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BACE and BMA Variable Selection and Forecasting for UK Money Demand and Inflation with Gretl

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Abstract: In this paper, we apply Bayesian averaging of classical estimates (BACE) and Bayesian model averaging (BMA) as an automatic modeling procedures for two well-known macroeconomic models: UK demand for narrow money and long-term inflation. Empirical results verify the correctness of BACE and BMA selection and exhibit similar or better forecasting performance compared with a non-pooling approach. As a benchmark, we use Autometrics—an algorithm for automatic model selection. Our study is implemented in the easy-to-use gretl packages, which support parallel processing, automates numerical calculations, and allows for efficient computations.

Keywords: model uncertainty; Bayesian pooling; MPI; model averaging

JEL Classification: C22; C52; C53

1. Introduction

In this paper we consider two procedures of variable selection and forecasting for linear dynamic single-equation models: Bayesian averaging of classical estimates (BACE), introduced by [Sala-i-Martin et al. \(2004\)](#) and Bayesian model averaging (BMA) (see [Raftery et al. 1997](#)). The BACE and BMA methods are natural extension of the standard Bayesian inference methods in which one does not only make inference using single model, but also allowing pooling approach with combined estimation and prediction. As a benchmark we use Autometrics procedure which is non-pooling method based on general-to-specific approach with multiple path of searching algorithm implemented in OxMetrics software (see [Doornik 2009](#); [Doornik and Hendry 2013](#)). We present empirical results for two non-trivial UK macroeconomic models: demand for narrow money (see [Krolzig and Hendry 2001](#)), and long-term inflation (see [Hendry 2001](#)).

In the last two decades we can observe a growing number of publications related to Bayesian model averaging in many fields of science like engineering, medicine, biology, sociology and others (see [Fragoso et al. 2018](#)). Not surprisingly, this type of approach has also been long-used in economics and it is still important, especially for identification of the sources of economic growth ([Fernández et al. 2001a, 2001b](#); [Błażejowski et al. 2019](#)). The ideas stated in this paper were reviewed, among others, by [Hoeting et al. \(1999\)](#) and [Wasserman \(2000\)](#). A comprehensive study on the use of model averaging in economics, both from the frequentist and Bayesian approaches, was discussed in [Steel \(2019\)](#).

The BACE approach is an approximation of BMA and it is not purely Bayesian but relies on Schwarz approximation to compute the Bayes factor (see [Ley and Steel 2009](#)). Nevertheless, both the BACE and BMA approaches account for model uncertainty, which often requires the consideration

of many possible linear combinations of variables and lead to a large model space that needs to be explored and then demands intensive computational effort. As an approximation, BACE is usually faster than the standard BMA approach; nevertheless, obtaining the output in a reasonable amount of time still remains a significant challenge, especially in time-series modeling and forecasting. [Raftery et al. \(1997\)](#) showed that standard variable selection procedures lead to different estimates and conflicting conclusions about the main questions of interest. Moreover, econometric models that are firmly based on economic theory do not always work for forecasting. The BACE and BMA approaches combine the knowledge obtained from many possible models and accounts for uncertainty by averaging the parameter estimates from different specifications. Consequently, both methods can better identify significant determinants of a dependent variable and generate more accurate forecasts without any specific knowledge.

In BACE and BMA we can penalize large dynamic models using different model prior assumptions putting higher probabilities for more parsimonious models. This type of approach does not cover all possible solutions. One of the potential alternative is assigning lower prior probabilities over lags length, such as Minnesota Prior (see [Doan et al. 1984](#)). We also assume stability of the relation between dependent and independent variables over time and, as a consequence, all slope parameters and other posterior characteristics in our BACE and BMA packages are time invariant. In the case of time-varying parameters, it is possible to employ dynamic model averaging presented in [Drachal \(2018\)](#); [Raftery et al. \(2010\)](#).

The remainder of this paper is structured as follows. In Section 2, we discuss some aspects of BACE. Section 3 briefly outlines Bayesian model averaging for dynamic linear regression models along with short information about implementation of both packages in the *gretl*. In Section 4 we provide basic information about *Autometrics*—a PcGive module for automatic model selection. Section 5 presents empirical results for two selected UK macroeconomic models: demand for narrow money and long-term inflation. In this section, we also compare the variable selection strategies and forecasting performance of BACE and BMA with those of *Autometrics*. Additionally, in Section 6 we analyze the robustness and computational run-times of BACE and BMA. Finally, we conclude the paper in Section 7.

2. The BACE Method

In [Sala-i-Martin et al. \(2004\)](#), the authors proposed averaging parameter estimates using a technique—Bayesian averaging of classical estimates—that enabled the measurement of the importance of particular potential regressors. In this method, parameter estimates are obtained by applying ordinary least squares (OLS) and then averaged across all possible combinations of models. The BACE approach is not purely Bayesian but relies on Schwarz approximation to compute the Bayes factor. This approach is an alternative to the familiar and earlier-applied BMA technique, from which it differs i.e., by using non-informative prior assumptions of regression parameters¹. A full discussion that compares BACE and BMA is presented in [Ley and Steel \(2009\)](#).

Among the many articles that have applied the BACE technique are [van Dijk \(2004\)](#) for US inflation and [Białowolski et al. \(2014\)](#) for gross domestic product, inflation, and unemployment in Poland. [Jones and Schneider \(2006\)](#) used BACE analysis to verify the human capital effect on economic growth, while [Mapa and Briones \(2007\)](#) and [Simo-Kengne \(2016\)](#) used BACE analysis to obtain variables associated with economic growth. [Cuaresma and Doppelhofer \(2007\)](#) extended the BACE approach by allowing for the uncertainty of nonlinear threshold effects to identify determinants of long-term economic growth. [Bergh and Karlsson \(2010\)](#) applied BACE to investigate the relation between government size and the control of economic freedom and globalization for a panel of rich countries. In an empirical investigation of industrial production forecasting, [Feldkircher \(2012\)](#) focused

¹ BACE is implicitly based on fixed Zellner's *g*-prior, whereas, in the BMA framework, *g*-prior can be set explicitly.

on the forecasting performance resulting from model averaging by measuring the root-mean-square error (RMSE). [Albis and Mapa \(2014\)](#) used BACE to verify misspecification issues in vector autoregressive models for artificial data.

Let us consider the following dynamic linear regression model M_j ($j = 1, 2, \dots, K$):

$$y = X_j\beta_j + \epsilon \tag{1}$$

where y is a $(Tx1)$ vector of observations, X_j is a (Txk_j) matrix, where $X_j = [Y_{j-} Z_j]$ and Y_{j-} is a $(T \times k_j^y)$ matrix containing k_j^y lagged values of dependent variable, while Z_j is $(T \times k_j^z)$ matrix of exogenous variables, $\beta_j = [\beta_j^y \ \beta_j^z]'$ is a vector of unknown parameters, where $\beta_j^y \in R^{k_j^y}$, $\beta_j^z \in R^{k_j^z}$, ϵ is an $(Tx1)$ vector of errors that are assumed to be normally distributed (i.e., $\epsilon \sim N(0_T, \sigma^2 I_T)$) and $N(\mu, \Sigma)$ denotes a normal distribution with location μ and covariance Σ .

From OLS estimates (see [Sala-i-Martin et al. 2004](#)), we can calculate the approximation of the posterior probability of model M_j (i.e., $\Pr(M_j | y)$) using the following formula:

$$\Pr(M_j | y) \approx \frac{\Pr(M_j)T^{-k_j/2}SSE_j^{-T/2}}{\sum_{i=1}^{2^K} \Pr(M_i)T^{-k_i/2}SSE_i^{-T/2}}, \tag{2}$$

where SSE_j and SSE_i are the OLS sum of squared errors, 2^K denotes the total number of potential combinations of K independent variables, and k_j and k_i are the number of regression parameters β_j and β_i . In $T^{-k_j/2}SSE_j^{-T/2} \approx p(y | M_j)$, $p(y | M_j)$ denotes the density of the marginal distribution of y conditional on model M_j .

Prior probabilities $\Pr(M_j)$ and $\Pr(M_i)$ of models M_j and M_i are binomially distributed; that is,

$$\Pr(M_j) = \theta^{k_j}(1 - \theta)^{K-k_j}, \theta \in [0, 1]. \tag{3}$$

The binomial distribution implies that we only need to specify a prior expected model size $E(\Xi) = K\theta$, where $E(\Xi) \in (0, K]$. For example, if we define the value of $E(\Xi)$, then our BACE package will automatically produce a value of prior inclusion probability for all competitive models. If $\theta = 0.5$, then the prior expected model size is equal to the average of the number of potential regressors, and the model prior distribution is uniform ($\Pr(M_i) = 2^{-K}$) and reflects a lack of previous knowledge about the models.

Using BACE, we can also easily evaluate the mean and variance of the posterior distribution of regression parameters β for the whole model space (see [Leamer 1978](#); [Sala-i-Martin et al. 2004](#)):

$$E(\beta | y) \approx \sum_{i=1}^{2^K} \Pr(M_i | y)\hat{\beta}_i, \tag{4}$$

$$Var(\beta | y) \approx \sum_{i=1}^{2^K} \Pr(M_i | y)Var(\beta_i | y, M_i) + \sum_{i=1}^{2^K} \Pr(M_i | y) (\hat{\beta}_i - E(\beta | y))^2, \tag{5}$$

where $\hat{\beta}_i = E(\beta_i | y, M_i)$ and $Var(\beta_i | y, M_i)$ are the OLS estimates of β_i from model M_i .

Another useful and popular characteristic of the BACE approach is posterior inclusion probability (PIP), which is defined as the posterior probability that the variable x_i is relevant in the explanation of the dependent variable (see [Leamer 1978](#); [Mitchell and Beauchamp 1988](#)). In our case, the PIP is calculated as the sum of the posterior model probabilities for all of the models that include a specific variable:

$$\Pr(\beta_i \neq 0 | y) = \sum_{i=1}^{2^K} \Pr(M_i | \beta_i \neq 0, y). \tag{6}$$

For model averaging, a Bayesian pooling strategy can also provide useful information about future observations of the dependent variable on the basis of the whole model space:

$$E(y_f | y) \approx \sum_{i=1}^{2^K} \Pr(M_i | y) E(y_f | y, M_i), \tag{7}$$

$$\text{Var}(y_f | y) \approx \sum_{i=1}^{2^K} \Pr(M_i | y) \text{Var}(y_f | y, M_i) + \sum_{i=1}^{2^K} \Pr(M_i | y) \left(E(y_f | y, M_i) - E(y_f | y) \right)^2, \tag{8}$$

where $E(y_f | y)$ and $\text{Var}(y_f | y)$ denote the mean and variance of future observations y_f .

3. The BMA Method

Another model building strategy is Bayesian model averaging wherein we can make an inference based on full posterior distribution. From Bayesian perspective uncertainty is a natural way of decision making process and therefore it can be easily included in the model selection rules (Koop 2003; Zellner 1971). Among the many seminal papers about Bayesian model averaging are Hoeting et al. (1999) and Fernández et al. (2001a,2001b). The most recent detailed overview is presented in Steel (2019).

Once again, we are dealing with a problem which model and variables are the most appropriate in the analysis of the dependencies, but in this case we use a natural and explicit way of combining prior information with data, without any approximation of marginal data density and Bayes factors. We consider two variants of BMA framework. The first one where we impose stationary conditions for autoregressive parameters, and the second one without restrictions.

Now let us consider the first one:

$$y = X_j \beta_j + \varepsilon, \tag{9}$$

where y is a vector of T observations, X_j is $(T \times k_j)$ matrix, and β_j is a $(k_j \times 1)$ vector of parameters, ε is a vector of dimensions $(T \times 1)$ with a normal distribution $N(0, \sigma^2 I_T)$, where σ^2 is a variance of random error ε and I_T is an identity matrix of size T . Moreover $X_j = [Y_{j-} \ Z_j]$, where Y_{j-} is a $(T \times k_j^y)$ matrix containing k_j^y lagged values of dependent variable, while Z_j is $(T \times k_j^z)$ matrix of exogenous variables. Furthermore, $\beta_j = [\beta_j^y \ \beta_j^z]'$ is a vector of unknown parameters, where $\beta_j^y \in \Gamma \subseteq R^{k_j^y}$, $\beta_j^z \in R^{k_j^z}$, and Γ is stationary region for the parameters of autoregressive processes. We also assume that we observe initial values $y_{(0)}$.

Let us consider a prior density of the following form:

$$p(\beta_j, h | M_j) = p(\beta_j | h, M_j) p(h), \tag{10}$$

where:

$$p(\beta_j | h, M_j) \propto f_N(\beta_j | \underline{\beta}_j, h^{-1} \underline{V}_j) I(\beta_j^y \in \Gamma) \tag{11}$$

and $f_N(\beta_j | \mu, \Sigma)$ denotes the multivariate normal density with mean μ and covariance matrix Σ , $I(A)$ is the indicator function, $\underline{\beta}_j$ is k_j -vector of prior means for regression coefficients and \underline{V}_j is a $k_j \times k_j$ positive definite prior covariance matrix of the form:

$$\underline{V}_j = \left(g_j X_j' X_j \right)^{-1}. \tag{12}$$

For the error precision h which is defined as $h = 1/\sigma^2$ we use noninformative prior:

$$p(h) \propto h^{-1}, h > 0. \tag{13}$$

The factor of proportionality g_j ($j = 1, 2, \dots, K$) is part of the so-called g-prior, as introduced in Zellner (1986). In our research we use Benchmark prior, recommended by Fernández et al. (2001a):

$$g_j = \begin{cases} 1/K^2 & \text{for } T \leq K^2 \\ 1/T & \text{for } T > K^2 \end{cases} \tag{14}$$

Assuming the prior structure in Equation (10) we obtain the following joint posterior density:

$$p(\beta_j, h | y, M_j) = c_j \cdot f_{NG}(\beta_j, h | \bar{\beta}_j, \bar{V}_j, \bar{s}_j^{-2}, \bar{v}_j) I(\beta_j^y \in \Gamma), \tag{15}$$

where c_j is normalizing constant and f_{NG} is normal-gamma density (see Koop et al. 2007). In our case constant c_j plays important role to obtain the Bayes factor between competitive models and can be obtained by Monte Carlo simulations.

Using the properties of normal-gamma density, Equation (15) leads to:

$$p(\beta_j | h, y, M_j) \propto f_N(\bar{\beta}_j, h^{-1}\bar{V}_j) I(\beta_j^y \in \Gamma), \tag{16}$$

$$p(h | y) = f_G(\bar{s}_j^{-2}, \bar{v}_j), \tag{17}$$

where

$$\bar{V}_j = (V_j^{-1} + X_j'X_j)^{-1}, \tag{18}$$

$$\bar{\beta}_j = \bar{V}_j (V_j^{-1}\underline{\beta}_j + X_j'X_j\hat{\beta}_j), \tag{19}$$

and $\bar{v}_j = T$. We also have:

$$\hat{\beta}_j = (X_j'X_j)^{-1} X_j'y, \tag{20}$$

$$s_j^2 = \frac{(y - X_j\hat{\beta}_j)'(y - X_j\hat{\beta}_j)}{v_j}, \tag{21}$$

$$\bar{v}_j\bar{s}_j^2 = v_js_j^2 + (\hat{\beta}_j - \underline{\beta}_j)' [V_j + (X_j'X_j)^{-1}]^{-1} (\hat{\beta}_j - \underline{\beta}_j), \tag{22}$$

where $v_j = T - k_j$.

The marginal data density $p(y | M_j)$ as well as posterior means and standard deviations of regression coefficients can be calculated numerically using Monte Carlo integration by sampling from the posterior distribution in Equation (15). In our case, we first draw error precision h from Equation (17) and then we draw β_j from Equation (16). We only accept those candidate values which lie in stationary region for the parameters of autoregressive processes. The constant c_j can be calculated as an inverse of the acceptance ratio i.e., inverse of the fraction of random numbers accepted in Monte Carlo simulation.

The posterior probability of any variant of regression model M_j can be calculated by the following formula, which is crucial for Bayesian model averaging:

$$\Pr(M_j | y) = \frac{\Pr(M_j) p(y | M_j)}{\sum_{i=1}^{2^K} \Pr(M_i) p(y | M_i)}, \tag{23}$$

where $\Pr(M_1), \Pr(M_2), \dots, \Pr(M_K)$ denote the prior probabilities of competitive models (see Equation (3)). Other characteristics, like posterior model probabilities (PIP) as well as the mean and variance of the

posterior distribution of regression parameters β for the whole model space can be calculated in the same manner as described for BACE method.

In case of BMA variant without stationary restrictions for the parameters of autoregressive processes, we assume that $\beta_j^y \in R^{k_j^y}$ and Equations (11), (15) and (16) takes the following form, while the other equations remain unchanged:

$$p(\beta_j | h, M_j) = f_N(\beta_j | \underline{\beta}_j, h^{-1}V_j), \quad (24)$$

$$p(\beta_j, h | y, M_j) = f_{NG}(\beta_j, h | \bar{\beta}_j, \bar{V}_j, \bar{s}_j^{-2}, \bar{v}_j), \quad (25)$$

$$p(\beta_j | h, y, M_j) = f_N(\bar{\beta}_j, \bar{V}_j). \quad (26)$$

BACE and BMA in Gretl

In order to perform Bayesian averaging of classical estimates, we used the BACE 2.0 package². This code implements an automatic BACE procedure that is available in the gretl³ program as an open-source software. In the procedure's main window, we can specify e.g., the following parameters: the list of independent variables, the prior distribution over the model space, the number of out-of-sample forecasts, and general parameters for the Monte Carlo simulation. As a result, the BACE package prints basic posterior characteristics, such as PIP, and the posterior means of coefficients, together with their standard errors. In addition, the package presents rankings of the most probable specifications according to their explanatory power and generates forecasts of the dependent variable.

In this paper we also use a software package that implements Bayesian model averaging for Autoregressive Distributed Lag models BMA_ADL ver. 0.9 in gretl⁴. The BMA_ADL package as well as the output is similar to BACE package. Although these two packages are similar there is a principle difference between them. In BMA_ADL we draw samples from posterior distribution of slope parameters β and we check roots of characteristic polynomial of the autoregressive process, although this feature can be explicitly switched off by user. Detailed information about the package can be found in Błażejowski and Kwiatkowski (2020).

Since exploration of many possible models demands intensive computational effort, we run BACE and BMA_ADL through the Message Passing Interface (MPI)⁵. It is especially useful for a large number of explanatory variables, which results in a computational complexity that exceeds the computing power of modern PCs, because it performs parallel computations through MPI.

Both packages are written in gretl's internal scripting language HansL (see Cottrell and Lucchetti 2019b) with an easy-to-use graphical user interface (GUI). Therefore, they can be treated as an automatic model selection procedure and would be a useful for users who are not familiar with model averaging.

4. Autometrics

Autometrics procedure of variables model selection is built on the basis of PcGets module implemented in OxMetrics software and is fully described in Doornik (2009) and Doornik and Hendry (2013). This conception is based on general-to-specific approach with multiple path of searching (reducing) algorithm. The assumption underlying empirical model selection is discovering the local data generating process (LDGP), which is tend to explain the relations which occur in real world in the space of available variables. One needs to select the model from the set of

² The BACE 2.0 package is available at http://ricardo.ecn.wfu.edu/gretl/cgi-bin/gretldata.cgi?opt=SHOW_FUNCS and was developed by co-authors (see Błażejowski and Kwiatkowski 2018).

³ Gretl is an open-source software for econometric analysis and is available at <http://gretl.sf.net>.

⁴ The BMA_ADL package for gretl is available in Supplementary Materials along with scripts to replicate all analysis.

⁵ MPI is a standard that supports running a given program simultaneously on several CPU cores, so it supports a very flexible type of parallelism of Monte Carlo integration see (Cottrell and Lucchetti 2020, 2019a).

potential specifications ensuring that model is congruent and encompasses LDGP. The crucial issue here is test-based reduction strategy (see [Desboulets 2018](#)).

The procedure of selecting variables in Autometrics is proceed in following stages. The starting point for automatic procedure is general unrestricted model (GUM), which should remain congruent and include all potentially relevant variables according to sample size, theoretical, or empirical considerations. This solution increases chance that LDGP is nested in GUM and can be discovered. The variables, which have strong importance and influence should remain in model and the less significant ones should not be retained. The mis-specification test is applied to ensure the congruence postulate and to avoid badly-specified GUM. Additionally, encompassing test is used to evaluate if small model can explain larger one, which is encompassed within. Such a procedure can be treated as progressive research strategy of reduction and defines partial order of considered model specifications (see [Hendry et al. 2008](#)).

Autometrics ensures the tree-search approach for examining the whole model space using three strategies of path evaluation: pruning, bunching and chopping (see [Hendry and Doornik 2014](#)). Before the main multi-path reduction of variables is launched, the pre-search is initiated to eliminate most insignificant and irrelevant variables. During reductions and simplifications diagnostic tests are employed to ensure the congruence and to find valid specification. The terminal model is received at the end of each branch of the tree-search algorithm. Moreover, Autometrics also take into consideration following modeling issues: cointegration, functional form, economic theory or data accuracy.

Application of Autometrics or PcGets can be found in works, for example: [Clements and Hendry \(2008\)](#); [Hendry \(2001\)](#) for UK inflation, [Hendry \(2011\)](#) for consumers' expenditures, [Castle et al. \(2012\)](#) for US real interest rates, [Ericsson and Kamin \(2009\)](#) for Argentine broad money demand, [Marczak and Proietti \(2016\)](#) for industrial production, [Kamarudin and Ismail \(2016\)](#) for water quality index, or [Ackah and Asomani \(2015\)](#) for renewable energy.

5. Empirical Results

In this section, we analyze the BACE and BMA results for data used in two well-known dynamic macroeconomic models: model for M1 money demand in UK (UKM1), which was proposed in [Hendry and Ericsson \(1991\)](#), and the long-term UK inflation model, as introduced in [Hendry \(2001\)](#). We focus on the modeling and forecasting of narrow money and inflation in the UK using the BACE and BMA methods along with the Autometrics program⁶. We analyze the estimation results using standard posterior characteristics, such as posterior inclusion probabilities, the posterior means of regression parameters, and the posterior standard deviations, as defined in Section 2. We compare forecasting accuracies using three measures, namely, root-mean-square error (RMSE), mean average percentage error (MAPE), and Theil's U coefficient (see [Theil 1966](#), pp. 33–36) divided into three factors: bias proportion U^M (measures differences between averages of actual and predicted values), regression proportion U^R (evaluates the slope coefficient from a regression of changes in actual values on changes in predicted values), and disturbance proportion U^D (measures proportion of forecast error associated with random disturbance). Two first factors stand for systematic error and should be 0, while disturbance proportion is an unsystematic element and should equal 1.

Based on the methods discussed here, we also consider two additional models associated with BACE and BMA output. [Barbieri and Berger \(2004\)](#) introduced median probability model, which is defined as the model consisting of those variables which have an overall posterior probability greater than or equal to 0.5 of being in a model. According to the authors, median probability model considerably outperforms the most probable model in terms of predictive accuracy. Therefore it seems reasonable to include this model in our analysis and compare its forecasting performance.

⁶ We used gretl version 2019d-git and PcGive version 14.2 with Ox Professional version 7.20 on a PC machine running under Debian GNU/Linux 64 bits.

5.1. Modeling and Forecasting Demand for Narrow Money in the UK: UKM1

We based the first empirical illustration on the UKM1 model proposed in [Hendry and Ericsson \(1991\)](#) in the following form:

$$\Delta(m - p)_t = -0.69\Delta p_t - 0.17\Delta(m - p - y)_{t-1} - 0.63Rn_t - 0.093(m - p - y)_{t-1} + 0.023 \quad (27)$$

where small letters indicate the log-transformed variables defined as follows⁷:

- M_t : nominal narrow money, M1 aggregate in million £,
- Y_t : real total final expenditure (TFE) for 1985 prices in million £,
- P_t : deflator of TFE,
- Rn_t : net interest rate of the cost of holding money (calculated as the difference between the three-month interest rate and learning-adjusted own interest rate).

The data for the UK narrow money M1 aggregate are quarterly and span from 1964:3 to 1989:2⁸. Figure 1 presents plots of the time series used in the analysis.

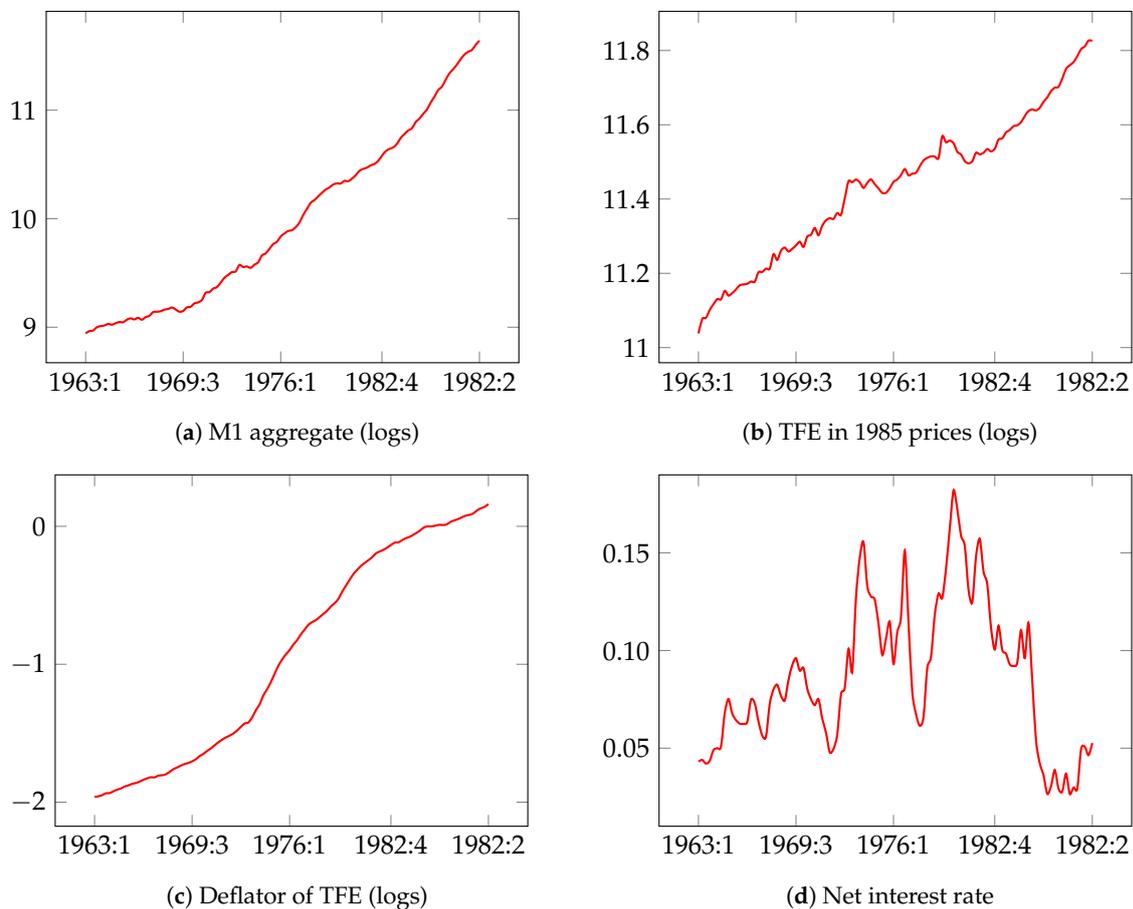


Figure 1. Times-series used in the model for M1 money demand in UK (UKM1).

⁷ Exogeneity of variables used in UKM1 model is discussed in ([Hendry and Nielsen 2012](#), pp. 266–67; [Hendry 1995](#), pp. 605–6; [Hendry 2015](#), pp. 127–33) and the results show that modeling demand for narrow money in UK as a single equation is valid in general.

⁸ All data were retrieved from <https://www.nuffield.ox.ac.uk/media/2502/dynects.zip>.

Model (27) was later replicated as an unrestricted autoregressive distributed lag (ADL) model in PcGets (see Krolzig and Hendry 2001, p. 29). In their paper, narrow money was measured in nominal terms instead of real terms, so the ADL representation of the general unrestricted model (GUM) was defined as follows:

$$m_t = \sum_{s=1}^4 \alpha_s m_{t-s} + \sum_{s=0}^4 \beta_s p_{t-s} + \sum_{s=0}^4 \gamma_s y_{t-s} + \sum_{s=0}^4 \delta_s Rn_{t-s} + const + \varepsilon_t. \quad (28)$$

After reduction⁹, they obtained the following empirical model:

$$\hat{m}_t = 0.67m_{t-1} + 0.21m_{t-4} + 0.33p_t - 0.20p_{t-3} + 0.13y_t - 0.58Rn_t - 0.34Rn_{t-2}. \quad (29)$$

In our research, following Krolzig and Hendry (2001), we estimated the GUM in the form shown in Equation (28) using the sample 1964:1–1985:2 ($T = 86$) and used the last 4 years (1985:3–1989:2) for forecasting purposes. We compared the variable selection and forecasting accuracy of BACE and BMA with those of Autometrics, which is an alternative automatic model selection procedure. Table 1 presents the estimation and variable selection results for UKM1 in the ADL form, Equation (28). Model space consists of $2^{20} = 1,048,576$ specifications that must be considered. The total number of variables is 20, including current values of an explanatory variables and their lags (up to order 4), lagged values of the dependent variable (up to order 4) and constant.

According to the results in Table 1, the variables used in the BACE analysis can be divided into three groups: high-probability determinants (m_{t-1}, Rn_t, p_t) with $PIP \geq 2/3$, medium-probability determinants ($m_{t-2}, m_{t-4}, p_{t-1}, y_{t-1}$) with $1/3 \leq PIP < 2/3$, and low-probability determinants (the remaining variables) with $PIP < 1/3$. The top four most probable variables are the same as those selected by Autometrics, although only three of them are classified as highly probable determinants (one variable, i.e., y_{t-1} is close to being highly probable). This discrepancy between the two selections can be explained by the fact that the Autometrics model, which is the most probable one in BACE, has only 1.53% of the total posterior probability mass (see Table 2).

In case of BMA with stationarity restrictions, we get similar results although there are some slight changes. Again the top four most probable variables are the same as those selected by BACE and Autometrics, however the only two them (m_{t-1}, Rn_t) can be classified as highly probable, while in the group of medium-probability determinants we can include: p_t, p_{t-1}, y_{t-1} . The most likely model is again the model selected by Autometrics, although in this case the posterior probability for the top model is higher than in BACE and equals to 8.09% (see Table 3). The BMA procedure without stationarity restrictions points the m_{t-1} and Rn_t as highly probable variables, while p_t and y_{t-1} are medium probable. The most probable model is still the same as indicated in BMA with stationarity restrictions, but models (M_2) and (M_3) have changed the order in the list (see Table 4). In the vast majority of cases, BMA PIP coefficients take lower values than in the case of BACE. As a consequence, we find little difference in posterior mean and variance of regression parameters comparing BACE to BMA. Nevertheless, it is difficult to state clearly which point estimates are closer to the results obtained by Autometrics, however, the BACE ranking is more consistent with the Autometrics output. It seems that the both BMA methods prefer a more parsimonious specifications that do not include some variables found to be important in the BACE and Autometrics.

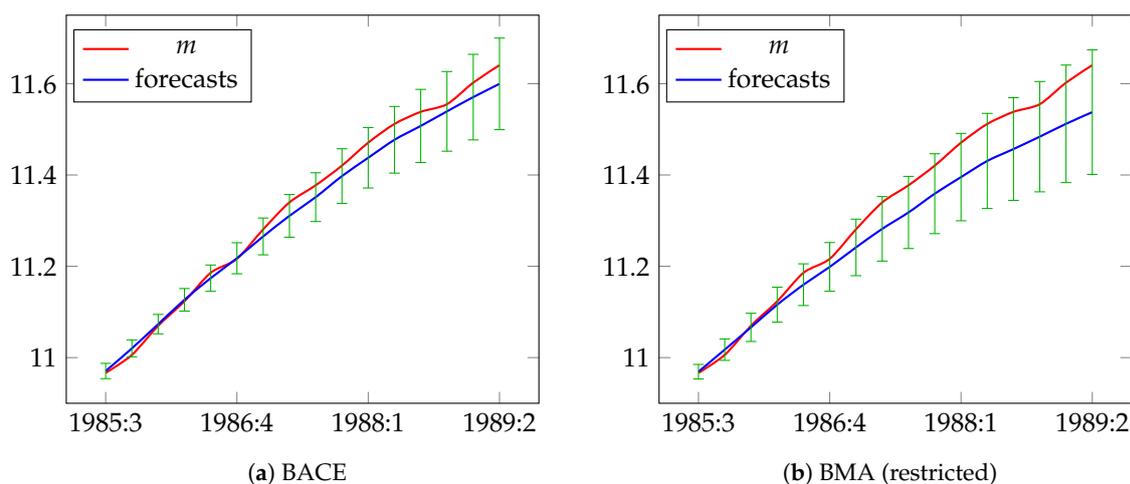
⁹ Authors understand ‘reduction’ as a structured path of elimination insignificant variables based on t -statistics together with pre-search analysis and encompassing tests.

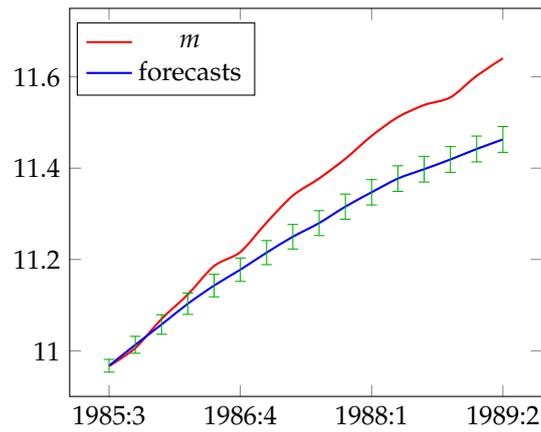
In the next step, we decided to compare the accuracy of forecasts. Table 5 presents the BACE, B A (with and without stationarity restriction) and Autometrics forecasts of nominal narrow money in the UK for the period from 1985:3 to 1989:2, which covers 16 quarters. The second column includes the logs of the actual values of the dependent variable. The next columns contain the weighted averages of individual model forecasts and errors for BACE, BMA, and Autometrics, respectively. Additionally, we include results for so-called median probability models introduced by Barbieri and Berger (2004). Moreover, the five bottom rows of the table contain well-known measures of forecast error: RMSE, MAPE, and Theil's U coefficients.

Two accuracy measures indicate that the BACE forecasts are relatively close to the real values of nominal narrow money in the UK. For BACE, RMSE is 0.0224 and MAPE is 0.17%, while RMSE and MAPE for BMA with stationarity restrictions are 0.0592 and 0.43%, respectively. Forecast generated by BMA without stationarity restrictions have slightly lower forecast errors than forecasts from BMA with stationarity restrictions. In the other cases, i.e., for Autometrics and median probability models the results are in the range of 0.0994–0.1018 and 0.72–0.74%, respectively, while both median BMA approaches give exact equal results. It means that the RMSE calculated for BACE is two and a half times smaller than the RMSE resulting from BMA and almost five times smaller than for Autometrics. We can see almost the same scenario for MAPE measure where BACE measure returns the smallest errors. As the last conclusion about these results is that the median probability models do not outperform the mixture of models in terms of predictive performance.

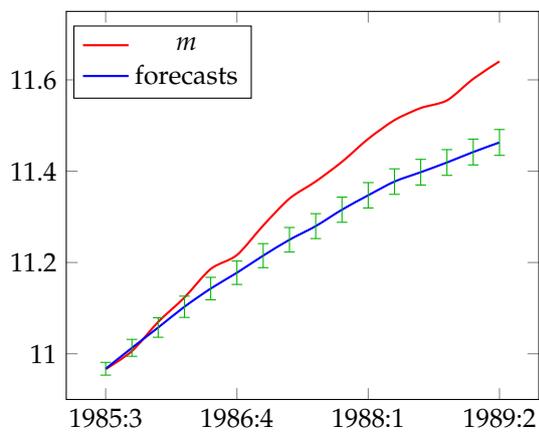
For all methods, the largest factor of forecast error is bias proportion, which has a considerable impact on forecast accuracy, although for BACE is the smallest one. This is clearly reflected in Figure 2, which shows the actual and forecasted values of nominal narrow money. In this figure, the bias in the forecasts generated by BMA, Autometrics and two other methods substantially grows as the forecast horizon increases.

One potential explanation of this observation is that the forecasts in Autometrics and median probability models are generated by only one model. According to the BACE and BMA with stationarity restrictions results, the use of a single model (M_1) leaves 98.5% and 91.9% of the total posterior probability mass. On the other hand, BACE and BMA calculates forecasts from the whole model space and accounts for the mixture of all considered specifications, which are weighted by their posterior probabilities.

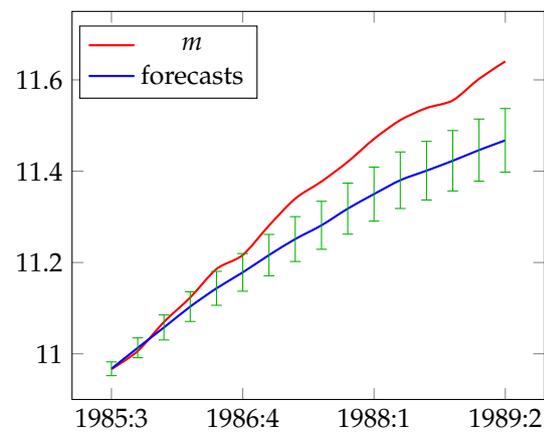




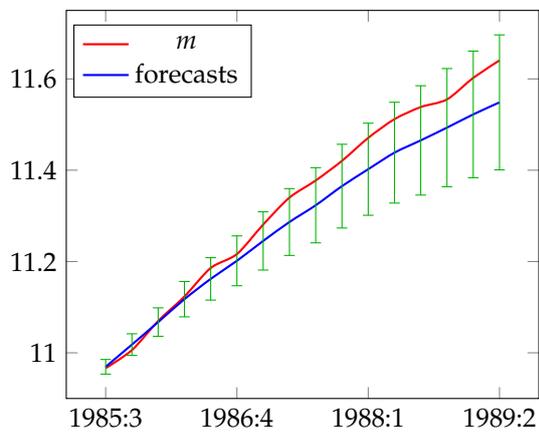
(c) Autometrics



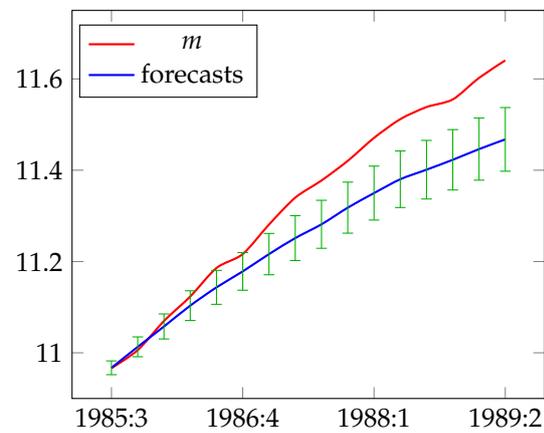
(d) Median probability model - BACE



(e) Median probability model - BMA (restricted)



(f) BMA (unrestricted)



(g) Median probability model - BMA (unrestricted)

Figure 2. Actual values and forecasts of the logs of M1 for the period from 1985:3 to 1989:2.

Table 2. Cont.

Model M_j	M_1	M_2	M_3	M_4	M_5	M_6	M_7	M_8	M_9	M_{10}
$P(M_j y)$	1.53%	0.64%	0.60%	0.59%	0.46%	0.44%	0.38%	0.37%	0.33%	0.32%
m_{t-2}				0.1431					0.1761	0.1853
p_{t-3}			-0.2071							
p_{t-2}					-0.2685			-0.1251		-0.1826
Rn_{t-2}			-0.3563		-0.3143					
const									-0.6718	
y_{t-2}							-0.1408			
y_t						0.1255				

Table 3. BMA (with stationary restrictions) posterior probabilities and coefficient estimates for the top 10 models of nominal narrow money demand in the UK.

Model M_j	M_1	M_2	M_3	M_4	M_5	M_6	M_7	M_8	M_9	M_{10}
$P(M_j y)$	8.09%	3.55%	2.82%	2.06%	1.35%	1.30%	1.19%	1.18%	1.07%	0.91%
m_{t-1}	0.8710	0.8620	0.8725	0.8916	0.7228	0.8687	0.8645	0.8842	0.8861	0.8546
Rn_t	-0.5059	-0.4756	-0.4843	-0.4912	-0.5527	-0.4955	-0.4530	-0.5132	-0.4635	-0.4463
p_t	0.1141	0.1355	0.1126	0.0986	0.1208	0.1157		0.0961		0.1423
y_{t-1}	0.1273				0.1334	0.2695		0.1581		
p_{t-1}		0.1200					0.1178		0.1020	
m_{t-2}					0.1425					
p_{t-2}										0.1249
const								-0.4988		
y_{t-2}						-0.1402				
y_t			0.1256				0.1329			
y_{t-4}				0.1083					0.1132	

Table 4. BMA (without stationary restrictions) posterior probabilities and coefficient estimates for the top 10 models of nominal narrow money demand in the UK.

Model M_j	M_1	M_2	M_3	M_4	M_5	M_6	M_7	M_8	M_9	M_{10}
$P(M_j y)$	7.06%	3.28%	3.14%	2.18%	1.42%	1.16%	0.97%	0.95%	0.88%	0.87%
m_{t-1}	0.8710	0.8725	0.8621	0.8914	0.7229	0.8878	0.8862	0.8991	0.8834	0.8687
Rn_t	-0.5051	-0.4844	-0.4763	-0.4925	-0.5528	-0.4995	-0.4630	-0.5396	-0.4997	-0.4948
p_t	0.1140	0.1126		0.0987	0.1206	0.1018		0.1774	0.1051	0.1157

Table 4. Cont.

Model M_j	M_1	M_2	M_3	M_4	M_5	M_6	M_7	M_8	M_9	M_{10}
$P(M_j y)$	7.06%	3.28%	3.14%	2.18%	1.42%	1.16%	0.97%	0.95%	0.88%	0.87%
y_{t-1}	0.1273		0.1354		0.1332			0.1012		0.2710
p_{t-1}			0.1199				0.1019			
y_t		0.1256								
m_{t-2}					0.1427					
y_{t-2}									0.1158	-0.1418
y_{t-3}						0.1118				
y_{t-4}				0.1085				0.1131		
p_{t-3}									-0.0831	

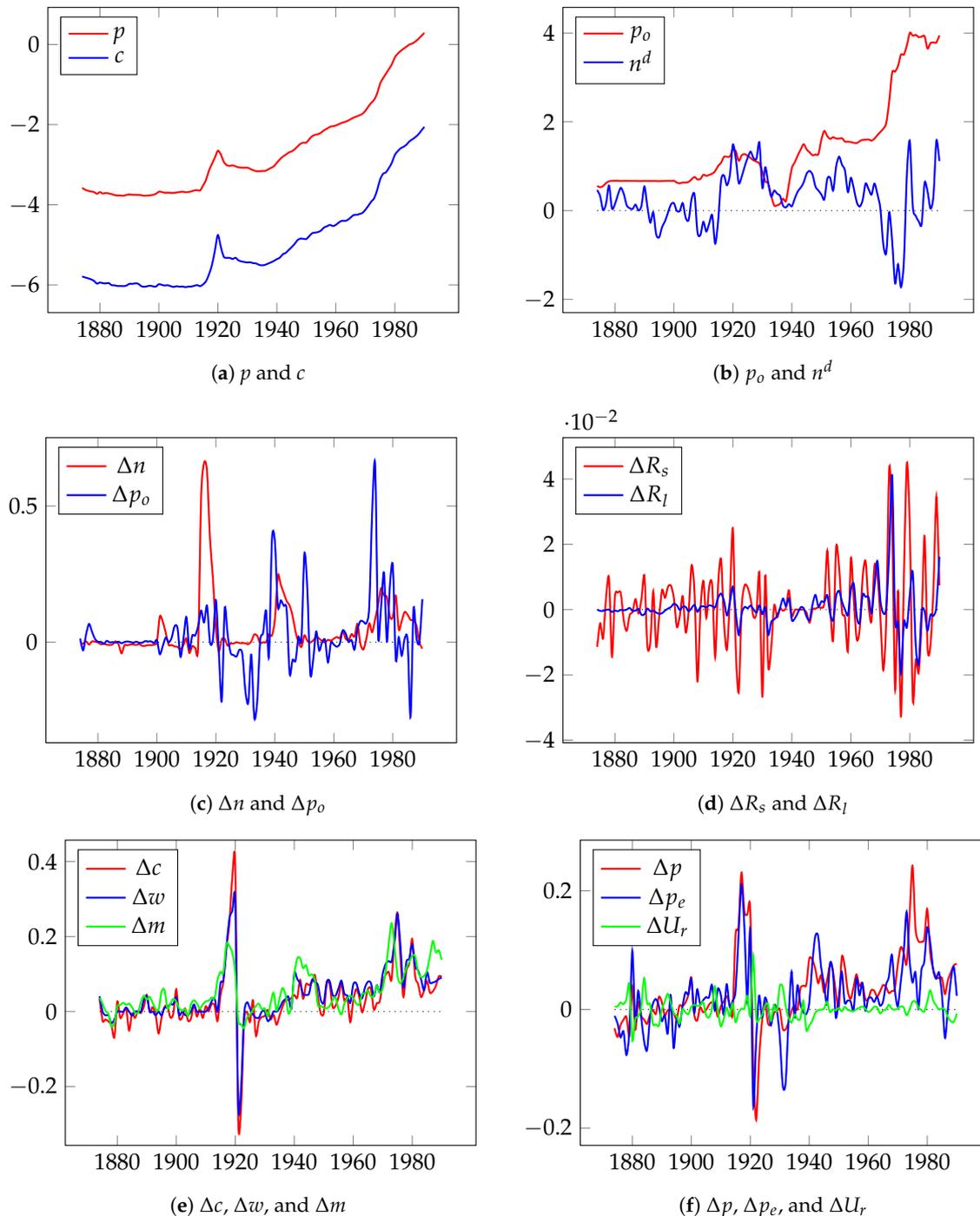
Table 5. Forecasting results of m in the UK based on BACE, BMA, Autometrics, and median probability models.

Date	Actual	BACE		BMA (Restricted)		BMA (Unrestricted)		Autometrics		Median BACE		Median BMA (Restricted)		Median BMA (Unrestricted)	
		Fcast.	SE	Fcast.	SE	Fcast.	SE	Fcast.	SE	Fcast.	SE	Fcast.	SE	Fcast.	SE
1985:3	10.966	10.971	0.0167	10.969	0.0159	10.969	0.0160	10.967	0.0140	10.967	0.0140	10.967	0.0151	10.967	0.0151
1985:4	11.006	11.020	0.0185	11.017	0.0235	11.018	0.0237	11.013	0.0186	11.013	0.0186	11.013	0.0218	11.013	0.0218
1986:1	11.070	11.073	0.0212	11.066	0.0309	11.067	0.0312	11.058	0.0214	11.058	0.0214	11.058	0.0274	11.058	0.0274
1986:2	11.123	11.127	0.0247	11.116	0.0383	11.118	0.0387	11.103	0.0233	11.103	0.0233	11.103	0.0326	11.103	0.0326
1986:3	11.186	11.174	0.0288	11.160	0.0456	11.162	0.0464	11.143	0.0247	11.143	0.0247	11.143	0.0372	11.143	0.0372
1986:4	11.216	11.218	0.0340	11.199	0.0533	11.202	0.0546	11.178	0.0256	11.178	0.0256	11.178	0.0412	11.178	0.0412
1987:1	11.281	11.265	0.0403	11.241	0.0620	11.245	0.0638	11.215	0.0264	11.215	0.0264	11.216	0.0452	11.216	0.0452
1987:2	11.340	11.311	0.0468	11.282	0.0707	11.287	0.0732	11.250	0.0269	11.250	0.0269	11.251	0.0491	11.251	0.0491
1987:3	11.377	11.351	0.0534	11.318	0.0790	11.323	0.0823	11.280	0.0273	11.280	0.0273	11.282	0.0526	11.282	0.0526
1987:4	11.421	11.398	0.0600	11.359	0.0875	11.365	0.0917	11.316	0.0276	11.316	0.0276	11.318	0.0559	11.318	0.0559
1988:1	11.471	11.438	0.0662	11.395	0.0957	11.402	0.1009	11.347	0.0278	11.347	0.0278	11.350	0.0591	11.350	0.0591
1988:2	11.512	11.477	0.0730	11.431	0.1041	11.438	0.1104	11.377	0.0280	11.377	0.0280	11.380	0.0619	11.380	0.0619
1988:3	11.538	11.507	0.0801	11.457	0.1124	11.465	0.1198	11.398	0.0281	11.398	0.0281	11.401	0.0642	11.401	0.0642
1988:4	11.555	11.539	0.0872	11.484	0.1208	11.493	0.1294	11.419	0.0282	11.419	0.0282	11.423	0.0661	11.423	0.0661
1989:1	11.602	11.571	0.0937	11.512	0.1287	11.522	0.1387	11.442	0.0283	11.442	0.0283	11.446	0.0680	11.446	0.0680
1989:2	11.640	11.600	0.1003	11.538	0.1364	11.549	0.1478	11.463	0.0283	11.463	0.0283	11.468	0.0697	11.468	0.0697
RMSE		0.0224		0.0592		0.05317		0.1018		0.1018		0.0995		0.0995	
MAPE		0.17%		0.43%		0.39%		0.74%		0.74%		0.72%		0.72%	
U^M (bias)		49.5%		64.4%		63.6%		67.3%		67.3%		67.4%		67.4%	
U^R (regression)		40.0%		34.0%		34.4%		31.9%		31.8%		31.9%		31.8%	
U^D (disturbance)		10.5%		1.6%		2.0%		0.8%		0.8%		0.8%		0.8%	

BMA (restricted) indicates variant where we impose stationary conditions for autoregressive parameters, while BMA (unrestricted) denotes variant without stationary restrictions.

5.2. Modeling and Forecasting Long-Term UK Inflation

In the second empirical example, we used the long-term UK inflation model developed in Hendry (2001) for 1875–1991 years ($T = 117$). The data set¹⁰ used in this research is described in Table 6, and Figure 3 presents the time-series plots (small letters indicate log-transformed variables).



¹⁰ All series are freely available in the Journal of Applied Econometrics Data Archive at <http://qed.econ.queensu.ca/jae/2001-v16.3/hendry>. Exogeneity of variables used in this model is mentioned in (Hendry 2001, p. 261; Hendry 2015, p. 150).

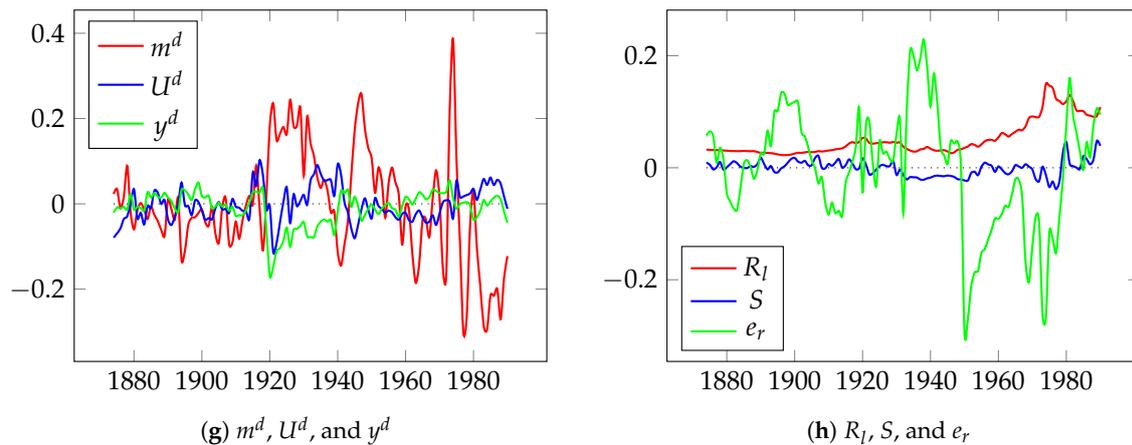


Figure 3. Time-series used in the long-term UK inflation model.

Table 6. List of variables and their definitions used in the long-term UK inflation model.

Variable	Definition	Variable	Definition
Y_t	real GDP, £ million, 1985 prices	$P_{e,t}$	world prices (1985 = 1)
P_t	implicit deflator of GDP (1985 = 1)	E_t	annual-average effective exchange rate
M_t	nominal broad money, million £	$P_{nni,t}$	deflator of net national income (1985 = 1)
$R_{s,t}$	three-month treasury bill rate, fraction p.a.	$P_{cpi,t}$	consumer price index (1985 = 1)
$R_{l,t}$	long-term bond interest rate, fraction p.a.	$P_{o,t}$	commodity price index, \$
$R_{n,t}$	opportunity cost of money measure	m_t^d	money excess demand
N_t	nominal National Debt, £ million	y_t^d	GDP excess demand
U_t	unemployment	S_t	short-long spread
$Wpop_t$	working population	n_t^d	excess demand for debt
$U_{r,t}$	unemployment rate, fraction	$e_{r,t}$	real exchange rate
L_t	employment	π_t^*	profit markup
K_t	gross capital stock	U_t^d	excess demand for labor
W_t	wages	$p_{o,t}$	commodity prices in Sterling
H_t	normal hours (from 1920)	C_t	nominal unit labor costs

The final specification after a number of variable transformations and model pre-reduction was as follows¹¹ (see Hendry 2001):

$$\Delta p_t = f(\Delta p_{t-1}, y_{t-1}^d, m_{t-1}^d, n_{t-1}^d, U_{t-1}^d, S_{t-1}, R_{l,t-1}, \Delta p_{e,t}, \Delta p_{e,t-1}, \Delta U_{r,t-1}, \Delta w_{t-1}, \Delta c_{t-1}, \Delta m_{t-1}, \Delta n_{t-1}, \Delta R_{s,t-1}, \Delta R_{l,t-1}, \Delta p_{o,t-1}, I_{d,t}, \pi_{t-1}^*; \varepsilon_t), \tag{30}$$

where $\pi_t^* = 0.25e_{r,t} - 0.675(c - p)_t^* - 0.075(p_o - p)_t + 0.11I_{2,t} + 0.25$, $(c - p)_t^* = c_t - p_t + 0.006 \times (trend - 69.5) + 2.37$, and I_d is a combination of year indicator dummies. Model space consists of $2^{20} = 1,048,576$ linear combinations that must be considered. After the reduction at a 1% significance level, specification in Equation (30) was reduced to the following empirical model (see Hendry 2001):

$$\Delta \hat{p}_t = 0.18y_{t-1}^d + 0.19\Delta m_{t-1} - 0.83S_{t-1} + 0.62\Delta R_{s,t-1} - 0.19\pi_{t-1}^* + 0.27\Delta p_{e,t} + 0.04I_{d,t} + 0.04\Delta p_{o,t-1} + 0.27\Delta p_{t-1}. \tag{31}$$

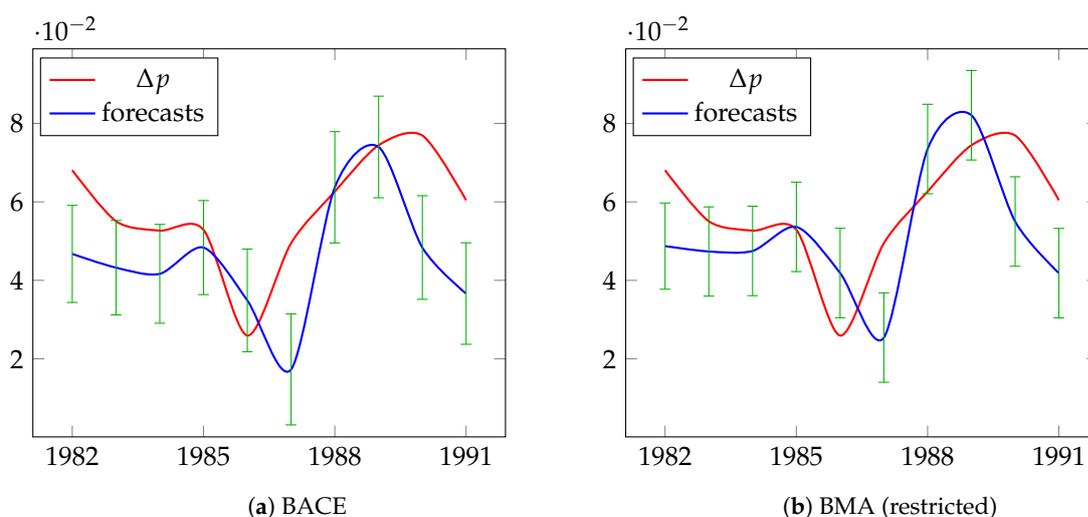
¹¹ The full replication of this model using the BACE approach, together with a detailed discussion on variable selection strategy and discovering the reduction path, is presented in Błażejowski et al. (2020).

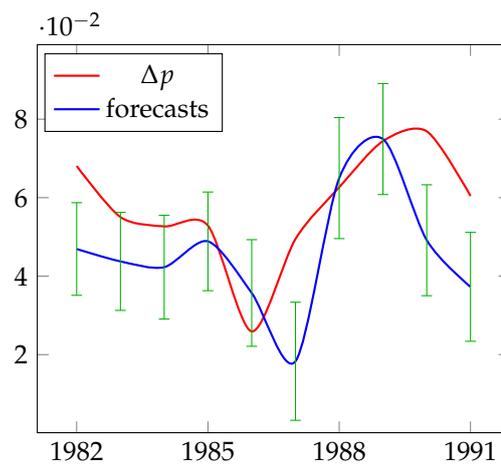
The results in Table 7 show that the BACE, BMA, and Autometrics identify the same set of significant determinants of UK inflation as in Hendry (2001). Moreover, both BMA procedures, with and without stationarity restrictions, give exactly the same results. This can be explained by the fact that dependent variable Δp_t is far away from non-stationary region, so imposing stationarity restrictions does not result in rejecting any of draws from posterior. Hereafter, we formulate comments without division into restricted or unrestricted case. BACE and BMA indicate that the following variables are highly probable: π_{t-1}^* , $I_{d,t}$, $\Delta p_{e,t}$, S_{t-1} , Δp_{t-1} , y_{t-1}^d , $\Delta R_{s,t-1}$, Δm_{t-1} , $\Delta p_{o,t-1}$. Autometrics selects the same set, reducing model (30) at the 1% significance level.

Tables 8–10 present the BACE and BMA posterior probability and coefficient estimates for the top 10 models. In the case of BACE the most probable model (M_1) has a posterior probability of 21.9%, while the second model in the ranking (M_2) has a probability of 6.4%. For the other models, the posterior probability does not exceed 4.7%. Although the posterior probability of the highest-ranked model (M_1) is more than three times larger than that of the second model (M_2), an inference that is based only on M_1 leaves 78.1% of the posterior probability mass. As a consequence, estimates of the average mean of coefficients are slightly different from those in Autometrics. We can meet a similar situation in the case of BMA, although the highest-ranked model (M_1) is even more preferred by the data with posterior probability equals to 32.66%. The second model in the ranking (M_2) is almost two times less likely.

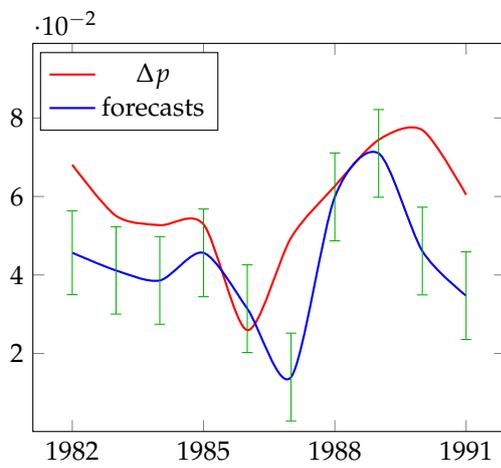
Table 11 presents detailed information about the predictions for UK inflation resulting from BACE, BMA, Autometrics, and median probability models. This table includes actual values, forecast values, and forecast standard errors, as well as accuracy measures, for the period from 1982 to 1991, which covers 10 years. The actual and forecast values of UK inflation are presented in Figure 4. For BACE, RMSE is 0.0179 and MAPE is 26.06%, for BMA we have RMSE—0.0175 and MAPE—25.85%, while RMSE and MAPE in Autometrics are 0.0151 and 25.06%, respectively. Forecast errors of the median probability models are the largest compared to other methods. As we can see BACE, BMA, and Autometrics generate forecasts of almost the same quality, but the sources of errors are different. For BACE and BMA, the greatest factor of forecast error is bias proportion, while the greatest factor for Autometrics is disturbance proportion.

One explanation of the equivalent forecasting performances is the fact that, according to the results in Tables 8–10, the top 10 most probable specifications have almost the same set of nine the most probable variables and cover over 50% of the posterior probability mass, including the second-ranked model (M_2) selected by Autometrics.

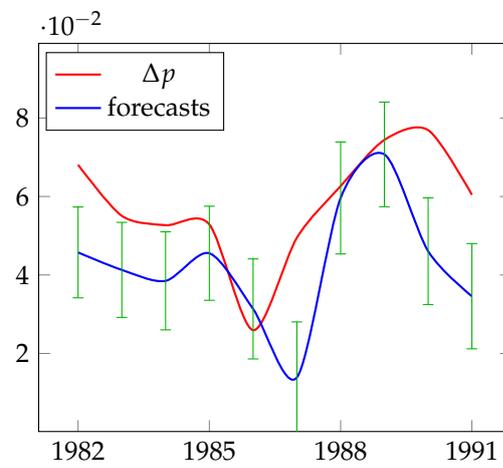




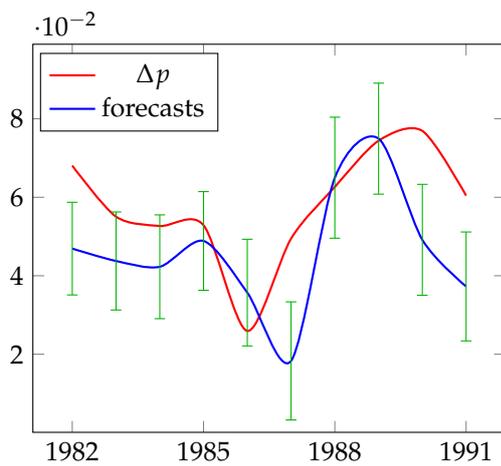
(c) Autometrics



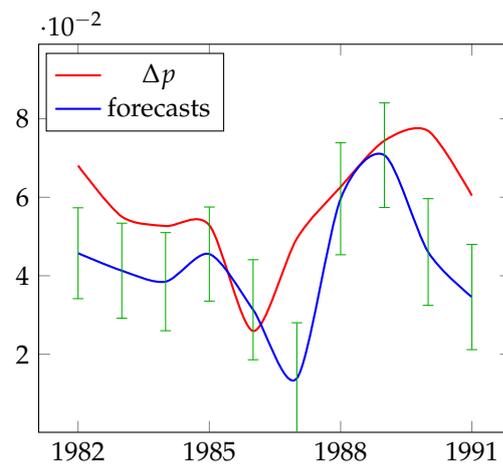
(d) Median probability model - BACE



(e) Median probability model - BMA (restricted)



(f) BMA (unrestricted)



(g) Median probability model - BMA (unrestricted)

Figure 4. Actual and forecast values (expressed in logs) of differences in UK inflation for the period 1982–1991.

Table 7. BACE, BMA, and Autometrics estimates for the long-term UK inflation model (30).

Variable	BACE			BMA (Restricted)			BMA (Unrestricted)			Autometrics		
	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.	Coeff.	Std. Error	
Hendry's model (31)	$I_{d,t}$	1.00	0.0380	0.0015	1.00	0.0379	0.0014	1.00	0.0379	0.0014	0.0377	0.0015
	$\Delta p_{e,t}$	1.00	0.2612	0.0248	1.00	0.2617	0.0236	1.00	0.2617	0.0236	0.2608	0.0247
	S_{t-1}	1.00	-0.9786	0.1060	1.00	-0.9696	0.1024	1.00	-0.9696	0.1024	-0.9234	0.0997
	y_{t-1}^d	1.00	0.1898	0.0381	1.00	0.1875	0.0352	1.00	0.1875	0.0352	0.1872	0.0330
	Δp_{t-1}	1.00	0.2818	0.0353	1.00	0.2800	0.0322	1.00	0.2800	0.0322	0.2638	0.0264
	π_{t-1}^*	0.99	-0.1674	0.0295	1.00	-0.1684	0.0281	1.00	-0.1684	0.0281	-0.1778	0.0273
	$\Delta R_{s,t-1}$	0.99	0.6896	0.1273	0.99	0.6903	0.1199	0.99	0.6903	0.1199	0.6723	0.1182
	$\Delta p_{o,t-1}$	0.99	0.0492	0.0111	0.99	0.0489	0.0106	0.99	0.0490	0.0106	0.0487	0.0110
	Δm_{t-1}	0.99	0.1531	0.0325	0.99	0.1575	0.0309	0.99	0.1575	0.0309	0.1732	0.0293
	U_{t-1}^d	0.71	-0.0548	0.0443	0.60	-0.0472	0.0449	0.60	-0.0472	0.0449		
	n_{t-1}^d	0.20	0.0006	0.0016	0.12	0.0004	0.0013	0.12	0.0004	0.0013		
	$R_{l,t-1}$	0.15	0.0060	0.0217	0.09	0.0038	0.0170	0.09	0.0039	0.0170		
	$\Delta p_{e,t-1}$	0.12	0.0030	0.0134	0.07	0.0017	0.0099	0.07	0.0018	0.0100		
	Δn_{t-1}	0.12	0.0014	0.0063	0.06	0.0007	0.0044	0.06	0.0007	0.0044		
	<i>const</i>	0.11	0.0001	0.0007	0.07	0.0001	0.0005	0.07	0.0001	0.0005		
	Δw_{t-1}	0.10	-0.0001	0.0132	0.05	0.0001	0.0083	0.05	0.0001	0.0083		
	$\Delta U_{r,t-1}$	0.10	-0.0009	0.0230	0.05	-0.0001	0.0164	0.05	-0.0001	0.0164		
	m_{t-1}^d	0.10	-0.0001	0.0043	0.05	-0.0001	0.0028	0.05	0.0000	0.0029		
	Δc_{t-1}	0.09	0.0003	0.0104	0.05	0.0001	0.0066	0.05	0.0001	0.0066		
	$\Delta R_{l,t-1}$	0.09	0.0012	0.0839	0.05	0.0017	0.0591	0.05	0.0017	0.0590		

BMA (restricted) indicates variant where we impose stationary conditions for autoregressive parameters, while BMA (unrestricted) denotes variant without stationary restrictions.

Table 8. BACE posterior probabilities and coefficient estimates for the top 10 models of UK inflation.

Model M_j	M_1	M_2	M_3	M_4	M_5	M_6	M_7	M_8	M_9	M_{10}
$P(M_j y)$	21.93%	6.42%	4.63%	3.28%	3.06%	3.01%	2.80%	2.57%	2.41%	2.41%
$I_{d,t}$	0.0382	0.0377	0.0381	0.0383	0.0379	0.0378	0.0379	0.0380	0.0382	0.0382
$\Delta p_{e,t}$	0.2639	0.2608	0.2619	0.2610	0.2581	0.2583	0.2623	0.2635	0.2634	0.2635
S_{t-1}	-0.9935	-0.9234	-1.0122	-1.0002	-0.9979	-0.9607	-0.9866	-0.9896	-0.9873	-0.9946
y_{t-1}^d	0.1788	0.1872	0.2069	0.1768	0.1858	0.2267	0.1829	0.1856	0.1785	0.1790
Δp_{t-1}	0.2924	0.2638	0.2922	0.2837	0.2835	0.2676	0.2885	0.2930	0.2947	0.2952

Table 8. Cont.

Model M_j	M_1	M_2	M_3	M_4	M_5	M_6	M_7	M_8	M_9	M_{10}
$P(M_j y)$	21.93%	6.42%	4.63%	3.28%	3.06%	3.01%	2.80%	2.57%	2.41%	2.41%
π_{t-1}^*	-0.1618	-0.1778	-0.1701	-0.1642	-0.1690	-0.1875	-0.1545	-0.1619	-0.1627	-0.1620
$\Delta R_{s,t-1}$	0.7149	0.6723	0.6605	0.6937	0.7248	0.5996	0.7165	0.7146	0.6998	0.7171
$\Delta p_{o,t-1}$	0.0482	0.0487	0.0513	0.0479	0.0485	0.0532	0.0487	0.0488	0.0478	0.0480
Δm_{t-1}	0.1555	0.1732	0.1468	0.1485	0.1482	0.1579	0.1470	0.1465	0.1547	0.1562
U_{t-1}^d	-0.0790		-0.0710	-0.0806	-0.0814		-0.0716	-0.0744	-0.0833	-0.0794
n_{t-1}^d			0.0026			0.0038				
$\Delta p_{e,t-1}$				0.0254						
Δn_{t-1}					0.0123					
$R_{l,t-1}$							0.0253			
const								0.0009		
$\Delta U_{r,t-1}$									-0.0262	
Δw_{t-1}										-0.0028

Table 9. BMA (with stationarity restrictions) posterior probabilities and coefficient estimates for the top 10 models of UK inflation.

Model M_j	M_1	M_2	M_3	M_4	M_5	M_6	M_7	M_8	M_9	M_{10}
$P(M_j y)$	32.66%	17.63%	3.74%	3.24%	2.95%	2.80%	2.39%	1.94%	1.92%	1.90%
$I_{d,t}$	0.0381	0.0377	0.0378	0.0381	0.0373	0.0383	0.0379	0.0379	0.0375	0.0380
$\Delta p_{e,t}$	0.2638	0.2609	0.2585	0.2616	0.2583	0.2610	0.2580	-0.9864	0.2604	0.2636
S_{t-1}	-0.9948	-0.9224	-0.9602	-1.0122	-0.9228	-1.0017	-0.9973	0.2621	-0.9241	-0.9898
y_{t-1}^d	0.1787	0.1874	0.2264	0.2067	0.1942	0.1767	0.1860	0.1825	0.2002	0.1855
Δp_{t-1}	0.2927	0.2638	0.2676	0.2925	0.2614	0.2838	0.2831	0.2888	0.2687	0.2930
π_{t-1}^*	-0.1615	-0.1782	-0.1875	-0.1699	-0.1595	-0.1639	-0.1690	-0.1544	-0.1758	-0.1619
$\Delta R_{s,t-1}$	0.7163	0.6718	0.5991	0.6610	0.6844	0.6944	0.7237	0.7165	0.6779	0.7140
$\Delta p_{o,t-1}$	0.0482	0.0488	0.0534	0.0514	0.0496	0.0478	0.0486	0.0487	0.0499	0.0488
Δm_{t-1}	0.1554	0.1730	0.1576	0.1466	0.1517	0.1484	0.1484	0.1471	0.1515	0.1466
U_{t-1}^d	-0.0793			-0.0711		-0.0807	-0.0812	-0.0718		-0.0746
n_{t-1}^d			0.0038	0.0026						
$\Delta p_{e,t-1}$						0.0254				
Δn_{t-1}							0.0124			
$R_{l,t-1}$					0.0527			0.0251		
const									0.0018	0.0008

Table 10. BMA (without stationarity restrictions) posterior probabilities and coefficient estimates for the top 10 models of UK inflation.

Model M_j	M_1	M_2	M_3	M_4	M_5	M_6	M_7	M_8	M_9	M_{10}
$P(M_j y)$	32.66%	17.63%	3.74%	3.24%	2.95%	2.80%	2.39%	1.94%	1.92%	1.90%
$I_{d,t}$	0.0381	0.0377	0.0378	0.0381	0.0373	0.0383	0.0379	0.0379	0.0375	0.0380
$\Delta p_{e,t}$	0.2638	0.2609	0.2585	0.2616	0.2583	0.2610	0.2580	-0.9864	0.2604	0.2636
S_{t-1}	-0.9948	-0.9224	-0.9602	-1.0122	-0.9228	-1.0017	-0.9973	0.2621	-0.9241	-0.9898
y_{t-1}^d	0.1787	0.1874	0.2264	0.2067	0.1942	0.1767	0.1860	0.1825	0.2002	0.1855
Δp_{t-1}	0.2927	0.2638	0.2676	0.2925	0.2614	0.2838	0.2831	0.2888	0.2687	0.2930
π_{t-1}^*	-0.1615	-0.1782	-0.1875	-0.1699	-0.1595	-0.1639	-0.1690	-0.1544	-0.1758	-0.1619
$\Delta R_{s,t-1}$	0.7163	0.6718	0.5991	0.6610	0.6844	0.6944	0.7237	0.7165	0.6779	0.7140
$\Delta p_{o,t-1}$	0.0482	0.0488	0.0534	0.0514	0.0496	0.0478	0.0486	0.0487	0.0499	0.0488
Δm_{t-1}	0.1554	0.1730	0.1576	0.1466	0.1517	0.1484	0.1484	0.1471	0.1515	0.1466
U_{t-1}^d	-0.0793			-0.0711		-0.0807	-0.0812	-0.0718		-0.0746
n_{t-1}^d			0.0038	0.0026						
$\Delta p_{e,t-1}$						0.0254				
Δn_{t-1}							0.0124			
$R_{l,t-1}$					0.0527			0.0251		
const									0.0018	0.0008

Table 11. BACE, BMA, Autometrics, and median probability models forecasting results for Δp_t in the UK.

Date	Actual	BACE		BMA (Restricted)		BMA Median BMA (Unrestricted)		Autometrics		Median BACE (Restricted)		Median BMA (Unrestricted)			
		Fcast.	SE	Fcast.	SE	Fcast.	SE	Fcast.	SE	Fcast.	SE	Fcast.	SE	Fcast.	SE
1982	0.0681	0.0467	0.0124	0.0469	0.0118	0.0469	0.0118	0.0487	0.0110	0.0457	0.0107	0.0457	0.0116	0.0457	0.0116
1983	0.0551	0.0432	0.0120	0.0438	0.0125	0.0438	0.0125	0.0474	0.0114	0.0412	0.0111	0.0413	0.0121	0.0413	0.0121
1984	0.0527	0.0417	0.0126	0.0423	0.0132	0.0423	0.0132	0.0475	0.0114	0.0386	0.0112	0.0385	0.0125	0.0385	0.0125
1985	0.0529	0.0484	0.0120	0.0489	0.0126	0.0489	0.0126	0.0536	0.0114	0.0456	0.0112	0.0455	0.0120	0.0455	0.0120
1986	0.0259	0.0349	0.0131	0.0357	0.0136	0.0357	0.0136	0.0419	0.0114	0.0314	0.0112	0.0313	0.0127	0.0313	0.0127
1987	0.0495	0.0173	0.0142	0.0183	0.0151	0.0183	0.0151	0.0254	0.0114	0.0140	-0.0112	0.0139	0.0142	0.0139	0.0142
1988	0.0626	0.0637	0.0142	0.0650	0.0154	0.0650	0.0154	0.0735	0.0114	0.0599	0.0112	0.0596	0.0143	0.0596	0.0143
1989	0.0744	0.0740	0.0129	0.0749	0.0141	0.0749	0.0141	0.0821	0.0114	0.0710	0.0112	0.0707	0.0133	0.0707	0.0133
1990	0.0769	0.0484	0.0132	0.0492	0.0141	0.0492	0.0141	0.0550	0.0114	0.0461	0.0112	0.0461	0.0136	0.0461	0.0136
1991	0.0604	0.0366	0.0129	0.0373	0.0139	0.0373	0.0139	0.0418	0.0114	0.0347	0.0112	0.0346	0.0134	0.0346	0.0134
RMSE		0.0179		0.0175		0.0175		0.0151		0.0196		0.0197		0.0197	
MAPE		26.06%		25.85%		25.85%		25.06%		28.31%		28.41%		28.41%	
U^M (bias)		54.5%		51.3%		51.3%		21.9%		65.0%		65.3%		65.3%	
U^R (regression)		0.3%		0.3%		0.3%		1.2%		0.2%		0.2%		0.2%	
U^D (disturbance)		45.2%		48.3%		48.3%		76.9%		34.8%		34.5%		34.5%	

BMA (restricted) indicates variant where we impose stationary conditions for autoregressive parameters, while BMA (unrestricted) denotes variant without stationary restrictions.

6. Robustness and Run Time Analysis

6.1. Robustness

In order to confirm the empirical findings for variable and model selection obtained by BACE and BMA, we performed a robustness analysis using different prior model assumptions. We apply philosophy proposed in Osiewalski and Steel (1993) and we set different variants of the prior average model size in order to penalize large models. In Section 5, the prior average model size is set to $E(\Xi) = K/2$ (where K is the total number of independent variables). This means that we do not prefer any specification, so all possible models are equally probable. We considered robustness scenario as different specifications of prior model size, estimating the models in Equations (28) and (30) using three competitive variants: $E(\Xi) = K/4$, $E(\Xi) = K/5$, and $E(\Xi) = K/8$ (the most restrictive case). Tables 12 and 13 present the BACE estimates, Tables 14 and 15 show results for BMA with stationarity restrictions, while Tables 16 and 17 relate to results for BMA without stationarity restrictions.

According to the results concerning BACE method, which are presented in Tables 12 and 13, there are no substantial differences in the output between $E(\Xi) = K/4$, $E(\Xi) = K/5$, and $E(\Xi) = K/8$. Similar conclusion can be formulated for BMA outcome included in Tables 14–17. Moreover, comparing the results in Tables 12–17 with those in Tables 1 and 7 reveals that the observed differences are negligible.

Table 12. BACE coefficient estimates of the UKM1 model for different average prior model size assumptions.

Variable	$E(\Xi) = K/8$			$E(\Xi) = K/5$			$E(\Xi) = K/4$		
	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.
m_{t-1}	1.00	0.7695	0.1224	1.00	0.7676	0.1224	1.00	0.7734	0.1220
m_{t-2}	0.35	0.0687	0.1161	0.35	0.0681	0.1157	0.34	0.0664	0.1144
m_{t-3}	0.12	−0.0074	0.0506	0.13	−0.0073	0.0512	0.13	−0.0068	0.0510
m_{t-4}	0.39	0.0607	0.0962	0.40	0.0632	0.0976	0.38	0.0584	0.0950
p_t	0.67	0.1562	0.1581	0.67	0.1582	0.1607	0.66	0.1541	0.1593
p_{t-1}	0.37	0.0783	0.2002	0.37	0.0793	0.2028	0.37	0.0801	0.2049
p_{t-2}	0.28	−0.0598	0.1657	0.29	−0.0628	0.1711	0.31	−0.0657	0.1752
p_{t-3}	0.29	−0.0548	0.1207	0.29	−0.0547	0.1219	0.27	−0.0491	0.1172
p_{t-4}	0.19	−0.0178	0.0682	0.19	−0.0179	0.0693	0.19	−0.0174	0.0680
y_t	0.22	0.0180	0.0555	0.22	0.0183	0.0561	0.23	0.0188	0.0570
y_{t-1}	0.65	0.1155	0.1173	0.64	0.1143	0.1171	0.64	0.1148	0.1178
y_{t-2}	0.22	−0.0269	0.0860	0.22	−0.0259	0.0856	0.23	−0.0269	0.0878
y_{t-3}	0.15	−0.0031	0.0488	0.15	−0.0030	0.0498	0.15	−0.0024	0.0493
y_{t-4}	0.20	0.0195	0.0544	0.20	0.0192	0.0540	0.20	0.0185	0.0534
Rn_t	0.99	−0.5208	0.1111	0.99	−0.5187	0.1143	0.99	−0.5195	0.1115
Rn_{t-1}	0.23	−0.0553	0.1334	0.24	−0.0601	0.1395	0.23	−0.0554	0.1334
Rn_{t-2}	0.27	−0.0650	0.1400	0.27	−0.0658	0.1406	0.26	−0.0610	0.1354
Rn_{t-3}	0.10	0.0034	0.0435	0.10	0.0032	0.0436	0.10	0.0040	0.0453
Rn_{t-4}	0.10	−0.0030	0.0341	0.10	−0.0026	0.0346	0.09	−0.0028	0.0340
<i>const</i>	0.23	−0.1519	0.3652	0.22	−0.1503	0.3661	0.22	−0.1487	0.3626

Table 13. BACE coefficient estimates of UK inflation for different average prior model size assumptions.

Variable	E(Ξ) = K/8			E(Ξ) = K/5			E(Ξ) = K/4		
	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.
$I_{d,t}$	1.00	0.0380	0.0015	1.00	0.0380	0.0015	1.00	0.0380	0.0015
$\Delta p_{e,t}$	1.00	0.2612	0.0248	1.00	0.2612	0.0248	1.00	0.2612	0.0248
S_{t-1}	1.00	-0.9786	0.1060	1.00	-0.9786	0.1060	1.00	-0.9786	0.1060
y_{t-1}^d	1.00	0.1898	0.0381	1.00	0.1898	0.0381	1.00	0.1898	0.0381
Δp_{t-1}	1.00	0.2818	0.0352	1.00	0.2818	0.0352	1.00	0.2818	0.0352
π_{t-1}^*	0.99	-0.1674	0.0295	0.99	-0.1673	0.0295	1.00	-0.1674	0.0295
$\Delta R_{s,t-1}$	0.99	0.6896	0.1272	0.99	0.6897	0.1272	0.99	0.6896	0.1273
$\Delta p_{o,t-1}$	0.99	0.0492	0.0111	0.99	0.0492	0.0111	0.99	0.0492	0.0111
Δm_{t-1}	0.99	0.1532	0.0325	0.99	0.1532	0.0325	0.99	0.1532	0.0325
U_{t-1}^d	0.71	-0.0549	0.0443	0.71	-0.0549	0.0443	0.71	-0.0549	0.0443
n_{t-1}^d	0.20	0.0006	0.0016	0.20	0.0006	0.0016	0.20	0.0006	0.0016
$R_{l,t-1}$	0.15	0.0059	0.0216	0.15	0.0059	0.0216	0.15	0.0059	0.0217
$\Delta p_{e,t-1}$	0.12	0.0030	0.0133	0.12	0.0030	0.0133	0.12	0.0030	0.0133
Δn_{t-1}	0.12	0.0014	0.0063	0.12	0.0014	0.0063	0.12	0.0014	0.0063
<i>const</i>	0.11	0.0001	0.0007	0.11	0.0001	0.0007	0.11	0.0001	0.0007
Δw_{t-1}	0.10	-0.0001	0.0130	0.10	-0.0001	0.0130	0.10	-0.0001	0.0130
$\Delta U_{r,t-1}$	0.09	-0.0009	0.0229	0.09	-0.0009	0.0229	0.10	-0.0009	0.0229
m_{t-1}^d	0.09	-0.0001	0.0042	0.10	-0.0001	0.0042	0.09	-0.0001	0.0042
Δc_{t-1}	0.09	0.0003	0.0102	0.09	0.0003	0.0102	0.09	0.0003	0.0103
$\Delta R_{l,t-1}$	0.09	0.0011	0.0831	0.09	0.0011	0.0832	0.09	0.0011	0.0833

Table 14. BMA (with stationarity restrictions) coefficient estimates of the UKM1 model for different average prior model size assumptions.

Variable	E(Ξ) = K/8			E(Ξ) = K/5			E(Ξ) = K/4		
	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.
m_{t-1}	1.00	0.8318	0.0966	1.00	0.8292	0.0978	1.00	0.8298	0.0980
m_{t-2}	0.20	0.0356	0.0857	0.20	0.0362	0.0865	0.20	0.0364	0.0863
m_{t-3}	0.06	-0.0011	0.0287	0.07	-0.0014	0.0291	0.06	-0.0013	0.0287
m_{t-4}	0.15	0.0178	0.0550	0.16	0.0196	0.0572	0.16	0.0190	0.0570
p_t	0.64	0.1069	0.1170	0.65	0.1090	0.1178	0.65	0.1091	0.1184
p_{t-1}	0.33	0.0556	0.1450	0.33	0.0553	0.1483	0.33	0.0529	0.1455
p_{t-2}	0.20	-0.0279	0.1233	0.20	-0.0286	0.1254	0.20	-0.0275	0.1245
p_{t-3}	0.15	-0.0216	0.0789	0.15	-0.0223	0.0797	0.15	-0.0211	0.0783
p_{t-4}	0.11	-0.0083	0.0447	0.10	-0.0082	0.0449	0.10	-0.0085	0.0442
y_t	0.18	0.0173	0.0498	0.21	0.0199	0.0526	0.19	0.0178	0.0505
y_{t-1}	0.60	0.0911	0.0951	0.59	0.0906	0.0953	0.59	0.0907	0.0952
y_{t-2}	0.13	-0.0074	0.0585	0.13	-0.0072	0.0592	0.14	-0.0069	0.0594
y_{t-3}	0.12	0.0041	0.0396	0.11	0.0034	0.0377	0.10	0.0030	0.0363
y_{t-4}	0.19	0.0191	0.0497	0.17	0.0176	0.0478	0.19	0.0200	0.0505
Rn_t	1.00	-0.5090	0.0925	1.00	-0.5081	0.0944	1.00	-0.5080	0.0945
Rn_{t-1}	0.09	-0.0173	0.0758	0.10	-0.0199	0.0829	0.10	-0.0192	0.0822
Rn_{t-2}	0.11	-0.0212	0.0823	0.12	-0.0220	0.0837	0.12	-0.0224	0.0846
Rn_{t-3}	0.05	0.0012	0.0274	0.05	0.0014	0.0276	0.05	0.0016	0.0287
Rn_{t-4}	0.06	-0.0030	0.0267	0.06	-0.0026	0.0256	0.07	-0.0033	0.0278
<i>const</i>	0.14	-0.0985	0.3076	0.14	-0.0934	0.2985	0.14	-0.0998	0.3097

Table 15. BMA (with stationarity restrictions) coefficient estimates of UK inflation for different average prior model size assumptions.

Variable	E(Ξ) = K/8			E(Ξ) = K/5			E(Ξ) = K/4		
	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.
$I_{d,t}$	1.00	0.0379	0.0014	1.00	0.0379	0.0014	1.00	0.0379	0.0014
$\Delta p_{e,t}$	1.00	0.2617	0.0238	1.00	0.1879	0.0354	1.00	0.1879	0.0354
S_{t-1}	1.00	-0.9687	0.1024	1.00	-0.9686	0.1024	1.00	-0.9685	0.1024
y_{t-1}^d	1.00	0.1877	0.0353	1.00	0.2617	0.0238	1.00	0.2617	0.0238
Δp_{t-1}	1.00	0.2797	0.0324	1.00	0.2796	0.0324	1.00	0.2794	0.0324
π_{t-1}^*	1.00	-0.1685	0.0280	1.00	-0.1687	0.0281	1.00	-0.1687	0.0281
$\Delta R_{s,t-1}$	0.99	0.6893	0.1196	0.99	0.6889	0.1201	0.99	0.6889	0.1198
$\Delta p_{o,t-1}$	0.99	0.0490	0.0106	0.99	0.1577	0.0308	0.99	0.1577	0.0308
Δm_{t-1}	0.99	0.1575	0.0310	0.99	0.0489	0.0107	0.99	0.0489	0.0106
U_{t-1}^d	0.59	-0.0465	0.0449	0.59	-0.0463	0.0449	0.59	-0.0460	0.0449
n_{t-1}^d	0.12	0.0004	0.0013	0.12	0.0004	0.0013	0.12	0.0004	0.0013
$R_{l,t-1}$	0.10	0.0042	0.0176	0.09	0.0039	0.0171	0.09	0.0040	0.0172
$\Delta p_{e,t-1}$	0.07	0.0016	0.0096	0.07	0.0017	0.0097	0.07	0.0017	0.0097
Δn_{t-1}	0.06	0.0008	0.0045	0.07	0.0008	0.0047	0.07	0.0008	0.0047
<i>const</i>	0.07	0.0001	0.0005	0.07	0.0001	0.0006	0.07	0.0001	0.0006
Δw_{t-1}	0.05	0.0001	0.0086	0.05	-0.0003	0.0165	0.05	-0.0001	0.0163
$\Delta U_{r,t-1}$	0.06	-0.0003	0.0167	0.05	0.0002	0.0070	0.06	0.0001	0.0092
m_{t-1}^d	0.05	<0.0000	0.0028	0.05	0.0001	0.0085	0.05	<0.0000	0.0028
Δc_{t-1}	0.05	0.0002	0.0068	0.05	0.0022	0.0619	0.05	0.0023	0.0611
$\Delta R_{l,t-1}$	0.05	0.0016	0.0591	0.05	<0.0001	0.0029	0.05	0.0002	0.0069

Table 16. BMA (without stationarity restrictions) coefficient estimates of the UKM1 model for different average prior model size assumptions.

Variable	E(Ξ) = K/8			E(Ξ) = K/5			E(Ξ) = K/4		
	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.
m_{t-1}	1.00	0.8320	0.0982	1.00	0.8332	0.0973	1.00	0.8315	0.0982
m_{t-2}	0.20	0.0360	0.0861	0.20	0.0363	0.0865	0.21	0.0374	0.0875
m_{t-3}	0.06	-0.0013	0.0281	0.07	-0.0014	0.0292	0.06	-0.0013	0.0277
m_{t-4}	0.16	0.0193	0.0573	0.15	0.0175	0.0545	0.15	0.0181	0.0554
p_t	0.64	0.1102	0.1203	0.65	0.1089	0.1180	0.65	0.1112	0.1202
p_{t-1}	0.33	0.0547	0.1486	0.33	0.0521	0.1451	0.33	0.0523	0.1472
p_{t-2}	0.20	-0.0286	0.1258	0.18	-0.0247	0.1176	0.20	-0.0264	0.1243
p_{t-3}	0.16	-0.0231	0.0809	0.16	-0.0229	0.0806	0.17	-0.0240	0.0849
p_{t-4}	0.11	-0.0098	0.0477	0.11	-0.0097	0.0473	0.11	-0.0093	0.0482
y_t	0.20	0.0191	0.0517	0.20	0.0195	0.0522	0.20	0.0189	0.0514
y_{t-1}	0.56	0.0857	0.0945	0.57	0.0880	0.0956	0.57	0.0873	0.0952
y_{t-2}	0.13	-0.0066	0.0575	0.14	-0.0070	0.0591	0.13	-0.0071	0.0591
y_{t-3}	0.11	0.0039	0.0376	0.11	0.0030	0.0377	0.11	0.0030	0.0371
y_{t-4}	0.20	0.0205	0.0511	0.19	0.0191	0.0493	0.20	0.0199	0.0500
Rn_t	1.00	-0.5099	0.0926	1.00	-0.5087	0.0936	1.00	-0.5089	0.0960
Rn_{t-1}	0.09	-0.0177	0.0773	0.09	-0.0181	0.0792	0.09	-0.0186	0.0814
Rn_{t-2}	0.11	-0.0221	0.0848	0.10	-0.0192	0.0790	0.11	-0.0210	0.0821
Rn_{t-3}	0.05	0.0013	0.0265	0.06	0.0015	0.0287	0.06	0.0016	0.0299
Rn_{t-4}	0.06	-0.0029	0.0267	0.06	-0.0028	0.0258	0.06	-0.0031	0.0268
<i>const</i>	0.14	-0.0996	0.3097	0.14	-0.0956	0.3035	0.13	-0.0898	0.2958

Table 17. BMA (without stationarity restrictions) coefficient estimates of UK inflation for different average prior model size assumptions.

Variable	E(Ξ) = K/8			E(Ξ) = K/5			E(Ξ) = K/4		
	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.	PIP	Avg. Mean	Avg. Std. Dev.
$I_{d,t}$	1.00	0.0379	0.0014	1.00	0.0379	0.0014	1.00	0.0379	0.0014
$\Delta p_{e,t}$	1.00	0.2617	0.0238	1.00	0.1879	0.0354	1.00	0.1879	0.0354
S_{t-1}	1.00	-0.9687	0.1024	1.00	-0.9686	0.1024	1.00	-0.9685	0.1024
y_{t-1}^d	1.00	0.1877	0.0353	1.00	0.2617	0.0238	1.00	0.2617	0.0238
Δp_{t-1}	1.00	0.2797	0.0324	1.00	0.2796	0.0324	1.00	0.2794	0.0324
π_{t-1}^*	1.00	-0.1685	0.0280	1.00	-0.1687	0.0281	1.00	-0.1687	0.0281
$\Delta R_{s,t-1}$	0.99	0.6893	0.1196	0.99	0.6889	0.1201	0.99	0.6889	0.1198
$\Delta p_{o,t-1}$	0.99	0.0490	0.0106	0.99	0.1577	0.0308	0.99	0.1577	0.0308
Δm_{t-1}	0.99	0.1575	0.0310	0.99	0.0489	0.0107	0.99	0.0489	0.0106
U_{t-1}^d	0.59	-0.0465	0.0449	0.59	-0.0463	0.0449	0.59	-0.0460	0.0449
n_{t-1}^d	0.12	0.0004	0.0013	0.12	0.0004	0.0013	0.12	0.0004	0.0013
$R_{l,t-1}$	0.10	0.0042	0.0176	0.09	0.0039	0.0171	0.09	0.0040	0.0172
$\Delta p_{e,t-1}$	0.07	0.0016	0.0096	0.07	0.0017	0.0097	0.07	0.0017	0.0097
Δn_{t-1}	0.06	0.0008	0.0045	0.07	0.0008	0.0047	0.07	0.0008	0.0047
<i>const</i>	0.07	0.0001	0.0005	0.07	0.0001	0.0006	0.07	0.0001	0.0006
Δw_{t-1}	0.05	0.0001	0.0086	0.05	-0.0003	0.0165	0.05	-0.0001	0.0163
$\Delta U_{r,t-1}$	0.06	-0.0003	0.0167	0.05	0.0002	0.0070	0.06	0.0001	0.0092
m_{t-1}^d	0.05	<0.0000	0.0028	0.05	0.0001	0.0085	0.05	<0.0000	0.0028
Δc_{t-1}	0.05	0.0002	0.0068	0.05	0.0022	0.0619	0.05	0.0023	0.0611
$\Delta R_{l,t-1}$	0.05	0.0016	0.0591	0.05	<0.0001	0.0029	0.05	0.0002	0.0069

6.2. BACE and BMA Run Times

Tables 18–20 present computational timings¹² of BACE and BMA analysis conducted in two general variants, with and without forecasting, for two earlier considered empirical examples, i.e., UKM1 and inflation. In the case of BACE analysis, total number of iterations in MC³ sampling algorithm equals 500,000, while for BMA is 150,000. The difference in the total number of MC³ iterations in BACE and BMA gretl packages is related with different ways of employing MPI parallel computations, which results in different pace of convergence.

Table 18. Run times of BACE gretl package.

CPUs	UKM1				UK Inflation			
	without Forecasts		with Forecasts		without Forecasts		with Forecasts	
	Nrep	Run Time	Nrep	Run Time	Nrep	Run Time	Nrep	Run Time
1	5×10^5	147	5×10^5	169	5×10^5	112	5×10^5	128
4	5×10^5	128	5×10^5	143	5×10^5	49	5×10^5	54
20	5×10^5	23	5×10^5	28	5×10^5	15	5×10^5	17

CPUs denotes the total number of processors used in simulation experiment, Nrep means the total number of iterations in MC³ sampling algorithm, and Run time denotes computational time (in seconds).

Increasing the number of CPUs decreases run times of both packages more or less linearly. The highest boost is in the case of BACE for UKM1 with almost equal ratio. Both packages slow down in forecasting, but again with different ratios. In case of BACE, timings of simulations increase approximately by 10–20%, no matter how many CPUs are used. In the case of BMA, run times

¹² All computations were performed on so-called haave1mo machine (located at Dipartimento di Scienze Economiche e Sociali (DiSES), Ancona, Italy) which consists on 20 Hyper-Threaded Intel[®] Xeon[®] CPU E5-2640 v4 @ 2.40GHz with 256 GB operational memory running under Debian GNU/Linux 64 bits.

are multiply by a factor ranging from 12.64 to 26.07 for restricted case and from 32.33 to 825.29 for unrestricted case. Such a big increase of computational timings is related with necessity of generating predictive distributions step-by-step in order to compute dynamic forecasts. Longer run times for BMA are also related with stationarity restrictions for autoregressive parameters. We believe that in the future we will be able to improve speed of BMA computations.

Table 19. Run times of BMA gretl package (with stationary restrictions).

CPUs	UKM1				UK Inflation			
	without Forecasts		with Forecasts		without Forecasts		with Forecasts	
	Nrep	Run Time						
1	1.5×10^5	10,554	1.5×10^5	275,165	1.5×10^5	1457	1.5×10^5	35,996
4	1.5×10^5	2470	1.5×10^5	56,294	1.5×10^5	380	1.5×10^5	6829
20	1.5×10^5	1169	1.5×10^5	14,771	1.5×10^5	136	1.5×10^5	3044

CPUs denotes the total number of processors used in simulation experiment, Nrep means the total number of iterations in MC³ sampling algorithm and Run time denotes computational time (in seconds).

Table 20. Run times of BMA gretl package (without stationary restrictions).

CPUs	UKM1				UK Inflation			
	without Forecasts		with forecasts		without Forecasts		with Forecasts	
	Nrep	Run Time						
1	1.5×10^5	353	1.5×10^5	291,328	1.5×10^5	81	1.5×10^5	32,095
4	1.5×10^5	167	1.5×10^5	65,862	1.5×10^5	54	1.5×10^5	6556
20	1.5×10^5	103	1.5×10^5	16,630	1.5×10^5	55	1.5×10^5	1778

CPUs denotes the total number of processors used in simulation experiment, Nrep means the total number of iterations in MC³ sampling algorithm, and Run time denotes computational time (in seconds).

7. Conclusions

In this paper, we discussed the possibility of using the model averaging methods—BACE and BMA as a tool for selecting variables and forecasting in dynamic econometric modeling. Empirical examples with known, non-trivial macroeconomic models confirmed that the BACE and BMA procedures, by calculating a PIP value for each independent variable, correctly indicates the determinants of the dependent process. Robustness analysis results confirm the stability of variable selection in our examples.

Moreover, the BACE and BMA take into account model uncertainty and generates reasonably close or more accurate forecasts compared with Autometrics or median probability model. The UK inflation forecasts generated by BACE, BMA, and Autometrics have similar RMSE and MAPE values, but the demand for narrow money forecasts generated by BACE and BMA have several times smaller errors than those generated by Autometrics. A similar conclusion also applies to median probability models. Forecasts generated by simple averaging of all predictive models can provide better results than forecasts from single models. This advantage over the non-pooling inference is particularly evident when there is no one dominant model but rather many competing specifications with relatively low explanatory power.

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Abbreviations

The following abbreviations are used in this manuscript:

ADL	Autoregressive Distributed Lag
BACE	Bayesian Averaging of Classical Estimates
BMA	Bayesian Model Averaging
DGP	Data Generating Process
GDP	Gross Domestic Product
GUI	Graphical User Interface
GUM	General Unrestricted Model
LDGP	Local Data Generating Process
MAPE	Mean Absolute Percentage Error
MPI	Message Passing Interface
MC ³	Markov Chain Monte Carlo Model Composition
RMSE	Root-Mean-Square Error
TFE	Total Final Expenditure
UKM1	Model for M1 Money Demand in UK

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