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On the Global Well-Posedness of Rotating Magnetohydrodynamics Equations with Fractional Dissipation

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Abstract: This work considers the three-dimensional incompressible rotating magnetohydrodynamics equation spaces with fractional dissipation $(-\Delta)^\varphi$ for $\frac{1}{2} < \varphi \leq 1$. Furthermore, we use the Littlewood–Paley decomposition and frequency localization techniques to establish the global well-posedness of fractional rotating magnetohydrodynamics equations in a more generalized Besov spaces characterized by the time evolution semigroup related to the generalized linear Stokes–Coriolis operator.

Keywords: fractional dissipation; rotating magnetohydrodynamics equations; well-posedness

1. Introduction

In this paper, we study the following three-dimensional fractional rotating magnetohydrodynamics (MHD) equations:

$$\begin{cases} u_t + (u \cdot \nabla)u + \mu(-\Delta)^\varphi u + \mathfrak{S}e_3 \times u + \nabla P = (B \cdot \nabla)B & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ B_t + (u \cdot \nabla)B + \gamma(-\Delta)^\varphi B = (B \cdot \nabla)u & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ \operatorname{div} u = 0, \operatorname{div} B = 0 & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ u|_{t=0} = u_0, B|_{t=0} = B_0 & \text{in } \mathbb{R}^3, \end{cases} \quad (1)$$

where u is the incompressible velocity field, $\mathfrak{S}$ denotes the speed of rotation around a vertical unit vector $e_3 = (0, 0, 1)$, $P = p + \frac{1}{2}|B|^2$ in which B is the magnetic field and p is pressure, and μ and γ represent the viscosity coefficient and diffusion of the magnetic field, respectively. For convenience, we use $\mu = \gamma = 1$.

For $\varphi = 1$, Equation (1) explains why the Earth has a nonzero large-scale magnetic field, the polarity of which appears to change over several hundred centuries.

When $\mathfrak{S} = 0$, Equation (1) becomes the following fractional MHD equations:

$$\begin{cases} u_t + (u \cdot \nabla)u + (-\Delta)^\varphi u + \nabla P = (B \cdot \nabla)B & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ B_t + (u \cdot \nabla)B + (-\Delta)^\varphi B = (B \cdot \nabla)u & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ \operatorname{div} u = 0, \operatorname{div} B = 0 & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ u|_{t=0} = u_0, B|_{t=0} = B_0 & \text{in } \mathbb{R}^3. \end{cases} \quad (2)$$

Equation (2) studies the magnetic characteristics of electrically conducted fluids. Since Duvaut and Lions [1] developed a globally Leray–Hopf weak solution and a locally strong solution to the 3D inviscid MHD equations, the MHD equations remain a challenging open problem in terms of determining whether there is always a globally smooth solution for smooth initial data. Sermange and Temam further investigated the properties and conditions of these solutions [2]. Melo and Santos [3] proved the existence and decay rates of a unique global asymptotic solution for Equation (2) in Sobolev–Gevrey spaces, where Zhao and Li [4] obtained the time decay rate of weak solutions to (2) in $\mathbb{R}^2$. Liu et al. [5] obtained the existence of attractors for (2) with damping and overcame the



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main difficulty in dealing with the nonlinear term. For the detailed study related to the existence of a solution for fractional MHD equations, we refer the readers to [6–10].

When $B = 0$, $\Im \neq 0$ and $\wp = 1$, Equation (1) corresponds to the following Navier–Stokes equations with Coriolis force:

$$\begin{cases} u_t + (u \cdot \nabla)u - \Delta u + \Im e_3 \times u + \nabla P = 0 & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ \operatorname{div} u = 0, \operatorname{div} B = 0 & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ u|_{t=0} = u_0, & \text{in } \mathbb{R}^3. \end{cases} \quad (3)$$

Equation (3) has received considerable attention due to its importance in geophysical flows. The existence of a solution for Equation (3) starts with the work of Babin et al. [11–13], who established the global existence and regularity of solutions for Equation (3) with periodic initial velocity, when the rotation speed $\Im$ is sufficiently large. Under the smallness condition of initial data u_0 , Giga et al. [14] proved the uniform mild solution in $FM_0^{-1}(\mathbb{R}^3)$. The uniform global well-posedness was established by Hieber and Shibata [15] in $H^{\frac{1}{2}}(\mathbb{R}^3)$. More recently, for the fractional case $\frac{1}{2} < \wp \leq 1$, Wang and Wu [16] obtained the global well-posedness for small initial data belonging to Lei–Lin spaces $\mathcal{X}^s$.

When $B = 0$, $\Im = 0$ and $\wp = 1$, Equation (1) becomes the following classical Navier–Stokes equations:

$$\begin{cases} u_t + (u \cdot \nabla)u - \Delta u + \nabla P = 0 & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ \operatorname{div} u = 0, \operatorname{div} B = 0 & \text{in } \mathbb{R}^3 \times \mathbb{R}_+, \\ u|_{t=0} = u_0, & \text{in } \mathbb{R}^3. \end{cases} \quad (4)$$

Equation (4) is one of the most fundamental mathematical model in fluid dynamics. Numerous publications have addressed the global well-posedness of Equation (4) in critical spaces. This work originates with the work of Fujita and Kato [17], who established the existence of a strong solution to the Cauchy problem of Equation (4) under the smallness condition of u_0 in $H^{-1+\frac{n}{2}}(\mathbb{R}^n)$. In [18], they rewrote Equation (4) to an integral form and obtained the local well-posedness in some Sobolev and Lebesgue spaces. These results led to an intensive study of well-posedness for Navier–Stokes equations in various function spaces in recent years, such as [19–22]. As far as the fractional case is concerned, many authors have studied the existence of solutions. For reference we refer the readers to [23–25].

This paper considers the global well-posedness of Equation (1) in some function space characterized by the time evolution semigroup $T_{\Im, \wp}(t)$. We obtain the global well-posedness of Equation (1) in scaling subcritical spaces $X_{\Im}^{s, p, \pi}(\mathbb{R}^3)$ for $\frac{1}{2} < \wp \leq 1$, $\frac{2\wp}{\pi} + \frac{3}{p} < s + (2\wp - 1)$ and the critical spaces $X_{\Im}^p(\mathbb{R}^3)$ for $\frac{7}{8} < \wp \leq \frac{5}{4}$, $\frac{3}{2\wp-1} < p \leq 4$. The following are the main results of the paper.

Theorem 1. Let $\wp, s, p$, and π satisfy

$$\begin{aligned} \frac{1}{2} < \wp \leq 1, 3 - 3\wp < s < \frac{3(15 - 4\wp)}{2(9 + 8\wp)}, \\ \frac{1}{3} + \frac{s}{9} \leq \frac{1}{p} < \min \left\{ \frac{1}{4} + \frac{5}{16\wp} - \frac{s}{8\wp}, \frac{2\wp - 1}{3} + \frac{s}{3} \right\}, \\ \max \left\{ 0, \frac{2}{p} - \frac{1}{2\wp} \left(1 + \frac{3}{p} - s \right) \right\} < \frac{1}{\pi} < \min \left\{ \frac{1}{2}, 1 - \frac{1}{2\wp} \left(1 + \frac{3}{p} - s \right), \frac{1}{2} + \frac{1}{8\wp} - \frac{3}{2\wp p} + \frac{s}{4\wp} \right\}. \end{aligned}$$

Then, for $u_0, B_0 \in X_{\Im}^{s, p, \pi}(\mathbb{R}^3)^3 \cap \dot{H}^s(\mathbb{R}^3)^3$ with $\operatorname{div} u_0 = 0, \operatorname{div} B_0 = 0$ and

$$\|u_0\|_{X_{\Im}^{s, p, \pi}} + \|B_0\|_{X_{\Im}^{s, p, \pi}} \lesssim |\Im|^{1 - \frac{1}{2\wp} \left(1 + \frac{3}{p} - s \right) - \frac{1}{\pi}},$$

Equation (1) has a unique global solution

$$u, B \in L^\pi \left(0, \infty; \dot{W}^{s,p}(\mathbb{R}^3)^3 \right) \cap C \left([0, \infty); \dot{H}^s(\mathbb{R}^3)^3 \right)$$

such that $\operatorname{div} u = 0$ and $\operatorname{div} B = 0$.

Theorem 2. Let φ, s, p satisfy

$$\frac{7}{8} < \varphi \leq \frac{5}{4}, \quad 0 \leq s < 2\varphi - 1, \quad \max \left\{ \frac{1}{4}, \frac{s}{3} \right\} \leq \frac{1}{p} < \frac{2\varphi - 1}{3}$$

Then, for $u_0, B_0 \in X_{\mathfrak{S}}^p(\mathbb{R}^3)^3 \cap \dot{H}^s(\mathbb{R}^3)^3$ with $\operatorname{div} u_0 = 0$, $B_0 = 0$ and

$$\|u_0\|_{X_{\mathfrak{S}}^p} + \|B_0\|_{X_{\mathfrak{S}}^p} \leq \delta,$$

Equation (1) has a unique global solution

$$u, B \in C \left([0, \infty); \dot{H}^s(\mathbb{R}^3)^3 \right)$$

such that

$$\sup_{t>0} t^{\frac{1}{2\varphi}(1-\frac{3}{p})} \|u(t)\|_{L^p} + \sup_{t>0} t^{\frac{1}{2\varphi}(1-\frac{3}{p})} \|B(t)\|_{L^p} \leq 2 \left(\|u_0\|_{X_{\mathfrak{S}}^p} + \|B_0\|_{X_{\mathfrak{S}}^p} \right),$$

$\operatorname{div} u = 0$ and $\operatorname{div} B = 0$.

Throughout this paper we write $f \lesssim g$ to denote $f \leq Kg$, where K is positive constant.

2. Preliminaries

This section gives a brief review of important definitions and useful lemmas. By substituting $B = 0$ into Equation (1), we get the fractional Navier–Stokes equations with Coriolis force. We need to define an equivalent fractional Stokes–Coriolis semigroup $T_{\mathfrak{S},\varphi}$. Therefore, we consider the following fractional linear problem:

$$\begin{cases} u_t + (-\Delta)^\varphi u + \mathfrak{S}e_3 \times u + \nabla p = 0 & \text{in } \mathbb{R}^3 \times \mathbb{R}_+ \\ \operatorname{div} u = 0 & \text{in } \mathbb{R}^3 \times \mathbb{R}_+ \\ u|_{t=0} = u_0 & \text{in } \mathbb{R}^3 \end{cases} \quad (5)$$

The solution of Equation (5) can be obtained using the fractional Stokes–Coriolis semigroup $T_{\mathfrak{S},\varphi}$, which has an explicit representation of the following form [15,16]:

$$T_{\mathfrak{S},\varphi}(t)u = \mathcal{F}^{-1} \left[\cos \left(\mathfrak{S} \frac{\eta_3}{|\eta|} t \right) I + \sin \left(\mathfrak{S} \frac{\eta_3}{|\eta|} t \right) R(\eta) \right] * \left(e^{-(\Delta)^\varphi t} u \right), \quad (6)$$

where I denotes the unit matrix in $M_{3 \times 3}(\mathbb{R})$ and $N(\eta)$ denotes the skew-symmetric matrix given by

$$R(\eta) := \frac{1}{|\eta|} \begin{pmatrix} 0 & \eta_3 & -\eta_2 \\ -\eta_3 & 0 & \eta_1 \\ \eta_2 & -\eta_1 & 0 \end{pmatrix}, \quad \eta \in \mathbb{R}^3 \setminus \{0\}.$$

Therefore, we can write the semigroup as

$$\mathcal{A}_{\mathfrak{S},\varphi}(t) = \begin{pmatrix} T_{\mathfrak{S},\varphi}(t) & 0 \\ 0 & S_\varphi(t) \end{pmatrix},$$

where $S_\varphi(t) := e^{-(\Delta)^\varphi t} = \mathcal{F}^{-1} \left(e^{-|\eta|^{2\varphi} t} \right)$. Using the semigroup $\mathcal{A}_{\mathfrak{S},\varphi}(t)$, we can transform Equation (1) into the following integral form:

$$\begin{pmatrix} u \\ B \end{pmatrix} = \mathcal{A}_{\mathfrak{S}, \varphi}(t) \begin{pmatrix} u_0 \\ B_0 \end{pmatrix} - \int_0^t \mathcal{A}_{\mathfrak{S}, \varphi}(t-y) \mathfrak{N} \begin{pmatrix} \operatorname{div}(u \otimes u - B \otimes B) \\ \operatorname{div}(u \otimes B - B \otimes u) \end{pmatrix} (y) dy, \quad (7)$$

where $\mathfrak{N} = I - \nabla(-\Delta)^{-1} \operatorname{div}$ is the Leray–Hopf projection.

If (u, B) satisfies Equation (7) in a suitable function space, then (u, B) is a solution to Equation (1).

Now, we give the definitions of the function spaces $X_{\mathfrak{S}}^{s,p,\pi}(\mathbb{R}^3)$ and $X_{\mathfrak{S}}^p(\mathbb{R}^3)$ of Besov type, which are generated by the linear semigroup $T_{\mathfrak{S}, \varphi}$. The set of all tempered distributions is denoted by $\mathcal{S}'(\mathbb{R}^3)$. Let $-\infty < s, \mathfrak{S} < \infty$ and the function spaces $X_{\mathfrak{S}}^{s,p,\pi}(\mathbb{R}^3)$ and $X_{\mathfrak{S}}^p(\mathbb{R}^3)$ are defined as

$$X_{\mathfrak{S}}^{s,p,\pi}(\mathbb{R}^3) = \{u \in \mathcal{S}' \mid \|u\|_{X_{\mathfrak{S}}^{s,p,\pi}} < \infty\},$$

$$\|u\|_{X_{\mathfrak{S}}^{s,p,\pi}} = \|T_{\mathfrak{S}}(t)u\|_{L_t^{\pi}(0,\infty; \dot{W}_x^{s,p}(\mathbb{R}^3))}$$

and

$$X_{\mathfrak{S}}^p(\mathbb{R}^3) = \{u \in \mathcal{S}' \mid \|u\|_{X_{\mathfrak{S}}^p} < \infty\},$$

$$\|u\|_{X_{\mathfrak{S}}^p} = \sup_{t>0} t^{\frac{1}{2\varphi}(1-\frac{3}{p})} \|T_{\mathfrak{S}}(t)u\|_{L^p}.$$

When $\mathfrak{S} = 0$, $T_{\mathfrak{S}, \varphi}(t)$ becomes $T_{0, \varphi}(t)u = e^{-t(-\Delta)^{\varphi}}(t)u$. By [26], for $1 \leq \pi < \infty$, we have

$$\|u\|_{X_0^{s,p,\pi}} = \|t^{\frac{1}{\pi}} \|(-\Delta)^{\frac{s}{2}} e^{-t(-\Delta)^{\varphi}} u\|_{L^p} \|_{L^{\pi}(0,\infty; \frac{dt}{t})} \simeq \|(-\Delta)^{\frac{s}{2}} u\|_{\dot{B}_{p,\pi}^{-\frac{2\varphi}{\pi}}} = \|u\|_{\dot{B}_{p,\pi}^{s-\frac{2\varphi}{\pi}}}. \quad (8)$$

For $3 < p \leq \infty$, we see that

$$\|u\|_{X_0^p} = \|t^{\frac{1}{2\varphi}(1-\frac{3}{p})} \|e^{-t(-\Delta)^{\varphi}} u\|_{L^p} \|_{L^{\pi}(0,\infty; \frac{dt}{t})} \simeq \|u\|_{\dot{B}_{p,\pi}^{-1+\frac{3}{p}}}. \quad (9)$$

Hence, the function spaces and $X_{\mathfrak{S}}^{s,p,\pi}(\mathbb{R}^3)$ and $X_{\mathfrak{S}}^p(\mathbb{R}^3)$ can be considered as a generalization of the Besov spaces $\dot{B}_{p,\pi}^{s-\frac{2\varphi}{\pi}}$ and $\dot{B}_{p,\pi}^{-1+\frac{3}{p}}$, respectively.

Next, we recall the Littlewood–Paley decomposition tool. Let $\mathcal{S}(\mathbb{R}^3)$ be a Schwartz space and let $\psi \in \mathcal{S}(\mathbb{R}^3)$ satisfy the following conditions:

$$0 \leq \hat{\psi}_0(\eta) \leq 1 \quad \text{for all } \eta \in \mathbb{R}^3,$$

$$\operatorname{supp} \hat{\psi}_0 \subset \left\{ \eta \in \mathbb{R}^3 : \frac{1}{2} \leq |\eta| \leq 2 \right\}$$

and

$$\sum_{j \in \mathbb{Z}} \hat{\psi}_0(2^{-j}\eta) = 1 \quad \text{for all } \eta \in \mathbb{R}^3 \setminus \{0\},$$

where $\psi_j(x) := 2^{3j} \psi_0(2^j x)$ and $\Delta_j u := \psi_j * u$ for $u \in \mathcal{S}'(\mathbb{R}^3)$ and $j \in \mathbb{Z}$.

Now, we define the homogeneous Besov space $\dot{B}_{p,q}^s(\mathbb{R}^3)$. For $s \in \mathbb{R}$ and $p, q \in [1, \infty]$

$$\dot{B}_{p,q}^s(\mathbb{R}^3) := \left\{ u \in \mathcal{S}'(\mathbb{R}^3) \mid \|u\|_{\dot{B}_{p,q}^s} < +\infty \right\},$$

$$\|u\|_{\dot{B}_{p,q}^s} := \left(\sum_{j \in \mathbb{Z}} 2^{jsq} \|\Delta_j u\|_{L^p}^q \right)^{\frac{1}{q}}.$$

Further, we write the operator $\mathcal{G}$ as

$$\mathcal{G}_{\pm}(t)u(x) := e^{\pm it \frac{D_3}{|D|}} u(x) := \int_{\mathbb{R}^3} e^{ix \cdot \eta^2 \pm it \frac{\eta_3}{|\eta|}} \hat{u}(\eta) d\eta \quad \text{for } x \in \mathbb{R}^3 \text{ and } t \in \mathbb{R}.$$

So the operator $T_{\mathfrak{S}, \varphi}$ becomes

$$T_{\mathfrak{S}, \varphi}(t)u = \frac{1}{2}\mathcal{G} + (\mathfrak{S}t) \left[e^{-t(-\Delta)^{\varphi}} (I + J)u \right] + \frac{1}{2}\mathcal{G} - (\mathfrak{S}t) \left[e^{-t(-\Delta)^{\varphi}} (I - J)u \right],$$

where J is the singular integral operator matrix defined as

$$J := \begin{pmatrix} 0 & R_3 & -R_2 \\ -R_3 & 0 & R_1 \\ R_2 & -R_1 & 0 \end{pmatrix},$$

where R_k for $k = 1, 2, 3$ is the Riesz transforms in $\mathbb{R}^3$. Next, we give the following lemmas as important tools to prove our main results.

Lemma 1 ([26]). Let $u \in L^r(\mathbb{R}^n)$ and $1 \leq r \leq p \leq \infty$. Then, for $\varphi, \beta > 0$ we have

$$\left\| e^{-t(-\Delta)^{\varphi}} u \right\|_{L^p} \lesssim t^{-\frac{n}{2\varphi} \left(\frac{1}{r} - \frac{1}{p} \right)} \|u\|_{L^r},$$

and

$$\left\| (-\Delta)^{\frac{\beta}{2}} e^{-t(-\Delta)^{\varphi}} u \right\|_{L^p} \lesssim t^{-\frac{\beta}{2\varphi} - \frac{n}{2\varphi} \left(\frac{1}{r} - \frac{1}{p} \right)} \|u\|_{L^r}.$$

Lemma 2 ([27]). Let $1 \leq p, q \leq \infty$ and $-\infty < s_0 \leq s_1 < \infty$. Then,

$$\left\| e^{-t(-\Delta)^{\varphi}} u \right\|_{\dot{B}_{p,q}^{s_1}} \lesssim t^{-\frac{1}{2\varphi}(s_1 - s_0)} \|u\|_{\dot{B}_{p,q}^{s_0}}.$$

Lemma 3 ([28]). Let $1 \leq p_0 \leq p_1 \leq \infty, 1 \leq q \leq \infty$ and $-\infty < s_0 \leq s_1 < \infty$. Then,

$$\left\| e^{-t(-\Delta)^{\varphi}} u \right\|_{\dot{B}_{p_1,q}^{s_1}} \lesssim t^{-\frac{1}{2\varphi}(s_1 - s_0) - \frac{3}{2\varphi} \left(\frac{1}{p_0} - \frac{1}{p_1} \right)} \|u\|_{\dot{B}_{p_0,q}^{s_0}}.$$

Lemma 4 is used to obtain the dispersive estimate for the operator $\mathcal{G}_{\pm}(y)$.

Lemma 4 ([29]). Let $y, s \in \mathbb{R}, 2 \leq p \leq \infty$ and $1 \leq q \leq \infty$. Then,

$$\left\| \mathcal{G}_{\pm}(y)u \right\|_{\dot{B}_{p,q}^s} \lesssim (1 + |y|)^{-\left(1 - \frac{2}{p}\right)} \|u\|_{\dot{B}_{p',q}^{s+3(1-\frac{2}{p})}}$$

where $\frac{1}{p} + \frac{1}{p'} = 1$.

Lemma 5. Let $1 \leq p_0 \leq 2 \leq p_1 \leq \infty, 1 \leq q \leq \infty$. and $-\infty < s_0 \leq s_1 < \infty$. Then,

$$\left\| T_{\mathfrak{S}, \varphi}(t)u \right\|_{\dot{B}_{p_1,q}^{s_1}} \lesssim t^{-\frac{1}{2\varphi}(s_1 - s_0) - \frac{3}{2\varphi} \left(\frac{1}{p_0} - \frac{1}{p_1} \right)} \|u\|_{\dot{B}_{p_0,q}^{s_0}}.$$

Proof. According to Plancherel's theorem, $\mathcal{R}$ is bounded in $L^2(\mathbb{R}^3)$, and using the semi-group estimate $e^{-t(-\Delta)^{\varphi}}$ in $L^{p_0} - L^2$ and Lemmas 3, 4 we have

$$\begin{aligned} \left\| e^{-\frac{t}{2}(-\Delta)^{\varphi}} \mathcal{G}_{\pm}(\mathfrak{S}t) \left[e^{-\frac{t}{2}(-\Delta)^{\varphi}} (I \pm \mathcal{R})u \right] \right\|_{\dot{B}_{p_1,q}^{s_1}} &\lesssim t^{-\frac{1}{2\varphi}(s_1 - s_0) - \frac{3}{2\varphi} \left(\frac{1}{2} - \frac{1}{p_1} \right)} \left\| \mathcal{G}_{\pm}(\mathfrak{S}t) \left[e^{-\frac{t}{2}(-\Delta)^{\varphi}} u \right] \right\|_{\dot{B}_{2,q}^{s_0}} \\ &\lesssim t^{-\frac{1}{2\varphi}(s_1 - s_0) - \frac{3}{2\varphi} \left(\frac{1}{2} - \frac{1}{p_1} \right)} \left\| e^{-\frac{t}{2}(-\Delta)^{\varphi}} u \right\|_{\dot{B}_{2,q}^{s_0}} \\ &\lesssim t^{-\frac{1}{2\varphi}(s_1 - s_0) - \frac{3}{2\varphi} \left(\frac{1}{p_0} - \frac{1}{p_1} \right)} \|u\|_{\dot{B}_{p_0,q}^{s_0}}. \end{aligned}$$

□

Lemma 6. Let $1 < p_0 \leq 2 \leq p_1 < \infty$ and $0 \leq s < \infty$. Then,

$$\left\| \partial_x^\beta T_{\mathfrak{S}, \wp}(t)u \right\|_{H^s} \lesssim t^{-\frac{1}{2\wp}(s+|\beta|) - \frac{3}{2a}(\frac{1}{p_0} - \frac{1}{2})} \|u\|_{L^{p_0}},$$

and

$$\left\| \partial_x^\beta T_{\mathfrak{S}, \wp}(t)u \right\|_{L^{p_1}} \lesssim t^{-\frac{\beta}{2\wp} - \frac{3}{2\wp}(\frac{1}{p_0} - \frac{1}{p_1})} \|u\|_{L^{p_0}}.$$

Proof. By using Lemma 4 and the embeddings

$$L^p(\mathfrak{R}^3) \hookrightarrow \dot{B}_{p,2}^0(\mathfrak{R}^3),$$

$$\dot{B}_{p,2}^0(\mathfrak{R}^3) \hookrightarrow L^p(\mathfrak{R}^3), \text{ for } p \in (1, 2]$$

and

$$\dot{H}^s(\mathfrak{R}^3) = \dot{B}_{2,2}^s, \text{ for } p \in [2, \infty),$$

we can easily obtain the result. $\square$

Lemma 7 ([27]). Let $t > 0$, $\mathfrak{S} \in \mathfrak{R}$ and $s \in \mathfrak{R}$. Then,

$$\|T_{\mathfrak{S}, \wp}(t)u\|_{\dot{H}^s} \lesssim \|u\|_{\dot{H}^s}.$$

Lemma 8. Let $\wp, p, q$ and π satisfy $\frac{1}{2} < \wp < \frac{5}{4}, 2 < p < \frac{3}{2-\wp}$ and $1 - \frac{1}{p} \leq \frac{1}{q} < \frac{2\wp-1}{3} + \frac{1}{p}$, $\max\left\{0, 1 - \frac{1}{2\wp} - \frac{3}{2\wp}\left(\frac{1}{q} - \frac{1}{p}\right) - \left(1 - \frac{2}{p}\right)\right\} < \frac{1}{\pi} \leq \min\left\{\frac{1}{2}, 1 - \frac{1}{2\wp} - \frac{3}{2\wp}\left(\frac{1}{q} - \frac{1}{p}\right)\right\}$. Then,

$$\left\| \int_0^t T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla u(y) dy \right\|_{L^\pi(0, \infty; L^p)} \lesssim |\mathfrak{S}|^{-\left\{1 - \frac{1}{2a} - \frac{3}{2a}\left(\frac{1}{q} - \frac{1}{p}\right) - \frac{1}{\pi}\right\}} \|u\|_{L^{\frac{\pi}{2}}(0, \infty; L^q)} \quad (10)$$

for $u, B \in L^{\frac{\pi}{2}}(0, \infty; L^q)(\mathfrak{R}^3)$.

Proof. By considering the boundedness of $\mathfrak{N}$ in $L^q(\mathfrak{R}^3)$, using the embedding $\dot{B}_{p,2}^0(\mathfrak{R}^3) \hookrightarrow L^p(\mathfrak{R}^3)$ for $p \in [2, \infty)$, applying Lemmas 1, 3, and 4, we get

$$\left\| \int_0^t T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla u(y) dy \right\|_{L^\pi(0, \infty; L^p)} \lesssim \left\| \int_0^t k_{\mathfrak{S}}(t-y) \|u(y)\|_{L^q} dy \right\|_{L_t^\pi(0, \infty)},$$

where

$$k_{\mathfrak{S}}(t) := \{1 + |\mathfrak{S}|t\}^{-\left(1 - \frac{2}{p}\right)t - \frac{3}{2a}\left(\frac{1}{q} - \frac{1}{p}\right) - \frac{1}{2a}}$$

If $\frac{1}{\pi} < 1 - \frac{1}{2\wp} - \frac{3}{2\wp}\left(\frac{1}{q} - \frac{1}{p}\right)$, we have $\|k_{\mathfrak{S}}\|_{L'} \lesssim |\mathfrak{S}|^{-\left\{1 - \frac{1}{2\wp} - \frac{3}{2\wp}\left(\frac{1}{q} - \frac{1}{p}\right) - \frac{1}{\pi}\right\}}$. By using Young's inequality, $\frac{1}{\pi} = \frac{1}{\pi'} + \frac{2}{\pi} - 1$, we obtain inequality (10). $\square$

In order to prove the bilinear term in Equation (7), the following lemma is significant.

Lemma 9 ([29]). Let p, q , and s satisfy the conditions $\frac{s}{3} < \frac{1}{p} < \frac{1}{2} + \frac{s}{6}, \frac{1}{q} = \frac{2}{p} - \frac{s}{3}$ and $0 \leq s < 3$. Then,

$$\|uv\|_{\dot{W}^{s,q}} \lesssim \|u\|_{\dot{W}^{s,p}} \|v\|_{\dot{W}^{s,p}},$$

where $u, v \in \dot{W}^{s,p}(\mathfrak{R}^3)$.

Proof of Theorem 1: Let us define $\|\cdot\|_{Z_1} := \|\cdot\|_{L^\pi(0, \infty; \dot{W}^{s,p}(\mathfrak{R}^3)^3)}$. It is easy to get

$$\left\| \mathcal{A}_{\mathfrak{S}, \varphi}(t) \begin{pmatrix} u_0 \\ B_0 \end{pmatrix} \right\|_{Z_1} \leq \|T_{\mathfrak{S}, \varphi}(t)u_0\|_{Z_1} + \|S_{\varphi}(t)B_0\|_{Z_1} = \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} + \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}}. \quad (11)$$

Next, we write a complete metric space $(\mathcal{X}_1, d_1)$ with mapping $\mathcal{J}$ as:

$$\begin{aligned} \mathcal{X}_1 &:= \left\{ u, B \in L^\pi \left(0, \infty; \dot{W}^{s,p}(\mathbb{R}^3)^3 \right) \mid \|u\|_{Z_1} \leq 2\|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}}, \|B\|_{Z_1} \leq 2\|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \right\}, \\ d_1 \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} v \\ b \end{pmatrix} \right) &:= \|u - v\|_{Z_1} + \|B - b\|_{Z_1}, \\ \mathcal{J} \left(\begin{pmatrix} u \\ B \end{pmatrix} \right)(t) &:= \mathcal{A}_{\mathfrak{S}, \varphi} \left(\begin{pmatrix} u_0 \\ B_0 \end{pmatrix} \right)(t) - B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right), \end{aligned}$$

where

$$B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right) = \int_0^t \mathcal{A}_{\mathfrak{S}, \varphi}(t-y) \mathfrak{N} \begin{pmatrix} \operatorname{div}(u \otimes u - B \otimes B) \\ \operatorname{div}(u \otimes B - B \otimes u) \end{pmatrix} dy. \quad (12)$$

We can write

$$\left\| \mathcal{J} \left(\begin{pmatrix} u \\ B \end{pmatrix} \right)(t) \right\|_{Z_1} \leq \left\| \mathcal{A}_{\mathfrak{S}, \varphi} \left(\begin{pmatrix} u_0 \\ B_0 \end{pmatrix} \right)(t) \right\|_{Z_1} + \left\| B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right) \right\|_{Z_1} = I_1 + I_2. \quad (13)$$

I_1 is estimated in inequality (11). To estimate I_2 , let $\frac{1}{q} = \frac{2}{p} - \frac{s}{3}$, using Lemmas 7, 8, and Holder's inequality, it is easy to obtain that

$$\begin{aligned} \left\| \int_0^t T_{\mathfrak{S}, \varphi}(t-y) \mathfrak{N} \operatorname{div}(u \otimes u)(y) dy \right\|_{Z_1} &\lesssim |\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \|u\|_{Z_1}^2 \\ &\lesssim 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}}^2. \end{aligned} \quad (14)$$

Similarly, we have

$$\left\| \int_0^t T_{\mathfrak{S}, \varphi}(t-y) \mathfrak{N} \operatorname{div}(B \otimes B)(y) dy \right\|_{Z_1} \lesssim 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}}^2, \quad (15)$$

$$\left\| \int_0^t S_{\varphi}(t-y) \mathfrak{N} \operatorname{div}(u \otimes B)(y) dy \right\|_{Z_1} \lesssim 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}}, \quad (16)$$

and

$$\left\| \int_0^t S_{\varphi}(t-y) \mathfrak{N} \operatorname{div}(B \otimes u)(y) dy \right\|_{Z_1} \lesssim 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}}. \quad (17)$$

So from Equation (13), we have

$$\begin{aligned} \left\| \mathcal{J} \left(\begin{pmatrix} u \\ B \end{pmatrix} \right)(t) \right\|_{Z_1} &\lesssim \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} + \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} + 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}}^2 \\ &\quad + 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}}^2 \\ &\quad + 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \\ &\quad + 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \\ &= \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \left(1 + 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \left(\|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} + \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \right) \right) \\ &\quad + \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \left(1 + 4|\mathfrak{S}|^{-\left\{1 - \frac{1}{2\varphi} \left(1 + \frac{3}{p} - s\right) - \frac{1}{\pi}\right\}} \left(\|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} + \|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \right) \right). \end{aligned} \quad (18)$$

We can also write

$$\begin{aligned}
 & \left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} (t) - \mathcal{J} \begin{pmatrix} v \\ b \end{pmatrix} (t) \right\|_{Z_1} \\
 &= \left\| B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u-v \\ B-b \end{pmatrix} \right) + B \left(\begin{pmatrix} u-v \\ B-b \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right) \right\|_{Z_1} \\
 &\leq |\mathfrak{S}|^{-\left\{1-\frac{1}{2\varphi}\left(1+\frac{3}{p}-s\right)-\frac{1}{\pi}\right\}} (\|u\|_{Z_1} + \|v\|_{Z_1} + \|B\|_{Z_1} + \|b\|_{Z_1}) (\|u-v\|_{Z_1} + \|B-b\|_{Z_1}) \\
 &\lesssim 4|\mathfrak{S}|^{-\left\{1-\frac{1}{2\varphi}\left(1+\frac{3}{p}-s\right)-\frac{1}{\pi}\right\}} \left(\|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} + \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \right) (\|u-v\|_{Z_1} + \|B-b\|_{Z_1}).
 \end{aligned} \tag{19}$$

Let us consider that $u_0, B_0 \in X_{\mathfrak{S}}^{s,p,\pi}(\mathfrak{R}^3)^3 \cap \dot{H}^s(\mathfrak{R}^3)^3$ satisfies

$$\sup_{\mathfrak{S} \in \mathfrak{R} \setminus \{0\}} |\mathfrak{S}|^{-\left\{1-\frac{1}{2\varphi}\left(1+\frac{3}{p}-s\right)-\frac{1}{\pi}\right\}} \left(\|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} + \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \right) \leq \min \left\{ \frac{1}{8K_1}, \frac{1}{4K_2} \right\}. \tag{20}$$

Then, in the view of Equations (18) and (19), for all $\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} v \\ b \end{pmatrix} \in X_1$ we can obtain that

$$\begin{aligned}
 \left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} \right\|_{Z_1} &\leq 2 \left(\|u_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} + \|B_0\|_{X_{\mathfrak{S}}^{s,p,\pi}} \right), \\
 \left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} - \mathcal{J} \begin{pmatrix} v \\ b \end{pmatrix} \right\|_{Z_1} &\leq \frac{1}{2} (\|u-v\|_{Z_1} + \|B-b\|_{Z_1}).
 \end{aligned}$$

Therefore, by using Banach's contraction principle, there exists a unique solution $u, B \in X_1$ satisfying (7). Next, we need to show that the solution $u, B \in X_1$ also belongs to $C([0, \infty); H^s(\mathfrak{R}^3)^3)$.

$$\left\| \begin{pmatrix} u \\ B \end{pmatrix} (t) \right\|_{\dot{H}^s} \leq \left\| \mathcal{A}_{\mathfrak{S}, \varphi} \begin{pmatrix} u_0 \\ B_0 \end{pmatrix} (t) \right\|_{\dot{H}^s} + \left\| B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right) \right\|_{\dot{H}^s} = I_3 + I_4.$$

To obtain I_1 , we have $I_3 \lesssim \|u_0\|_{\dot{H}^s} + \|B_0\|_{\dot{H}^s}$. For I_4 , let $\frac{1}{q} = \frac{2}{p} - \frac{3}{s}$ with $q \in (1, 2]$, applying Lemmas 6, 9 and Holder's inequality, we have the following

$$\begin{aligned}
 I_4 &\lesssim \int \frac{1}{(t-y)^{\left(\frac{3}{p\varphi}-\frac{s}{2\varphi}-\frac{3}{4\varphi}+\frac{1}{2\varphi}\right)}} \|u \otimes u\|_{L^p} dy + \int \frac{1}{(t-y)^{\left(\frac{3}{p\varphi}-\frac{s}{2\varphi}-\frac{3}{4\varphi}+\frac{1}{2\varphi}\right)}} \|B \otimes B\|_{L^p} dy \\
 &+ \int \frac{1}{(t-y)^{\left(\frac{3}{p\varphi}-\frac{s}{2\varphi}-\frac{3}{4\varphi}+\frac{1}{2\varphi}\right)}} \|u \otimes B\|_{L^p} dy + \int \frac{1}{(t-y)^{\left(\frac{3}{p\varphi}-\frac{s}{2\varphi}-\frac{3}{4\varphi}+\frac{1}{2\varphi}\right)}} \|B \otimes u\|_{L^p} dy \\
 &\lesssim \left(\int_0^t \frac{1}{(t-y)^{\left(\frac{3}{p\varphi}-\frac{s}{2\varphi}-\frac{3}{4\varphi}+\frac{1}{2\varphi}\right)\left(\frac{\pi}{2}\right)'}} dy \right)^{\frac{1}{\left(\frac{\pi}{2}\right)'}} \|u\|_{L^\pi(0,\infty;\dot{W}^{s,p})}^2 \\
 &+ \left(\int_0^t \frac{1}{(t-y)^{\left(\frac{3}{p\varphi}-\frac{s}{2\varphi}-\frac{3}{4\varphi}+\frac{1}{2\varphi}\right)\left(\frac{\pi}{2}\right)'}} dy \right)^{\frac{1}{\left(\frac{\pi}{2}\right)'}} \|u\|_{L^\pi(0,\infty;\dot{W}^{s,p})}^2 \\
 &+ \left(\int_0^t \frac{1}{(t-y)^{\left(\frac{3}{p\varphi}-\frac{s}{2\varphi}-\frac{3}{4\varphi}+\frac{1}{2\varphi}\right)\left(\frac{\pi}{2}\right)'}} dy \right)^{\frac{1}{\left(\frac{\pi}{2}\right)'}} \|u\|_{L^\pi(0,\infty;\dot{W}^{s,p})}^2 \|B\|_{L^\pi(0,\infty;\dot{W}^{s,p})}^2 \\
 &+ \left(\int_0^t \frac{1}{(t-y)^{\left(\frac{3}{p\varphi}-\frac{s}{2\varphi}-\frac{3}{4\varphi}+\frac{1}{2\varphi}\right)\left(\frac{\pi}{2}\right)'}} dy \right)^{\frac{1}{\left(\frac{\pi}{2}\right)'}} \|B\|_{L^\pi(0,\infty;\dot{W}^{s,p})}^2 \|u\|_{L^\pi(0,\infty;\dot{W}^{s,p})}^2.
 \end{aligned} \tag{21}$$

Since $\frac{1}{\pi} < \frac{1}{2} + \frac{1}{8\varphi} + \frac{s}{4\varphi} - \frac{3}{2\varphi p}$, the time integral on the right hand side in inequality (21) converges and

$$\left(\int_0^t \frac{1}{(t-y)^{\left(\frac{3}{p\varphi} - \frac{s}{2\varphi} - \frac{3}{4\varphi} + \frac{1}{2\varphi} \left(\frac{\pi}{2}\right)'\right)}} dy \right)^{\frac{1}{\left(\frac{\pi}{2}\right)'}} \lesssim t^{2\left(\frac{1}{2} + \frac{1}{8\varphi} + \frac{s}{4\varphi} - \frac{3}{2\varphi p} - \frac{1}{\pi}\right)}.$$

This implies that for all $t \geq 0$, $u, B \in \dot{H}^s(\mathbb{R}^3)^3$. Similarly, it is easy to get that $u, B \in C([0, \infty); \dot{H}^s(\mathbb{R}^3)^3)$, which finishes the proof of Theorem 1. $\square$

Remark 1. By substituting $B = 0$ and $\varphi = 1$ in Theorem 1, we get Theorem 1.3, [30].

Proof of Theorem 2: Let us define

$$\|u\|_{Y_2} := \sup_{t>0} \|u(t)\|_{\dot{H}^s} \text{ and } \|u\|_{Z_2} := \sup_{t>0} t^{\frac{1}{2}\left(1-\frac{3}{p}\right)} \|u(t)\|_{L^p}. \quad (22)$$

It is easy to get

$$\left\| \mathcal{A}_{\mathfrak{S}, \varphi}(t) \begin{pmatrix} u_0 \\ B_0 \end{pmatrix} \right\|_{Y_1} \leq \|T_{\mathfrak{S}, \varphi}(t)u_0\|_{Y_1} + \|S_{\varphi}(t)B_0\|_{Y_1} \lesssim \|u_0\|_{\dot{H}^s} + \|B_0\|_{\dot{H}^s} \quad (23)$$

and

$$\left\| \mathcal{A}_{\mathfrak{S}, \varphi}(t) \begin{pmatrix} u_0 \\ B_0 \end{pmatrix} \right\|_{Z_2} \leq \|T_{\mathfrak{S}, \varphi}(t)u_0\|_{Z_2} + \|S_{\varphi}(t)B_0\|_{Z_2} = \|u_0\|_{X_{\mathfrak{S}}^p} + \|B_0\|_{X_{\mathfrak{S}}^p}. \quad (24)$$

Next, we write a complete metric space $(\mathcal{X}_2, d_2)$ with mapping $\mathcal{J}$ as:

$$\mathcal{X}_2 := \left\{ u, B \in C\left([0, \infty); \dot{H}^s(\mathbb{R}^3)^3\right) \right\}$$

such that $\|u\|_{Y_1} \lesssim 2\|u_0\|_{\dot{H}^s}$, $\|B\|_{Y_1} \lesssim 2\|B_0\|_{\dot{H}^s}$, $\|u\|_{Z_2} \leq 2\|u_0\|_{X_{\mathfrak{S}}^p}$, $\|B\|_{Z_2} \leq 2\|B_0\|_{X_{\mathfrak{S}}^p}$,

$$d_1\left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} v \\ b \end{pmatrix}\right) := \|u - v\|_{Y_1} + \|B - b\|_{Y_1},$$

$$\mathcal{J}\left(\begin{pmatrix} u \\ B \end{pmatrix}\right)(t) := \mathcal{A}_{\mathfrak{S}, \varphi}\left(\begin{pmatrix} u_0 \\ B_0 \end{pmatrix}\right)(t) - B\left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix}\right),$$

where the bilinear term $B\left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix}\right)$ is defined in Equation (12). We can write

$$\left\| \mathcal{J}\left(\begin{pmatrix} u \\ B \end{pmatrix}\right)(t) \right\|_{Y_1} \leq \left\| \mathcal{A}_{\mathfrak{S}, \varphi}\left(\begin{pmatrix} u_0 \\ B_0 \end{pmatrix}\right)(t) \right\|_{Y_1} + \left\| B\left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix}\right) \right\|_{Y_1} = I_5 + I_6. \quad (25)$$

I_5 is estimated in inequality (23). For I_6 , let $1 < r \leq 2$ and set $\frac{1}{r} = \frac{1}{s'} + \frac{1}{p}$, where $\frac{1}{s'} = \frac{1}{2} - \frac{s}{3}$ with $2 \leq s' < \frac{6}{5-4\varphi}$. Then, by Lemma 6, the boundedness of $\mathfrak{N}$ in $L^2(\mathbb{R}^n)$, and Holder's inequality, we have

$$\begin{aligned}
& \left\| B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right) \right\|_{\dot{H}^s} \\
& \leq \int_0^t \|T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla [u(y) \otimes u(y)]\|_{\dot{H}^s} dy + \int_0^t \|T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla [B(y) \otimes B(y)]\|_{\dot{H}^s} dy \\
& + \int_0^t \|T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla [u(y) \otimes B(y)]\|_{\dot{H}^s} dy + \int_0^t \|T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla [B(y) \otimes u(y)]\|_{\dot{H}^s} dy \\
& \lesssim \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}}} \|u(y) \otimes u(y)\|_{L^r} dy + \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}}} \|B(y) \otimes B(y)\|_{L^r} dy \\
& + \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}}} \|u(y) \otimes B(y)\|_{L^r} dy + \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}}} \|B(y) \otimes u(y)\|_{L^r} dy \\
& \lesssim \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}}} \|u(y)\|_{L^{s'}} \|u(y)\|_{L^p} dy + \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}}} \|B(y)\|_{L^{s'}} \|B(y)\|_{L^p} dy \\
& + \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}}} \|u(y)\|_{L^{s'}} \|B(y)\|_{L^p} dy + \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}}} \|B(y)\|_{L^{s'}} \|u(y)\|_{L^p} dy.
\end{aligned}$$

Using $\|\cdot\|_{Y_1}, \|\cdot\|_{Z_2}$ defined in Equation (22) with $\frac{1}{2\varphi} \left(1 - \frac{3}{p}\right) < 1$ and $\dot{H}^s(\mathfrak{R}^3) \hookrightarrow L^{s'}(\mathfrak{R}^3)$, we have

$$\begin{aligned}
& \left\| B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right) \right\|_{\dot{H}^s} \\
& \lesssim \|u\|_{Y_1} \|u\|_{Z_2} \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}} y^{\frac{1}{2\varphi} \left(1 - \frac{3}{p}\right)}} dy + \|B\|_{Y_1} \|B\|_{Z_2} \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}} y^{\frac{1}{2\varphi} \left(1 - \frac{3}{p}\right)}} dy \\
& + \|u\|_{Y_1} \|B\|_{Z_2} \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}} y^{\frac{1}{2\varphi} \left(1 - \frac{3}{p}\right)}} dy + C \|B\|_{Y_1} \|u\|_{Z_2} \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}} y^{\frac{1}{2\varphi} \left(1 - \frac{3}{p}\right)}} dy \\
& \lesssim \|u\|_{Y_1} \|u\|_{Z_2} + \|B\|_{Y_1} \|B\|_{Z_2} + \|u\|_{Y_1} \|B\|_{Z_2} + \|B\|_{Y_1} \|u\|_{Z_2}.
\end{aligned}$$

Therefore, from Equation (25), we have

$$\begin{aligned}
\left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} (t) \right\|_{Y_1} & \lesssim \|u_0\|_{\dot{H}^s} + \|B_0\|_{\dot{H}^s} \\
& + 4 \left(\|u_0\|_{\dot{H}^s} \|u_0\|_{X_3^p} + \|B_0\|_{\dot{H}^s} \|B_0\|_{X_3^p} + \|u_0\|_{\dot{H}^s} \|B_0\|_{X_3^p} + \|B_0\|_{\dot{H}^s} \|u_0\|_{X_3^p} \right) \\
& \lesssim (\|u_0\|_{\dot{H}^s} + \|B_0\|_{\dot{H}^s}) \left(1 + 4 \left(\|u_0\|_{X_3^p} + \|B_0\|_{X_3^p} \right) \right).
\end{aligned} \tag{26}$$

Similarly, we estimate the following

$$\left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} (t) \right\|_{Z_2} \leq \left\| \mathcal{A}_{\mathfrak{S}, \varphi} \begin{pmatrix} u_0 \\ B_0 \end{pmatrix} (t) \right\|_{Z_2} + \left\| B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right) \right\|_{Z_2} = I_7 + I_8. \tag{27}$$

I_7 is estimated in inequality (24) and we have to estimate I_8 . By using Lemma 6, Holder's inequality, and the definition of Z_2 defined in (22), we have

$$\begin{aligned}
& t^{\frac{1}{2\varphi}(1-\frac{3}{p})} \left\| B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right) \right\|_{L^p} \\
& \leq t^{\frac{1}{2\varphi}(1-\frac{3}{p})} \left(\int_0^t \|T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla [u(y) \otimes u(y)]\|_{L^p} dy + \int_0^t \|T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla [B(y) \otimes B(y)]\|_{L^p} dy \right) \\
& + t^{\frac{1}{2\varphi}(1-\frac{3}{p})} \left(\int_0^t \|T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla [u(y) \otimes B(y)]\|_{L^p} dy + \int_0^t \|T_{\mathfrak{S}}(t-y) \mathfrak{N} \nabla [B(y) \otimes u(y)]\|_{L^p} dy \right) \\
& \lesssim t^{\frac{1}{2\varphi}(1-\frac{3}{p})} \left(\int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}} \|u(y) \otimes v(y)\|_{L^{\frac{p}{2}}}^{\frac{p}{2}} dy} + \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}} \|u(y) \otimes v(y)\|_{L^{\frac{p}{2}}}^{\frac{p}{2}} dy} \right) \\
& + t^{\frac{1}{2\varphi}(1-\frac{3}{p})} \left(\int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}} \|u(y) \otimes v(y)\|_{L^{\frac{p}{2}}}^{\frac{p}{2}} dy} + \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}} \|u(y) \otimes v(y)\|_{L^{\frac{p}{2}}}^{\frac{p}{2}} dy} \right) \\
& \lesssim t^{\frac{1}{2\varphi}(1-\frac{3}{p})} (\|u\|_{Z_2} \|u\|_{Z_2} + \|B\|_{Z_2} \|B\|_{Z_2} + 2\|u\|_{Z_2} \|B\|_{Z_2}) \int_0^t \frac{1}{(t-y)^{\frac{1}{2\varphi} + \frac{3}{2\varphi p}} y^{\frac{1}{\varphi}(1-\frac{3}{p})}} dy \\
& \lesssim \|u\|_{Z_2} \|u\|_{Z_2} + \|B\|_{Z_2} \|B\|_{Z_2} + 2\|u\|_{Z_2} \|B\|_{Z_2}.
\end{aligned}$$

Here, we notice that $\frac{1}{2\varphi} + \frac{3}{2\varphi p} < 1$ as $p > \frac{3}{2\varphi-1}$. As a result, from Equation (27), we have

$$\begin{aligned}
\left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} (t) \right\|_{Z_2} & \lesssim \|u_0\|_{X_{\mathfrak{S}}^p} + \|B_0\|_{X_{\mathfrak{S}}^p} + 4 \left(\|u_0\|_{X_{\mathfrak{S}}^p}^2 + \|B_0\|_{X_{\mathfrak{S}}^p}^2 + 2\|u_0\|_{X_{\mathfrak{S}}^p} \|B_0\|_{X_{\mathfrak{S}}^p} \right) \\
& \lesssim (\|u_0\|_{X_{\mathfrak{S}}^p} + \|B_0\|_{X_{\mathfrak{S}}^p}) \left(1 + 4(\|u_0\|_{X_{\mathfrak{S}}^p} + \|B_0\|_{X_{\mathfrak{S}}^p}) \right).
\end{aligned} \tag{28}$$

Furthermore, we can write

$$\begin{aligned}
& \left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} (t) - \mathcal{J} \begin{pmatrix} v \\ b \end{pmatrix} (t) \right\|_{Y_1} \\
& = \left\| B \left(\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} u-v \\ B-b \end{pmatrix} \right) + B \left(\begin{pmatrix} u-v \\ B-b \end{pmatrix}, \begin{pmatrix} u \\ B \end{pmatrix} \right) \right\|_{Y_1} \\
& \lesssim (\|u\|_{Y_1} + \|v\|_{Y_1} + \|B\|_{Y_1} + \|b\|_{Y_1}) (\|u-v\|_{Y_1} + \|B-b\|_{Y_1}) \\
& \lesssim 4(\|u_0\|_{X_{\mathfrak{S}}^p} + \|B_0\|_{X_{\mathfrak{S}}^p}) (\|u-v\|_{Y_1} + \|B-b\|_{Y_1}).
\end{aligned} \tag{29}$$

Let us consider that $u_0, B_0 \in X_{\mathfrak{S}}^p(\mathfrak{R}^3)^3 \cap \dot{H}^s(\mathfrak{R}^3)^3$ satisfies

$$\sup_{\mathfrak{S} \in \mathfrak{R}} (\|u_0\|_{X_{\mathfrak{S}}^p} + \|B_0\|_{X_{\mathfrak{S}}^p}) \leq \min \left\{ \frac{1}{8K_1}, \frac{1}{4K_2}, \frac{1}{4K_3} \right\}. \tag{30}$$

Then, from Equations (19), (26) and (28), for all $\begin{pmatrix} u \\ B \end{pmatrix}, \begin{pmatrix} v \\ b \end{pmatrix} \in X_1$ we can easily obtain that

$$\begin{aligned}
& \left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} \right\|_{Y_1} \lesssim 2(\|u_0\|_{\dot{H}^s} + \|B_0\|_{\dot{H}^s}), \\
& \left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} \right\|_{Z_2} \leq 2(\|u_0\|_{X_{\mathfrak{S}}^p} + \|B_0\|_{X_{\mathfrak{S}}^p}), \\
& \left\| \mathcal{J} \begin{pmatrix} u \\ B \end{pmatrix} - \mathcal{J} \begin{pmatrix} v \\ b \end{pmatrix} \right\|_{Y_1} \leq \frac{1}{2} (\|u-v\|_{Y_1} + \|B-b\|_{Z_1}).
\end{aligned}$$

As a result, by using Banach's contraction principle, there exists a unique solution $u, B \in X_2$ that satisfies (7), which finishes the proof of Theorem 2. $\square$

Remark 2. By substituting $B = 0$ and $\varphi = 1$ in Theorem 1, we get Theorem 1.5, [30].

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