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Mathematical Analysis of an Anthroponotic Cutaneous Leishmaniasis Model with Asymptomatic Infection

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Abstract: This work aims mainly to study the impact of experiencing asymptomatic anthroponotic cutaneous leishmaniasis (ACL) infection on the overall dynamics and outcomes of the disease. Therefore, a deterministic model for the transmission dynamics of ACL of type SEAIS in the human host and SI in sandfly populations is proposed and mathematically analyzed. The model is shown to be well-posed. Its equilibrium and stability analyses are shown. The equilibrium analysis shows that the model has an ACL-free equilibrium that is proven to be locally and globally asymptotically stable if and only if $\mathcal{R}_0 < 1$. In addition, the model has a unique ACL-endemic equilibrium that is shown to exist and be locally asymptotically stable if and only if $\mathcal{R}_0 > 1$. Numerical simulations are performed to show the asymptotic stability of these equilibriums. In addition, the effect of ignoring asymptomatic infections is studied and the analysis shows that ignoring the development of asymptomatic infections overestimates the effort required to eliminate the infection. Moreover, it implies inaccurate measures of controlling ACL infection, especially those based on either using insecticide sprays or bednets.

Keywords: anthroponotic cutaneous leishmaniasis; asymptomatic infection; SEAIS endemic model; equilibriums; basic reproduction number; stability analysis

MSC: 92D25; 92D30; 92B99

1. Introduction

Cutaneous leishmaniasis (CL) is a neglected vector-borne disease spread in tropical and subtropical regions. It is spread mainly through the bite of an infected female sandfly while taking its meal from the definitive host. Although there has been a successful reduction in its burden, CL disease remains a public health challenge, as it is endemic in about ninety countries worldwide [1]. It is estimated that the yearly global incidence of CL ranges from 0.6 million to one million cases. Throughout the last decade, the disease has had various emerging outbreaks in different parts of the world [2]. Most of the cases occur in the Americas, the Mediterranean basin, the Middle East, and Central Asia [3]. Even in some countries, where CL is endemic, the disease is focused in certain parts/regions of them [4]. CL could either be anthroponotic (referred to by ACL) or zoonotic (referred to by ZCL). Both types have different clinical features, diverse epidemiological characteristics, and different etiological agents. For example, the main etiological agent of ZCL is Leishmania major, while that of ACL is Leishmania tropica [5]. In this work, we are interested in studying the spread dynamics of ACL, with an approach based on the use of a deterministic differential equations model on the population level.

Various studies have been published to increase knowledge on the transmissibility and controllability of leishmaniasis diseases. For example, Zhao et al. [6] developed and analyzed a mathematical model of type SEIHR in humans, SEI in sandflies, and SEIR in dogs to study the dynamics of zoonotic visceral leishmaniasis (ZVL) in Brazil. However,

Bi et al. [7] extended the SEIR -SEI-SEIHR zoonotic visceral leishmaniasis model to include age structure (i.e., partial differential equation model) in the human host. Other mathematical modeling studies on visceral leishmaniasis include the works of Barley et al. [8], Hussaini et al. [9], Kaabi and Zhioua [10], and those considered in the review article of Rock et al. [11].

Mathematical models have been used to study the transmission dynamics of cutaneous leishmaniasis too. For example, Chaves and Hernandez [12] introduced and analyzed a mathematical model for the spread of American cutaneous leishmaniasis. The authors presented and analyzed an SIS model in three populations (humans, reservoir, and sandfly populations) and obtained expressions that allow computing threshold conditions for the persistence of the infection. However, Bacaêr and Guernaoui [13] developed a mathematical model that considers the vector population's seasonality and the distribution of the latent period from infection to symptoms in humans. In addition, Barradas and Caja Rivera [14] introduced and analyzed a vector–host model (of type SIR in humans and SEI in the vector populations) for describing the dynamics of vector-borne diseases, with special application to the case of cutaneous leishmaniasis in Peru. Zamir et al. [15] presented a mathematical model of type SEIR in humans and SEI in the vector to describe the dynamics of ACL. The authors found the basic reproduction number of the model and analyzed its sensitive dependence on the model parameters. Then, they introduced some control parameters in the basic model and found the optimal control, taking into account the lowest cost. Other studies include those published by De Almeida et al. [16], Agyingi et al. [17], Biswas et al. [18], and the references therein.

The life cycle of ACL has two stages, namely, the human stage and the sandfly stage. Briefly, susceptible sandflies become infected when they bite a CL-infected human to feed on his/her blood. However, susceptible humans acquire ACL infection while an infected female sandfly takes its meal from a susceptible human. It is worth mentioning that humans acquire the infection and become latent, where they neither transmit the infection nor show symptoms of ACL. Those latent individuals may develop symptoms and become infected where they can transmit the infection to susceptible sandflies. However, it is evident that some people have a silent ACL infection, without any symptoms or signs [19]. Humans who develop clinical evidence of ACL infection have at least one sore on their skin. The ACL sores usually develop within a few weeks or months of the sandfly bite. They usually heal on their own, even without treatment, but they may last for months or even years. However, humans may acquire ACL infection more than once. Therefore, a mathematical model of type SEIS (susceptible–exposed–infected–susceptible) in humans would be appropriate to develop and use in describing ACL transmission dynamics.

In this work, we extend the previous works and take into account both the asymptomatic infections and the repeated infections, in the sense that human individuals may acquire the ACL infection more than once. Therefore, we introduce a model of type SEAIS in the human population. As the life expectancy of sandflies is very short compared to that of humans, we assume an SI model for the sandfly population. The model is described and formulated in Section 2. In Section 3, the equilibrium analysis is shown and the basic reproduction number is computed. The local stability of the equilibriums is established in Section 4. In Section 5, numerical simulations for the model with randomly selected initial conditions are used to numerically show the global stability of the equilibriums. The impact of ignoring the asymptomatic infection on ACL disease outcomes is shown in Section 6. A summary and conclusion are given in Section 7.

2. Model Formulation and Its Basic Properties

As we model the anthroponotic cutaneous leishmaniasis, we consider both human and sandfly populations. The total human population is split into four mutually independent categories: susceptible, exposed, asymptomatic infected, and symptomatic infected individuals. Their size at time t is denoted by $S_h(t)$, $E_h(t)$, $A_h(t)$, and $I_h(t)$, respectively. However, the sandfly population is subdivided into susceptible (with size $S_v(t)$) and infected (with

size $I_v(t)$) sandflies. Susceptible humans are assumed to recruit at the rate Λ_h and die naturally at the rate μ_h. They acquire CL infection, and become exposed, due to being bitten by infected sandflies at the infection rate $\lambda_{vh}(t)$, where

$$\lambda_{vh}(t) = \beta \times b_{vh} \times \frac{I_v}{N_h}.$$

Exposed humans are not capable of transmitting CL infection to susceptible sandflies, but they are assumed to leave their exposed status either by natural death at the rate μ_h or developing CL infection status at rate α, where it is assumed that a proportion q of them become asymptomatic, while the other proportion $(1 - q)$ develop symptoms and become symptomatic infected. Both asymptomatic and symptomatic infected individuals are assumed to die naturally at the rate μ_h and recover with temporal immunity at the rate γ_h.

The sandfly population is assumed to be recruited (susceptible) at the rate Λ_v and die naturally at the rate μ_v. Susceptible sandflies acquire CL infection at a rate λ_{hv} and become infected while taking their meals from either or both the symptomatic and asymptomatic infected humans, where

$$\lambda_{hv} = \beta \times b_{hv} \times \frac{(I_h + rA_h)}{N_h}.$$

A schematic diagram for the transition and interaction between the various model states is shown in Figure 1, while the physical meaning of the model states and parameters is summarized in Table 1.

Figure 1. A schematic diagram for the interaction and transition between the various states of model (1).

Table 1. Description of state variables and parameters for model (1).

State Variables and Parameters	Description
S_h	Number of susceptible humans at time t.
E_h	Number of exposed humans in the latent period at time t.
A_h	Number of asymptomatic humans (infected but without noticeable disease and infectious) at time t.
I_h	Number of infected humans at time t.
S_v	Number of susceptible sandflies at time t.
I_v	Number of infectious sandflies at time t.
N_h	Total human population size at time t.
N_v	Total sandflies population size at time t.
Λ_h	Recruitment rate of humans.
Λ_v	Recruitment rate of sandflies.
μ_h	Natural death rate of humans.
μ_v	Natural death rate of sandflies.
γ_h	Recovery rate (with temporal immunity) from symptomatic/asymptomatic cutaneous Leishmaniasis (CL) infection.
α	The rate at which human individuals leave the exposed state.
β	The rate at which sandflies bite the body of human individuals.
q	The probability that an exposed human develops asymptomatic CL infection after leaving the incubation period.
r	The relative transmissibility of asymptomatic with respect to symptomatic CL infection.
b_{hv}	The probability at which a susceptible sandfly acquires CL infection while taking its meal from a CL-infected human.
b_{vh}	The probability at which a susceptible human acquires CL infection while being bitten by a CL-infected sandfly.

The mathematical representation of the model is given by

$$
\begin{aligned}
\frac{dS_h}{dt} &= \Lambda_h - \frac{\beta b_{vh} I_v S_h}{N_h} - \mu_h S_h + \gamma_h (A_h + I_h), \\
\frac{dE_h}{dt} &= \frac{\beta b_{vh} I_v S_h}{N_h} - (\alpha + \mu_h) E_h, \\
\frac{dA_h}{dt} &= q\alpha E_h - (\mu_h + \gamma_h) A_h, \\
\frac{dI_h}{dt} &= (1-q)\alpha E_h - (\mu_h + \gamma_h) I_h, \\
\frac{dS_v}{dt} &= \Lambda_v - \frac{\beta b_{hv}(I_h + rA_h) S_v}{N_h} - \mu_v S_v, \\
\frac{dI_v}{dt} &= \frac{\beta b_{hv}(I_h + rA_h) S_v}{N_h} - \mu_v I_v
\end{aligned}
\tag{1}
$$

so that all parameters are positive and as defined in Table 2. As $N_h = S_h + E_h + A_h + I_h$ and $N_v = S_v + I_v$, then by adding the first four equations of (1), we obtain the following equation:

$$
\frac{dN_h}{dt} = \Lambda_h - \mu_h N_h.
\tag{2}
$$

Its solution is

$$
N_h(t) = \frac{\Lambda_h}{\mu_h} + \left(N_h(0) - \frac{\Lambda_h}{\mu_h}\right) e^{-\mu_h t}.
\tag{3}
$$

Similarly, we add the last two equations of (1) to obtain the following equation:

$$
\frac{dN_v}{dt} = \Lambda_v - \mu_v N_v
\tag{4}
$$

which has the solution

$$N_v(t) = \frac{\Lambda_v}{\mu_v} + \left(N_v(0) - \frac{\Lambda_v}{\mu_v}\right)e^{-\mu_v t}. \tag{5}$$

Both solutions indicate that $N_h(t), N_v(t) > 0$, and when t tends to ∞, then the pair $(N_h(t), N_v(t))$ tends to $(\Lambda_h/\mu_h, \Lambda_v/\mu_v)$. Hence, the appropriate closed set Ω on which model (1) along with (2) is defined reads

$$
\begin{aligned}
\Omega &= \Omega_h \cup \Omega_v \in \mathbb{R}_+^4 \times \mathbb{R}_+^2, \\
\Omega_h &= \left\{ (S_h, E_h, A_h, I_h) \in \mathbb{R}_+^4, 0 \le S_h + E_h + A_h + I_h \le \Lambda_h/\mu_h \right\}, \\
\Omega_v &= \left\{ (S_v, I_v) \in \mathbb{R}_+^2, 0 \le S_v + I_v \le \Lambda_v/\mu_v \right\}.
\end{aligned}
\tag{6}
$$

Table 2. Model (1) parameters and their baseline and references.

Parameter	Value	Range	Unit	Reference
Λ_h	12,327	–	Per week	[20]
Λ_v	112	[35–350]	Per week	[14,21]
μ_h	$1/(75.5 \times 52)$	–	Per week	[20]
μ_v	0.0945	[0.077, 0.525]	Per week	[14,22]
γ_h	0.0006391	[0.0000791–0.004991]	Per week	[14,21]
α	0.33	[0.125, 0.5]	Per week	[23]
β	0.48146	[4.1944–18.7754]	Per week	[14,21]
q	0.1	–	Dimensionless	Assumed
r	0.3	–	Dimensionless	Assumed
b_{hv}	0.0097	[0.0028–0.08]	Dimensionless	[14,21]
b_{vh}	0.7198	[0.08–0.9]	Dimensionless	[14]

It is easy to check that the right-hand side of each equation in the model (1) is a continuous function in the model state variables. Moreover, their partial derivatives (see Appendix A) do exist and are continuous, too. Therefore, they are locally Lipschitz. Hence, any solution, of model (1), starting with initial conditions $(S_h(0), E_h(0), A_h(0), I_h(0)) \in \Omega_h$ and $(S_v(0), I_v(0)) \in \Omega_v$ is unique. Appendix B shows the proof of the following proposition on the positivity and boundedness of the solutions.

Proposition 1. *The closed set Ω is positively invariant along with* (1).

It is worth mentioning that the positive invariance property of the set Ω could be proven by applying lemma 1 of Valle et al. [24] and also by following the approach shown in more detail in section II.A of De Leenheer and Aeyels [25].

3. Equilibrium Analysis and the Basic Reproduction Number

As model (1) is nonlinear, exact time-dependent solutions are impossible to derive, but the qualitative behavior of the solutions could be studied by analyzing the equilibrium. To this end, the derivatives in the left-hand side of (1) are set equal to zero and we solve the remaining nonlinear algebraic system in the state variables. At equilibrium, the A_h and I_h equations in (1) imply that

$$A_h = \frac{q\alpha E_h}{(\mu_h + \gamma_h)}, \tag{7}$$

$$I_h = \frac{(1-q)\alpha E_h}{(\mu_h + \gamma_h)}. \tag{8}$$

Hence,

$$I_h + rA_h = \frac{[(1-q) + rq]\alpha E_h}{(\mu_h + \gamma_h)}. \tag{9}$$

However, the equilibrium I_v equation in (1) implies that

$$I_h + rA_h = \frac{\mu_v I_v N_h}{\beta b_{hv} S_v}. \tag{10}$$

Hence, from (9) and (10), we obtain

$$\frac{[(1-q) + rq]\alpha E_h}{(\mu_h + \gamma_h)} - \frac{\mu_v I_v N_h}{\beta b_{hv} S_v} = 0. \tag{11}$$

The equilibrium E_h equation in (1) could be rewritten as

$$I_v = \frac{N_h(\alpha + \mu_h)E_h}{\beta b_{vh} S_h}. \tag{12}$$

Substituting from (12) into (11), we obtain

$$\left(\frac{((1-q) + rq)\alpha}{(\mu_h + \gamma_h)} - \frac{N_h^2 \mu_v(\alpha + \mu_h)}{\beta^2 b_{hv} b_{vh} S_h S_v} \right) E_h = 0. \tag{13}$$

3.1. CL-Free Equilibrium

If $E_h = 0$, then Equations (7), (8) and (12) imply that A_h, I_h, and $I_v = 0$, respectively. Therefore, the equilibrium S_h and S_v equations in (1) imply that $S_h = \frac{\Lambda_h}{\mu_h}$ and $S_v = \frac{\Lambda_v}{\mu_v}$. Thus, the CL-free equilibrium reads

$$E_0 = \left(S_h^0, E_h^0, A_h^0, I_h^0, S_v^0, I_v^0 \right)^T = \left(\frac{\Lambda_h}{\mu_h}, 0, 0, 0, \frac{\Lambda_v}{\mu_v}, 0 \right)^T \tag{14}$$

where the prime $(^T)$ denotes vector-transpose. Hence, we have the following proposition.

Proposition 2. *Model* (1) *has a cutaneous-Leishmaniasis-free equilibrium E_0, given by* (14).

3.2. The Basic Reproduction Number

The basic reproduction number is computed by following the general approach shown in van den Driessche and Watmough [26]. We first determine the vector matrices of new incidences $\mathcal{F}$ and transfer terms $\mathcal{V}$ from the four equations of infected humans and sandflies (i.e., E_h, A_h, I_h, and I_v equations), as

$$\mathcal{F} = \begin{pmatrix} \frac{\beta b_{vh} I_v S_h}{N_h} \\ 0 \\ 0 \\ \frac{\beta b_{hv}(I_h + rA_h)S_v}{N_h} \end{pmatrix} \quad \text{and} \quad \mathcal{V} = \begin{pmatrix} (\alpha + \mu_h)E_h \\ (\mu_h + \gamma_h)A_h - q\alpha E_h \\ (\mu_h + \gamma_h)I_h - (1-q)\alpha E_h \\ \mu_v I_v \end{pmatrix}.$$

Then, the new-infection terms matrix F and the remaining transfer terms matrix V are obtained by, respectively, computing the Jacobian matrices of both $\mathcal{F}$ and $\mathcal{V}$ (with respect to the state variable of infected terms E_h, A_h, I_h, and I_v) evaluated at the CL-free equilibrium E_0 as

$$
F = \begin{pmatrix} 0 & 0 & 0 & \beta b_{vh} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & \dfrac{\beta b_{hv} r \Lambda_v \mu_h}{\Lambda_h \mu_v} & \dfrac{\beta b_{hv} \Lambda_v \mu_h}{\Lambda_h \mu_v} & 0 \end{pmatrix} \quad \text{and} \quad V = \begin{pmatrix} \alpha + \mu_h & 0 & 0 & 0 \\ -q\alpha & \mu_h + \gamma_h & 0 & 0 \\ (1-q)\alpha & 0 & \mu_h + \gamma_h & 0 \\ 0 & 0 & 0 & \mu_v \end{pmatrix}.
$$

Hence, the basic reproduction number $\mathcal{R}_0$ is the dominant eigenvalue of the next generation matrix FV^{-1} and is given by

$$
\mathcal{R}_0 = \sqrt{\frac{\beta b_{vh}}{\mu_v} \times \frac{\beta b_{hv}}{\gamma_h + \mu_h} \times \frac{\alpha}{\alpha + \mu_h} \times \frac{\Lambda_v/\mu_v}{\Lambda_h/\mu_h} \times \left(1 - (1-r)q\right)}. \tag{15}
$$

In summary, we show the following proposition.

Proposition 3. *The basic reproduction number $\mathcal{R}_0$ of model (1) is given by Formula (15).*

3.3. Endemic Equilibrium

If $E_h \neq 0$, then Equation (13) implies that

$$
S_v = \frac{N_h^2 \mu_v (\alpha + \mu_h)(\mu_h + \gamma_h)}{\beta^2 b_{hv} b_{vh}[(1-q) + rq]\alpha S_h}. \tag{16}
$$

It is worth mentioning that, throughout the rest of the current subsection, N_h denotes the human population size at equilibrium and equals Λ_h/μ_h. By substituting Equation (12) into the equilibrium S_h-equation in (1), we obtain

$$
0 = \Lambda_h - (\alpha + \mu_h)E_h - \mu_h S_h + \gamma_h(A_h + I_h). \tag{17}
$$

Now, we use (7) and (8) in (17) and simplify to obtain

$$
E_h = \frac{(\Lambda_h - \mu_h S_h)(\mu_h + \gamma_h)}{\mu_h(\alpha + \mu_h + \gamma_h)}. \tag{18}
$$

In addition, using (10) and (16) in the equilibrium S_v-equation in (1), we obtain

$$
\Lambda_v = \mu_v I_v + \frac{\mu_v^2 N_h^2(\alpha + \mu_h)(\mu_h + \gamma_h)}{\beta^2 b_{hv} b_{vh}[(1-q) + rq]\alpha S_h}. \tag{19}
$$

Omitting I_v between (19) and (10) implies that

$$
\Lambda_v = \frac{\mu_v N_h(\alpha + \mu_h)E_h}{\beta b_{vh} S_h} + \frac{\mu_v^2 N_h^2(\alpha + \mu_h)(\mu_h + \gamma_h)}{\beta^2 b_{hv} b_{vh}[(1-q) + rq]\alpha S_h}. \tag{20}
$$

Upon substituting from (18) in (20), we obtain

$$
\Lambda_v = \frac{\mu_v N_h(\alpha + \mu_h)}{\beta b_{vh} S_h} \times \frac{(\Lambda_h - \mu_h S_h)(\mu_h + \gamma_h)}{\mu_h(\alpha + \mu_h + \gamma_h)} + \frac{\mu_v^2 N_h^2(\alpha + \mu_h)(\mu_h + \gamma_h)}{\beta^2 b_{hv} b_{vh}[(1-q) + rq]\alpha S_h}. \tag{21}
$$

Now, we extract S_h to obtain

$$
S_h = \frac{N_h \mu_v(\alpha + \mu_h)(\mu_h + \gamma_h)\kappa}{\beta b_{hv}\alpha[(1-q) + rq]\zeta} \tag{22}
$$

where

$$
\begin{aligned}
\kappa &= \Lambda_h \beta b_{hv}[(1-q) + rq]\alpha + \mu_v \mu_h N_h(\alpha + \mu_h + \gamma_h), \\
\zeta &= \Lambda_v \beta b_{vh} \mu_h(\alpha + \mu_h + \gamma_h) + \mu_v \mu_h N_h(\alpha + \mu_h)(\mu_h + \gamma_h).
\end{aligned}
$$

Upon using (22) in (16) and (18), we obtain

$$
S_v = \frac{N_h \zeta}{\beta b_{vh} \kappa}, \tag{23}
$$

$$
E_h = \frac{(\mu_h + \gamma_h)\tau}{\beta b_{hv} \alpha[(1-q) + rq]\zeta}. \tag{24}
$$

where

$$
\tau = \Lambda_h \Lambda_v \beta^2 b_{hv} b_{vh} \alpha[(1-q) + rq] - N_h^2 \mu_v^2 \mu_h(\alpha + \mu_h)(\mu_h + \gamma_h).
$$

In addition, we use (24) in (8) and (7) to obtain

$$
I_h = \frac{(1-q)\tau}{\beta b_{hv}[(1-q) + rq]\zeta} \quad \text{and} \quad A_h = \frac{q\tau}{\beta b_{hv}[(1-q) + rq]\zeta}. \tag{25}
$$

From inserting (22) and (24) into (12) we obtain

$$
I_v = \frac{\tau}{\beta b_{vh} \mu_v \kappa}. \tag{26}
$$

Hence, the endemic equilibrium is

$$
E_e = \left(S_h^e, E_h^e, A_h^e, I_h^e, S_v^e, I_v^e \right)^T \tag{27}
$$

where

$$
\begin{aligned}
S_h^e &= \frac{N_h \mu_v(\alpha + \mu_h)(\mu_h + \gamma_h)\kappa}{\beta b_{hv} \alpha[(1-q) + rq]\zeta}, & E_h^e &= \frac{(\mu_h + \gamma_h)\tau}{\beta b_{hv} \alpha[(1-q) + rq]\zeta}, \\
A_h^e &= \frac{q\tau}{\beta b_{hv}[(1-q) + rq]\zeta}, & I_h^e &= \frac{(1-q)\tau}{\beta b_{hv}[(1-q) + rq]\zeta}, \\
S_v^e &= \frac{N_h \zeta}{\beta b_{vh} \kappa}, & I_v^e &= \frac{\tau}{\beta b_{vh} \mu_v \kappa}.
\end{aligned} \tag{28}
$$

It is noteworthy that $\kappa > 0, \zeta > 0$, while $\tau > 0$ if and only if $\mathcal{R}_0 > 1$. Therefore, we summarize the above result in the following proposition.

Proposition 4. *Model* (1) *has a unique endemic equilibrium, given by* (27)*, that exists if and only if the basic reproduction number* $\mathcal{R}_0 > 1$.

4. Local Stability Analysis

The local stability analysis of the equilibrium points is established based on the linearization approach (Lyapunov's first method). Rather than considering model (1), we replace S_h and S_v equations with those of N_h and N_v, respectively, and substitute $S_h = N_h - (E_h + A_h + I_h)$ and $S_v = N_v - I_v$ to obtain

$$\frac{dN_h}{dt} = \Lambda_h - \mu_h N_h,$$

$$\frac{dE_h}{dt} = \beta b_{vh} I_v \left(1 - \frac{E_h + A_h + I_h}{N_h}\right) - (\alpha + \mu_h) E_h,$$

$$\frac{dA_h}{dt} = q\alpha E_h - (\mu_h + \gamma_h) A_h,$$

$$\frac{dI_h}{dt} = (1-q)\alpha E_h - (\mu_h + \gamma_h) I_h, \tag{29}$$

$$\frac{dN_v}{dt} = \Lambda_v - \mu_v N_v,$$

$$\frac{dI_v}{dt} = \frac{\beta b_{hv}(I_h + r A_h)}{N_h}(N_v - I_v) - \mu_v I_v.$$

Model (29) has generally the Jacobian matrix

$$J = \begin{pmatrix}
-\mu_h & 0 & 0 & 0 & 0 & 0 \\
J_{21} & J_{22} & -\dfrac{\beta b_{vh} I_v}{N_h} & -\dfrac{\beta b_{vh} I_v}{N_h} & 0 & \dfrac{\beta b_{vh} S_h}{N_h} \\
0 & q\alpha & -(\mu_h + \gamma_h) & 0 & 0 & 0 \\
0 & (1-q)\alpha & 0 & -(\mu_h + \gamma_h) & 0 & 0 \\
0 & 0 & 0 & 0 & -\mu_v & 0 \\
J_{61} & 0 & \dfrac{r\beta b_{hv} S_v}{N_h} & \dfrac{\beta b_{hv} S_v}{N_h} & J_{65} & \dfrac{-\beta b_{hv}(I_h + r A_h)}{N_h} - \mu_v
\end{pmatrix} \tag{30}$$

where

$$J_{21} = \frac{\beta b_{vh} I_v(E_h + A_h + I_h)}{N_h^2}, \qquad J_{22} = -\frac{\beta b_{vh} I_v(N_h - (E_h + A_h + I_h))}{N_h^2} - (\alpha + \mu_h),$$

$$J_{61} = \frac{-\beta b_{hv}(I_h + r A_h) S_v}{N_h^2}, \qquad J_{65} = \frac{\beta b_{hv}(I_h + r A_h)}{N_h}.$$

4.1. Local Stability of E_0

At the CL-free equilibrium E_0, the Jacobian matrix J has the three negative eigenvalues $-\mu_h, -\mu_v, -(\mu_h + \gamma_h)$, in addition to the roots of the characteristic equation

$$a_3 \lambda^3 + a_2 \lambda^2 + a_1 \lambda + a_0 = 0 \tag{31}$$

where

$$a_3 = 1,$$
$$a_2 = (\alpha + \mu_h) + (\mu_h + \gamma_h) + \mu_v,$$
$$a_1 = (\alpha + \mu_h)\mu_v + (\mu_h + \gamma_h)\mu_v + (\alpha + \mu_h)(\mu_h + \gamma_h),$$
$$a_0 = \mu_v(\alpha + \mu_h)(\mu_h + \gamma_h)(1 - \mathcal{R}_0^2).$$

Based on the Routh–Hurwitz criterion, all roots of the characteristic polynomial (31) have negative real part if and only if all coefficients a_i, $i \in \{0, 1, 2, 3\}$ and the determinants

Δ_1, Δ_2 are all positive, where $\Delta_1 = a_2 a_1 - a_0 a_3$ and $\Delta_2 = a_0 \Delta_1$. It is clear that $a_3, a_2, and a_1$ are positive, while a_0 is positive if and only if $\mathcal{R}_0 < 1$. Moreover,

$$
\begin{aligned}
\Delta_1 &= \Big((\alpha + \mu_h) + (\mu_h + \gamma_h) + \mu_v \Big) \Big((\alpha + \mu_h)\mu_v + (\mu_h + \gamma_h)\mu_v \\
&\quad + (\alpha + \mu_h)(\mu_h + \gamma_h) \Big) - \mu_v (1 - \mathcal{R}_0^2)(\alpha + \mu_h)(\mu_h + \gamma_h). \\
&= (\alpha + \mu_h)\Big((\alpha + \mu_h)\mu_v + (\mu_h + \gamma_h)\mu_v + (\alpha + \mu_h)(\mu_h + \gamma_h) \\
&\quad + (\mu_h + \gamma_h)^2 + (\mu_h + \gamma_h)\mu_v \mathcal{R}_0^2 \Big) + (\mu_h + \gamma_h)^2 \mu_v > 0 \quad \forall \quad \mathcal{R}_0 < 1
\end{aligned}
\tag{32}
$$

and

$$
\Delta_2 = \mu_v (1 - \mathcal{R}_0^2)(\alpha + \mu_h)(\mu_h + \gamma_h)\Delta_1 > 0 \qquad \forall \quad \mathcal{R}_0 < 1.
\tag{33}
$$

Collecting all together, we obtain the following proposition on the local stability of the CL-free equilibrium.

Proposition 5. *The CL-free equilibrium E_0 is locally asymptotically stable if and only if $\mathcal{R}_0 < 1$.*

4.2. Local Stability of the Endemic Equilibrium E_e

At the endemic equilibrium, the matrix (30) has the three negative eigenvalues $-\mu_v, -\mu_h, -(\gamma_h + \mu_h)$, in addition to the roots of the characteristic polynomial

$$
c_3 \lambda^3 + c_2 \lambda^2 + c_1 \lambda + c_0 = 0
\tag{34}
$$

where

$$
\begin{aligned}
c_3 &= 1, \\
c_2 &= (\mu_h + \gamma_h) + (\alpha + \mu_h) + \mu_v + \frac{\beta b_{vh} I_v}{N_h} + \frac{\beta b_{hv}(I_h + r A_h)}{N_h}, \\
c_1 &= (\mu_h + \gamma_h)\left((\alpha + \mu_h) + \mu_v + \frac{\beta b_{vh} I_v}{N_h} + \frac{\beta b_{hv}(I_h + r A_h)}{N_h} \right) \\
&\quad + \left(\alpha + \mu_h + \frac{\beta b_{vh} I_v}{N_h} \right)\left(\mu_v + \frac{\beta b_{hv}(I_h + r A_h)}{N_h} \right) + \frac{\beta b_{vh} I_v}{N_h}\alpha, \\
c_0 &= \frac{\beta b_{hv}(I_h + r A_h)}{N_h}\left((\mu_h + \gamma_h)(\alpha + \mu_h) + \frac{\beta b_{vh} I_v}{N_h}(\mu_h + \gamma_h + \alpha) \right) \\
&\quad + \frac{\beta b_{vh} I_v}{N_h}(\mu_h + \gamma_h + \alpha)\mu_v.
\end{aligned}
$$

It is clear that all coefficients $c_i, i \in \{0, 1, 2, 3\}$ are positive. Therefore, the Routh–Hurwitz criterion implies that the endemic equilibrium E_e is locally asymptotically stable if and only if the determinant $\tilde{\Delta}_1 = c_2 c_1 - c_0 c_3$ is positive. Appendix C shows that $\tilde{\Delta}_1 > 0$. Thus, E_e is locally asymptotically stable wherever it exists. In summary, we have the following result.

Proposition 6. *The CL-endemic equilibrium E_e is locally asymptotically stable wherever it exists.*

5. Global and Asymptotic Stability

The global stability of the CL-free equilibrium (for $\mathcal{R}_0 < 1$) is proven by following the general approach shown in Section 3 of Castillo-Chavez et al. [27], see also Section 3.4 of [28]. To this end, model (1) is rewritten as

$$
\frac{dx}{dt} = F_1(x, \mathbf{y}) \qquad \text{and} \qquad \frac{dy}{dt} = G_1(x, \mathbf{y})
\tag{35}
$$

where

$$x = (S_h, S_v)^T, \qquad \mathbf{y} = (E_h, A_h, I_h, I_v)^T$$

and

$$F_1 = \begin{pmatrix} \Lambda_h - \frac{\beta b_{vh} I_v S_h}{N_h} - \mu_h S_h + \gamma_h (A_h + I_h) \\ \\ \Lambda_v - \frac{\beta b_{hv}(I_h + r A_h) S_v}{N_h} - \mu_v S_v \end{pmatrix} \quad \text{and} \quad G_1 = \begin{pmatrix} \frac{\beta b_{vh} I_v S_h}{N_h} - (\alpha + \mu_h) E_h \\ \\ q\alpha E_h - (\mu_h + \gamma_h) A_h \\ \\ (1-q)\alpha E_h - (\mu_h + \gamma_h) I_h \\ \\ \frac{\beta b_{hv}(I_h + r A_h) S_v}{N_h} - \mu_v I_v \end{pmatrix}.$$

The components of $x \in \mathbb{R}_+^2$ denote the uninfected subpopulations, and those of $\mathbf{y} \in \mathbb{R}_+^4$ denote the infected subpopulations. The CL-free equilibrium E_0 is equivalent with $x = x^* = (\Lambda_h/\mu_h, \Lambda_v/\mu_v)^T$ and $\mathbf{y} = \mathbf{O} = (0,0,0,0)^T$. The approach is based on proving the following two conditions:

(H1) For $\frac{dx}{dt} = F_1(x, \mathbf{O})$, x^* is globally asymptotically stable.

(H2) $G_1(x, \mathbf{y}) = B\mathbf{y} - \hat{G}(x, \mathbf{y}), \hat{G}(x, \mathbf{y}) \geq 0$ for $(x, \mathbf{y}) \in \Omega$.

Here, $B = D_{\mathbf{y}} G_1(x^*, \mathbf{O})$ is an M-matrix. The condition **H1** is proved by considering the following Lyapunov function:

$$V(S_h, S_v) = S_h - \frac{\Lambda_h}{\mu_h} - \frac{\Lambda_h}{\mu_h} \ln\left(\frac{S_h}{\Lambda_h/\mu_h}\right) + S_v - \frac{\Lambda_v}{\mu_v} - \frac{\Lambda_v}{\mu_v} \ln\left(\frac{S_v}{\Lambda_v/\mu_v}\right).$$

Clearly, $V(S_h, S_v) \geq 0$ along the solution of the system

$$\frac{d}{dt}(S_h, S_v)^T = \left(\Lambda_h - \mu_h S_h, \Lambda_v - \mu_v S_v \right)^T \tag{36}$$

and is zero if and only if $(S_h, S_v)^T = (\Lambda_h/\mu_h, \Lambda_v/\mu_v)^T$. In addition, the time-derivative of V, computed along the solution of the system (36), is

$$\frac{d}{dt}V = -\mu_h S_h \left(1 - \frac{\Lambda_h}{\mu_h S_h}\right)^2 - \mu_v S_v \left(1 - \frac{\Lambda_v}{\mu_v S_v}\right)^2 < 0.$$

Therefore, $x^* = (\Lambda_h/\mu_h, \Lambda_v/\mu_v)^T$ is globally stable. This proves condition **H1**.

To prove condition **H2**, we rewrite the vector-matrix $G_1(x, \mathbf{y})$ as $B\mathbf{y} - \hat{G}(x, \mathbf{y}), \hat{G}(x, \mathbf{y}) \geq 0$, where

$$B = D_{\mathbf{y}} G_1(x^*, \mathbf{O}) = \begin{pmatrix} -(\alpha + \mu_h) & 0 & 0 & \beta b_{vh} \\ \\ q\alpha & -(\mu_h + \gamma_h) & 0 & 0 \\ \\ (1-q)\alpha & 0 & -(\mu_h + \gamma_h) & 0 \\ \\ 0 & \frac{r\beta b_{hv} \Lambda_v \mu_h}{\Lambda_h \mu_v} & \frac{\beta b_{hv} \Lambda_v \mu_h}{\Lambda_h \mu_v} & -\mu_v \end{pmatrix}$$

is an M-matrix (where its off-diagonal elements are non-negative) and

$$\hat{G}(x, \mathbf{y}) = \left(\beta b_{vh} I_v \left(1 - \frac{S_h}{N_h}\right), 0, 0, \beta b_{hv}(I_h + r A_h) \frac{\Lambda_v/\mu_v}{\Lambda_h/\mu_h} \left(1 - \frac{S_v}{\Lambda_v/\mu_v} \times \frac{\Lambda_h/\mu_h}{N_h}\right) \right)^T.$$

Therefore, we show the following proposition.

Proposition 7. *The CL-free equilibrium E_0 is globally stable if and only if $\mathcal{R}_0 < 1$.*

The asymptotic stability analysis of both the CL-free and CL-endemic equilibriums is established numerically. To this end, the function ode45 in Matlab, which is based on the Runge–Kutta method of order four, is employed to numerically solve model (1) with parameter values as presented in Table 2 and with various randomly generated initial conditions lying in the set Ω. Extensive simulations are performed with a β value corresponding to $\mathcal{R}_0 = 0.8 < 1$ and the simulations are shown in Figures 2 and 3. The figures show that if we start the solutions with any initial values lying in the domain Ω, the number of exposed, asymptomatic, and infected humans and infected sandflies approach zero in the long time run, while those of noninfected humans and sandflies tend to their level at the CL-free equilibrium. In other words, all trajectory solutions are attracted by the CL-free equilibrium. It is worth mentioning that the horizontally broken lines represent the equilibrium solutions.

Similarly, model (1) is extensively and numerically solved with a value of β such that $\mathcal{R}_0 = 1.83 > 1$, and the simulations are shown in Figures 4 and 5. These two figures show that for any initial values of the human and sandfly subpopulations (lying in the set Ω) and for a combination of model parameters chosen such that $\mathcal{R}_0 > 1$, the size of the time-dependent exposed, asymptomatic, and infected human subpopulations and infected sandfly subpopulation will eventually approach a positive level (their levels at the CL-endemic situation) and, hence, the infection persists in both human and sandfly populations. Definitely, the CL-endemic equilibrium attracts all model solutions for values of $\mathcal{R}_0 > 1$. Thus, motivated by the above results, the CL-free equilibrium is asymptotically stable if and only if $\mathcal{R}_0 < 1$, while the CL-endemic equilibrium is asymptotically stable wherever it exists.
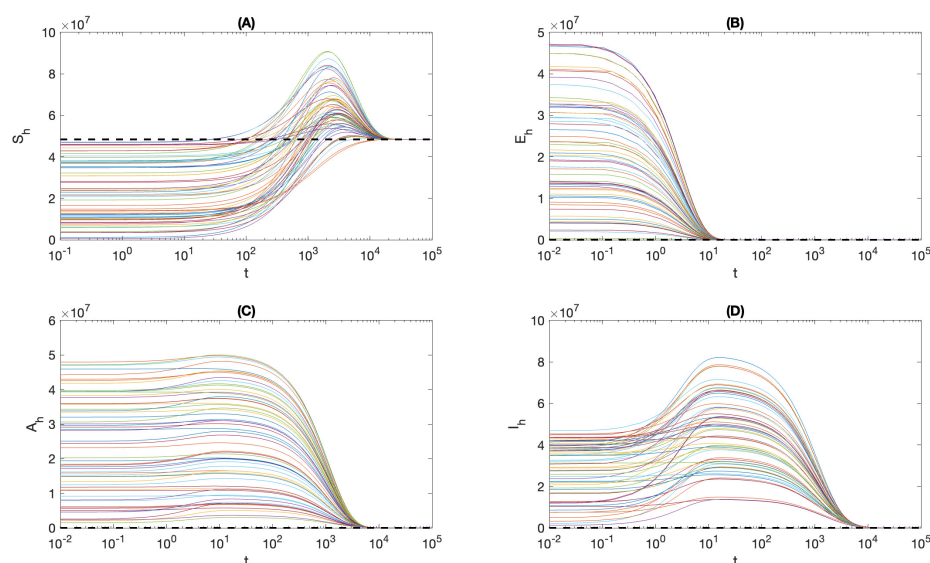

Figure 2. Time series analysis for model (1) with parameter values as shown in Table 2, except that β is chosen to make $\mathcal{R}_0 = 0.8 < 1$. Simulations are performed with randomly selected initial conditions from the set Ω. The broken horizontal line in each subfigure represents the corresponding equilibrium subpopulation number, while each curve represents a trajectory solution.

It is noteworthy that our in silico simulations (see Colquitt et al. [29]) show the existence of two scenarios for the evolution of the infection; either the infection dies out from both human and sandfly populations (see Figures 2 and 3, respectively), or it persists in both populations (see Figures 4 and 5). The first scenario is implemented if the combination of model parameter values is chosen such that $\mathcal{R}_0 < 1$, while the scenario of the infection's persistence holds if the model parameter values satisfy the condition $\mathcal{R}_0 > 1$. Therefore, the nonexistence of CL-endemic equilibrium (for $\mathcal{R}_0 < 1$) and the global asymptotic stability

of the CL-free equilibrium for $\mathcal{R}_0 < 1$ would imply that applying control measure aiming at reducing the basic reproduction number to slightly less than one would ensure effective control of cutaneous leishmaniasis infection.
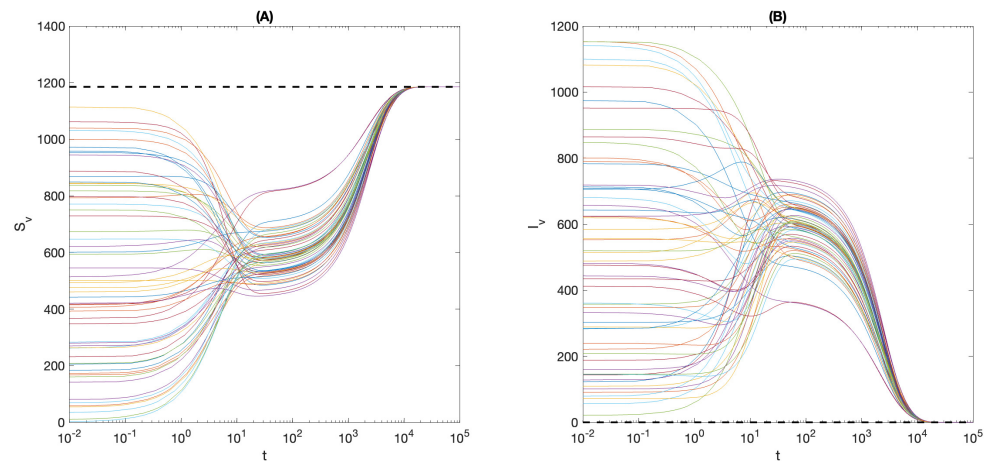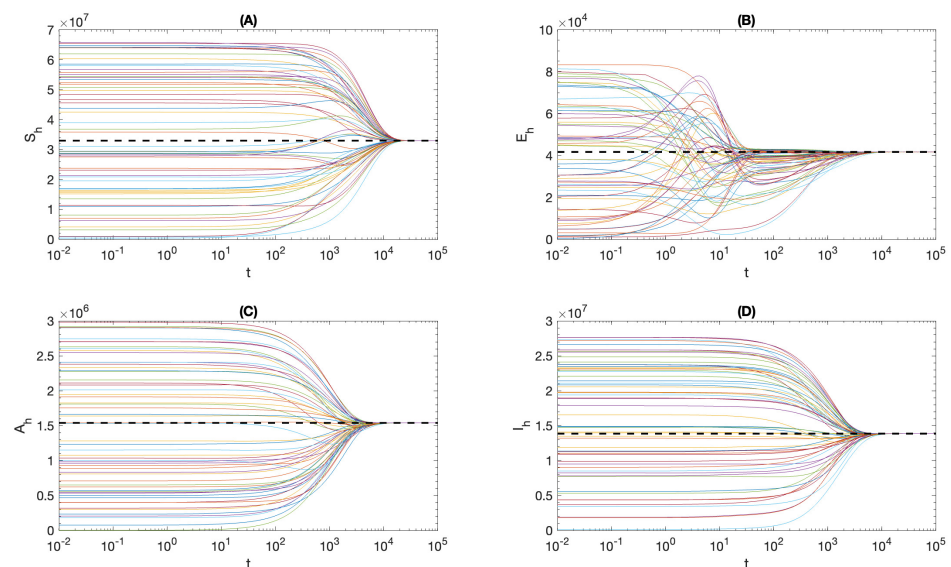

Figure 3. Time series analysis for model (1) with parameter values as shown in Table 2, except β is chosen to make $\mathcal{R}_0 = 0.80 < 1$. Simulations are performed with randomly selected initial conditions from the set Ω. The broken horizontal line in each subfigure represents the corresponding equilibrium subpopulation number, while each curve represents a trajectory solution.
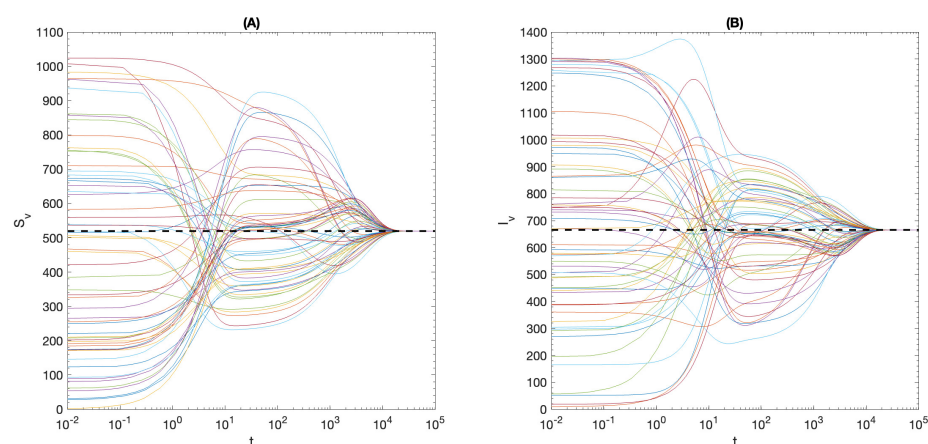

Figure 4. Time series analysis for model (1) with parameter values as shown in Table 2, except β is chosen to make $\mathcal{R}_0 = 1.83 > 1$. Simulations are performed with randomly selected initial conditions from the set Ω. The broken horizontal line in each subfigure represents the corresponding equilibrium subpopulation number, while each curve represents a trajectory solution.

Figure 5. Time series analysis for model (1) with parameter values as shown in Table 2, except β is chosen to make $\mathcal{R}_0 = 1.83 > 1$. Simulations are performed with randomly selected initial conditions from the set Ω. The broken horizontal line in each subfigure represents the corresponding equilibrium subpopulation number, while each curve represents a trajectory solution.

6. Effect of Ignoring Asymptomatic Infections

In the absence of asymptomatic infection (i.e., $q = 0$), model (1) becomes an SEIS-SI model with the infection-free equilibrium

$$
\widetilde{E}_0 = \left(\widetilde{S}_h^0, \widetilde{E}_h^0, \widetilde{I}_h^0, \widetilde{S}_v^0, \widetilde{I}_v^0\right)^T = \left(\frac{\Lambda_h}{\mu_h}, 0, 0, \frac{\Lambda_v}{\mu_v}, 0\right)^T \tag{37}
$$

and a unique endemic equilibrium $\widetilde{E}_e = \left(\widetilde{S}_h^e, \widetilde{E}_h^e, \widetilde{I}_h^e, \widetilde{S}_v^e, \widetilde{I}_v^e\right)^T$, whose components are derived from (28) by inputting $q = r = 0$. It is easy to check that $\widetilde{E}_e$ does exist if and only if $\widetilde{\mathcal{R}}_0 > 1$, where

$$
\widetilde{\mathcal{R}}_0 = \sqrt{\frac{\beta b_{vh}}{\mu_v} \times \frac{\beta b_{hv}}{\gamma_h + \mu_h} \times \frac{\alpha}{\alpha + \mu_h} \times \frac{\Lambda_v/\mu_v}{\Lambda_h/\mu_h}} \tag{38}
$$

is the basic reproduction number for the model in the absence of asymptomatic infection. It is clear that $\widetilde{\mathcal{R}}_0 \geq \mathcal{R}_0$, which means that ignoring the asymptomatic infection overestimates the value of the basic reproduction number and, in consequence, overestimates the effort needed to eliminate CL infection.

The equilibrium numbers of symptomatic and asymptomatic CL-infected humans are drawn as functions of the basic reproduction number $\mathcal{R}_0$ for various values of the probability q; see Figure 6. Figure 6A shows that I_h decreases with the increase of q which means that I_h is overestimated if the asymptomatic infection is neglected. In addition, both the human and vector forces of infections at equilibrium are depicted as functions of the basic reproduction number $\mathcal{R}_0$, for various values of the probability q, in Figure 7. The simulations show that the equilibrium (vector to) human force of infection λ_{vh} increases with the increase of q, which means that ignoring the asymptomatic infection underestimates the rate at which susceptible humans acquire CL infection. In summary, ignoring the asymptomatic infection underestimates the burden of CL infection in the human population and, therefore, overestimates the effort required to eliminate it.
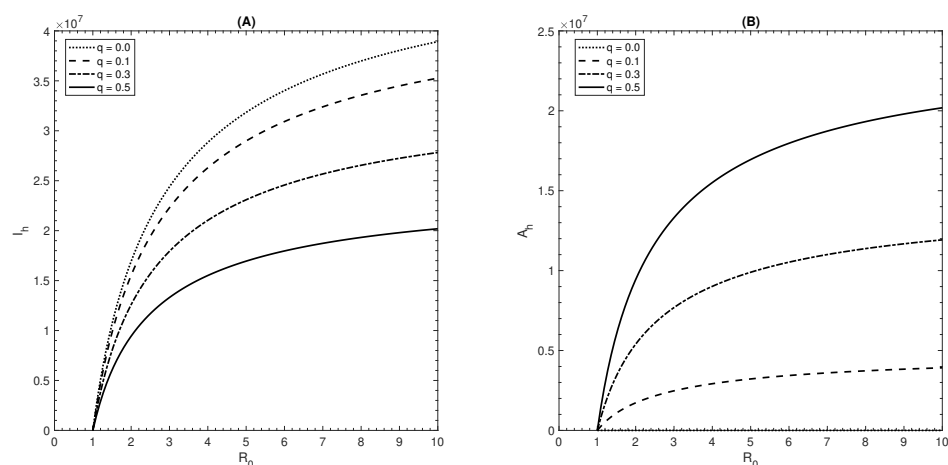
Figure 6. The endemic number of symptomatic I_h (**A**) and asymptomatic A_h (**B**) infected humans as a function of the basic reproduction number $\mathcal{R}_0$ for various values of q, while keeping the rest of the model parameters' values as in Table 2.
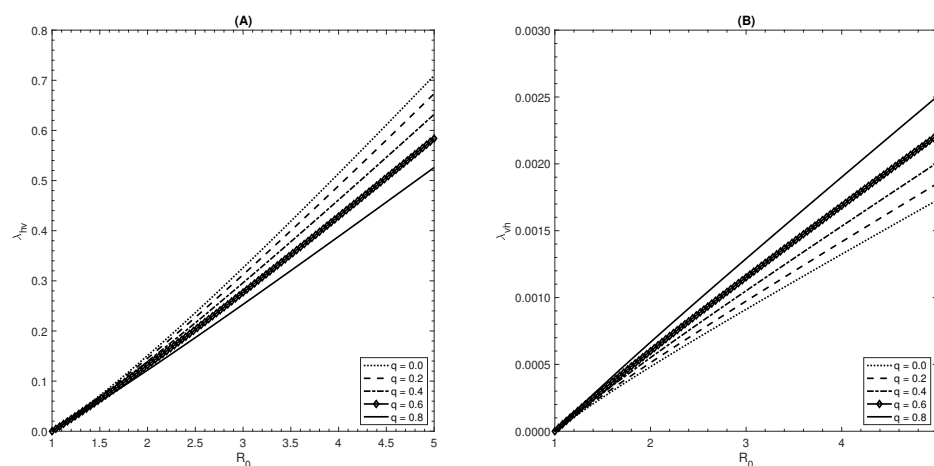

Figure 7. The endemic sandfly λ_{hv} (**A**) and human λ_{vh} (**B**) forces of infection as functions of the basic reproduction number $\mathcal{R}_0$ for various values of q, while keeping the rest of the model parameters' values as in Table 2.

7. Summary and Conclusions

Mathematical models have been used to study the dynamical spread of cutaneous leishmaniasis (CL) both on the cell [16] and population levels [12,30]. However, the effect of asymptomatic human infections on CL's dynamical spread and disease outcomes has not yet been studied. Therefore, an SEAIS-SI model for the anthroponotic CL was introduced and thoroughly analyzed. The model splits the human population into susceptible, exposed (i.e., infected, but neither shows symptoms nor capable of transmitting the infection), asymptomatic (i.e., does not show symptoms, but can transmit the infection), and infected (i.e., symptomatic and capable of transmitting the infection). The model assumes that exposed individuals leave their states at rate α and develop symptoms with probability $1 - q$. Moreover, it differentiates the infectiousness of symptomatic from asymptomatic individuals. As the life expectancy of the sandflies is very short compared to that of humans, the model ignores latency and temporal recovery in the sandflies population and splits it into susceptible and infected.

The model was shown to be well-posed, in the sense of existence and uniqueness of the time-dependent solution in addition to the positive invariance of the model space set of definition. Its equilibrium and stability analyses reveal that it has a CL-free equilibrium E_0 that is shown to be locally asymptotically stable if and only if the basic reproduction

number $\mathcal{R}_0 < 1$. The formula of $\mathcal{R}_0$ is defined within the text. Moreover, it has a unique endemic equilibrium E_e that is shown to exist and be locally asymptotically stable if and only if $\mathcal{R}_0 > 1$. Extensive simulations, with parameter values extracted from the literature, were performed to explore the global attractors of the solutions. The simulations were performed with randomly selected initial conditions all over the model definition set. It shows that the CL-free equilibrium attracts all the solutions if the model parameters have been chosen such that the basic reproduction number $\mathcal{R}_0 < 1$, while they are attracted by the CL-endemic equilibrium E_e if and only if $\mathcal{R}_0 > 1$.

The effect of ignoring asymptomatic infections on disease outcomes was examined. Throughout the analysis, it was found that ignoring the development of asymptomatic infections overestimates the value of the basic reproduction number $\mathcal{R}_0$ and, as a consequence, overestimates the effort required to eliminate the infection. Moreover, neglecting the asymptomatic infections underestimates (overestimates) the equilibrium vector-to-human (human-to-vector) force of infection which, as a consequence, implies inaccurate measures of controlling the CL infection, especially those based on either using insecticide sprays or bednets.

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Appendix A. Locally Lipschitz

The partial derivatives of the right-hand side of model (1) are the entire elements of its Jacobian matrix $\hat{J}$, where

$$
\hat{J} = \begin{pmatrix}
\hat{J}_{11} & \dfrac{\beta b_{vh} I_v S_h}{N_h^2} & \dfrac{\beta b_{vh} I_v S_h}{N_h^2} + \gamma_h & \dfrac{\beta b_{vh} I_v S_h}{N_h^2} + \gamma_h & 0 & -\dfrac{\beta b_{vh} S_h}{N_h} \\[2ex]
\hat{J}_{21} & \hat{J}_{22} & -\dfrac{\beta b_{vh} I_v S_h}{N_h^2} & -\dfrac{\beta b_{vh} I_v S_h}{N_h^2} & 0 & \dfrac{\beta b_{vh} S_h}{N_h} \\[2ex]
0 & q\alpha & -(\mu_h + \gamma_h) & 0 & 0 & 0 \\[2ex]
0 & (1-q)\alpha & 0 & -(\mu_h + \gamma_h) & 0 & 0 \\[2ex]
\hat{J}_{51} & \hat{J}_{52} & \hat{J}_{53} & \hat{J}_{54} & \hat{J}_{55} & 0 \\[2ex]
\hat{J}_{61} & \hat{J}_{62} & \dfrac{r\beta b_{hv}(N_h - A_h)S_v}{N_h^2} & \dfrac{\beta b_{hv}(N_h - I_h)S_v}{N_h^2} & \hat{J}_{65} & -\mu_v
\end{pmatrix}
\tag{A1}
$$

where

$$\hat{J}_{11} = -\frac{\beta b_{vh} I_v (N_h - S_h)}{N_h^2} - \mu_h, \quad \hat{J}_{21} = \frac{\beta b_{vh} I_v (N_h - S_h)}{N_h^2}, \quad \hat{J}_{22} = -\frac{\beta b_{vh} I_v S_h}{N_h^2} - (\alpha + \mu_h),$$

$$\hat{J}_{51} = \hat{J}_{52} = \frac{\beta b_{hv}(I_h + rA_h)S_v}{N_h^2}, \quad \hat{J}_{53} = -\frac{r\beta b_{hv}(N_h - A_h)S_v}{N_h^2}, \quad \hat{J}_{54} = -\frac{\beta b_{hv}(N_h - I_h)S_v}{N_h^2},$$

$$\hat{J}_{55} = -\frac{\beta b_{hv}(I_h + rA_h)}{N_h} - \mu_v, \quad \hat{J}_{61} = \hat{J}_{62} = -\frac{\beta b_{hv}(I_h + rA_h)S_v}{N_h^2}, \quad \hat{J}_{65} = \frac{\beta b_{hv}(I_h + rA_h)}{N_h}.$$

They are all continuous in the state variables S_h, E_h, A_h, I_h, S_v, and I_v.

Appendix B. Positivity and Boundedness—Proof of Proposition 1

To prove that the set Ω is positively invariant, we continue in the following manner.

$$\frac{dS_h}{dt} = \Lambda_h - \frac{\beta b_{vh} I_v S_h}{N_h} - \mu_h S_h + \gamma_h (A_h + I_h).$$

which leads to

$$\frac{dS_h}{dt} \geq -\left(\frac{\beta b_{vh} I_v}{N_h} + \mu_h\right)$$

Using a comparison theorem, we obtain

$$S_h(t) \geq S_h(0) e^{-\mu_h t - \beta b_{vh} \int_0^t \frac{I_v}{N_h} d\tau} \geq 0 \quad \forall \quad S_h(0) \geq 0.$$

Similarly, we can have that

$$
\begin{aligned}
E_h(t) &\geq E_h(0) e^{-(\alpha + \mu_h)t} & \geq 0 & \quad \forall & E_h(0) &\geq 0 \\
A_h(t) &\geq A_h(0) e^{-(\mu_h + \gamma_h)t} & \geq 0 & \quad \forall & A_h(0) &\geq 0 \\
I_h(t) &\geq I_h(0) e^{-(\mu_h + \gamma_h)t} & \geq 0 & \quad \forall & I_h(0) &\geq 0 \\
S_v(t) &\geq S_v(0) e^{-\mu_v t - \beta b_{hv} \int_0^t \frac{(I_v + rA_h)}{N_h} d\tau} & \geq 0 & \quad \forall & S_V(0) &\geq 0 \\
I_v(t) &\geq I_v(0) e^{-\mu_v t} & \geq 0 & \quad \forall & I_v(0) &\geq 0
\end{aligned}
$$

Hence,

$$S_h(t), E_h(t), A_h(t), I_h(t), S_v(t), I_v(t) \geq 0 \quad \forall \quad t \geq 0.$$

However,

$$0 \leq S_h(t) + E_h(t) + A_h(t) + I_h(t) = N_h(t) \leq \frac{\Lambda_h}{\mu_h}, \quad and \quad 0 \leq S_v(t) + I_v(t) = N_v(t) \leq \frac{\Lambda_v}{\mu_v}.$$

Therefore, Ω is positively invariant.

Appendix C. Proof of the Positivity of the Hurwitz Determinant $\tilde{\Delta}_1$

$$
\begin{aligned}
\tilde{\Delta}_1 &= c_2 c_1 - c_0 c_3. \\
&= \left((\mu_h + \gamma_h) + (\alpha + \mu_h) + \mu_v + \frac{\beta b_{vh} I_v}{N_h} + \frac{\beta b_{hv}(I_h + rA_h)}{N_h} \right) \left((\alpha + \mu_h)(\mu_h + \gamma_h) \right. \\
&+ \mu_v(\mu_h + \gamma_h) + \frac{\beta b_{vh} I_v}{N_h}(\mu_h + \gamma_h) + \frac{\beta b_{hv}(I_h + rA_h)}{N_h}(\mu_h + \gamma_h) + (\alpha + \mu_h)\mu_v \\
&+ \frac{\beta b_{vh} I_v}{N_h}\mu_v + \frac{\beta b_{hv}(I_h + rA_h)}{N_h}(\alpha + \mu_h) + \frac{\beta^2 b_{hv} b_{vh} I_v(I_h + rA_h)}{N_h^2} + \left. \frac{\beta b_{vh} I_v}{N_h}\alpha \right) \\
&- \frac{\beta b_{hv}(I_h + rA_h)}{N_h}\left((\mu_h + \gamma_h)(\alpha + \mu_h) + \frac{\beta b_{vh} I_v}{N_h}(\mu_h + \gamma_h) + \frac{\beta b_{vh} I_v}{N_h}\alpha \right) \\
&- \frac{\beta b_{vh} I_v}{N_h}(\mu_h + \gamma_h)\mu_v - \frac{\beta b_{vh} I_v}{N_h}\mu_v\alpha;
\end{aligned}
$$

i.e.,

$$
\begin{aligned}
\tilde{\Delta}_1 &= (\alpha + \mu_h)\left((\alpha + \mu_h)(\mu_h + \gamma_h) + 2\frac{\beta b_{vh} I_v}{N_h}(\mu_h + \gamma_h) + 3(\mu_h + \gamma_h)\mu_v \right. \\
&+ (\alpha + \mu_h)\mu_v + 2(\mu_h + \gamma_h)\frac{\beta b_{hv}(I_h + rA_h)}{N_h} + 2\frac{\beta b_{vh} I_v}{N_h}\mu_v + \frac{\beta b_{hv}(I_h + rA_h)}{N_h}(\alpha + \mu_h) \\
&+ 2\frac{\beta^2 b_{hv} b_{vh} I_v(I_h + rA_h)}{N_h^2} + \frac{\beta b_{vh} I_v}{N_h}\alpha + (\mu_h + \gamma_h)^2 + \mu_v^2 \\
&+ \frac{\beta^2 b_{hv}^2 (I_h + rA_h)^2}{N_h^2} + \left. 2\frac{\beta b_{hv}(I_h + rA_h)}{N_h}\mu_v \right) + (\mu_h + \gamma_h)\left((\mu_h + \gamma_h)\frac{\beta b_{vh} I_v}{N_h} \right. \\
&+ (\mu_h + \gamma_h)\mu_v + \frac{\beta b_{hv}(I_h + rA_h)}{N_h}(\mu_h + \gamma_h) + 2\frac{\beta b_{vh} I_v}{N_h}\mu_v + 2\frac{\beta^2 b_{hv} b_{vh} I_v(I_h + rA_h)}{N_h^2} \\
&+ \frac{\beta b_{vh} I_v}{N_h}\alpha + \frac{\beta^2 b_{vh}^2 I_v^2}{N_h^2} + \mu_v^2 + 2\frac{\beta b_{hv}(I_h + rA_h)}{N_h}\mu_v + \left. \frac{\beta^2 b_{hv}^2 (I_h + rA_h)^2}{N_h^2} \right) \\
&+ \mu_v\frac{\beta^2 b_{vh}^2 I_v^2}{N_h^2} + \frac{\beta^3 b_{hv} b_{vh}^2 I_v^2(I_h + rA_h)}{N_h^3} + \frac{\beta^2 b_{vh}^2 I_v^2}{N_h^2}\alpha + \frac{\beta b_{vh} I_v}{N_h}\mu_v^2 \\
&+ 2\frac{\beta^2 b_{hv} b_{vh} I_v(I_h + rA_h)}{N_h^2}\mu_v + \frac{\beta^3 b_{hv}^2 b_{vh} I_v(I_h + rA_h)}{N_h^3} > 0.
\end{aligned}
\tag{A2}
$$

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