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Analysis of General Humoral Immunity HIV Dynamics Model with HAART and Distributed Delays

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Abstract: This paper deals with the study of an HIV dynamics model with two target cells, macrophages and CD4⁺ T cells and three categories of infected cells, short-lived, long-lived and latent in order to get better insights into HIV infection within the body. The model incorporates therapeutic modalities such as reverse transcriptase inhibitors (RTIs) and protease inhibitors (PIs). The model is incorporated with distributed time delays to characterize the time between an HIV contact of an uninfected target cell and the creation of mature HIV. The effect of antibody on HIV infection is analyzed. The production and removal rates of the ten compartments of the model are given by general nonlinear functions which satisfy reasonable conditions. Nonnegativity and ultimately boundedness of the solutions are proven. Using the Lyapunov method, the global stability of the equilibria of the model is proven. Numerical simulations of the system are provided to confirm the theoretical results. We have shown that the antibodies can play a significant role in controlling the HIV infection, but it cannot clear the HIV particles from the plasma. Moreover, we have demonstrated that the intracellular time delay plays a similar role as the Highly Active Antiretroviral Therapies (HAAT) drugs in eliminating the HIV particles.

Keywords: global stability; HIV dynamics; antibody immunity; time delay

1. Introduction

Modeling the HIV dynamics has received considerable attention from mathematicians during the recent decades [1–22]. The first HIV dynamics model is proposed by Nowak and Bangham [1] as:

$$\dot{s}(t) = \rho - \delta s(t) - \bar{\lambda} s(t) p(t), \quad (1)$$

$$\dot{y}(t) = \bar{\lambda} s(t) p(t) - \eta y(t), \quad (2)$$

$$\dot{p}(t) = \bar{N} \eta y(t) - gp(t), \quad (3)$$

where s , y and p are the concentrations of the CD4⁺ T cells, infected cells and HIV particles; ρ , δ and $\bar{\lambda}$ represent the production, death and infection rates of the uninfected CD4⁺ T cells, respectively; η and g are the death rate constants of the infected cells and free HIV, respectively; \bar{N} is the average number of HIV particles generated in the lifetime of the infected cells. A class of latently infected cells has been modeled in the HIV dynamics in [23–26]. Elaiw et al. [27] have extended model (1)–(3) by considering

distributed time delays, B cells (x), and three categories of infected cells, short-lived (y), long-lived (u) and latent (w) as:

$$\dot{s} = \pi(s(t)) - \lambda Y(s(t), p(t)), \tag{4}$$

$$\dot{w} = \lambda_1 \int_0^{h_1} f_1(\tau) e^{-\mu_1 \tau} Y(s(t-\tau), p(t-\tau)) d\tau - (\alpha + \beta) \psi_1(w(t)), \tag{5}$$

$$\dot{y} = \lambda_2 \int_0^{h_2} f_2(\tau) e^{-\mu_2 \tau} Y(s(t-\tau), p(t-\tau)) d\tau + \alpha \psi_1(w(t)) - \eta \psi_2(y(t)), \tag{6}$$

$$\dot{u} = \lambda_3 \int_0^{h_3} f_3(\tau) e^{-\mu_3 \tau} Y(s(t-\tau), p(t-\tau)) d\tau - \nu \psi_3(u(t)), \tag{7}$$

$$\dot{p} = N\eta \psi_2(y(t)) + M\nu \psi_3(u(t)) - g\psi_4(p(t)) - \mu \psi_4(p(t)) \psi_5(x(t)), \tag{8}$$

$$\dot{x} = r\psi_4(p(t)) \psi_5(x(t)) - \omega \psi_5(x(t)), \tag{9}$$

where $f_i(\tau) e^{-\mu_i \tau}$ over the time interval $[0, h_i]$, $i = 1, 2, 3$ represents the probabilities that uninfected cells contacted by HIV at time $t - \tau$ survived τ time units and become infected at time t ; $Y, \pi, \psi_j, j = 1, \dots, 5$ are general nonlinear functions. The probability distribution function $f_i(\tau)$ satisfies $f_i(\tau) > 0$ and

$$\int_0^{h_i} f_i(\tau) d\tau = 1, \quad \int_0^{h_i} f_i(\eta) e^{v\eta} d\eta < \infty, \quad i = 1, 2, 3,$$

where $v > 0$. Let us denote $\Theta_i(\tau) = f_i(\tau) e^{-\mu_i \tau}$ and $F_i = \int_0^{h_i} \Theta_i(\tau) d\tau$, thus $0 < F_i \leq 1, i = 1, 2, 3$.

Model (4)–(9) assumes that the HIV infects one category of target cells, CD4⁺ T cells. However, Perleson et al. have observed that after the rapid first phase of decay during the initial 1–2 weeks of an antiretroviral treatment, plasma virus levels declined at a considerably slower rate [28]. This second phase of viral decay was attributed to the turnover of infected macrophages. Therefore, the HIV model with two categories of target cells, CD4⁺ T cells and macrophages is more accurate than that model with only one category target cells, CD4⁺ T cells. As a result, more accurate drug efficacy can be determined when using the HIV model with two classes of target cells. Recently, many efforts have been devoted to the analysis of various mathematical models of HIV dynamics with two categories of target cells (see, e.g., [29–37]). However, in these papers, the production and removal rates of the HIV particles and cells are given by linear functions; moreover, only one or two classes of infected cells are considered.

The aim of the present paper is to propose and analyze an HIV dynamics model which extends model (4)–(9) and describes the dynamics of HIV with two categories of target cells, CD4⁺ T cells and macrophages. We study the basic and global properties of the model. Using Lyapunov function and LaSalle’s invariance principle, we have established the global asymptotic stability of the three equilibria of the model. We have shown that the antibodies can reduce the HIV level, but they cannot clear the HIV particles completely. The effect of HAART drugs and intracellular time delays in stabilizing the HIV dynamics system around the infection-free equilibrium are shown. The importance of considering the second class of target cells (macrophages) in the HIV dynamics is also shown.

The rest of the paper is organized as follows: in Section 2, we present the HIV model and study its basic properties. In Section 3, the global stability of three equilibria is established. In Section 4, we offer some numerical simulations to confirm our analytical results. The paper ends with some conclusions and discussion in Section 5.

2. Mathematical Model

We propose the following model:

$$\dot{s}_i = \pi_i(s_i(t)) - \lambda_i Y_i(s_i(t), p(t)), \tag{10}$$

$$\dot{w}_i = \lambda_{1i} \int_0^{h_{1i}} f_{1i}(\tau) e^{-\mu_{1i}\tau} Y_i(s_i(t-\tau), p(t-\tau)) d\tau - (\alpha_i + \beta_i) \psi_{1i}(w_i(t)), \tag{11}$$

$$\dot{y}_i = \lambda_{2i} \int_0^{h_{2i}} f_{2i}(\tau) e^{-\mu_{2i}\tau} Y_i(s_i(t-\tau), p(t-\tau)) d\tau + \alpha_i \psi_{1i}(w_i(t)) - \eta_i \psi_{2i}(y_i(t)), \tag{12}$$

$$\dot{u}_i = \lambda_{3i} \int_0^{h_{3i}} f_{3i}(\tau) e^{-\mu_{3i}\tau} Y_i(s_i(t-\tau), p(t-\tau)) d\tau - \nu_i \psi_{3i}(u_i(t)), \tag{13}$$

$$\dot{p} = \sum_{i=1}^2 \left(N_i \eta_i \int_0^{h_{4i}} f_{4i}(\tau) e^{-\mu_{4i}\tau} \psi_{2i}(y_i(t-\tau)) d\tau + M_i \nu_i \int_0^{h_{5i}} f_{5i}(\tau) e^{-\mu_{5i}\tau} \psi_{3i}(u_i(t-\tau)) d\tau \right) - g \psi_{41}(p(t)) - \mu \psi_{41}(p(t)) \psi_{42}(x(t)), \tag{14}$$

$$\dot{x} = r \psi_{41}(p(t)) \psi_{42}(x(t)) - \omega \psi_{42}(x(t)), \tag{15}$$

where $i = 1$ for the CD4⁺ T cells and $i = 2$ for the macrophages. We have $\lambda_{m1} = (1 - \varepsilon_1) \bar{\lambda}_{m1}$, $\lambda_{m2} = (1 - f\varepsilon_1) \bar{\lambda}_{m2}$, $m = 1, 2, 3$, $N_1 = (1 - \varepsilon_2) \bar{N}_1$, $M_1 = (1 - \varepsilon_2) \bar{M}_1$, $N_2 = (1 - h\varepsilon_2) \bar{N}_2$, $M_2 = (1 - h\varepsilon_2) \bar{M}_2$, $\lambda_i = \lambda_{1i} + \lambda_{2i} + \lambda_{3i}$, and $f, h \in (0, 1)$. Let $f_{ji}(\tau) e^{-\mu_{ji}\tau}$ over the time interval $[0, h_{ji}]$, $j = 1, \dots, 5$, $i = 1, 2$, are the probabilities that uninfected target cells contacted by HIV at time $t - \tau$ survived τ time units and became infected at time t . Denote $\Theta_{ji}(\tau) = f_{ji}(\tau) e^{-\mu_{ji}\tau}$ and $F_{ji} = \int_0^{h_{ji}} \Theta_{ji}(\tau) d\tau$; thus $0 < F_{ji} \leq 1$, $j = 1, \dots, 5$, $i = 1, 2$. We assume that:

Hypothesis 1 (H1). (i) There exists s_i^0 such that $\pi_i(s_i^0) = 0$, $\pi_i(s_i) > 0$ for $s_i \in [0, s_i^0)$, (ii) $\pi'_i(s_i) < 0$ for $s_i > 0$; (iii) there are $b_i > 0$ and $\bar{b}_i > 0$ such that $\pi_i(s_i) \leq b_i - \bar{b}_i s_i$ for $s_i \geq 0$.

Hypothesis 2 (H2). (i) $Y_i(s_i, p) > 0$ and $Y_i(0, p) = Y_i(s_i, 0) = 0$ for $s_i, p > 0$, (ii) $\frac{\partial Y_i(s_i, p)}{\partial s_i} > 0$, $\frac{\partial Y_i(s_i, p)}{\partial p} > 0$ and, $\frac{\partial Y_i(s_i, 0)}{\partial p} > 0$ for all $s_i, p > 0$, (iii) $\frac{d}{ds_i} \left(\frac{\partial Y_i(s_i, 0)}{\partial p} \right) > 0$ for $s_i > 0$.

Hypothesis 3 (H3). (i) $\psi_{ji}(\eta) > 0$ for $\eta > 0$, $\psi_{ji}(0) = 0$, $j = 1, \dots, 4$, $i = 1, 2$, (ii) $\psi'_{ji}(\eta) > 0$, $\psi'_{42}(\eta) > 0$ for $\eta > 0$, $j = 1, 2, 3$, $i = 1, 2$, $\psi'_{41}(\eta) > 0$, for $\eta \geq 0$; (iii) there are $\alpha_{ji} > 0$, $j = 1, \dots, 4$, $i = 1, 2$, such that $\psi_{ji}(\eta) \geq \alpha_{ji} \eta$ for $\eta \geq 0$.

Hypothesis 4 (H4). $\frac{Y_i(s_i, p)}{\psi_{41}(p)}$ is decreasing function w.r.t. p , for $p > 0$.

Remark 1. From H1–H4, we have

$$(Y_i(s_i, p) - Y_i(s_i, p^*)) \left(\frac{Y_i(s_i, p)}{\psi_{41}(p)} - \frac{Y_i(s_i, p^*)}{\psi_{41}(p^*)} \right) \leq 0,$$

which gives

$$\left(1 - \frac{Y_i(s_i, p^*)}{Y_i(s_i, p)} \right) \left(\frac{Y_i(s_i, p)}{Y_i(s_i, p^*)} - \frac{\psi_{41}(p)}{\psi_{41}(p^*)} \right) \leq 0.$$

We consider systems (10)–(15) with the initial conditions:

$$\begin{aligned} s_1(t) &= \varphi_1(\theta), s_2(t) = \varphi_2(\theta), w_1(t) = \varphi_3(\theta), w_2(t) = \varphi_4(\theta), y_1(t) = \varphi_5(\theta), \\ y_2(t) &= \varphi_6(\theta), u_1(t) = \varphi_7(\theta), u_2(t) = \varphi_8(\theta), p(t) = \varphi_9(\theta), x(t) = \varphi_{10}(\theta), \\ \varphi_j(\theta) &\geq 0, \theta \in [-\varsigma, 0], j = 1, \dots, 10, \end{aligned} \tag{16}$$

where $\varsigma = \max\{h_{11}, h_{12}, h_{21}, h_{22}, h_{31}, h_{32}, h_{41}, h_{42}, h_{51}, h_{52}\}$ and denoted by C is the Banach space of continuous functions mapping the interval $[-\varsigma, 0]$ into $\mathbb{R}_{\geq 0}$ and $(\varphi_1(\theta), \dots, \varphi_{10}(\theta)) \in C\left([-\varsigma, 0], \mathbb{R}_{\geq 0}^{10}\right)$. According to [38], there exists a unique solution for system (10)–(15) with initial (16).

2.1. Properties of Solutions

Lemma 1. Suppose that H1–H3 hold, then the solutions of system (10)–(15) are non-negative and ultimately bounded.

The proof Lemma 1 is given in Appendix A.

Lemma 1 shows that

$$\begin{aligned} \Omega = \{ & (s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x) \in C^{10} : \|s_i\| \leq M_{1i}, \|w_i\| \leq M_{1i}, \\ & \|y_i\| \leq M_{2i}, \|u_i\| \leq M_{3i}, \|p\| \leq M_{41}, \|x\| \leq M_{42} \} \end{aligned}$$

is positively invariant with respect to system (10)–(15).

2.2. Equilibria

The basic reproduction number R_0 of system (10)–(15) is given by:

$$R_0 = \sum_{i=1}^2 \frac{\gamma_i}{\psi'_{41}(0)} \frac{\partial Y_i(s_i^0, 0)}{\partial p}.$$

The equilibria of system (10)–(15) satisfy the following equations:

$$0 = \pi_i(s_i) - \lambda_i Y_i(s_i, p), \tag{17}$$

$$0 = \lambda_{1i} F_{1i} Y_i(s_i, p) - (\alpha_i + \beta_i) \psi_{1i}(w_i), \tag{18}$$

$$0 = \lambda_{2i} F_{2i} Y_i(s_i, p) + \alpha_i \psi_{1i}(w_i) - \eta_i \psi_{2i}(y_i), \tag{19}$$

$$0 = \lambda_{3i} F_{3i} Y_i(s_i, p) - \nu_i \psi_{3i}(u_i), \tag{20}$$

$$0 = \sum_{i=1}^2 (N_i \eta_i F_{4i} \psi_{2i}(y_i) + M_i \nu_i F_{5i} \psi_{3i}(u_i)) - g \psi_{41}(p) - \mu \psi_{41}(p) \psi_{42}(x), \tag{21}$$

$$0 = r \psi_{41}(p) \psi_{42}(x) - \omega \psi_{42}(x). \tag{22}$$

From Equation (22), we have $x = 0$ or $p = \psi_{41}^{-1}(\omega/r)$. Let us define

$$\begin{aligned} \Lambda_{1i}(s_i) &= \psi_{1i}^{-1} \left(\frac{\lambda_{1i} F_{1i}}{\lambda_i (\alpha_i + \beta_i)} \pi_i(s_i) \right), \Lambda_{2i}(s_i) = \psi_{2i}^{-1} \left(\frac{\alpha_i \lambda_{1i} F_{1i} + (\alpha_i + \beta_i) \lambda_{2i} F_{2i}}{\lambda_i \eta_i (\alpha_i + \beta_i)} \pi_i(s_i) \right), \\ \Lambda_{3i}(s_i) &= \psi_{3i}^{-1} \left(\frac{\lambda_{3i} F_{3i}}{\lambda_i \nu_i} \pi_i(s_i) \right), \Lambda_4(s_i) = \psi_{41}^{-1} \left(\sum_{i=1}^2 \frac{\gamma_i}{\lambda_i} \pi_i(s_i) \right), \end{aligned} \tag{23}$$

where $\gamma_i = \sum_{i=1}^2 \frac{N_i F_{4i} (\alpha_i \lambda_{1i} F_{1i} + (\alpha_i + \beta_i) \lambda_{2i} F_{2i}) + M_i F_{5i} \lambda_{3i} (\alpha_i + \beta_i)}{g (\alpha_i + \beta_i)}$. It follows from Equations (17)–(21) that:

$$w_i = \Lambda_{1i}(s_i), \quad y_i = \Lambda_{2i}(s_i), \quad u_i = \Lambda_{3i}(s_i), \quad p = \Lambda_4(s_i). \tag{24}$$

Obviously, $\Lambda_{1i}(s_i), \Lambda_{2i}(s_i), \Lambda_{3i}(s_i), \Lambda_4(s_i) > 0$ for $s_i \in [0, s_i^0]$ and $\Lambda_{1i}(s_i^0) = \Lambda_{2i}(s_i^0) = \Lambda_{3i}(s_i^0) = \Lambda_4(s_i^0) = 0, i = 1, 2$. From Equations (17), (23), and (24), we obtain

$$\sum_{i=1}^2 \gamma_i Y_i(s_i, \Lambda_4(s_i)) - \psi_{41}(\Lambda_4(s_i)) = 0. \tag{25}$$

Equation (25) has two possible solutions, $\Lambda_4 = 0$ and $\Lambda_4 \neq 0$. The solution $\Lambda_4 = 0$ implies $s_i = s_i^0$ which gives the infection-free equilibrium $\Pi_0(s_1^0, s_2^0, 0, 0, 0, 0, 0, 0, 0)$. The other solution $\Lambda_4 \neq 0$ admits an antibody-inactivated infection equilibrium $\Pi_1(\bar{s}_1, \bar{s}_2, \bar{w}_1, \bar{w}_2, \bar{y}_1, \bar{y}_2, \bar{u}_1, \bar{u}_2, \bar{p}, 0)$, where

$$\begin{aligned} \pi_i(\bar{s}_i) &= \lambda_i Y_i(\bar{s}_i, \bar{p}), \quad \lambda_{1i} F_{1i} Y_i(\bar{s}_i, \bar{p}) = (\alpha_i + \beta_i) \psi_{1i}(\bar{w}_i), \\ \eta_i \psi_{2i}(\bar{y}_i) &= \lambda_{2i} F_{2i} Y_i(\bar{s}_i, \bar{p}) + \alpha_i \psi_{1i}(\bar{w}_i), \\ \nu_i \psi_{3i}(\bar{u}_i) &= \lambda_{3i} F_{3i} Y_i(\bar{s}_i, \bar{p}), \quad g \psi_{41}(\bar{p}) = \sum_{i=1}^2 (N_i \eta_i F_{4i} \psi_{2i}(\bar{y}_i) + M_i \nu_i F_{5i} \psi_{3i}(\bar{u}_i)). \end{aligned} \tag{26}$$

Now, we consider the other solution of Equation (22) is $\bar{p} = \psi_{41}^{-1} \left(\frac{\omega}{r} \right) > 0$. Substitute $p = \bar{p} = \psi_{41}^{-1} \left(\frac{\omega}{r} \right)$ in Equation (17) and let $\Delta_i(s_i) = \pi_i(s_i) - \lambda_i Y_i(s_i, \bar{p}) = 0$. Using H1 and H2, we have Δ_i is strictly decreasing, $\Delta_i(0) = \pi_i(0) > 0$ and $\Delta_i(s_i^0) = -\lambda_i Y_i(s_i^0, \bar{p}) < 0$. Thus, there exists unique $\bar{s}_i \in (0, s_i^0)$ such that $\Delta_i(\bar{s}_i) = 0$. It follows from Equations (21) and (24) that

$$\begin{aligned} \bar{w}_i &= \Lambda_{1i}(\bar{s}_i) > 0, \quad \bar{y}_i = \Lambda_{2i}(\bar{s}_i) > 0, \quad \bar{u}_i = \Lambda_{3i}(\bar{s}_i) > 0, \\ \bar{p} &= \psi_{41}^{-1} \left(\frac{\omega}{r} \right) > 0, \quad \bar{x} = \psi_{42}^{-1} \left(\frac{g}{\mu} \left(\sum_{i=1}^2 \gamma_i \frac{Y_i(\bar{s}_i, \bar{p})}{\psi_{41}(\bar{p})} - 1 \right) \right). \end{aligned}$$

Thus, $\bar{x} > 0$ when $\sum_{i=1}^2 \gamma_i \frac{Y_i(\bar{s}_i, \bar{p})}{\psi_{41}(\bar{p})} > 1$. Define R_1 as follows:

$$R_1 = \sum_{i=1}^2 \gamma_i \frac{Y_i(\bar{s}_i, \bar{p})}{\psi_{41}(\bar{p})},$$

which represents the antibody immune response activation number.

If $R_1 > 1$, then $\bar{x} = \psi_{42}^{-1} \left(\frac{g}{\mu} (R_1 - 1) \right) > 0$, and there exists an antibody-activated infection equilibrium $\Pi_2(\bar{s}_1, \bar{s}_2, \bar{w}_1, \bar{w}_2, \bar{y}_1, \bar{y}_2, \bar{u}_1, \bar{u}_2, \bar{p}, \bar{x})$. Clearly, from H2 and H4, we have

$$\begin{aligned} R_1 &= \sum_{i=1}^2 \gamma_i \frac{Y_i(\bar{s}_i, \bar{p})}{\psi_{41}(\bar{p})} \leq \sum_{i=1}^2 \lim_{p \rightarrow 0^+} \gamma_i \frac{Y_i(\bar{s}_i, p)}{\psi_{41}(p)} \leq \sum_{i=1}^2 \frac{\gamma_i}{\psi'_{41}(0)} \frac{\partial Y_i(\bar{s}_i, 0)}{\partial p} \leq \sum_{i=1}^2 \frac{\gamma_i}{\psi'_{41}(0)} \frac{\partial Y_i(s_i^0, 0)}{\partial p} \\ &= R_0. \end{aligned}$$

3. Global Stability

Denote $(s_i, w_i, y_i, u_i, p, x) = (s_i(t), w_i(t), y_i(t), u_i(t), p(t), x(t))$.

Theorem 1. *Let hypotheses H1–H4 be valid and $R_0 \leq 1$; then, Π_0 is globally asymptotically stable.*

Lemma 2. *Suppose that $R_0 > 1$ and H1–H4 hold; then,*

$$\text{sgn}(R_1 - 1) = \text{sgn}(\bar{p} - \bar{p}) = \text{sgn}(\bar{s}_i - \bar{s}_i).$$

Theorem 2. *Suppose that hypotheses H1–H4 are satisfied, Π_1 exists and $R_1 \leq 1$, then Π_1 is globally asymptotically stable.*

Theorem 3. *Let hypotheses H1–H4 hold true and $R_1 > 1$, then Π_2 is globally asymptotically stable.*

The proofs of Lemma 2 and Theorems 1–3 are given in Appendix A.

4. Numerical Simulations

We choose

$$\begin{aligned} \pi_1(s_1(t)) &= \rho_1 - \beta_{11}s_1(t) + Bs_1(t) \left(1 - \frac{s_1(t)}{s_{\max}}\right), \quad \pi_2(s_2(t)) = \rho_2 - \beta_{12}s_2(t), \\ Y_i(s_i(t), p(t)) &= s_i(t)p(t), \quad \psi_{ji}(\theta) = \theta, \quad j = 1, \dots, 4, \quad i = 1, 2, \end{aligned}$$

where $B < \beta_{11}$. Clearly, $\pi_i(0) = \rho_i > 0$ and $\pi_i(s_i^0) = 0$, where

$$s_1^0 = \frac{s_{\max}}{2B} \left(B - \beta_{11} + \sqrt{(B - \beta_{11})^2 + \frac{4\rho_1 B}{s_{\max}}} \right), \quad s_2^0 = \frac{\rho_2}{\beta_{12}}.$$

We have

$$\pi'_1(s_1) = -\beta_{11} + B - \frac{2Bs_1}{s_{\max}} < 0, \quad \pi'_2(s_2) = -\beta_{12}.$$

Clearly, $\pi_i(s_i) > 0$ for $s_i \in [0, s_i^0)$ and

$$\begin{aligned} \pi_1(s_1) &= \rho_1 - (\beta_{11} - B)s_1 - B \frac{s_1^2}{s_{\max}} \leq \rho_1 - (\beta_{11} - B)s_1, \\ \pi_2(s_2) &= \rho_2 - \beta_{12}s_2. \end{aligned}$$

Then, H1 is satisfied. Clearly $Y_i(s_i, p) > 0$, $Y_i(0, p) = Y(s_i, 0) = 0$ for $s_i, p \in (0, \infty)$, and

$$\frac{\partial Y_i(s_i, p)}{\partial s_i} = p, \quad \frac{\partial Y_i(s_i, p)}{\partial p} = s_i, \quad \frac{\partial Y_i(s_i, 0)}{\partial p} = s_i.$$

Then, $\frac{\partial Y_i(s_i, p)}{\partial s_i} > 0$, $\frac{\partial Y_i(s_i, p)}{\partial p} > 0$ and $\frac{\partial Y_i(s_i, 0)}{\partial p} > 0$ for all $s_i, p \in (0, \infty)$. Therefore, H1 is satisfied. In addition

$$\left(\frac{\partial Y_i(s_i, 0)}{\partial p} \right)' = 1 > 0 \text{ for all } s_i > 0.$$

It follows that, H2 is satisfied. One can show that function ψ_{ji} satisfies H3. Moreover,

$$\frac{\partial}{\partial p} \left(\frac{Y_i(s_i, p)}{\psi_{41}(p)} \right) = 0.$$

Therefore, H4 holds true.

In addition, we take a particular form of the probability distributed function as:

$$f_{ji}(\tau) = \delta(t - \tau_{ji}), \quad j = 1, \dots, 5, \quad i = 1, 2,$$

where $\delta(\cdot)$ is the Dirac delta function and $\tau_{ji} \in [0, h_{ji}]$, $j = 1, \dots, 5, i = 1, 2$ are constants. When $h_{ji} \rightarrow \infty$, we have:

$$\int_0^\infty f_{ji}(\tau) d\tau = 1, \quad j = 1, \dots, 5, \quad i = 1, 2.$$

We have

$$F_{ji} = \int_0^\infty \delta(t - \tau_{ji}) e^{-\mu_{ji}\tau} d\tau = e^{-\mu_{ji}\tau_{ji}}, \quad j = 1, \dots, 5, \quad i = 1, 2.$$

Moreover,

$$\int_0^\infty \delta(t - \tau_{ji}) e^{-\mu_{ji}\tau} s_i(t - \tau) p(t - \tau) d\tau = e^{-\mu_{ji}\tau_{ji}} s_i(t - \tau_{ji}) p(t - \tau_{ji}), \quad j = 1, 2, 3, \quad i = 1, 2,$$

$$\int_0^\infty \delta(t - \tau_{4i}) e^{-\mu_{4i}\tau} y_i(t - \tau) d\tau = e^{-\mu_{4i}\tau_{4i}} y_i(t - \tau_{4i}),$$

$$\int_0^\infty \delta(t - \tau_{5i}) e^{-\mu_{5i}\tau} u_i(t - \tau) d\tau = e^{-\mu_{5i}\tau_{5i}} u_i(t - \tau_{5i}), \quad i = 1, 2.$$

Hence, model (10)–(15) becomes:

$$\dot{s}_1(t) = \rho_1 - \delta_1 s_1(t) + B s_1(t) \left(1 - \frac{s_1(t)}{s_{\max}}\right) - (1 - \varepsilon_1) \bar{\lambda}_1 s_1(t) p(t), \tag{27}$$

$$\dot{s}_2(t) = \rho_2 - \delta_2 s_2(t) - (1 - f\varepsilon_1) \bar{\lambda}_2 s_2(t) p(t), \tag{28}$$

$$\dot{w}_1(t) = (1 - \varepsilon_1) \bar{\lambda}_{11} e^{-\mu_{11}\tau_{11}} s_1(t - \tau_{11}) p(t - \tau_{11}) - (\alpha_1 + \beta_1) w_1(t), \tag{29}$$

$$\dot{w}_2(t) = (1 - f\varepsilon_1) \bar{\lambda}_{12} e^{-\mu_{12}\tau_{12}} s_2(t - \tau_{12}) p(t - \tau_{12}) - (\alpha_2 + \beta_2) w_2(t), \tag{30}$$

$$\dot{y}_1(t) = (1 - \varepsilon_1) \bar{\lambda}_{21} e^{-\mu_{21}\tau_{21}} s_1(t - \tau_{21}) p(t - \tau_{21}) + \alpha_1 w_1(t) - \eta_1 y_1(t), \tag{31}$$

$$\dot{y}_2(t) = (1 - f\varepsilon_1) \bar{\lambda}_{22} e^{-\mu_{22}\tau_{22}} s_2(t - \tau_{22}) p(t - \tau_{22}) + \alpha_2 w_2(t) - \eta_2 y_2(t), \tag{32}$$

$$\dot{u}_1(t) = (1 - \varepsilon_1) \bar{\lambda}_{31} e^{-\mu_{31}\tau_{31}} s_1(t - \tau_{31}) p(t - \tau_{31}) - \nu_1 u_1(t), \tag{33}$$

$$\dot{u}_2(t) = (1 - f\varepsilon_1) \bar{\lambda}_{32} e^{-\mu_{32}\tau_{32}} s_2(t - \tau_{32}) p(t - \tau_{32}) - \nu_2 u_2(t), \tag{34}$$

$$\begin{aligned} \dot{p}(t) = & (1 - \varepsilon_2) \bar{N}_1 \eta_1 e^{-\mu_{41}\tau_{41}} y_1(t - \tau_{41}) \\ & + (1 - h\varepsilon_2) \bar{N}_2 \eta_2 e^{-\mu_{42}\tau_{42}} y_2(t - \tau_{42}) \\ & + (1 - \varepsilon_2) \bar{M}_1 \nu_1 e^{-\mu_{51}\tau_{51}} u_1(t - \tau_{51}) \\ & + (1 - h\varepsilon_2) \bar{M}_2 \nu_2 e^{-\mu_{52}\tau_{52}} u_2(t - \tau_{52}) - gp(t) - \mu p(t) x(t), \end{aligned} \tag{35}$$

$$\dot{x}(t) = rp(t)x(t) - \omega x(t). \tag{36}$$

The parameters R_0 and R_1 for this application are given by:

$$R_0 = \sum_{i=1}^2 \frac{(\{N_i A_i e^{-\mu_{4i}\tau_{4i}} + M_i \lambda_{3i} (\alpha_i + \beta_i) e^{-\mu_{3i}\tau_{3i} - \mu_{5i}\tau_{5i}}\}}{g(\alpha_i + \beta_i)} s_i^0,$$

$$R_1 = \sum_{i=1}^2 \frac{(\{N_i A_i e^{-\mu_{4i}\tau_{4i}} + M_i \lambda_{3i} (\alpha_i + \beta_i) e^{-\mu_{3i}\tau_{3i} - \mu_{5i}\tau_{5i}}\}}{g(\alpha_i + \beta_i)} \bar{s}_i,$$

$$A_i = \alpha_i \lambda_{1i} e^{-\mu_{1i}\tau_{1i}} + (\alpha_i + \beta_i) \lambda_{2i} e^{-\mu_{2i}\tau_{2i}}.$$

In Table 1, we present the values of parameters of system (27)–(36). We let $\tau_{ij} = \tau, \mu_{ij} = \mu_e, i = 1, 2, \dots, 5, j = 1, 2$. We solve the system of delay differential Equations (27)–(36) with constant delays by using dde23 program in MATLAB (version 7).

Table 1. The data of example (27)–(36).

Parameter	Value	Parameter	Value	Parameter	Value	Parameter	Value
ρ_1	10	ρ_2	0.03198	η_1	0.35	η_2	0.03
δ_1	0.01	δ_2	0.002	ν_1	0.03	ν_2	0.01
B	0.0002	x_{\max}	1200	g	3	μ	0.5
α_1	0.2	α_2	0.01	ω	0.1	μ_e	1
β_1	0.02	β_2	0.001	f	0.3	h	0.3
\bar{N}_1	30	\bar{N}_2	5	\bar{M}_1	10	\bar{M}_2	2
ε_1	varied	ε_2	varied	r	varied	τ	varied
$\bar{\lambda}_{i1}$	0.0000625	$\bar{\lambda}_{i2}$	0.0000625	-	-	-	-

4.1. Stability of the Equilibria of the System

In this part of simulation, we choose three different initial conditions:

IC1: $(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x)(\theta) = (450, 8, 6, 0.15, 6, 0.18, 35, 0.3, 10, 6),$

IC2: $(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x)(\theta) = (650, 10, 4, 0.1, 5, 0.06, 25, 0.1, 7, 4),$

IC3: $(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x)(\theta) = (850, 12, 2, 0.05, 3, 0.02, 15, 0.02, 4, 2), \theta \in [-\tau, 0].$

We study three cases by choosing $\varepsilon_1, \varepsilon_2, \tau$ and r . In Figures 1–10, we want to confirm our global stability results given in Theorems 1–3, by showing that any initial points taken from a feasible set the trajectory of the system will tend to one of the three equilibria of the system.

Case (I): Choose $\varepsilon_1 = 0.7, \varepsilon_2 = 0.7, \tau = 0.85$ and $r = 0.009$, which gives $R_0 = 0.2778 < 1$ and $R_1 = 0.1156 < 1$. Figures 1–10 show that the concentrations of the uninfected CD4⁺ T cells and macrophages are increasing and reach the values $s_1^0 = 1003.3$ and $s_2^0 = 16$, respectively. In other words, concentrations of short-lived, long-lived and latently infected cells as well as HIV particles and B cells converge to zero. This confirms the result of Theorem 1, which is Π_0 is globally asymptotically stable. As a result, the HIV is removed from the plasma.

Case (II): We take $\varepsilon_1 = 0.2, \varepsilon_2 = 0.3, \tau = 0.5$ and $r = 0.004$. For these values, $R_1 = 0.6692 < 1 < R_0 = 3.1775$. From Figures 1–10, we can see that for IC1–IC3 the state $\Pi_1 = (346.147, 7.549, 6.054, 0.31, 7.265, 0.217, 44.397, 0.341, 12.688, 0.0)$ is reached, where the HIV infection is chronic and the antibody immune system is inactive. Hence, Theorem 2 is confirmed.

Case (III): $\varepsilon_1 = 0.2, \varepsilon_2 = 0.3, \tau = 0.5$ and $r = 0.05$. Then, we calculate $R_0 = 3.1775 > 1$ and $R_1 = 2.4497 > 1$. From Figures 1–10, we see that for IC1–IC3, the state $\Pi_2 = (773.46, 13.594, 2.132, 0.088, 2.559, 0.062, 15.638, 0.097, 2, 7.405)$ is reached, where the HIV infection is chronic and the antibody immune system is active. Thus, Theorem 3 is confirmed.

We mention that, R_0 does not depends on the parameters ω, r and μ . This fact seems to suggest that antibody immune response does not play a role in clearing the HIV particles. From above, we can see that R_1 can be increased by increasing the value of r . When we compare the Cases (II) and (III), we can see from the figures that, when the antibody immune response is activated (i.e., $R_1 > 1$), it reduces the concentrations of HIV free particles and infected (short-lived, long-lived and latent) cells and increases the concentration of uninfected target cells. It means that the antibody immune response can play a significant role in controlling the infection.

Effect of the Drug Efficacy on the Stability of the System

We take $\varepsilon_1 = \varepsilon_2 = \varepsilon, \tau = 0.5$, and $r = 0.05$. In Table 2, we present the values of R_0 and R_1 for selected values of ε . It is seen that the values of R_0 and R_1 are decreased as ε is increased. Using the values of the parameters given in Table 1, we obtain the following cases:

- (i) if $0 \leq \varepsilon < 0.54636$, then $R_1 > 1, \Pi_2$ exists and it is globally asymptotically stable,
- (ii) if $0.54636 \leq \varepsilon < 0.58032$, then $R_1 \leq 1, \Pi_1$ exists and it is globally asymptotically stable and
- (iii) if $0.58032 \leq \varepsilon \leq 1$, then $R_0 \leq 1$ and Π_0 is globally asymptotically stable.

Thus, the results of Theorems 1–3 and the numerical results are compatible. Therefore, we can say that treatment with sufficient drug efficacy can successfully clear the virus from the plasma.

Table 2. The values of the steady states, R_0 and R_1 for model (27)–(36) with different values of ε .

ε	Equilibria	R_0	R_1
0	$\Pi_2 = (731.427, 13.4656, 2.5206, 0.0928, 3.0248, 0.065, 18.4847, 0.1021, 2, 16.6341)$	5.6732	4.1361
0.2	$\Pi_2 = (773.4604, 13.5944, 2.1324, 0.0881, 2.5589, 0.0617, 15.6376, 0.0969, 2, 9.3198)$	3.6313	2.7995
0.5	$\Pi_2 = (846.3064, 13.7922, 1.4583, 0.0808, 1.7499, 0.0566, 10.6940, 0.0889, 2, 0.5505)$	1.4191	1.1970
0.54636	$\Pi_1 = (941.6053, 15.0676, 0.5739, 0.0339, 0.6887, 0.0237, 4.2086, 0.0372, 0.7797, 0)$	1.1683	1
0.55	$\Pi_1 = (956.889, 15.2913, 0.4318, 0.0256, 0.5182, 0.0179, 3.1666, 0.0282, 0.582, 0)$	1.1496	0.9852
0.58032	$\Pi_0 = (1003.3, 16, 0, 0, 0, 0, 0, 0, 0, 0)$	1	0.8654
0.7	$\Pi_0 = (1003.3, 16, 0, 0, 0, 0, 0, 0, 0, 0)$	0.5114	0.4602

4.2. Effect of the Time Delay on the Stability of the System

Choose $\varepsilon_1 = \varepsilon_2 = 0$, and $r = 0.05$. The initial conditions are considered to be $(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x)(\theta) = (800, 14, 4, 0.1, 4, 0.05, 20, 0.015, 6, 5)$, $\theta \in [-\tau, 0]$. Figures 11–20 and Table 3 show the effect of the time delay parameter τ on the stability of Π_0 , Π_1 and Π_2 . It can be seen that, as τ is increased, the concentration of the uninfected target cells is increased, while the concentrations of short-lived, long-lived and latently infected cells, free HIV particles and B cells are decreased. From Figures 11–20, we can see that, in the case of smaller values of τ , the trajectory of system will converge to Π_2 . When the value of τ is increased, the trajectory will converge to Π_1 and finally approach Π_0 . From a biological point of view, the intracellular time delay plays a similar role as the anti-HIV drugs in eliminating the virus. We observe that sufficiently large delay suppresses viral replication and clears the virus from the body. This gives us some suggestions on new drugs to prolong the increase in the intracellular delay period.

Table 3. The values of steady states, R_0 and R_1 for model (27)–(36) with different values of τ .

τ	Equilibria	R_0	R_1
0.1	$\Pi_2 = (731.43, 13.47, 3.76, 0.14, 4.51, 0.1, 27.58, 0.15, 2, 44.37)$	11.70	8.53
0.5	$\Pi_2 = (731.43, 13.47, 2.52, 0.09, 3.03, 0.07, 18.49, 0.1, 2, 16.63)$	5.67	4.14
1.0	$\Pi_2 = (731.43, 13.47, 1.53, 0.06, 1.84, 0.04, 11.21, 0.06, 2, 2.33)$	2.39	1.74
1.2	$\Pi_1 = (786.28, 14.03, 1, 0.04, 1.2, 0.03, 7.33, 0.04, 1.49, 0.00)$	1.72	1.25
1.3	$\Pi_1 = (960.39, 15.63, 0.18, 0.01, 0.22, 0.00, 1.32, 0.01, 0.24, 0.00)$	1.1	1.46
1.5	$\Pi_0 = (1003.3, 16, 0, 0, 0, 0, 0, 0, 0, 0)$	1.06	0.77
2	$\Pi_0 = (1003.3, 16, 0, 0, 0, 0, 0, 0, 0, 0)$	0.50	0.37

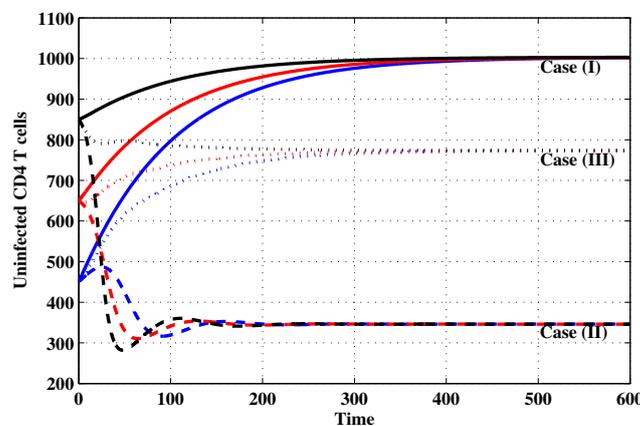


Figure 1. The evolution of uninfected CD4⁺ T cells with three initial conditions IC1–IC3 for Cases (I)–(III).

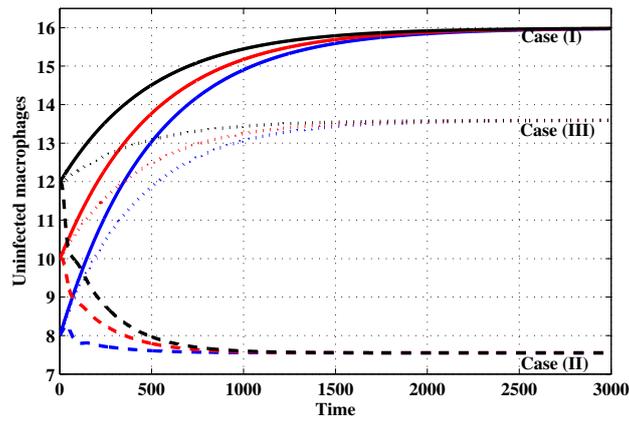


Figure 2. The evolution of uninfected macrophages with three initial conditions IC1–IC3 for Cases (I)–(III).

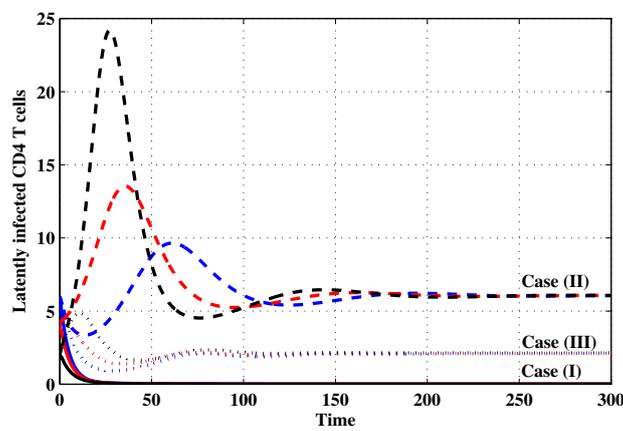


Figure 3. The evolution of latently infected CD4⁺ T cells with three initial conditions IC1–IC3 for Cases (I)–(III).

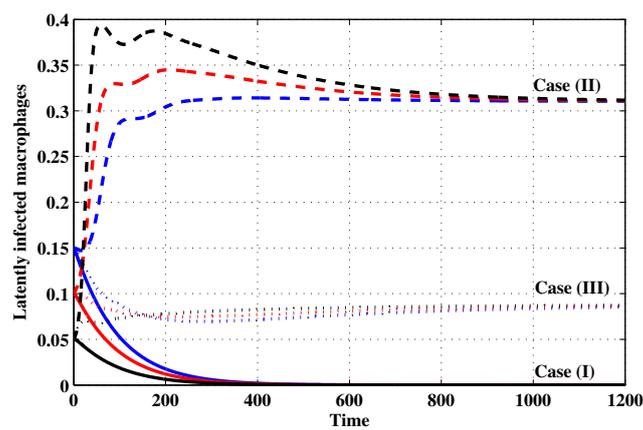


Figure 4. The evolution of latently infected macrophages with three initial conditions IC1–IC3 for Cases (I)–(III).

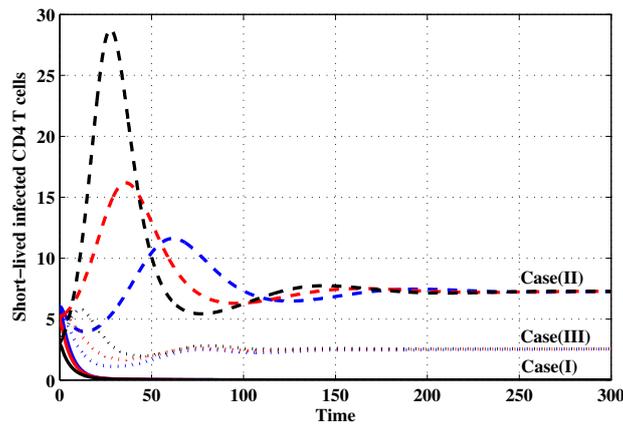


Figure 5. The evolution of short-lived productively infected CD4⁺ T cells with three initial conditions IC1–IC3 for Cases (I)–(III).

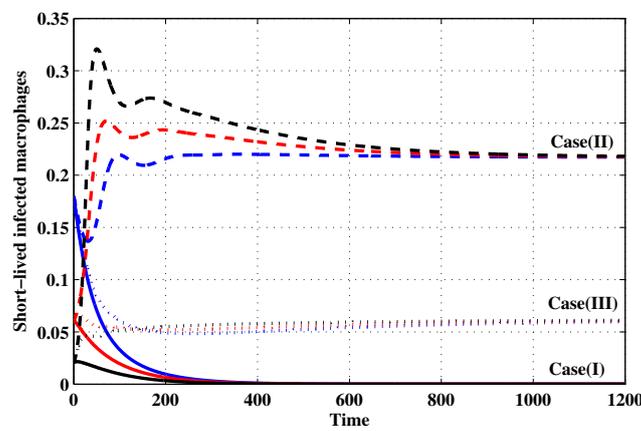


Figure 6. The evolution of short-lived productively infected macrophages with three initial conditions IC1–IC3 for Cases (I)–(III).

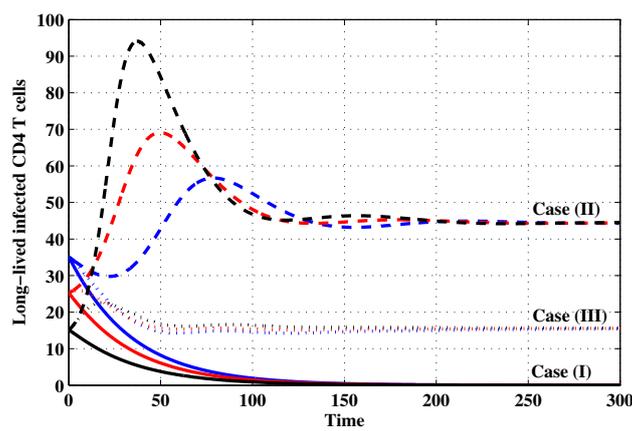


Figure 7. The evolution of long-lived productively infected CD4⁺ T cells with three initial conditions IC1–IC3 for Cases (I)–(III).

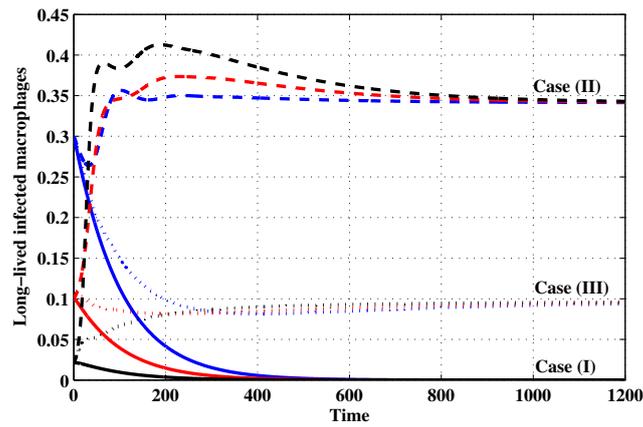


Figure 8. The evolution of long-lived productively infected macrophages with three initial conditions IC1–IC3 for Cases (I)–(III).

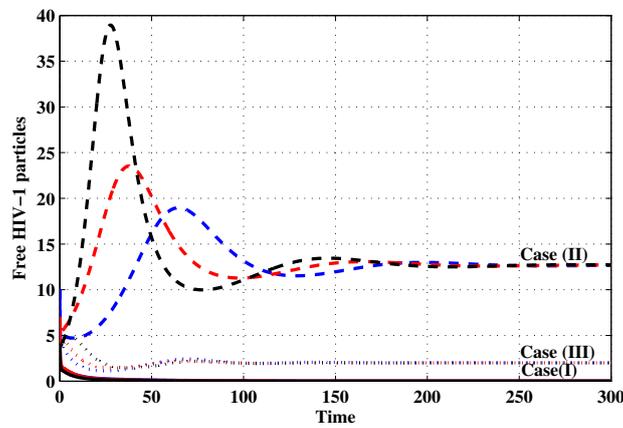


Figure 9. The evolution of free HIV particles with three initial conditions IC1–IC3 for Cases (I)–(III).

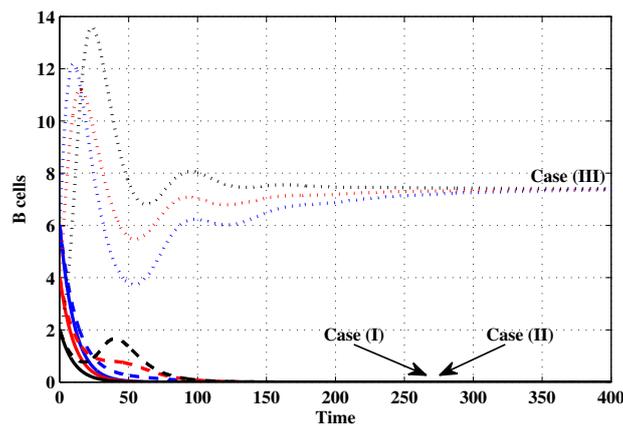


Figure 10. The evolution of B cells with three initial conditions IC1–IC3 for Cases (I)–(III).

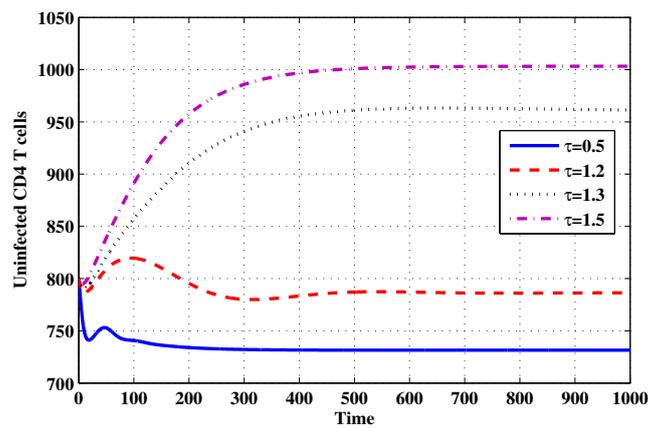


Figure 11. The evolution of uninfected CD4⁺ T cells for selected values of the delay parameter τ .

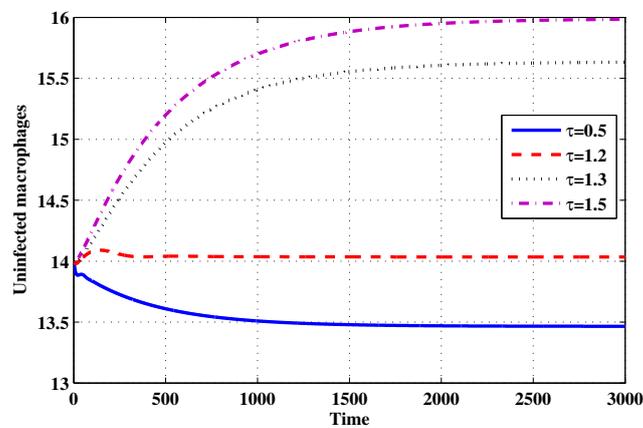


Figure 12. The evolution of uninfected macrophages for selected values of the delay parameter τ .

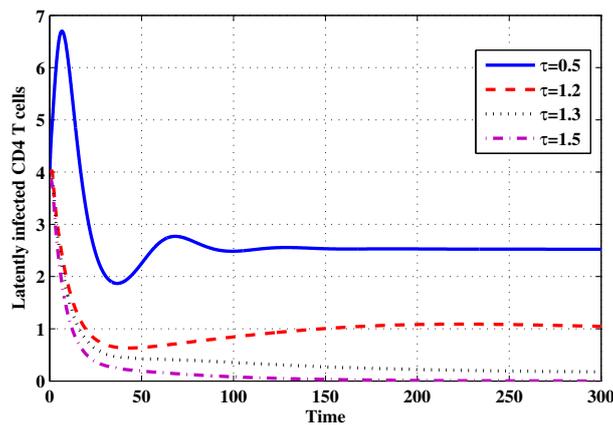


Figure 13. The evolution of latently infected CD4⁺ T cells for selected values of the delay parameter τ .

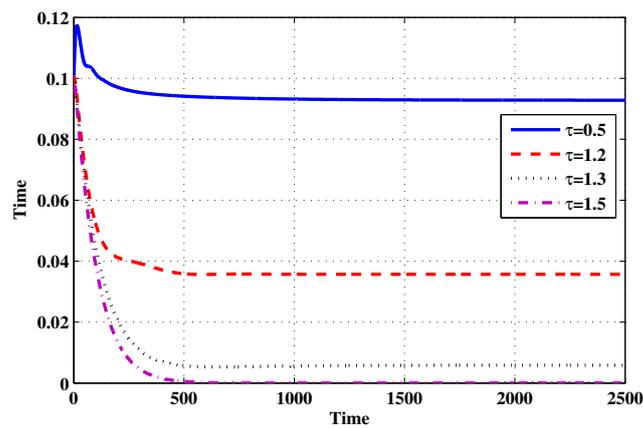


Figure 14. The evolution of latently infected macrophages for selected values of the delay parameter τ .

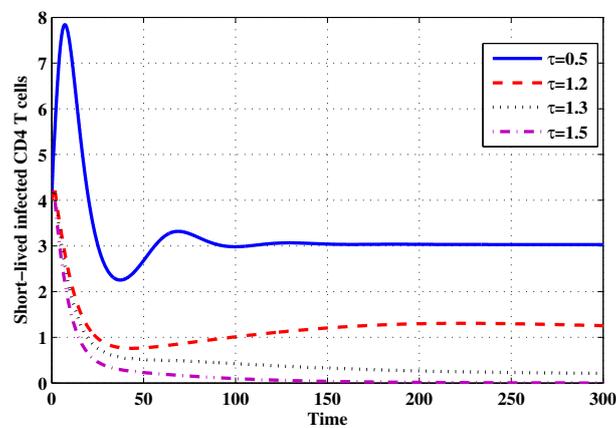


Figure 15. The evolution of short-lived productively infected CD4⁺ T cells for selected values of the delay parameter τ .

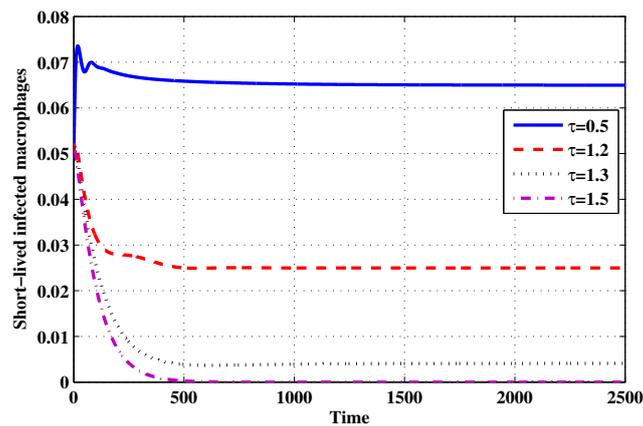


Figure 16. The evolution of short-lived productively infected macrophages for selected values of the delay parameter τ .

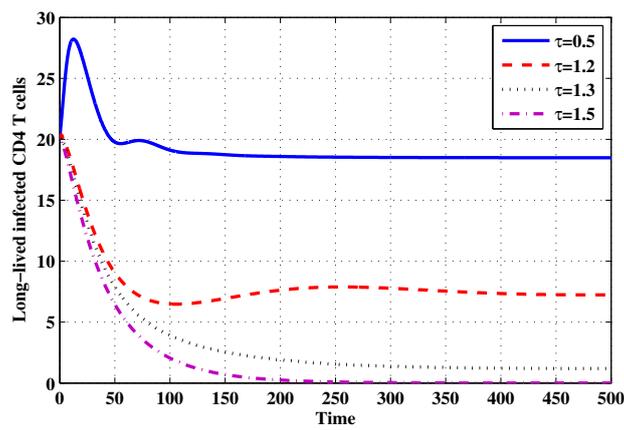


Figure 17. The evolution of long-lived productively infected CD4⁺ T cells for selected values of the delay parameter τ .

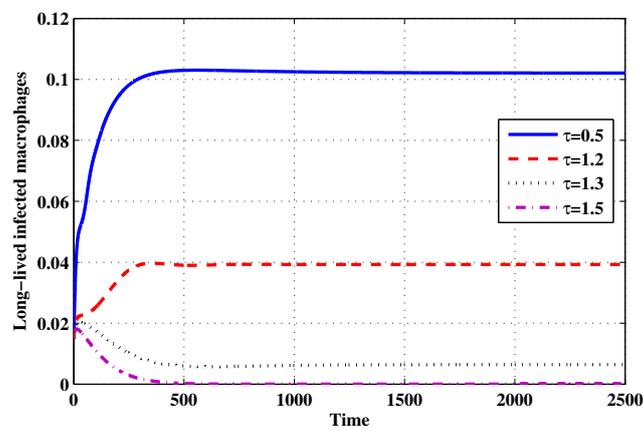


Figure 18. The evolution of long-lived productively infected macrophages for selected values of the delay parameter τ .

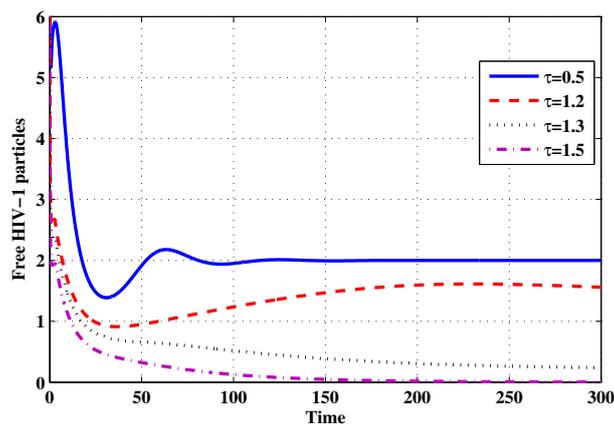


Figure 19. The evolution of free HIV particles for selected values of the delay parameter τ .

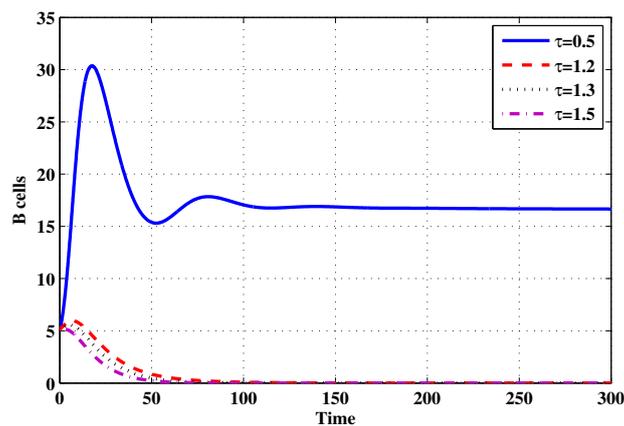


Figure 20. The evolution of B cells for selected values of the delay parameter τ .

5. Discussion

All of the HIV infection mathematical models with three categories of infected cells, short-lived, long-lived and latent presented in the literature have studied the HIV infection and production in one class of target cells, $CD4^+$ T cells. However, it has been reported in several papers that HIV can infect both $CD4^+$ T cells and macrophages. In this paper, we have proposed an HIV infection model with three categories of infected cells and two classes of target cells, $CD4^+$ T cells and macrophages. We have incorporated multiple distributed time delays to characterize the time between an HIV contacts an uninfected target cell and the creation of mature HIV particles. The effect of antibody immune response has been modeled. The production and removal rates of all compartments are represented by general nonlinear functions. The incidence rate of infection is also given by a general nonlinear function. The model can be seen as a generalization of several HIV dynamics models presented in the literature. We have shown that the solutions of the model are nonnegative and ultimately bounded, which ensures the well-posedness of the model. We have derived two threshold numbers R_0 (the basic reproduction number) and antibody immune response activation number R_1 , which determine the stability of the three equilibria of the model. We have investigated the global stability of the equilibria of the model by using Lyapunov method and LaSalle's invariance principle. We have proven that (i) if $R_0 \leq 1$, then the infection-free equilibrium Π_0 is globally asymptotically stable and the HIV is predicted to be completely cleared from the HIV infected patients, (ii) if the antibody-inactivated infection equilibrium Π_1 exists then it is globally asymptotically stable and a chronic HIV infection with inactive antibody immunity is attained, and (iii) if $R_1 > 1$, then the antibody-activated infection equilibrium Π_2 is globally asymptotically stable and a chronic HIV infection with active antibody immunity is attained. We have conducted numerical simulations and have shown that both the theoretical and numerical results are consistent.

Our analysis extends the results presented in [27], where the global stability was analyzed for a model with one target cell population. When we consider the HIV dynamics with only one class of target cells, CD4⁺ T cells, then model (10)–(15) leads to the following model:

$$\dot{s}_1(t) = \rho_1 - \delta_1 s_1(t) + B s_1(t) \left(1 - \frac{s_1(t)}{s_{\max}}\right) - (1 - \varepsilon_1) \bar{\lambda}_1 s_1(t) p(t), \tag{37}$$

$$\dot{w}_1(t) = (1 - \varepsilon_1) \bar{\lambda}_{11} e^{-\mu_{11} \tau_{11}} s_1(t - \tau_{11}) p(t - \tau_{11}) - (\alpha_1 + \beta_1) w_1(t), \tag{38}$$

$$\dot{y}_1(t) = (1 - \varepsilon_1) \bar{\lambda}_{21} e^{-\mu_{21} \tau_{21}} s_1(t - \tau_{21}) p(t - \tau_{21}) + \alpha_1 w_1(t) - \eta_1 y_1(t), \tag{39}$$

$$\dot{u}_1(t) = (1 - \varepsilon_1) \bar{\lambda}_{31} e^{-\mu_{31} \tau_{31}} s_1(t - \tau_{31}) p(t - \tau_{31}) - \nu_1 u_1(t), \tag{40}$$

$$\begin{aligned} \dot{p}(t) = & (1 - \varepsilon_2) \bar{N}_1 \eta_1 e^{-\mu_{41} \tau_{41}} y_1(t - \tau_{41}) + (1 - \varepsilon_2) \bar{M}_1 \nu_1 e^{-\mu_{51} \tau_{51}} u_1(t - \tau_{51}) \\ & - g p(t) - \mu p(t) x(t), \end{aligned} \tag{41}$$

$$\dot{x}(t) = r p(t) x(t) - \omega x(t). \tag{42}$$

Let us define the overall HAART effect as $\varepsilon_e = \varepsilon_1 + \varepsilon_2 - \varepsilon_1 \varepsilon_2$ [39]. If $\varepsilon_e = 0$, then the HAART has no effect, if $\varepsilon_e = 1$, the HIV-1 growth is completely halted. Consequently, the basic reproduction number for system (37)–(42) is given by

$$\begin{aligned} R_0^C(\varepsilon_e) &= \frac{(1 - \varepsilon_e) [\bar{N}_1 \bar{A}_1 e^{-\mu_{41} \tau_{41}} + \bar{M}_1 \bar{\lambda}_{31} (\alpha_1 + \beta_1) e^{-\mu_{31} \tau_{31} - \mu_{51} \tau_{51}}]}{g(\alpha_1 + \beta_1)} s_1^0, \\ \bar{A}_1 &= \alpha_1 \bar{\lambda}_{11} e^{-\mu_{11} \tau_{11}} + (\alpha_1 + \beta_1) \bar{\lambda}_{21} e^{-\mu_{21} \tau_{21}}. \end{aligned}$$

For comparison purposes, we assume that $h = f = 1$; then, the basic reproduction number for system (27)–(36) can be written as: $R_0 = R_0^{CM}(\varepsilon_e) = R_0^C(\varepsilon_e) + R_0^M(\varepsilon_e)$ where:

$$\begin{aligned} R_0^M(\varepsilon_e) &= \frac{(1 - \varepsilon_e) [\bar{N}_2 \bar{A}_2 e^{-\mu_{42} \tau_{42}} + \bar{M}_2 \bar{\lambda}_{32} (\alpha_2 + \beta_2) e^{-\mu_{32} \tau_{32} - \mu_{52} \tau_{52}}]}{g(\alpha_2 + \beta_2)} s_2^0, \\ \bar{A}_2 &= \alpha_2 \bar{\lambda}_{12} e^{-\mu_{12} \tau_{12}} + (\alpha_2 + \beta_2) \bar{\lambda}_{22} e^{-\mu_{22} \tau_{22}}, \end{aligned}$$

where $R_0^M(\varepsilon_e)$ is the basic reproduction number of a model that describes the HIV dynamics with only macrophages and neglecting the CD4⁺ T cells. For system (37)–(42), one can determine drug efficacy ε_e^C such that $R_0^C(\varepsilon_e^C) = 1$ as:

$$\varepsilon_e^C = \max \left\{ \frac{R_0^C(0) - 1}{R_0^C(0)}, 0 \right\}.$$

Therefore, if $\varepsilon_e^C \leq \varepsilon_e \leq 1$, then $R_0^C(\varepsilon_e) \leq 1$. For system (27)–(36), one can also determine the drug efficacy ε_e^{CM} such that $R_0^{CM}(\varepsilon_e^{CM}) = 1$ as:

$$\varepsilon_e^{CM} = \max \left\{ \frac{R_0^{CM}(0) - 1}{R_0^{CM}(0)}, 0 \right\}.$$

Therefore, if $\varepsilon_e^{CM} \leq \varepsilon_e \leq 1$, then $R_0^{CM}(\varepsilon_e^{CM}) \leq 1$.

Assume that $R_0^C(0) > 1$, then Π_0 of system (37)–(42) is unstable in the absence of treatment. Since $R_0^C(0) < R_0^{CM}(0)$, then $\varepsilon_e^C < \varepsilon_e^{CM}$. Therefore, if we apply drugs with ε_e such that $\varepsilon_e^C \leq \varepsilon_e < \varepsilon_e^{CM}$, this guarantees that $R_0^C(\varepsilon_e) \leq 1$ and the system (37)–(42) can be stabilized around Π_0 ; however, $R_0^{CM}(\varepsilon_e) > 1$ and then Π_0 of (27)–(36) is unstable. Therefore, more accurate drug efficacy ε_e is determined when using the model with two classes of target cells. This shows the importance of considering the effect of the macrophages in the HIV dynamics.

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Appendix A

The following equalities will be used in the proofs of the Theorems 2 and 3:

$$\begin{aligned}
 \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) &= \ln \left(\frac{\psi_{1i}(\hat{w}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{1i}(w_i) Y_i(\hat{s}_i, \hat{p})} \right) + \ln \left(\frac{Y_i(\hat{s}_i, \hat{p})}{Y_i(s_i, \hat{p})} \right) \\
 &+ \ln \left(\frac{\psi_{41}(p) Y_i(s_i, \hat{p})}{\psi_{41}(\hat{p}) Y_i(s_i, p)} \right) + \ln \left(\frac{\psi_{41}(\hat{p}) \psi_{2i}(y_i)}{\psi_{41}(p) \psi_{2i}(\hat{y}_i)} \right) \\
 &+ \ln \left(\frac{\psi_{2i}(\hat{y}) \psi_{1i}(w_i)}{\psi_{2i}(y_i) \psi_{1i}(\hat{w}_i)} \right), \\
 \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) &= \ln \left(\frac{\psi_{2i}(\hat{y}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{2i}(y_i) Y_i(\hat{s}_i, \hat{p})} \right) + \ln \left(\frac{Y_i(\hat{s}_i, \hat{p})}{Y_i(s_i, \hat{p})} \right) \\
 &+ \ln \left(\frac{\psi_{41}(\hat{p}) \psi_{2i}(y_i)}{\psi_{41}(p) \psi_{2i}(\hat{y}_i)} \right) + \ln \left(\frac{\psi_{41}(p) Y_i(s_i, \hat{p})}{\psi_{41}(\hat{p}) Y_i(s_i, p)} \right), \\
 \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) &= \ln \left(\frac{\psi_{3i}(\hat{u}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{3i}(u_i) Y_i(\hat{s}_i, \hat{p})} \right) + \ln \left(\frac{Y_i(\hat{s}_i, \hat{p})}{Y_i(s_i, \hat{p})} \right) \\
 &+ \ln \left(\frac{\psi_{3i}(u_i) \psi_{41}(\hat{p})}{\psi_{3i}(\hat{u}_i) \psi_{41}(p)} \right) + \ln \left(\frac{\psi_{41}(p) Y_i(s_i, \hat{p})}{\psi_{41}(\hat{p}) Y_i(s_i, p)} \right), \\
 \ln \left(\frac{\psi_{2i}(y_i(t-\tau))}{\psi_{2i}(y_i)} \right) &= \ln \left(\frac{\psi_{2i}(y_i(t-\tau)) \psi_{41}(\hat{p})}{\psi_{2i}(\hat{y}_i) \psi_{41}(p)} \right) + \ln \left(\frac{\psi_{2i}(\hat{y}_i) \psi_{41}(p)}{\psi_{2i}(y_i) \psi_{41}(\hat{p})} \right), \\
 \ln \left(\frac{\psi_{3i}(u_i(t-\tau))}{\psi_{3i}(u_i)} \right) &= \ln \left(\frac{\psi_{3i}(u_i(t-\tau)) \psi_{41}(\hat{p})}{\psi_{3i}(\hat{u}_i) \psi_{41}(p)} \right) + \ln \left(\frac{\psi_{3i}(\hat{u}_i) \psi_{41}(p)}{\psi_{3i}(u_i) \psi_{41}(\hat{p})} \right). \tag{A1}
 \end{aligned}$$

Proof of Lemma 1. Denote $k = (s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x)^T$, $L = (L_1, L_2, \dots, L_{10})^T$. Then, systems (10)–(15) can be written as $\dot{k}(t) = L(k(t))$, where

$$L(k(t)) = \begin{pmatrix} L_1(k(t)) \\ L_2(k(t)) \\ \vdots \\ L_{10}(k(t)) \end{pmatrix},$$

$$L = \left(\begin{array}{c} \pi_1(s_1(t)) - \lambda_1 Y_1(s_1(t), p(t)) \\ \pi_2(s_2(t)) - \lambda_2 Y_2(s_2(t), p(t)) \\ \lambda_{11} \int_0^{h_{11}} \Theta_{11} Y_1(s_1(t-\tau), p(t-\tau)) d\tau - (\alpha_1 + \beta_1) \psi_{11}(w_1(t)) \\ \lambda_{12} \int_0^{h_{12}} \Theta_{12} Y_2(s_2(t-\tau), p(t-\tau)) d\tau - (\alpha_2 + \beta_2) \psi_{12}(w_2(t)) \\ \lambda_{21} \int_0^{h_{21}} \Theta_{21} Y_1(s_1(t-\tau), p(t-\tau)) d\tau + \alpha_1 \psi_{11}(w_1(t)) - \eta_1 \psi_{21}(y_1(t)), \\ \lambda_{22} \int_0^{h_{22}} \Theta_{22} Y_2(s_2(t-\tau), p(t-\tau)) d\tau + \alpha_2 \psi_{12}(w_2(t)) - \eta_2 \psi_{22}(y_2(t)), \\ \lambda_{31} \int_0^{h_{31}} \Theta_{31} Y_1(s_1(t-\tau), p(t-\tau)) d\tau - \nu_1 \psi_{31}(u_1(t)) \\ \lambda_{32} \int_0^{h_{32}} \Theta_{32} Y_2(s_2(t-\tau), p(t-\tau)) d\tau - \nu_2 \psi_{32}(u_2(t)) \\ \sum_{i=1}^2 \left(N_i \eta_i \int_0^{h_{4i}} \Theta_{4i} \psi_{2i}(y_i(t-\tau)) d\tau + M_i \nu_i \int_0^{h_{5i}} \Theta_{5i} \psi_{3i}(u_i(t-\tau)) d\tau \right) - g \psi_{41}(p(t)) \\ - \mu \psi_{41}(p(t)) \psi_{42}(x(t)), \\ r \psi_{41}(p(t)) \psi_{42}(x(t)) - \omega \psi_{42}(x(t)) \end{array} \right).$$

We have

$$L_j(k(t))|_{k(t) \in \mathbb{R}_{>0}^{10}} \geq 0, \quad j = 1, \dots, 10.$$

Applying Lemma 2 in [40], we get $k(t) \in \mathbb{R}_{\geq 0}^{10}$ for all $t \geq 0$.

Equation (10) implies that $\lim_{t \rightarrow \infty} \sup s_i(t) \leq M_{1i}$, where $M_{1i} = \frac{b_i}{b_i}$. Let

$$G_i(t) = N_i \int_0^{h_{1i}} \Theta_{1i}(\tau) s_i(t-\tau) d\tau + N_i \int_0^{h_{2i}} \Theta_{2i}(\tau) s_i(t-\tau) d\tau + M_i \int_0^{h_{3i}} \Theta_{3i}(\tau) s_i(t-\tau) d\tau \\ + N_i w_i(t) + N_i y_i(t) + M_i u_i(t),$$

then

$$\begin{aligned}
 \dot{G}_i(t) &= N_i \int_0^{h_{1i}} \Theta_{1i}(\tau) [\pi_i(s_i(t-\tau)) - \lambda_i Y_i(s_i(t-\tau), p(t-\tau))] d\tau \\
 &+ N_i \int_0^{h_{2i}} \Theta_{2i}(\tau) [\pi_i(s_i(t-\tau)) - \lambda_i Y_i(s_i(t-\tau), p(t-\tau))] d\tau \\
 &+ M_i \int_0^{h_{3i}} \Theta_{3i}(\tau) [\pi_i(s_i(t-\tau)) - \lambda_i Y_i(s_i(t-\tau), p(t-\tau))] d\tau \\
 &+ N_i \left[\lambda_{1i} \int_0^{h_{1i}} \Theta_{1i}(\tau) Y_i(s_i(t-\tau), p(t-\tau)) d\tau - (\alpha_i + \beta_i) \psi_{1i}(w_i(t)) \right] \\
 &+ N_i \left[\lambda_{2i} \int_0^{h_{2i}} \Theta_{2i}(\tau) Y_i(s_i(t-\tau), p(t-\tau)) d\tau + \alpha_i \psi_{1i}(w(t)) - \eta_i \psi_{2i}(y_i(t)) \right] \\
 &+ M_i \left[\lambda_{3i} \int_0^{h_{3i}} \Theta_{3i}(\tau) Y_i(s_i(t-\tau), p(t-\tau)) d\tau - \nu_i \psi_{3i}(u_i(t)) \right] \\
 &\leq N_i \int_0^{h_{1i}} \Theta_{1i}(\tau) [b_i - \bar{b}_i s_i(t-\tau)] d\tau + N_i \int_0^{h_{2i}} \Theta_{2i}(\tau) [b_i - \bar{b}_i s_i(t-\tau)] d\tau \\
 &+ M_i \int_0^{h_{3i}} \Theta_{3i}(\tau) [b_i - \bar{b}_i s_i(t-\tau)] d\tau - N_i \beta_i \alpha_{1i} w_i(t) - N_i \eta_i \alpha_{2i} y_i(t) - M_i \nu_i \alpha_{3i} u_i(t) \\
 &\leq b_i (N_i F_{1i} + N_i F_{2i} + M_i F_{3i}) - \sigma_i \left[N_i \int_0^{h_{1i}} \Theta_{1i}(\tau) s_i(t-\tau) d\tau + N_i \int_0^{h_{2i}} \Theta_{2i}(\tau) s_i(t-\tau) d\tau \right. \\
 &\left. + M_i \int_0^{h_{3i}} \Theta_{3i}(\tau) s_i(t-\tau) d\tau + N_i w_i(t) + N_i y_i(t) + M_i u_i(t) \right] \\
 &\leq b_i (2N_i + M_i) - \sigma_i G_i(t),
 \end{aligned}$$

where $\sigma_i = \min\{\bar{b}_i, \beta_i \alpha_{1i}, \eta_i \alpha_{2i}, \nu_i \alpha_{3i}\}$. Then, $\lim_{t \rightarrow \infty} \sup G_i(t) \leq \frac{b_i (2N_i + M_i)}{\sigma_i}$ and

$$\begin{aligned}
 \limsup_{t \rightarrow \infty} w_i(t) &\leq \frac{b_i (2N_i + M_i)}{N_i \sigma_i} = M_{2i}, \\
 \limsup_{t \rightarrow \infty} y_i(t) &\leq \frac{b_i (2N_i + M_i)}{N_i \sigma_i} = M_{2i}, \\
 \limsup_{t \rightarrow \infty} u_i(t) &\leq \frac{b_i (2N_i + M_i)}{M_i \sigma_i} = M_{3i}.
 \end{aligned}$$

Moreover, we let $G_3(t) = p(t) + \frac{\mu}{r}x(t)$. Then,

$$\begin{aligned} \dot{G}_3 &= \sum_{i=1}^2 \left(N_i \eta_i \int_0^{h_{4i}} \Theta_{4i}(\tau) \psi_{2i}(y_i(t-\tau)) d\tau + M_i \nu_i \int_0^{h_{5i}} \Theta_{5i}(\tau) \psi_{3i}(u_i(t-\tau)) d\tau \right) \\ &\quad - g \psi_{41}(p) - \frac{q\omega}{r} \psi_{42}(x) \\ &\leq \sum_{i=1}^2 (N_i \eta_i F_{4i} \psi_{2i}(M_{2i}) + M_i \nu_i F_{5i} \psi_{3i}(M_{3i})) - g \alpha_{41} p - \frac{\mu\omega}{r} \alpha_{42} x \\ &\leq \sum_{i=1}^2 (N_i \eta_i F_{4i} \psi_{2i}(M_{2i}) + M_i \nu_i F_{5i} \psi_{3i}(M_{3i})) - \sigma_3 G_3(t), \end{aligned}$$

where $\sigma_3 = \min\{g\alpha_{41}, \omega\alpha_{42}\}$. Hence,

$$\limsup_{t \rightarrow \infty} G_3(t) \leq \sum_{i=1}^2 \frac{(N_i \eta_i F_{4i} \psi_{2i}(M_{2i}) + M_i \nu_i F_{5i} \psi_{3i}(M_{3i}))}{\sigma_3} = M_{41},$$

$$\limsup_{t \rightarrow \infty} p(t) \leq M_{41},$$

$$\limsup_{t \rightarrow \infty} x(t) \leq \frac{rM_{41}}{\mu} = M_{42}.$$

Therefore, $s_i(t), w_i(t), y_i(t), u_i(t), p(t)$, and $x(t)$ are ultimately bounded. \square

Proof of Theorem 1. Define a Lyapunov functional $U_0(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x)$ as follows:

$$\begin{aligned} U_0 &= \sum_{i=1}^2 \gamma_i \left[s_i - s_i^0 - \int_{s_i^0}^{s_i} \lim_{p \rightarrow 0^+} \frac{Y_i(s_i^0, p)}{Y_i(\eta, p)} d\eta + k_{1i} w_i + k_{2i} y_i + k_{3i} u_i \right. \\ &\quad + k_{1i} \lambda_{1i} \int_0^{h_{1i}} \Theta_{1i}(\tau) \int_0^\tau Y_i(s_i(t-\theta), p(t-\theta)) d\theta d\tau \\ &\quad + k_{2i} \lambda_{2i} \int_0^{h_{2i}} \Theta_{2i}(\tau) \int_0^\tau Y_i(s_i(t-\theta), p(t-\theta)) d\theta d\tau \\ &\quad + k_{3i} \lambda_{3i} \int_0^{h_{3i}} \Theta_{3i}(\tau) \int_0^\tau Y_i(s_i(t-\theta), p(t-\theta)) d\theta d\tau \\ &\quad + k_{4i} \eta_i \int_0^{h_{4i}} \Theta_{4i}(\tau) \int_0^\tau \psi_{2i}(y_i(t-\theta)) d\theta d\tau \\ &\quad \left. + k_{5i} \nu_i \int_0^{h_{5i}} \Theta_{5i}(\tau) \int_0^\tau \psi_{3i}(u_i(t-\theta)) d\theta d\tau \right] + k_{61} p + k_{62} x, \end{aligned}$$

where $k_{1i}, \dots, k_{5i}, k_{61}$ and k_{62} satisfy the following equations:

$$\begin{aligned} \lambda_i &= \lambda_{1i} k_{1i} F_{1i} + \lambda_{2i} k_{2i} F_{2i} + \lambda_{3i} k_{3i} F_{3i}, \quad (\alpha_i + \beta_i) k_{1i} = \alpha_i k_{2i}, \quad k_{2i} = k_{4i} F_{4i}, \\ k_{3i} &= k_{5i} F_{5i}, \quad \gamma_i k_{4i} = N_i k_{61}, \quad \gamma_i k_{5i} = M_i k_{61}, \quad \mu k_{61} = r k_{62}. \end{aligned} \tag{A2}$$

The solution of Equations (A2) is given by

$$k_{1i} = \frac{\alpha_i N_i \lambda_i F_{4i}}{\gamma_i g (\alpha_i + \beta_i)}, k_{2i} = \frac{N_i \lambda_i F_{4i}}{\gamma_i g}, k_{3i} = \frac{M_i \lambda_i F_{5i}}{\gamma_i g},$$

$$k_{4i} = \frac{N_i \lambda_i}{\gamma_i g}, k_{5i} = \frac{M_i \lambda_i}{\gamma_i g}, i = 1, 2, k_{61} = \frac{\lambda_i}{g}, k_{62} = \frac{\mu \lambda_i}{rg}.$$

It is seen that $U_0(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x) > 0$ for all $s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x > 0$ and $U_0(s_1^0, s_2^0, 0, 0, 0, 0, 0, 0, 0, 0) = 0$. We calculate $\frac{dU_0}{dt}$ along the trajectories of systems (10)–(15) as follows:

$$\begin{aligned} \frac{dU_0}{dt} = & \sum_{i=1}^2 \gamma_i \left[\left(1 - \lim_{p \rightarrow 0^+} \frac{Y_i(s_i^0, p)}{Y_i(s_i, p)} \right) (\pi_i(s_i) - \lambda_i Y_i(s_i, p)) \right. \\ & + k_{1i} \left(\lambda_{1i} \int_0^{h_{1i}} \Theta_{1i}(\tau) Y_i(s_i(t - \tau), p(t - \tau)) d\tau - (\alpha_i + \beta_i) \psi_{1i}(w_i) \right) \\ & + k_{2i} \left(\lambda_{2i} \int_0^{h_{2i}} \Theta_{2i}(\tau) Y_i(s_i(t - \tau), p(t - \tau)) d\tau + \alpha_i \psi_{1i}(w_i) - \eta_i \psi_{2i}(y_i) \right) \\ & + k_{3i} \left(\lambda_{3i} \int_0^{h_{3i}} \Theta_{3i}(\tau) Y_i(s_i(t - \tau), p(t - \tau)) d\tau - \nu_i \psi_{3i}(u_i) \right) \\ & + k_{1i} \lambda_{1i} \int_0^{h_{1i}} \Theta_{1i}(\tau) (Y_i(s_i, p) - Y_i(s_i(t - \tau), p(t - \tau))) d\tau \\ & + k_{2i} \lambda_{2i} \int_0^{h_{2i}} \Theta_{2i}(\tau) (Y_i(s_i, p) - Y_i(s_i(t - \tau), p(t - \tau))) d\tau \\ & + k_{3i} \lambda_{3i} \int_0^{h_{3i}} \Theta_{3i}(\tau) (Y_i(s_i, p) - Y_i(s_i(t - \tau), p(t - \tau))) d\tau \\ & + k_{4i} \eta_i \int_0^{h_{4i}} \Theta_{4i}(\tau) (\psi_{2i}(y_i) - \psi_{2i}(y_i(t - \tau))) d\tau \\ & + k_{5i} \nu_i \int_0^{h_{5i}} \Theta_{5i}(\tau) (\psi_{3i}(u_i) - \psi_{3i}(u_i(t - \tau))) d\tau \left. \right] \\ & + k_{61} \sum_{i=1}^2 \left(N_i \eta_i \int_0^{h_{4i}} \Theta_{4i}(\tau) \psi_{2i}(y_i(t - \tau)) d\tau + M_i \nu_i \int_0^{h_{5i}} \Theta_{5i}(\tau) \psi_{3i}(u_i(t - \tau)) d\tau \right) \\ & - k_{61} g \psi_{41}(p) - k_{61} \mu \psi_{41}(p) \psi_{42}(x) + k_{62} (r \psi_{41}(p) \psi_{42}(x) - \omega \psi_{42}(x)). \end{aligned} \tag{A3}$$

Simplifying Equation (A3) and utilizing $\pi(s_i^0) = 0$, we obtain

$$\begin{aligned} \frac{dU_0}{dt} &= \sum_{i=1}^2 \gamma_i (\pi_i(s_i) - \pi_i(s_i^0)) \left(1 - \lim_{p \rightarrow 0^+} \frac{Y_i(s_i^0, p)}{Y_i(s_i, p)} \right) \\ &+ \sum_{i=1}^2 \gamma_i \lambda_i Y_i(s_i, p) \lim_{p \rightarrow 0^+} \frac{Y_i(s_i^0, p)}{Y_i(s_i, p)} - k_{61}g\psi_{41}(p) - k_{62}\omega\psi_{42}(x) \\ &\leq \sum_{i=1}^2 \gamma_i (\pi_i(s_i) - \pi_i(s_i^0)) \left(1 - \lim_{p \rightarrow 0^+} \frac{Y_i(s_i^0, p)}{Y_i(s_i, p)} \right) \\ &+ \left(\sum_{i=1}^2 \gamma_i \lambda_i \lim_{p \rightarrow 0^+} \frac{Y_i(s_i, p)}{\psi_{41}(p)} \lim_{p \rightarrow 0^+} \frac{Y_i(s_i^0, p)}{Y_i(s_i, p)} - k_{61}g \right) \psi_{41}(p) - k_{62}\omega\psi_{42}(x) \\ &= \sum_{i=1}^2 \gamma_i (\pi_i(s_i) - \pi_i(s_i^0)) \left(1 - \frac{\partial Y_i(s_i^0, 0)/\partial p}{\partial Y_i(s_i, 0)/\partial p} \right) \\ &+ k_{61}g \left(\sum_{i=1}^2 \frac{\gamma_i \lambda_i}{k_{61}g\psi'_{41}(0)} \frac{\partial Y_i(s_i^0, 0)}{\partial p} - 1 \right) \psi_{41}(p) - k_{62}\omega\psi_{42}(x) \\ &= \sum_{i=1}^2 \gamma_i (\pi_i(s_i) - \pi_i(s_i^0)) \left(1 - \frac{\partial Y_i(s_i^0, 0)/\partial p}{\partial Y_i(s_i, 0)/\partial p} \right) + k_{61}g(R_0 - 1)\psi_{41}(p) \\ &- k_{62}\omega\psi_{42}(x). \end{aligned}$$

By H1 and H2, we get

$$(\pi_i(s_i) - \pi_i(s_i^0)) \left(1 - \frac{\partial Y_i(s_i^0, 0)/\partial p}{\partial Y_i(s_i, 0)/\partial p} \right) \leq 0.$$

Therefore, if $R_0 \leq 1$, then $\frac{dU_0}{dt} \leq 0$ for $s_i, p, x \in (0, \infty)$. Clearly, $\frac{dU_0}{dt} = 0$ at Π_0 . Applying LaSalle’s invariance principle, we get that Π_0 is globally asymptotically stable. \square

Proof of Lemma 2. From H1 and H2, we get

$$(\tilde{s}_i - \bar{s}_i) (\pi_i(\tilde{s}_i) - \pi_i(\bar{s}_i)) > 0, \tag{A4}$$

$$(\tilde{s}_i - \bar{s}_i) (Y_i(\tilde{s}_i, \bar{p}) - Y_i(\bar{s}_i, \bar{p})) > 0, \tag{A5}$$

$$(\bar{p} - \tilde{p}) (Y_i(\tilde{s}_i, \bar{p}) - Y_i(\tilde{s}_i, \tilde{p})) > 0, \tag{A6}$$

for $\tilde{s}_i, \bar{s}_i, \tilde{p}, \bar{p} > 0$. From H4, we get

$$(\tilde{p} - \bar{p}) \left(\frac{Y_i(\tilde{s}_i, \bar{p})}{\psi_{41}(\bar{p})} - \frac{Y_i(\tilde{s}_i, \tilde{p})}{\psi_{41}(\tilde{p})} \right) > 0. \tag{A7}$$

We first prove that $\text{sgn}(\tilde{p} - \bar{p}) = \text{sgn}(\bar{s}_i - \tilde{s}_i)$. Assume that $\text{sgn}(\bar{p} - \tilde{p}) = \text{sgn}(\bar{s}_i - \tilde{s}_i)$. Using the equilibrium conditions of Π_1 and Π_2 , we get

$$\begin{aligned} \pi_i(\bar{s}_i) - \pi_i(\tilde{s}_i) &= \lambda_i [Y_i(\bar{s}_i, \bar{p}) - Y_i(\tilde{s}_i, \tilde{p})] \\ &= \lambda_i [(Y_i(\bar{s}_i, \bar{p}) - Y_i(\tilde{s}_i, \bar{p})) + (Y_i(\tilde{s}_i, \bar{p}) - Y_i(\tilde{s}_i, \tilde{p}))]. \end{aligned}$$

Therefore, from the inequalities (A4)–(A6), we obtain $\text{sgn}(\tilde{s}_i - \bar{s}_i) = \text{sgn}(\tilde{s}_i - \bar{s}_i)$, and this is a contradiction. It follows that $\text{sgn}(\tilde{p} - \bar{p}) = \text{sgn}(\tilde{s}_i - \bar{s}_i)$. Using Equation (26) and the definition of R_1 , we get

$$\begin{aligned} R_1 - 1 &= \sum_{i=1}^2 \gamma_i \left(\frac{Y_i(\tilde{s}_i, \tilde{p})}{\psi_{41}(\tilde{p})} - \frac{Y_i(\bar{s}_i, \bar{p})}{\psi_{41}(\bar{p})} \right) \\ &= \sum_{i=1}^2 \gamma_i \left[\frac{1}{\psi_{41}(\tilde{p})} (Y_i(\tilde{s}_i, \tilde{p}) - Y_i(\bar{s}_i, \bar{p})) + \frac{Y_i(\tilde{s}_i, \tilde{p})}{\psi_{41}(\tilde{p})} - \frac{Y_i(\bar{s}_i, \bar{p})}{\psi_{41}(\bar{p})} \right]. \end{aligned}$$

Thus, from inequalities (A5) and (A7), we obtain $\text{sgn}(R_1 - 1) = \text{sgn}(\tilde{p} - \bar{p})$. □

Proof of Theorem 2. Let $U_1(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x)$

$$\begin{aligned} U_1 &= \sum_{i=1}^2 \gamma_i \left[s_i - \bar{s}_i - \int_{\tilde{s}_i}^{s_i} \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(\eta, \tilde{p})} d\eta + k_{1i} \left(w_i - \bar{w}_i - \int_{\tilde{w}_i}^{w_i} \frac{\psi_{1i}(\tilde{w}_i)}{\psi_{1i}(\eta)} d\eta \right) \right. \\ &\quad + k_{2i} \left(y_i - \tilde{y}_i - \int_{\tilde{y}_i}^{y_i} \frac{\psi_{2i}(\tilde{y}_i)}{\psi_{2i}(\eta)} d\eta \right) + k_{3i} \left(u_i - \tilde{u}_i - \int_{\tilde{u}_i}^{u_i} \frac{\psi_{3i}(\tilde{u}_i)}{\psi_{3i}(\eta)} d\eta \right) \\ &\quad + k_{1i} \lambda_{1i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{1i}} \Theta_{1i} \int_0^\tau F \left(\frac{Y_i(s_i(t-\theta), p(t-\theta))}{Y_i(\tilde{s}_i, \tilde{p})} \right) d\theta d\tau \\ &\quad + k_{2i} \lambda_{2i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{2i}} \Theta_{2i} \int_0^\tau F \left(\frac{Y_i(s_i(t-\theta), p(t-\theta))}{Y_i(\tilde{s}_i, \tilde{p})} \right) d\theta d\tau \\ &\quad + k_{3i} \lambda_{3i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{3i}} \Theta_{3i} \int_0^\tau F \left(\frac{Y_i(s_i(t-\theta), p(t-\theta))}{Y_i(\tilde{s}_i, \tilde{p})} \right) d\theta d\tau \\ &\quad + k_{4i} \eta_i \psi_{2i}(\tilde{y}_i) \int_0^{h_{4i}} \Theta_{4i} \int_0^\tau F \left(\frac{\psi_{2i}(y_i(t-\theta))}{\psi_{2i}(\tilde{y}_i)} \right) d\theta d\tau \\ &\quad + k_{5i} \nu_i \psi_{3i}(\tilde{u}_i) \int_0^{h_{5i}} \Theta_{5i} \int_0^\tau F \left(\frac{\psi_{3i}(u_i(t-\theta))}{\psi_{3i}(\tilde{u}_i)} \right) d\theta d\tau \left. \right] \\ &\quad + k_{61} \left(p - \bar{p} - \int_{\tilde{p}}^p \frac{\psi_{41}(\tilde{p})}{\psi_{41}(\eta)} d\eta \right) + k_{62} x. \end{aligned}$$

It can be seen that $U_1(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x) > 0$ for all $s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x > 0$ and $U_1(\tilde{s}_1, \tilde{s}_2, \tilde{w}_1, \tilde{w}_2, \tilde{y}_1, \tilde{y}_2, \tilde{u}_1, \tilde{u}_2, \tilde{p}, 0) = 0$. Evaluating $\frac{dU_1}{dt}$ along the solutions of systems (10)–(15), we obtain:

$$\begin{aligned}
 \frac{dU_1}{dt} = & \sum_{i=1}^2 \gamma_i \left[\left(1 - \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) (\pi_i(s_i) - \lambda_i Y_i(s_i, p)) \right. \\
 & + k_{1i} \left(1 - \frac{\psi_{1i}(\tilde{w}_i)}{\psi_{1i}(w_i)} \right) \left(\lambda_{1i} \int_0^{h_{1i}} \Theta_{1i} Y_i(s_i(t-\tau), p(t-\tau)) d\tau - (\alpha_i + \beta_i) \psi_{1i}(w_i) \right) \\
 & + k_{2i} \left(1 - \frac{\psi_{2i}(\tilde{y}_i)}{\psi_{2i}(y_i)} \right) \left(\lambda_{2i} \int_0^{h_{2i}} \Theta_{2i} Y_i(s_i(t-\tau), p(t-\tau)) d\tau + \alpha_i \psi_{1i}(w_i) - \eta_i \psi_{2i}(y_i) \right) \\
 & + k_{3i} \left(1 - \frac{\psi_{3i}(\tilde{u}_i)}{\psi_{3i}(u_i)} \right) \left(\lambda_{3i} \int_0^{h_{3i}} \Theta_{3i} Y_i(s_i(t-\tau), p(t-\tau)) d\tau - \nu_i \psi_{3i}(u_i) \right) \\
 & + k_{1i} \lambda_{1i} \int_0^{h_{1i}} \Theta_{1i} (Y_i(s_i, p) - Y_i(s_i(t-\tau), p(t-\tau))) d\tau \\
 & + Y_i(\tilde{s}_i, \tilde{p}) k_{1i} \lambda_{1i} \int_0^{h_{1i}} \Theta_{1i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 & + k_{2i} \lambda_{2i} \int_0^{h_{2i}} \Theta_{2i} (Y_i(s_i, p) - Y_i(s_i(t-\tau), p(t-\tau))) d\tau \\
 & + Y_i(\tilde{s}_i, \tilde{p}) k_{2i} \lambda_{2i} \int_0^{h_{2i}} \Theta_{2i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 & + k_{3i} \lambda_{3i} \int_0^{h_{3i}} \Theta_{3i} (Y_i(s_i, p) - Y_i(s_i(t-\tau), p(t-\tau))) d\tau \\
 & + Y_i(\tilde{s}_i, \tilde{p}) k_{3i} \lambda_{3i} \int_0^{h_{3i}} \Theta_{3i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 & + k_{4i} \eta_i \int_0^{h_{4i}} \Theta_{4i} \left(\psi_{2i}(y_i) - \psi_{2i}(y_i(t-\tau)) + \psi_{2i}(\tilde{y}_i) \ln \left(\frac{\psi_{2i}(y_i(t-\tau))}{\psi_{2i}(y_i)} \right) \right) d\tau \\
 & + k_{5i} \nu_i \int_0^{h_{5i}} \Theta_{5i} \left(\psi_{3i}(u_i) - \psi_{3i}(u_i(t-\tau)) + \psi_{3i}(\tilde{u}_i) \ln \left(\frac{\psi_{3i}(u_i(t-\tau))}{\psi_{3i}(u_i)} \right) \right) d\tau \left. \right] \\
 & + k_{61} \left(1 - \frac{\psi_{41}(\tilde{p})}{\psi_{41}(p)} \right) \sum_{i=1}^2 \left(N_i \eta_i \int_0^{h_{4i}} \Theta_{4i} \psi_{2i}(y_i(t-\tau)) d\tau \right. \\
 & + M_i \nu_i \int_0^{h_{5i}} \Theta_{5i} \psi_{3i}(u_i(t-\tau)) d\tau \left. \right) - k_{61} \left(1 - \frac{\psi_{41}(\tilde{p})}{\psi_{41}(p)} \right) (g\psi_{41}(p) + \mu\psi_{41}(p)\psi_{42}(x)) \\
 & + k_{62} (r\psi_{41}(p)\psi_{42}(x) - \omega\psi_{42}(x)). \tag{A8}
 \end{aligned}$$

Collecting terms of Equation (A8) and applying $\pi_i(\tilde{s}_i) = \lambda_i Y_i(\tilde{s}_i, \tilde{p})$, we get

$$\begin{aligned} \frac{dU_1}{dt} = & \sum_{i=1}^2 \gamma_i \left[(\pi_i(s_i) - \pi_i(\tilde{s}_i)) \left(1 - \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) \right. \\ & + \lambda_i Y_i(\tilde{s}_i, \tilde{p}) \left(1 - \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) + \lambda_i Y_i(s_i, p) \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \\ & - k_{1i} \lambda_{1i} \int_0^{h_{1i}} \Theta_{1i} \frac{Y_i(s_i(t-\tau), p(t-\tau)) \psi_{1i}(\tilde{w}_i)}{\psi_{1i}(w_i)} d\tau + k_{1i}(\alpha_i + \beta_i) \psi_{1i}(\tilde{w}_i) \\ & + k_{2i} \eta_i \psi_{2i}(\tilde{y}_i) - k_{2i} \lambda_{2i} \int_0^{h_{2i}} \Theta_{2i} \frac{Y_i(s_i(t-\tau), p(t-\tau)) \psi_{2i}(\tilde{y}_i)}{\psi_{2i}(y_i)} d\tau \\ & - \alpha_i k_{2i} \frac{\psi_{1i}(w_i) \psi_{2i}(\tilde{y}_i)}{\psi_{2i}(y_i)} - k_{3i} \lambda_{3i} \int_0^{h_{3i}} \Theta_{3i} \frac{Y_i(s_i(t-\tau), p(t-\tau)) \psi_{3i}(\tilde{u}_i)}{\psi_{3i}(u_i)} d\tau \\ & + k_{3i} \nu_i \psi_{3i}(\tilde{u}_i) + k_{1i} \lambda_{1i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{1i}} \Theta_{1i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\ & + k_{2i} \lambda_{2i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{2i}} \Theta_{2i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\ & + k_{3i} \lambda_{3i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{3i}} \Theta_{3i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(x, p)} \right) d\tau \\ & + k_{4i} \eta_i \psi_{2i}(\tilde{y}_i) \int_0^{h_{4i}} \Theta_{4i} \ln \left(\frac{\psi_{2i}(y_i(t-\tau))}{\psi_{2i}(y_i)} \right) d\tau \\ & + k_{5i} \nu_i \psi_{3i}(\tilde{u}_i) \int_0^{h_{5i}} \Theta_{5i} \ln \left(\frac{\psi_{3i}(u_i(t-\tau))}{\psi_{3i}(u_i)} \right) d\tau \left. \right] - k_{61} g \psi_{41}(p) \\ & - k_{61} \sum_{i=1}^2 N_i \eta_i \int_0^{h_{4i}} \Theta_{4i} \frac{\psi_{2i}(y_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{41}(p)} d\tau \\ & - k_{61} \sum_{i=1}^2 M_i \nu_i \int_0^{h_{5i}} \Theta_{5i} \frac{\psi_{3i}(u_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{41}(p)} d\tau + k_{61} g \psi_{41}(\tilde{p}) \\ & + \mu k_{61} \psi_{41}(\tilde{p}) \psi_{42}(x) - k_{62} \omega \psi_{42}(x). \end{aligned}$$

Using the equilibrium conditions for Π_1 :

$$\begin{aligned} (\alpha_i + \beta_i) \psi_{1i}(\tilde{w}_i) &= \lambda_{1i} F_{1i} Y_i(\tilde{s}_i, \tilde{p}), \quad k_{2i} \eta_i \psi_{2i}(\tilde{y}_i) = (k_{1i} \lambda_{1i} F_{1i} + k_{2i} \lambda_{2i} F_{2i}) Y_i(\tilde{s}_i, \tilde{p}), \\ \nu_i \psi_{3i}(\tilde{u}_i) &= \lambda_{3i} F_{3i} Y_i(\tilde{s}_i, \tilde{p}), \quad k_{61} g \psi_{41}(\tilde{p}) = \sum_{i=1}^2 \gamma_i \lambda_i Y_i(\tilde{s}_i, \tilde{p}), \end{aligned}$$

we have

$$\begin{aligned}
 \frac{dU_1}{dt} = & \sum_{i=1}^2 \gamma_i \left[(\pi_i(s_i) - \pi_i(\tilde{s}_i)) \left(1 - \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) + \lambda_i Y_i(\tilde{s}_i, \tilde{p}) \left(1 - \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) \right. \\
 & + k_{1i} \lambda_{1i} F_{1i} Y_i(\tilde{s}_i, \tilde{p}) + \lambda_i Y_i(\tilde{s}_i, \tilde{p}) \left(\frac{Y_i(s_i, p)}{Y_i(s_i, \tilde{p})} - \frac{\psi_{41}(p)}{\psi_{41}(\tilde{p})} \right) \\
 & - k_{1i} \lambda_{1i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{1i}} \Theta_{1i} \frac{Y_i(s_i(t-\tau), p(t-\tau)) \psi_{1i}(\tilde{w}_i)}{Y_i(\tilde{s}_i, \tilde{p}) \psi_{1i}(w_i)} d\tau \\
 & - k_{2i} \lambda_{2i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{2i}} \Theta_{2i} \frac{Y_i(s_i(t-\tau), p(t-\tau)) \psi_{2i}(\tilde{y}_i)}{Y_i(\tilde{s}_i, \tilde{p}) \psi_{2i}(y_i)} d\tau \\
 & - k_{1i} \lambda_{1i} F_{1i} Y_i(\tilde{s}_i, \tilde{p}) \frac{\psi_{2i}(\tilde{y}_i) \psi_{1i}(w_i)}{\psi_{2i}(y_i) \psi_{1i}(\tilde{w}_i)} + (k_{1i} \lambda_{1i} F_{1i} + k_{2i} \lambda_{2i} F_{2i}) Y_i(\tilde{s}_i, \tilde{p}) \\
 & + k_{3i} \lambda_{3i} F_{3i} Y_i(\tilde{s}_i, \tilde{p}) - k_{3i} \lambda_{3i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{3i}} \Theta_{3i} \frac{Y_i(s_i(t-\tau), p(t-\tau)) \psi_{3i}(\tilde{u}_i)}{Y_i(\tilde{s}_i, \tilde{p}) \psi_{3i}(u_i)} d\tau \\
 & + k_{1i} \lambda_{1i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{1i}} \Theta_{1i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 & + k_{2i} \lambda_{2i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{2i}} \Theta_{2i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 & + k_{3i} \lambda_{3i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{3i}} \Theta_{3i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 & + \frac{(k_{1i} \lambda_{1i} F_{1i} + k_{2i} \lambda_{2i} F_{2i}) Y_i(\tilde{s}_i, \tilde{p})}{F_{4i}} \int_0^{h_{4i}} \Theta_{4i} \ln \left(\frac{\psi_{2i}(y_i(t-\tau))}{\psi_{2i}(y_i)} \right) d\tau \\
 & + \frac{k_{3i} \lambda_{3i} F_{3i} Y_i(\tilde{s}_i, \tilde{p})}{F_{5i}} \int_0^{h_{5i}} \Theta_{5i} \ln \left(\frac{\psi_{3i}(u_i(t-\tau))}{\psi_{3i}(u_i)} \right) d\tau \left. + \sum_{i=1}^2 \gamma_i \lambda_i Y_i(\tilde{s}_i, \tilde{p}) \right. \\
 & - \sum_{i=1}^2 \frac{\gamma_i (k_{1i} \lambda_{1i} F_{1i} + k_{2i} \lambda_{2i} F_{2i}) Y_i(\tilde{s}_i, \tilde{p})}{F_{4i}} \int_0^{h_{4i}} \Theta_{4i} \frac{\psi_{2i}(y_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{2i}(\tilde{y}_i) \psi_{41}(p)} d\tau \\
 & - \sum_{i=1}^2 \frac{\gamma_i k_{3i} \lambda_{3i} F_{3i} Y_i(\tilde{s}_i, \tilde{p})}{F_{5i}} \int_0^{h_{5i}} \Theta_{5i} \frac{\psi_{3i}(u_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{3i}(\tilde{u}_i) \psi_{41}(p)} d\tau \\
 & \left. + rk_{62} \left(\psi_{41}(\tilde{p}) - \frac{\omega}{r} \right) \psi_{42}(x). \right.
 \end{aligned}$$

Using the Equalities (A1) with $\hat{s}_i = \tilde{s}_i, \hat{w}_i = \tilde{w}_i, \hat{y}_i = \tilde{y}_i, \hat{u}_i = \tilde{u}_i$ and $\hat{p} = \tilde{p}$, we have

$$\begin{aligned}
 \frac{dU_1}{dt} = & \sum_{i=1}^2 \gamma_i \left[(\pi_i(s_i) - \pi_i(\tilde{s}_i)) \left(1 - \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) \right. \\
 & + \lambda_i Y_i(\tilde{s}_i, \tilde{p}) \left(\frac{Y_i(s_i, p)}{Y_i(s_i, \tilde{p})} - \frac{\psi_{41}(p)}{\psi_{41}(\tilde{p})} - 1 + \frac{\psi_{41}(p) Y_i(s_i, \tilde{p})}{\psi_{41}(\tilde{p}) Y_i(s_i, p)} \right) \\
 & - \lambda_i Y_i(\tilde{s}_i, \tilde{p}) \left(\frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} - 1 - \ln \left(\frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) \right) \\
 & - \lambda_i Y_i(\tilde{s}_i, \tilde{p}) \left(\frac{\psi_{41}(p) Y_i(s_i, \tilde{p})}{\psi_{41}(\tilde{p}) Y_i(s_i, p)} - 1 - \ln \left(\frac{\psi_{41}(p) Y_i(s_i, \tilde{p})}{\psi_{41}(\tilde{p}) Y_i(s_i, p)} \right) \right) \\
 & - k_{1i} \lambda_{1i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{1i}} \Theta_{1i} \left(\frac{\psi_{1i}(\tilde{w}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{1i}(w_i) Y_i(\tilde{s}_i, \tilde{p})} \right. \\
 & \left. - 1 - \ln \left(\frac{\psi_{1i}(\tilde{w}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{1i}(w_i) Y_i(\tilde{s}_i, \tilde{p})} \right) \right) d\tau \\
 & - k_{2i} \lambda_{2i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{2i}} \Theta_{2i} \left(\frac{\psi_{2i}(\tilde{y}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{2i}(y_i) Y_i(\tilde{s}_i, \tilde{p})} \right. \\
 & \left. - 1 - \ln \left(\frac{\psi_{2i}(\tilde{y}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{2i}(y_i) Y_i(\tilde{s}_i, \tilde{p})} \right) \right) d\tau \\
 & - k_{3i} \lambda_{3i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{3i}} \Theta_{3i} \left(\frac{\psi_{3i}(\tilde{u}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{3i}(u_i) Y_i(\tilde{s}_i, \tilde{p})} \right. \\
 & \left. - 1 - \ln \left(\frac{\psi_{3i}(\tilde{u}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{3i}(u_i) Y_i(\tilde{s}_i, \tilde{p})} \right) \right) d\tau \\
 & - k_{1i} \lambda_{1i} F_{1i} Y_i(\tilde{s}_i, \tilde{p}) \left(\frac{\psi_{2i}(\tilde{y}_i) \psi_{1i}(w_i)}{\psi_{2i}(y_i) \psi_{1i}(\tilde{w}_i)} - 1 - \ln \left(\frac{\psi_{2i}(\tilde{y}_i) \psi_{1i}(w_i)}{\psi_{2i}(y_i) \psi_{1i}(\tilde{w}_i)} \right) \right) \\
 & - \frac{(k_{1i} \lambda_{1i} F_{1i} + k_{2i} \lambda_{2i} F_{2i}) Y_i(\tilde{s}_i, \tilde{p})}{F_{4i}} \int_0^{h_{4i}} \Theta_{4i} \left(\frac{\psi_{2i}(y_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{2i}(\tilde{y}_i) \psi_{41}(p)} \right. \\
 & \left. - 1 - \ln \left(\frac{\psi_{2i}(y_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{2i}(\tilde{y}_i) \psi_{41}(p)} \right) \right) d\tau \\
 & - \frac{k_{3i} \lambda_{3i} F_{3i} Y_i(\tilde{s}_i, \tilde{p})}{F_{5i}} \int_0^{h_{5i}} \Theta_{5i} \left(\frac{\psi_{3i}(u_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{3i}(\tilde{u}_i) \psi_{41}(p)} - 1 \right. \\
 & \left. - \ln \left(\frac{\psi_{3i}(u_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{3i}(\tilde{u}_i) \psi_{41}(p)} \right) \right) d\tau \Big] + rk_{62} (\psi_{41}(\tilde{p}) - \psi_{41}(p)) \psi_{42}(x). \tag{A9}
 \end{aligned}$$

Equation (A9) becomes

$$\begin{aligned} \frac{dU_1}{dt} = & \sum_{i=1}^2 \gamma_i \left[(\pi_i(s_i) - \pi_i(\tilde{s}_i)) \left(1 - \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) \right. \\ & + \lambda_i Y_i(\tilde{s}_i, \tilde{p}) \left(\frac{Y_i(s_i, p)}{Y_i(s_i, \tilde{p})} - \frac{\psi_{41}(p)}{\psi_{41}(\tilde{p})} \right) \left(1 - \frac{Y_i(s_i, \tilde{p})}{Y_i(s_i, p)} \right) \\ & - \lambda_i Y_i(\tilde{s}_i, \tilde{p}) \left(F \left(\frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) + F \left(\frac{\psi_{41}(p) Y_i(s_i, \tilde{p})}{\psi_{41}(\tilde{p}) Y_i(s_i, p)} \right) \right) \\ & - k_{1i} \lambda_{1i} F_{1i} Y_i(\tilde{s}_i, \tilde{p}) F \left(\frac{\psi_{2i}(\tilde{y}_i) \psi_{1i}(w_i)}{\psi_{2i}(y_i) \psi_{1i}(\tilde{w}_i)} \right) \\ & - k_{1i} \lambda_{1i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{1i}} \Theta_{1i} F \left(\frac{\psi_{1i}(\tilde{w}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{1i}(w_i) Y_i(\tilde{s}_i, \tilde{p})} \right) d\tau \\ & - k_{2i} \lambda_{2i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{2i}} \Theta_{2i} F \left(\frac{\psi_{2i}(\tilde{y}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{2i}(y_i) Y_i(\tilde{s}_i, \tilde{p})} \right) d\tau \\ & - k_{3i} \lambda_{3i} Y_i(\tilde{s}_i, \tilde{p}) \int_0^{h_{3i}} \Theta_{3i} F \left(\frac{\psi_{3i}(\tilde{u}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{3i}(u_i) Y_i(\tilde{s}_i, \tilde{p})} \right) d\tau \\ & - \frac{(k_{1i} \lambda_{1i} F_{1i} + k_{2i} \lambda_{2i} F_{2i}) Y_i(\tilde{s}_i, \tilde{p})}{F_{4i}} \int_0^{h_{4i}} \Theta_{4i} F \left(\frac{\psi_{2i}(y_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{2i}(\tilde{y}_i) \psi_{41}(p)} \right) d\tau \\ & - \left. \frac{k_{3i} \lambda_{3i} F_{3i} Y_i(\tilde{s}_i, \tilde{p})}{F_{5i}} \int_0^{h_{5i}} \Theta_{5i} F \left(\frac{\psi_{3i}(u_i(t-\tau)) \psi_{41}(\tilde{p})}{\psi_{3i}(\tilde{u}_i) \psi_{41}(p)} \right) d\tau \right] \\ & + rk_{62} (\psi_{41}(\tilde{p}) - \psi_{41}(p)) \psi_{42}(x). \end{aligned}$$

From H1, H2 and H4, we have

$$\begin{aligned} (\pi_i(s_i) - \pi_i(\tilde{s}_i)) \left(1 - \frac{Y_i(\tilde{s}_i, \tilde{p})}{Y_i(s_i, \tilde{p})} \right) & \leq 0, \\ \left(\frac{Y_i(s_i, p)}{Y_i(s_i, \tilde{p})} - \frac{\psi_{41}(p)}{\psi_{41}(\tilde{p})} \right) \left(1 - \frac{Y_i(s_i, \tilde{p})}{Y_i(s_i, p)} \right) & \leq 0. \end{aligned}$$

Moreover, if $R_1 \leq 1$, then $\psi_{41}(\tilde{p}) - \psi_{41}(p) \leq 0$. Thus, for all $s_i, y_i, p, x > 0$, we have $\frac{dU_1}{dt} \leq 0$ and $\frac{dU_1}{dt} = 0$ at Π_1 . LIP Π_1 is globally asymptotically stable. \square

Proof of Theorem 3. Define $U_2(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x)$

$$\begin{aligned}
 U_2 = & \sum_{i=1}^2 \gamma_i \left[s_i - \bar{s}_i - \int_{\bar{s}_i}^{s_i} \frac{Y_i(\bar{s}_i, \bar{p})}{Y_i(\eta, \bar{p})} d\eta + k_{1i} \left(w_i - \bar{w}_i - \int_{\bar{w}_i}^{w_i} \frac{\psi_{1i}(\bar{w}_i)}{\psi_{1i}(\eta)} d\eta \right) \right. \\
 & + k_{2i} \left(y_i - \bar{y}_i - \int_{\bar{y}_i}^{y_i} \frac{\psi_{2i}(\bar{y}_i)}{\psi_{2i}(\eta)} d\eta \right) + k_{3i} \left(u_i - \bar{u}_i - \int_{\bar{u}_i}^{u_i} \frac{\psi_{3i}(\bar{u}_i)}{\psi_{3i}(\eta)} d\eta \right) \\
 & + k_{1i} \lambda_{1i} Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{1i}} \Theta_{1i}(\tau) \int_0^\tau F \left(\frac{Y_i(s_i(t-\theta), p(t-\theta))}{Y_i(\bar{s}_i, \bar{p})} \right) d\theta d\tau \\
 & + k_{2i} \lambda_{2i} Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{2i}} \Theta_{2i}(\tau) \int_0^\tau F \left(\frac{Y_i(s_i(t-\theta), p(t-\theta))}{Y_i(\bar{s}_i, \bar{p})} \right) d\theta d\tau \\
 & + k_{3i} \lambda_{3i} Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{3i}} \Theta_{3i}(\tau) \int_0^\tau F \left(\frac{Y_i(s_i(t-\theta), p(t-\theta))}{Y_i(\bar{s}_i, \bar{p})} \right) d\theta d\tau \\
 & + k_{4i} \eta_i \psi_{2i}(\bar{y}_i) \int_0^{h_{4i}} \Theta_{4i}(\tau) \int_0^\tau F \left(\frac{\psi_{2i}(y_i(t-\theta))}{\psi_{2i}(\bar{y}_i)} \right) d\theta d\tau \\
 & \left. + k_{5i} \nu_i \psi_{3i}(\bar{u}_i) \int_0^{h_{5i}} \Theta_{5i}(\tau) \int_0^\tau F \left(\frac{\psi_{3i}(u_i(t-\theta))}{\psi_{3i}(\bar{u}_i)} \right) d\theta d\tau \right] \\
 & + k_{61} \left(p - \bar{p} - \int_{\bar{p}}^p \frac{\psi_{41}(\bar{p})}{\psi_{41}(\eta)} d\eta \right) + k_{62} \left(x - \bar{x} - \int_{\bar{x}}^x \frac{\psi_{42}(\bar{x})}{\psi_{42}(\eta)} d\eta \right).
 \end{aligned}$$

Note that, $U_2(s_1, s_2, w_1, w_2, y_1, y_2, u_1, u_2, p, x) > 0$ for all $s_1, s_2, w_1, w_2, y_1, y_2, p, x > 0$ and $U_2(\bar{s}_1, \bar{s}_2, \bar{w}_1, \bar{w}_2, \bar{y}_1, \bar{y}_2, \bar{u}_1, \bar{u}_2, \bar{p}, \bar{x}) = 0$. Calculating $\frac{dU_2}{dt}$ along the solutions of system (10)–(15), we get

$$\begin{aligned}
 \frac{dU_2}{dt} = & \sum_{i=1}^2 \gamma_i \left[\left(1 - \frac{Y_i(\bar{s}_i, \bar{p})}{Y_i(s_i, \bar{p})} \right) (\pi_i(s_i) - \lambda_i Y_i(s_i, p)) \right. \\
 & + k_{1i} \left(1 - \frac{\psi_{1i}(\bar{w}_i)}{\psi_{1i}(w_i)} \right) \left(\lambda_{1i} \int_0^{h_{1i}} \Theta_{1i} Y_i(s_i(t-\tau), p(t-\tau)) d\tau - (\alpha_i + \beta_i) \psi_{1i}(w_i) \right) \\
 & + k_{2i} \left(1 - \frac{\psi_{2i}(\bar{y}_i)}{\psi_{2i}(y_i)} \right) \left(\lambda_{2i} \int_0^{h_{2i}} \Theta_{2i} Y_i(s_i(t-\tau), p(t-\tau)) d\tau + \alpha_i \psi_{1i}(w_i) - \eta_i \psi_{2i}(y_i) \right) \\
 & + k_{3i} \left(1 - \frac{\psi_{3i}(\bar{u}_i)}{\psi_{3i}(u_i)} \right) \left(\lambda_{3i} \int_0^{h_{3i}} \Theta_{3i} Y_i(s_i(t-\tau), p(t-\tau)) d\tau - \nu_i \psi_{3i}(u_i) \right) \\
 & + k_{1i} \lambda_{1i} \int_0^{h_{1i}} \Theta_{1i} (Y_i(s_i, p) - Y_i(s_i(t-\tau), p(t-\tau))) d\tau \\
 & + Y_i(\bar{s}_i, \bar{p}) k_{1i} \lambda_{1i} \int_0^{h_{1i}} \Theta_{1i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 & + k_{2i} \lambda_{2i} \int_0^{h_{2i}} \Theta_{2i} (Y_i(s_i, p) - Y_i(s_i(t-\tau), p(t-\tau))) d\tau \\
 & + Y_i(\bar{s}_i, \bar{p}) k_{2i} \lambda_{2i} \int_0^{h_{2i}} \Theta_{2i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 & + k_{3i} \lambda_{3i} \int_0^{h_{3i}} \Theta_{3i} (Y_i(s_i, p) - Y_i(s_i(t-\tau), p(t-\tau))) d\tau \\
 & + Y_i(\bar{s}_i, \bar{p}) k_{3i} \lambda_{3i} \int_0^{h_{3i}} \Theta_{3i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 & + k_{4i} \eta_i \int_0^{h_{4i}} \Theta_{4i} \left(\psi_{2i}(y_i) - \psi_{2i}(y_i(t-\tau)) + \psi_{2i}(\bar{y}_i) \ln \left(\frac{\psi_{2i}(y_i(t-\tau))}{\psi_{2i}(y_i)} \right) \right) d\tau \\
 & + k_{5i} \nu_i \int_0^{h_{5i}} \Theta_{5i} \left(\psi_{3i}(u_i) - \psi_{3i}(u_i(t-\tau)) + \psi_{3i}(\bar{u}_i) \ln \left(\frac{\psi_{3i}(u_i(t-\tau))}{\psi_{3i}(u_i)} \right) \right) d\tau \left. \right] \\
 & + k_{61} \left(1 - \frac{\psi_{41}(\bar{p})}{\psi_{41}(p)} \right) \sum_{i=1}^2 \left(N_i \eta_i \int_0^{h_{4i}} \Theta_{4i} \psi_{2i}(y_i(t-\tau)) d\tau + M_i \nu_i \int_0^{h_{5i}} \Theta_{5i} \psi_{3i}(u_i(t-\tau)) d\tau \right) \\
 & - k_{61} \left(1 - \frac{\psi_{41}(\bar{p})}{\psi_{41}(p)} \right) (g \psi_{41}(p) + \mu \psi_{41}(p) \psi_{42}(x)) \\
 & + k_{62} \left(1 - \frac{\psi_{42}(\bar{x})}{\psi_{42}(x)} \right) (r \psi_{41}(p) \psi_{42}(x) - \omega \psi_{42}(x)).
 \end{aligned}
 \tag{A10}$$

Collecting terms of Equation (A10), applying $\pi_i(\bar{s}_i) = \lambda_i Y_i(\bar{s}_i, \bar{p})$ and using the equilibrium conditions for Π_2 :

$$\begin{aligned}
 (\alpha_i + \beta_i)\psi_{1i}(\bar{w}_i) &= \lambda_{1i}F_{1i}Y_i(\bar{s}_i, \bar{p}), \quad k_{2i}\eta_i\psi_{2i}(\bar{y}_i) = (k_{1i}\lambda_{1i}F_{1i} + k_{2i}\lambda_{2i}F_{2i})Y_i(\bar{s}_i, \bar{p}), \\
 \nu_i\psi_{3i}(\bar{u}_i) &= \lambda_{3i}F_{3i}Y_i(\bar{s}_i, \bar{p}), \quad k_{61}g\psi_{41}(\bar{p}) = \sum_{i=1}^2 \gamma_i\lambda_i Y_i(\bar{s}_i, \bar{p}) - \mu k_{61}\psi_{41}(\bar{p})\psi_{42}(\bar{x}),
 \end{aligned}$$

we obtain

$$\begin{aligned}
 \frac{dU_2}{dt} &= \sum_{i=1}^2 \gamma_i \left[(\pi_i(s_i) - \pi_i(\bar{s}_i)) \left(1 - \frac{Y_i(\bar{s}_i, \bar{p})}{Y_i(s_i, \bar{p})} \right) \right. \\
 &+ \lambda_i Y_i(\bar{s}_i, \bar{p}) \left(1 - \frac{Y_i(\bar{s}_i, \bar{p})}{Y_i(s_i, \bar{p})} \right) + \lambda_i Y_i(\bar{s}_i, \bar{p}) \left(\frac{Y_i(s_i, p)}{Y_i(s_i, \bar{p})} - \frac{\psi_{41}(p)}{\psi_{41}(\bar{p})} \right) \\
 &+ k_{1i}\lambda_{1i}F_{1i}Y_i(\bar{s}_i, \bar{p}) - k_{1i}\lambda_{1i}Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{1i}} \Theta_{1i} \frac{Y_i(s_i(t-\tau), p(t-\tau))\psi_{1i}(\bar{w}_i)}{Y_i(\bar{s}_i, \bar{p})\psi_{1i}(w_i)} d\tau \\
 &- k_{2i}\lambda_{2i}Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{2i}} \Theta_{2i} \frac{Y_i(s_i(t-\tau), p(t-\tau))\psi_{2i}(\bar{y}_i)}{Y_i(\bar{s}_i, \bar{p})\psi_{2i}(y_i)} d\tau \\
 &- k_{1i}\lambda_{1i}F_{1i}Y_i(\bar{s}_i, \bar{p}) \frac{\psi_{2i}(\bar{y}_i)\psi_{1i}(w_i)}{\psi_{2i}(y_i)\psi_{1i}(\bar{w}_i)} + (k_{1i}\lambda_{1i}F_{1i} + k_{2i}\lambda_{2i}F_{2i})Y_i(\bar{s}_i, \bar{p}) \\
 &+ k_{3i}\lambda_{3i}F_{3i}Y_i(\bar{s}_i, \bar{p}) - k_{3i}\lambda_{3i}Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{3i}} \Theta_{3i} \frac{Y_i(s_i(t-\tau), p(t-\tau))\psi_{3i}(\bar{u}_i)}{Y_i(\bar{s}_i, \bar{p})\psi_{3i}(u_i)} d\tau \\
 &+ k_{1i}\lambda_{1i}Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{1i}} \Theta_{1i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 &+ k_{2i}\lambda_{2i}Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{2i}} \Theta_{2i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 &+ k_{3i}\lambda_{3i}Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{3i}} \Theta_{3i} \ln \left(\frac{Y_i(s_i(t-\tau), p(t-\tau))}{Y_i(s_i, p)} \right) d\tau \\
 &+ \frac{(k_{1i}\lambda_{1i}F_{1i} + k_{2i}\lambda_{2i}F_{2i})Y_i(\bar{s}_i, \bar{p})}{F_{4i}} \int_0^{h_{4i}} \Theta_{4i} \ln \left(\frac{\psi_{2i}(y_i(t-\tau))}{\psi_{2i}(y_i)} \right) d\tau \\
 &+ \frac{k_{3i}\lambda_{3i}F_{3i}Y_i(\bar{s}_i, \bar{p})}{F_{5i}} \int_0^{h_{5i}} \Theta_{5i} \ln \left(\frac{\psi_{3i}(u_i(t-\tau))}{\psi_{3i}(u_i)} \right) d\tau \left. \right] + \sum_{i=1}^2 \gamma_i \lambda_i Y_i(\bar{s}_i, \bar{p}) \\
 &- \sum_{i=1}^2 \gamma_i \frac{(k_{1i}\lambda_{1i}F_{1i} + k_{2i}\lambda_{2i}F_{2i})Y_i(\bar{s}_i, \bar{p})}{F_{4i}} \int_0^{h_{4i}} \Theta_{4i} \frac{\psi_{2i}(y_i(t-\tau))\psi_{41}(\bar{p})}{\psi_{2i}(\bar{y}_i)\psi_{41}(p)} d\tau \\
 &- \sum_{i=1}^2 \gamma_i \frac{k_{3i}\lambda_{3i}F_{3i}Y_i(\bar{s}_i, \bar{p})}{F_{5i}} \int_0^{h_{5i}} \Theta_{5i} \frac{\psi_{3i}(u_i(t-\tau))\psi_{41}(\bar{p})}{\psi_{3i}(\bar{u}_i)\psi_{41}(p)} d\tau.
 \end{aligned}$$

By Equalities (A1) with $\hat{s}_i = \bar{s}_i, \hat{w}_i = \bar{w}_i, \hat{y}_i = \bar{y}_i, \hat{u}_i = \bar{u}_i$ and $\hat{p} = \bar{p}$, we can get

$$\begin{aligned} \frac{dU_2}{dt} = & \sum_{i=1}^2 \gamma_i \left[(\pi_i(s_i) - \pi_i(\bar{s}_i)) \left(1 - \frac{Y_i(\bar{s}_i, \bar{p})}{Y_i(s_i, \bar{p})} \right) \right. \\ & + \lambda_i Y_i(\bar{s}_i, \bar{p}) \left(\frac{Y_i(s_i, p)}{Y_i(s_i, \bar{p})} - \frac{\psi_{41}(p)}{\psi_{41}(\bar{p})} \right) \left(1 - \frac{Y_i(s_i, \bar{p})}{Y_i(s_i, p)} \right) \\ & - \lambda_i Y_i(\bar{s}_i, \bar{p}) \left[F \left(\frac{Y_i(\bar{s}_i, \bar{p})}{Y_i(s_i, \bar{p})} \right) + F \left(\frac{\psi_{41}(p) Y_i(s_i, \bar{p})}{\psi_{41}(\bar{p}) Y_i(s_i, p)} \right) \right] \\ & - k_{1i} \lambda_{1i} F_{1i} Y_i(\bar{s}_i, \bar{p}) F \left(\frac{\psi_{2i}(\bar{y}_i) \psi_{1i}(w_i)}{\psi_{2i}(y_i) \psi_{1i}(\bar{w}_i)} \right) \\ & - k_{1i} \lambda_{1i} Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{1i}} \Theta_{1i} F \left(\frac{\psi_{1i}(\bar{w}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{1i}(w_i) Y_i(\bar{s}_i, \bar{p})} \right) d\tau \\ & - k_{2i} \lambda_{2i} Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{2i}} \Theta_{2i} F \left(\frac{\psi_{2i}(\bar{y}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{2i}(y_i) Y_i(\bar{s}_i, \bar{p})} \right) d\tau \\ & - k_{3i} \lambda_{3i} Y_i(\bar{s}_i, \bar{p}) \int_0^{h_{3i}} \Theta_{3i} F \left(\frac{\psi_{3i}(\bar{u}_i) Y_i(s_i(t-\tau), p(t-\tau))}{\psi_{3i}(u_i) Y_i(\bar{s}_i, \bar{p})} \right) d\tau \\ & - \frac{(k_{1i} \lambda_{1i} F_{1i} + k_{2i} \lambda_{2i} F_{2i}) Y_i(\bar{s}_i, \bar{p})}{F_{4i}} \int_0^{h_{4i}} \Theta_{4i} F \left(\frac{\psi_{2i}(y_i(t-\tau)) \psi_{41}(\bar{p})}{\psi_{2i}(\bar{y}_i) \psi_{41}(p)} \right) d\tau \\ & \left. - \frac{k_{3i} \lambda_{3i} F_{3i} Y_i(\bar{s}_i, \bar{p})}{F_{5i}} \int_0^{h_{5i}} \Theta_{5i} F \left(\frac{\psi_{3i}(u_i(t-\tau)) \psi_{41}(\bar{p})}{\psi_{3i}(\bar{u}_i) \psi_{41}(p)} \right) d\tau \right]. \end{aligned}$$

From H1–H4, we get $\frac{dU_2}{dt} \leq 0$ and $\frac{dU_2}{dt} = 0$ at Π_2 . LIP implies that Π_2 is globally asymptotically stable. \square

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