support cellular connectivity.

The BLE and Wi-Fi positioning method is efficient for environments with multiple Wi-Fi APs and BLE beacons. It is suitable for indoor and outdoor applications. Location accuracy improves if the device to be tracked also supports cellular connectivity. The approach entails scanning nearby Wi-Fi networks and BLE devices to collect information such as network names, MAC addresses of routers and BLE devices, and signal strength (which

is inversely related to distance). If the device also has cellular connectivity capabilities, data regarding nearby cellular towers are included. Then, these data are transmitted in JSON format to a geolocation service, such as Google Geolocation, via an HTTPS call to the service's API. The geolocation service maintains a database containing MAC addresses, router names, and beacon names along with their corresponding locations. Consequently, it provides the position (geolocation) corresponding to the data collected by the device being tracked.

All these operations can be executed rapidly, nearly in real-time, by a μ C connected to the Internet and outfitted with a Wi-Fi module and BLE module, such as the Arduino Nano RP2040 Connect board utilized in this project.

The precision of geolocation using this method is highly variable, contingent upon numerous factors, primarily the quantity of collected data. It consistently provides an approximate estimation of the position, with accuracy ranging from a few meters to tens of kilometers. The accuracy of this method is generally deemed acceptable, particularly in indoor settings, where it performs well. In outdoor scenarios, it emerges as the preferred method only when a GPS hardware module is unavailable on the tracked device.

An alternative geolocation technique, which circumvents direct dependence on a GPS module, utilizes IP address data. Several services cater to this purpose [46–49]. It relies on HTTP or HTTPS calls to two distinct services: the initial service retrieves the public IP address of the target device, which must be connected to the Internet via a Wi-Fi hotspot [49,50]; the subsequent service is invoked by supplying the obtained public IP address and returns the corresponding geolocation [45–47]. However, this method has been evaluated in the “no pAIn” project and has shown limited accuracy, often resulting in geolocations within a radius of several hundred kilometers.

The final alternative approach to geolocation, explored within the scope of the “no pAIn” project, involves leveraging the geolocation capabilities of smartphones. Smartphones commonly integrate GPS modules along with highly precise geolocation algorithms designed for accurate tracking in both indoor and outdoor environments. Thus, the concept involves the “no pAIn” device utilizing geolocation data from a smartphone. For this to occur, it is essential for both the “no pAIn” device and the smartphone to be connected to the same cloud service. Periodically (the frequency is customizable by the designer), the smartphone uploads the acquired geolocation coordinates to the cloud, which can then be retrieved by the device as necessary. This solution is notably swift and accurate, capitalizing on the precise geolocation capabilities of modern smartphones indoors and outdoors. Moreover, it reduces hardware requirements since the “no pAIn” device does not require a physical GPS module.

Hence, for the purpose of prototyping the “no pAIn” device, a geolocation technique based on the collaborative use of smartphones and cloud technology has been chosen.

An effective tool for implementing this design solution may be the OwnTracks service [51], which offers a smartphone application and a cloud server. The smartphone application automatically launches upon smartphone startup, operates in the background, and records GPS coordinates on the OwnTracks server. These coordinates are then accessible to the device, from the cloud, when needed. No user intervention is required for either recording or retrieving the geolocation coordinates.

The same concept can be easily implemented in the “no pAIn” device using OwnTracks or any other smartphone application that is automatically launched upon smartphone startup. Operating in the background, this app periodically transmits GPS coordinates to a cloud service from the smartphone. The μ C embedded within the “no pAIn” device can retrieve the location data by connecting to the designated cloud service and reading them. This process is fully automated, highly accurate, and fast, requiring no user intervention. It involves minimal instructions in the Arduino sketch to retrieve geolocation coordinates from the cloud. This results in optimization and reduction of the memory and time resources utilized by the “no pAIn” device to achieve precise geolocation in any situation.

For the smartphone application, the author has chosen a proprietary solution by developing a minimalistic app using the Simulink Android support package. Consequently, the corresponding choice for the cloud service is ThingSpeak [52], powered by MathWorks Inc., which aligns with Simulink. The developed application, named “GPSsender”, is designed to be minimalistic, ensuring its invisibility during operation on the smartphone while also minimizing the consumption of smartphone resources, particularly the battery. Its sole function is to periodically record GPS coordinates from the smartphone and transmit them to the ThingSpeak cloud. To accomplish this, the initial step entails creating a channel within the ThingSpeak cloud where GPS coordinates can be stored and retrieved. Within the channel, three fields are designated: one for latitude, another for longitude, and a third for altitude, respectively.

The architecture of the Simulink model, which is then automatically translated into an app installable on smartphones via MATLAB environment, is very simple, as shown in Figure 4.

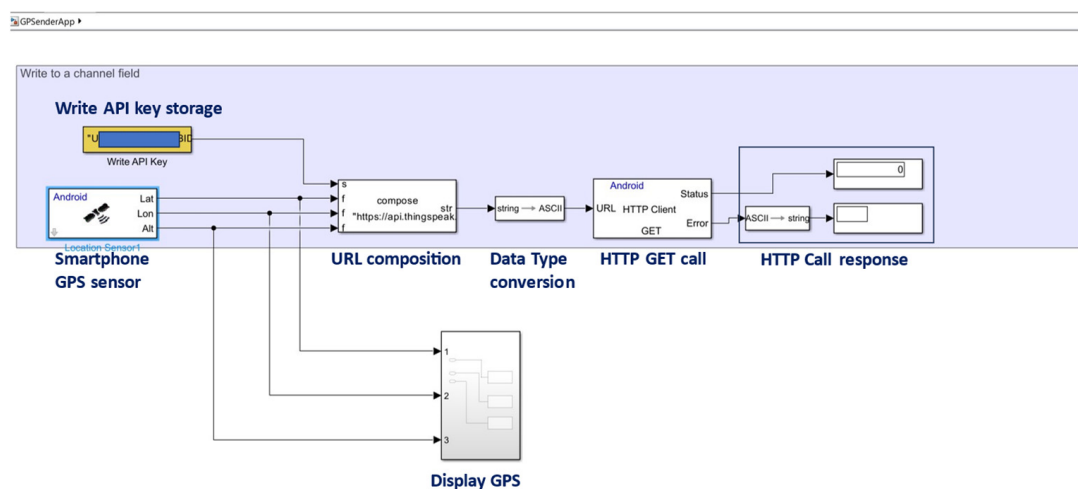


Figure 4. Simulink model of the GPSsender app 1.0 for android devices.

The GPS signal is acquired via the “Smartphone GPS sensor” block, integrated within smartphones. The API key necessary to write to the ThingSpeak channel via an HTTP call is stored in the “Write API key storage” block. Subsequently, the “URL composition” block effectively creates a URL string that includes the acquired GPS coordinates and the “write API key”, enabling writing operations in the specifically created ThingSpeak channel. In fact, the format of the URL string composed by the “URL composition” block is `https://api.thingspeak.com/update?api_key=%s&field1=%f&field2=%f&field3=%f` (accessed on 26 March 2024).

The “Data Type conversion” block transforms the generated URL string into ASCII code. Subsequently, the ASCII-encoded URL is handled by the “HTTP GET call” block, which triggers an HTTPS call using the GET method. This call records the GPS coordinates obtained from the smartphone into the ThingSpeak channel. The values of the three GPS coordinates are stored in their respective fields in the ThingSpeak channel.

The “HTTP call response” block is intended solely for debugging purposes and displays the outcome of the HTTP call, indicating whether it was successful or not.

The “Display GPS” block, as depicted in Figure 4, is not essential for the proper operation of the app but serves solely for debugging purposes. Its function is to validate the accurate acquisition of GPS coordinates. On the smartphone where the app runs, no visible indication is present. The user of the “no pAIIn” device (which is also the owner of the smartphone) is the only person to be aware of its operation having expressly agreed to its execution.

When needed, the μC within the “no pAI_n” device, connected to the Internet, retrieves the GPS coordinates from the corresponding channel fields by issuing an HTTPS GET request to the ThingSpeak channel, utilizing the appropriate “read API keys”.

The format of the URL is `https://api.thingspeak.com/channels/<channelID>/feeds.json?api_key=<XXXXXXX>&results=2` (accessed on 26 March 2024).

Location data are retrieved by the “no pAI_n” device through an HTTPS GET call in JSON format.

```
void GPSread() { //function to retrieve location data
  if (!client.connect(host, httpsPort)) {
    Serial.println("connection failed");
    return;
  }
  String url = "/channels/YYYYYY/feeds.json?api_key=XXXXXXX&results=2";
  client.print(String("GET ") + url + " HTTP/1.1\r\n" +
    "Host: " + host + "\r\n" +
    "Connection: close\r\n\r\n");
  // Reading data from ThingSpeak
  String response = "";
  // Wait for response
  while (client.connected()) {
    if (client.available()) {
      String response = client.readString();
    }
  }
  client.stop();
}
```

Subsequently, these data are unpacked by the μC and then attached to the alert notifications. Indeed, when the AI recognizes the wake-up keyword (“help” in our project) that transitions the “no pAI_n” device from the “Trigger” state to the “Command” state, the Wi-Fi Internet connection is suddenly established and the GPS coordinates are promptly retrieved from the cloud (or from the physical module, if available). This ensures that the device is prepared to transmit real-time location data along with help notifications upon detecting a danger. By default, the coordinates are acquired every 5 s, although the time intervals can be customized as desired.

It is noteworthy that although there exists a ThingSpeak library for Arduino, it currently does not function on the ARM M0+ microcontroller, which is the microcontroller utilized in the Arduino Nano RP2040 Connect board employed for creating the “no pAI_n” prototype. Consequently, the Arduino code for reading GPS coordinates from the ThingSpeak channel was specifically developed without reliance on that library.

The “no pAI_n” device can benefit from employing both the direct acquisition of GPS coordinates from a physical module connected to the device and retrieving them from a cloud updated by a smartphone app. Simultaneous utilization of these two methods provides redundancy, thereby enhancing the device’s reliability. However, it is important to remark that while the direct use of a physical GPS module increases the device’s size, power consumption, and cost, leveraging cloud technologies in conjunction with a smartphone app in the “no pAI_n” prototype mitigates these limitations.

3.5. Alert Delivery Methods

While the “no pAI_n” device remains in its “Trigger” state, it operates by actively listening and utilizing its built-in AI engine to classify spoken words. When the “no pAI_n” device detects the keyword “help” and transitions from the “Trigger” state to the “Command” state, that is, the “Sentinel” operating mode, as previously explained and depicted in Figure 2, it automatically establishes an Internet connection and acquires geolocation coordinates as a precautionary measure. Subsequently, while in the “Sentinel” mode, if the device identifies speech indicating a state of danger based on recognized words,

it transitions to the “Alert” state (or “Notification transmission” mode) and initiates requests for assistance to predefined recipients. To streamline this feature, several approaches for sending alert notifications were evaluated to identify the most suitable options for integration into the “no pAI” prototype.

These methods are categorized into two groups, as illustrated in Figure 5: direct calls to alert services from the device (via multiple calls from the μ C) and alert service calls routed through cloud services triggered by a single μ C call.

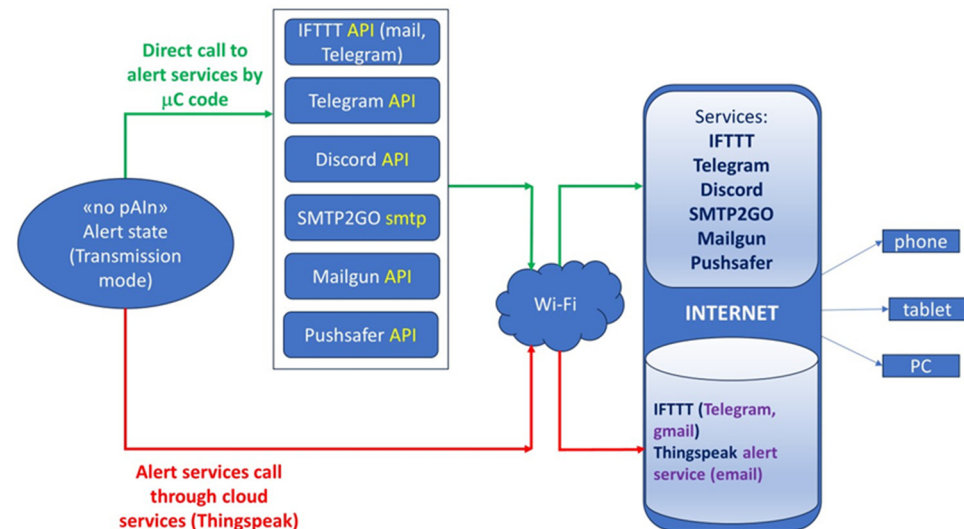


Figure 5. Alert methods have been implemented and tested to determine the optimal choice for prototyping purposes.

In the former scenario, direct calls were executed by the “no pAI” device μ C as follows: for email dispatch, an API call was made to “Mailgun” [53], and SMTP protocol was utilized with the “SMTP2GO” [54] service. Moreover, for message dissemination, HTTPS calls were placed to the APIs of “Pushsafer” [55], “Telegram” [56], and “Discord” [57], respectively. Furthermore, a single HTTPS call initiated by the μ C to the API of IFTTT [58] enabled the transmission of email and Telegram messages. Specifically, the configured IFTTT service sends an email and Telegram message using webhooks and associated applets, as will be elaborated upon later.

Conversely, in the latter scenario of alert service calls routed through cloud services triggered by a single μ C call, the “no pAI” device simply transmits an alert code to a cloud service, ThingSpeak in the current project, where have been configured an alert channel (to store the alert code) and two associated ThingSpeak apps: “reaction” and “MATLAB Analysis”.

As will be detailed later, upon receiving the alert code sent from the “no pAI” device, ThingSpeak initiates a “reaction” process, which involves the automatic execution of a MATLAB code written in the “MATLAB Analysis” application, disseminating notifications through various services, such as IFTTT and ThingSpeak alert service. Hence, the utilization of the IFTTT service has been evaluated from the “no pAI” device, both via direct API calls from the μ C and through MATLAB code integrated within the “MATLAB Analysis” application. The triggering mechanism involves a ThingSpeak “reaction” in response to the alert code transmitted by the μ C.

In every alert notification, both messages and emails include attached location coordinates along with a text indicating a request for assistance. Further specifics regarding each alert delivery solution are outlined in the subsequent subsections.

3.5.1. IFTTT, Webhooks and Applets

IFTTT is a platform that enables the creation of conditional command sequences, referred to as “applets”, connecting various services and devices. Through the utilization of webhooks, users can conveniently configure IFTTT to issue notifications, emails, and Telegram messages in response to specific events. The operational mechanism is illustrated in Figure 6.

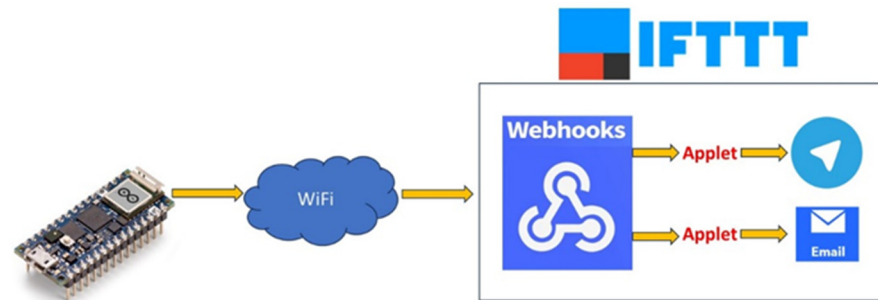


Figure 6. Flow chart illustrating the functioning of IFTTT (If This Then That).

A webhook, commonly utilized to trigger various cloud services, is literally termed a “webhook”. It enables the real-time transmission of information from one application to another through an HTTP request triggered by a specific event. In essence, it serves as a means for web applications to communicate autonomously, exchanging data automatically in response to predefined events without requiring human intervention. Therefore, webhooks are customizable mechanisms activated by an event to transmit data to a preconfigured URL [59,60]. They enable the automation of tasks across different web applications. For instance, upon updating a database, a webhook can automatically trigger a notification or update another application. Webhooks enhance software efficiency by facilitating immediate responses to specific events, such as order updates or message receipts. Given their simple structure, they are easy to access even for less experienced programmers. Due to their features, webhooks find widespread utility in integrating and automating interactions between various online services, including IFTTT, content management systems, e-commerce platforms, and more.

To integrate an IFTTT service into an ES-based project, a few configurations need to be performed. Within the personal IFTTT account, users are instructed to search for and activate the webhooks service. Upon activation, a unique URL is provided for triggering events. Subsequently, users must create one or more applets by selecting “Create” and then “This” to specify the trigger. “Webhooks” is chosen as the service, with “Receive a web request” designated as the trigger type. Users then input the event name that will activate the applet. Once the trigger is configured, the user proceeds to select the action by clicking on “That”. To send an email, the “Email” service must be selected and the requisite details input. For sending a Telegram message, the “Telegram” service is chosen, and the recipient’s Telegram account is connected. The action is then configured with the message details.

To execute the applet, users must send an HTTP (or HTTPS) POST request to the IFTTT webhook URL with the configured event name. This can be accomplished via a browser, script, or any application supporting HTTP(S) requests.

The format of the URL is `https://maker.ifttt.com/trigger/NAME/with/key/API-KEY`, accessed on 26 March 2024.

For the “no pAIn” device, the HTTPS POST request can be directly sent through the proper Arduino code or delegated to a MATLAB code executed as part of a “reaction” when an alert code is transmitted by “no pAIn” to the ThingSpeak alert channel in the cloud.

Once the event is triggered, IFTTT executes the configured action, such as sending an email, Telegram message, and so on. In the “no pAIn” project, one webhook service and two applets are configured. Upon receipt of the webhook, one applet dispatches an

email via Gmail provider, while the other sends a Telegram message. In both instances, the device's previously acquired geolocation coordinates are included in the notifications.

There are also a couple of Arduino libraries available to facilitate the writing of code for making an IFTTT POST call (IFTTTMaker library and IFTTTWebhook library), but neither library currently works well for the ARM M0+ microcontroller of the RP2040 Connect board. Therefore, the code for the HTTPS call has been written from scratch and functions perfectly.

3.5.2. E-Mail Direct Sending

The transmission of email messages has been evaluated using both cloud-based methods and direct transmission by the “no pAI” device's μ C. Email sending via the IFTTT applet has been previously explained. The email sending using the alert services of ThingSpeak will be further detailed in the next subsection.

In this subsection, the methods for directly sending emails by the μ C of the “no pAI” device are detailed.

The first method utilizes the Simple Mail Transfer Protocol (SMTP) and relies on the SMTP2GO service [54]. This service facilitates email sending, including through Arduino projects. The process entails configuring the Arduino to connect to the SMTP2GO server using the SMTP protocol. Once connected, the μ C of the Arduino board can transmit emails by supplying crucial details including sender address, recipient address, subject, and message content. SMTP2GO serves as an intermediary between the Arduino and the recipient's email server, ensuring reliable delivery. This simplifies the integration of communication and notifications into various applications.

The second method assessed is based on the “Mailgun” service [55]. This service is an efficient email management tool, particularly suitable for Arduino use as it allows sending email messages to multiple recipients simultaneously via a straightforward HTTPS call using the API. The service call is executed with a simple Arduino code, primarily comprising instructions for performing an HTTPS call.

The procedure for utilizing this service is remarkably straightforward. Upon creating an account on the service's website, a domain is assigned for use as the sender of the emails. Following this, users select the preferred technology, whether the SMTP protocol or the HTTPS call the API (chosen in this project), and generate the “Sending API key”. This key serves as the “token” to be incorporated into the Arduino code.

```
String request = "/v3/" + String(mailgun_domain) + "/messages";
String authorization = "Basic " + base64Encode("api:" + String(mailgun_token));
String text = "Probabile bisogno di soccorso in http://maps.google.com/maps/place/" +
String(latitude, 6) + "," + String(longitude, 6);
String body = "from=" + urlEncode(from) + "&to=" + urlEncode(to) + "&subject=" +
urlEncode(subject) + "&text=" + urlEncode(text);
httpClient.beginRequest();
httpClient.post(request);
httpClient.sendHeader("Authorization", authorization);
httpClient.sendHeader("Content-Type", "application/x-www-form-urlencoded");
httpClient.sendHeader("Content-Length", body.length());
httpClient.beginBody();
httpClient.print(body);
httpClient.endRequest();
```

3.5.3. ThingSpeak Cloud Service

Sending notifications via ThingSpeak operates according to the flowchart depicted in Figure 7.

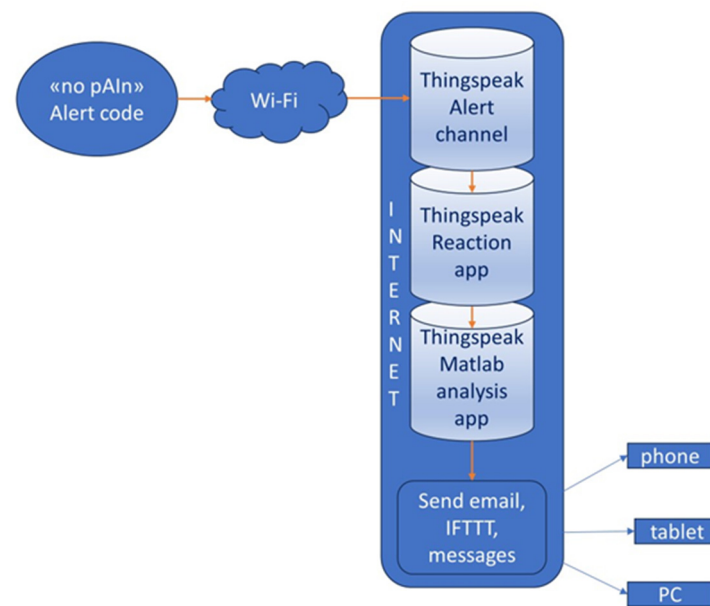


Figure 7. Flowchart illustrating the process of sending notifications via cloud service using ThingSpeak.

Initially, an alert channel is created in the user's own ThingSpeak account, where the "no pAI n" device inputs the alert code. The device transmits the alert code via an HTTP GET call to ThingSpeak, employing the appropriate "write API key".

Subsequently, the creation of a "React" type app, or a "reaction", is necessary. This reaction is triggered when the device transmits the alert code to the alert channel by a simple function.

```

void thingspeakReac() {
if (client.connect(host, 80)) {
    String url = "/update?api_key=";
    url += writeApiKey;
    url += "&field1=";
    url += alertCode;
    client.print(String("GET ") + url + " HTTP/1.1\r\n" + "Host: " + host + "\r\n" + "Connection:
close\r\n\r\n");
    delay(100);
    client.stop();
}
}

```

The reaction involves executing a "MATLAB analysis", constituting the third element to be established in the ThingSpeak account. Within the "MATLAB analysis", the MATLAB code is authored to execute upon detection of the alert code in the designated channel.

It is important to note that in this scenario, the μC of the "no pAI n" device operates swiftly, solely focusing on writing the alert code to the dedicated ThingSpeak channel. Consequently, all tasks related to sending notifications are handled by the reaction within the ThingSpeak cloud. As a result, the "no pAI n" device can promptly resume its "Sentinel" function, as it is not occupied with sending notifications.

Upon execution, the code of the "MATLAB analysis" app entails the following:

- Sending an email via the ThingSpeak alerts service, through an HTTPS call. The URL utilized is <https://api.thingspeak.com/alerts/send> (accessed on 26 March 2024). and the corresponding MATLAB command is `webwrite(alertUrl, "body", alertBody, "subject", alertSubject, options);`
- Making the HTTPS call the IFTTT service, which subsequently dispatches notifications via Gmail and Telegram (configured as actions within the IFTTT applets). The URL for this operation is <https://maker.ifttt.com/trigger/PainAI/with/key/<yourkey>>

(accessed on 26 March 2024) and the corresponding MATLAB command is `webwrite(alertUrl, v'alue1', queryString);`

The GPS coordinates, retrieved by the “no pAIIn” μ C as previously explained, are always included in the “queryString” or “alertBody” of the alert notifications. If the physical GPS module is present as a part of the “no pAIIn” device, the μ C transmits the geolocation coordinates to the appropriate ThingSpeak channel, along with the alert code. However, if the GPS coordinates are written into ThingSpeak location channel by the smartphone, their retrieval is performed using the appropriate MATLAB code included in the “MATLAB Analysis” app and included in the body of the notifications to be sent.

3.5.4. Telegram Messages

Telegram [56] is a free-of-charge instant messaging and voice-over-IP service accessible via web clients and native applications for various operating systems. It allows users to exchange messages, photos, videos, stickers, and files, as well as create groups and channels for broadcasting to unlimited audiences.

Telegram has significant advantages over similar platforms. Indeed, Telegram places a strong emphasis on privacy and security by providing end-to-end encryption for secret chats, optional two-factor authentication, and self-destructing messages. Additionally, Telegram offers unlimited cloud storage for messages and media, enabling users to seamlessly access their data from multiple devices. It supports the transmission of large files of up to 2 GB, making it well suited for sharing high-quality media files without compression.

Moreover, Telegram’s Bot API empowers developers to create robust and interactive Bots for a variety of purposes, ranging from customer service to automation and entertainment. Bots are complete programs that mainly deal with user interaction, receiving commands and consequently carrying out operations, according to the instructions given to them in the development phase. Bots can also integrate the use of webhooks to access additional features.

Given Telegram’s focus on privacy and encryption, as well as the availability of the Bot API, it emerges as a compelling solution for the “no pAIIn” project.

Sending messages via Telegram using Arduino RP2040 Connect involves using the Telegram Bot API. Developers can create a Telegram Bot and obtain an API token, which they can then use to send messages programmatically. The recipients of the messages are identified by means of their own “chatID”.

Creating a Telegram Bot entails some steps, as follows.

Initiate a conversation with the BotFather (@BotFather) in Telegram. Use the “/newbot” command to create a new Bot and follow the prompts to set a name and username. After Bot creation, BotFather provides an API token essential for interaction with the Telegram Bot API. It is also possible to set up a webhook for the Bot to receive updates from Telegram whenever there is new activity or a new interaction.

To execute HTTPS calls and automatically dispatch messages to predefined recipients via the Telegram Bot API, it is necessary to obtain the chat IDs of the recipients intended to receive messages by capturing them in the Bot logic through user interactions.

Therefore, it is possible to implement an HTTPS call to make a POST request to the Telegram Bot API, including essential parameters such as the API token, chat ID, and message text in the request body. It is also possible to trigger message sending activating the HTTPS call from the Bot logic whenever necessary to send messages to the predefined recipients, based on specific conditions or events.

The Arduino RP2040 Connect communicates with Telegram servers and dispatches messages using HTTPS requests or dedicated libraries. One prominent library for this purpose is the “Universal Telegram Bot” library.

In the present project, the alert Telegram message has been tested both directly (via HTTPS call to the Telegram API) and utilizes the “Universal Telegram Bot” library, as well as employs the IFTTT webhook and relevant applet. Between using the library and directly implementing the HTTPS call to Telegram’s API, the author has opted for the

latter approach. Although libraries offer convenience, they are susceptible to updates, necessitating constant maintenance by their own author to prevent significant malfunctions. Conversely, by developing proprietary code, these issues are circumvented, affording the developer complete control over their project. Anyway, the solution adopted in the prototype of the “no pAIn” device, owing to its speed, involves sending Telegram messages utilizing an IFTTT webhook activated by the programmed reaction in ThingSpeak upon receiving the alert code.

3.5.5. Discord Messages

The platform Discord allows users to create, manage, and participate in communication channels organized in well-defined structures [57]. In fact, Discord has a very simple structure that encloses the channels within the program’s secondary servers. Users can independently manage one or more servers and, for each server, one or more channels, allowing or not allowing other users to take part.

The primary tools provided to programmers include Bots and the webhook service, to execute an action in response to a trigger event. To seamlessly incorporate Discord notifications into the “no pAIn” project, a webhook service activated by the μ C of the “no pAIn” device is utilized through an HTTPS POST call, initiating the notification dispatch process.

To achieve this, the initial step involves creating a server within a Discord account. Subsequently, within the server, a text-type channel is established, inviting the intended recipients of alert notifications to subscribe. Finally, within the created channel, the “Create Webhook” item is generated via the “Integrations” option. Upon creation of the webhook, Discord provides a webhook URL. This URL serves as the address through which users can interact with the service. At this juncture, the remaining task involves configuring the code responsible for making the HTTPS POST call to the created webhook service.

```
#include <ArduinoHttpClient.h>
const String discord_tts = "true";
const char server[] = "discordapp.com";
const int port = 443;
const String discord_webhook = "WEBHOOK_URL";
int status = WL_IDLE_STATUS;
WiFiSSLClient client;
HttpClient http_client = HttpClient(client, server, port);
```

The content to be transmitted is delineated within the parameters of the POST call. The primary code snippet for dispatching messages is as follows:

```
void discord_send(String content) {
  http_client.post(discord_webhook, "application/json", "{ \"content\": \"\" + content + \"\",
  \"tts\": \"\" + discord_tts + \"\" }");
}
```

3.5.6. Pushsafer Notifications

Pushsafer [55] is a service that allows a μ C to send alerts and notifications to devices where the Pushsafer app is installed, through an HTTPS API call. It enables users to customize notifications with various parameters such as message content, title, icon, sound, and vibration. Additionally, Pushsafer supports various platforms including Android, iOS, and desktop browsers, making it versatile for different device types. Users can send notifications either through direct HTTPS calls or by utilizing their provided libraries and plugins for popular programming languages and platforms. Overall, Pushsafer offers a flexible and customizable solution for sending notifications across different devices and platforms. A notable feature of Pushsafer is its inherent geolocation service.

The Pushsafer service is accessed via its API using an HTTP call to the following URL: <https://www.pushsafer.com/api?k=XXXXXXXX&d=a&t=Alert! Serious danger!&m=Message>

from nopAIn&s=8&v=1&i=1&c=#FFCCCC&u=https://www.pushsafer.com&ut=Open Pushsafer.com (accessed on 26 March 2024)

The method and the corresponding Arduino code remain consistent with any other HTTPS call.

The summary of this section (refer to Figure 5) outlines the implementation of Telegram alert message transmission through both the μ C and the IFTTT applet. Email services have been utilized via the μ C (employing “Mailgun” and SMTP2GO), the IFTTT applet, and ThingSpeak (in two ways: utilizing ThingSpeak’s alert services and through a call from ThingSpeak to IFTTT applets). Discord alert messages have been transmitted via the μ C. Additionally, Pushsafer notifications have been sent through the μ C, although implementing the HTTPS call via ThingSpeak with a few lines of MATLAB code in the “MATLAB Analysis” app is straightforward.

The decision for the prototype of the “no pAIn” device is to adopt a cloud-based approach for transmitting alert notifications, as depicted in Figure 7.

It is important to note that in the prototype implementation of the “no pAIn” device, ThingSpeak serves as a cloud resource not only for transmitting alert notifications but also for storing and retrieving geolocation data. Therefore, when the “no pAIn” device switches into the “Alert” state, the μ C transmits the alert code to the ThingSpeak alert channel. Upon receiving the alert code, the chain of events, namely “reaction—MATLAB Analysis”, is initiated in the cloud. Consequently, two tasks are executed in the cloud: sending an email through ThingSpeak alert services and triggering a call to the IFTTT service. Subsequently, the IFTTT applets dispatch an email (via the Gmail provider) and a Telegram message.

The advantage of this scenario is evident: the μ C only needs to transmit the alert code to a ThingSpeak alert channel. This enhances the device’s reliability, reduces power consumption, minimizes device resource requirements, and improves operational speed. Moreover, thanks to the cloud solution, the “no pAIn” device does not necessitate a real-time operating system. Instead, it delegates all notification-sending operations to the cloud, merely transmitting an alert code and promptly reverting to a “Sentinel” mode, to detect any further critical or dangerous situations. Utilizing real-time operating systems would exacerbate the device’s resource demands in terms of memory and complicate its management. By simplifying this aspect, the device has significantly reduced requirements and operates reliably.

Certainly, if desired, alongside the cloud approach, one or more of the other methods of directly transmitting alert notifications by the μ C, which have been previously described and successfully tested, can be implemented. This redundancy would undoubtedly enhance the device’s reliability, although this advantage must be carefully weighed against the drawback of increased power consumption and greater hardware resource requirements.

4. Working of the System and Results

The prototype of the “no pAIn” device underwent testing by connecting it to the Arduino IDE serial monitor for debugging purposes. The device testing simply aims at verifying its functionality because it is a prototype and not an engineered device for conducting certification and commercialization tests. This is a phase that will come later and is not the subject of the paper. Since the device incorporates very advanced and cutting-edge technologies, the testing solely aims at ensuring that its operation is smooth, without appreciable delays, and is compliant with the specifications.

During the testing phase, screens of both the PC where the device was connected (with the Arduino IDE serial monitor activated) and a smartphone receiving alert notifications were simultaneously recorded. A test scenario was initiated (refer to Figure 8) wherein a woman initially engaged in a calm conversation with their interlocutor, during which the “no pAIn” device operated in the “Listen&Recognize” mode. The green LED onboard illuminates during this interaction, indicating the activation of the “Trigger” state of the device. As the conversation progressed, the speech became more agitated and becomes suspicious, prompting the woman to request assistance (the keyword “help” has been detected) and

causing the “no pAIIn” device to transition to the “Sentinel” mode in which it immediately establishes an Internet connection and acquires GPS coordinates for alert transmission preparation. The red onboard LED always illuminates for debugging purposes, indicating the device’s transition to the “Sentinel” mode (protection activated). Subsequently, the speech escalates to a level indicating serious danger, and the device switches from the “Sentinel” mode to the “Transmission” mode, initiating the transmission of relevant notifications, containing geolocation data and seeking assistance.



Figure 8. Real functioning of the “no pAIIn” device. The translation in English is in Appendix A.

The prototype was developed using the Italian language; therefore, all messages in Figure 8 are in Italian. However, Appendix A provides English translations of the text displayed in the images captured from the recorded screen video.

Figure 9 displays the sequence of alerts received on a smartphone: a Telegram message via IFTTT, an email by Gmail via IFTTT, and an email via ThingSpeak alert service, all containing requests for assistance along with location coordinates.

Upon observing the smartphone screens depicted in both Figures 8 and 9, it becomes apparent that within a minute (or seconds in reality, as evidenced by the consistent time reading of 10:16 from the onset of speech to the receipt of notifications), all expected notifications arrive, accompanied by the victim’s location.

Speech recognition operates seamlessly in real-time, without any noticeable delays. Notifications are promptly delivered to the smartphone in real-time as soon as the “no pAIIn” device transitions from the “Sentinel” to “Transmission” mode.

Within mere fractions of seconds from the request for help, the victim’s location is pinpointed, and potential helpers are immediately alerted. Consequently, the device demonstrates exceptional efficiency in preventing gender-based crimes.

It results in the present prototype, utilizing the Arduino Nano RP2040 Connect board equipped with a built-in omnidirectional microphone and Wi-Fi connectivity, demonstrating highly promising results regarding the reliability of speech classification and the prompt transmission of alert notifications.

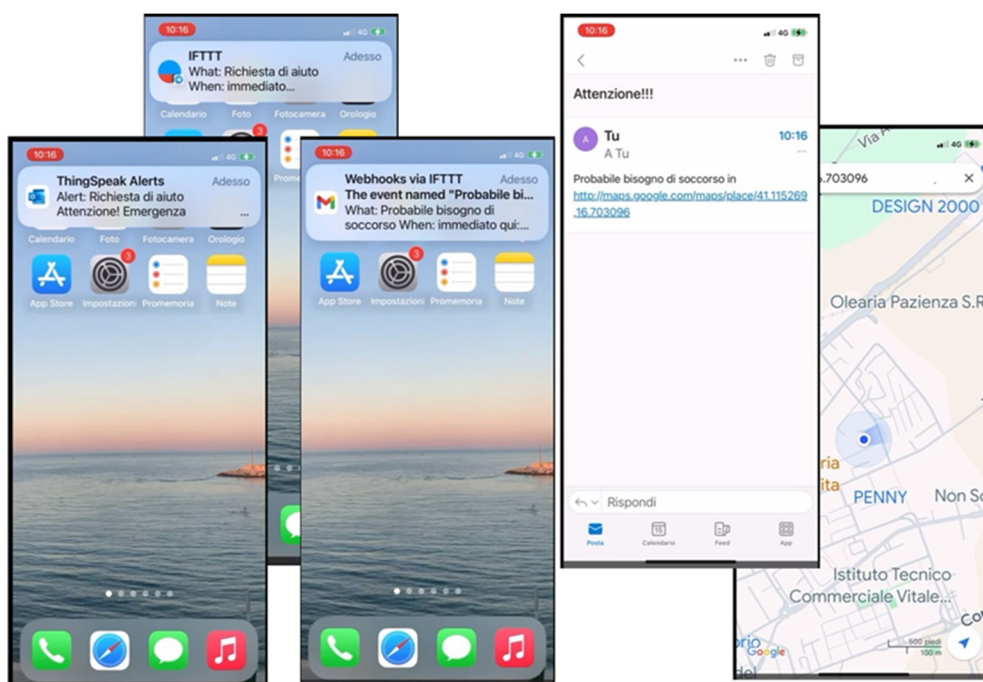


Figure 9. Screens of a smartphone receiving alert notifications along with geolocation data during the device testing phase.

The outcomes derived from the prototype implementation and testing reveal that despite the device boasting intricate and technologically advanced functionalities, its cost appears to be remarkably low (a few tens of dollars). Moreover, owing to the utilization of highly advanced technologies in its construction, the degree of automation is exceptionally high, eliminating the necessity for users to possess any specialized skills; they simply need to power on the device, and all operations proceed seamlessly on their own. Therefore, the most significant attribute of the “no pAI” device lies in its ability to be marketed at a reasonably low cost, rendering it accessible to a wide demographic. Additionally, it is suitable for both indoor and outdoor applications. Its discreet form factor enables it to be easily concealed, ensuring that potential attackers remain unaware of their victim’s protection. This feature facilitates the early identification of domestic and gender violence risks, thereby enabling the prevention of such tragic events with a high degree of probability. Furthermore, the device operates in fully automatic mode, requiring no user intervention beyond the initial switch-on.

The limitations of the device stem from potential connectivity issues in the area and at the time of intervention, as well as from potential misclassification of speech by artificial intelligence. Regarding the former, there are no avenues for improvement except utilizing the device in its “full optional” version, which includes its own SIM card. As for the latter, the device relies on the reliability of the artificial intelligence engine, which has been designed by a professional software house for professional use. It has not been developed by the author, so it is not their responsibility to validate it; instead, they rely on the validation data provided by a reputable software house like Cyberon.

5. Conclusions

This paper outlines a new, low-cost device, powered by AI, designed to prevent gender-based violence. The device represents an electronic plea for help to protect victims who are unable to make hand gestures or any other form of request for assistance. Operating entirely autonomously, it requires no user interaction beyond the initial power-up, highlighting distinct operational features tailored for violence prevention. It serves as a personal device, managed discreetly, as the victim directly utilizes it, akin to an invisible bodyguard—

constantly vigilant yet unseen, safeguarding their health and life. Fully automated, the AI detects hazardous situations and sends requests for aid remotely with geolocation coordinates, requiring no user intervention. Importantly, a key advantage of the “no pAIIn” device is its ability to detect signs of gender violence at their earliest stages, effectively preventing harmful consequences. The device currently stands out as unique and original due to its operational characteristics, leveraging cutting-edge AI, Internet, geolocation, and ES project technologies. The design solutions and strategies aimed at enhancing the device and optimizing its performance have been extensively discussed.

The prototype is a minimal version that requires connection to a hotspot and interaction with a smartphone to function, as explained in the article. However, all the required implementation solutions have also been successfully tested so that the device can be produced in a fully optional version, equipped with a physical GPS module and its own SIM card, thereby becoming completely autonomous in performing all its functions. In this case, there is an increase in cost and size, although it remains a miniaturized device.

A further design development pertains to some third-party services used by the hardware device, which could be specifically developed.

There is also the possibility of transforming the entire project into a smartphone app, although the design and functional aspects of such an app are still under evaluation. Indeed, in principle, the functionality of the device could also be replicated through a smartphone application. However, due to the prevalent nature of gender-based violence where attackers often deactivate or discard the victim’s smartphone, such an approach would pose safety and reliability concerns. Conversely, the standalone version of “no pAIIn”, particularly when equipped with its own SIM card and discreetly concealed, offers enhanced reliability as the attacker is less likely to detect its presence and operation.

Another potential advancement, perhaps more pertinent than a smartphone app, could be a smartwatch app. Nevertheless, like smartphone apps, this option presents comparable vulnerabilities; the attacker might seize the victim’s smartwatch. Even if such an eventuality is avoided, the associated costs would be considerably higher, given that smartwatches are substantially more expensive than the standalone “no pAIIn” device. This elevated cost could impede widespread adoption, which is a desirable outcome.

The commercial prospects are also noteworthy and may involve not only the marketing of the device but also certain services. These include software technologies underlying its operation (which could be specifically developed and provided by a service provider) and the alert and rescue organization service. For instance, a dedicated company could handle the marketing or rental of the device, receive, and manage the requests for help it sends 24 h a day, and consequently coordinate requests for assistance (such as contacting the police). There is also consideration for a type of “insurance” against attacks based on the use of the device and related services.

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Appendix A

Translation of Figure 8 caption

Ciao, come stai?	Hi, how are you?
ma no, no, cosa fai?	but no, no, what are you doing?
Aiuto	Help
Lasciami stare, lasciami andare	Leave me alone, let me go
Vuoi farmi male?	Do you want to hurt me?
Aiutatemi	Help me
Chiedo aiuto	I ask for help
Chiamate la polizia	Call the police
Chiamate i carabinieri	Call the police

Traslate the “no pAIIn” actions as follows:

no pAIIn attivo	no pAIIn activated
Tutto ok	that's ok
Situazione sospetta	Suspicious situation
Coordinate GPS acquisite	location tracked
Situazione critica. Protezione attivata	Critical situation. Protection activated
Pericolo imminente. Alert trasmesso	Sudden danger. Alert sent
Richiesta di aiuto inviata!	Request for help sent.

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