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Co-Variational Inequality Problem Involving Two Generalized Yosida Approximation Operators

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Abstract: We focus our study on a co-variational inequality problem involving two generalized Yosida approximation operators in real uniformly smooth Banach space. We show some characteristics of a generalized Yosida approximation operator, which are used in our main proof. We apply the concept of nonexpansive sunny retraction to obtain a solution to our problem. Convergence analysis is also discussed.

Keywords: Yosida; solution; convergence; inequality; operator

MSC: 65J15; 47J25; 65K15



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1. Introduction

Variational inequality theory is an influential unifying methodology for solving many obstacles of pure as well as applied sciences. In 1966, Hartman and Stampacchia [1] initiated the study of variational inequalities while dealing with some problems of mechanics.

The concept of variational inequalities provides us with various devices for modelling many problems existing in variational analysis related to applicable sciences. One can ensure the existence of a solution and the convergence of iterative sequences using these devices. The concept of variational inequality is applicable for the study of stochastic control, network economics, the computation of equilibria, and many other physical problems of real life. For more applications, see [2–12] and references mentioned there.

Alber and Yao [13] first considered and studied a co-variational inequality problem using the nonexpansive sunny retraction concept. They obtained a solution of the co-variational inequality problem and discussed the convergence criteria. Their work is extended by Ahmad and Irfan [14] with a slightly different approach.

Yosida approximation operators are useful for obtaining solutions of various types of differential equations. Petterson [15] first solved the stochastic differential equation by using the Yosida approximation operator approach. For the study of heat equations, the problem of couple sound and heat flow in compressible fluids and wave equations, etc., the concept of the Yosida approximation operator is applicable. For our purpose, we consider a generalized Yosida approximation operator and we have shown that it is Lipschitz continuous as well as strongly accretive. For more details, we refer to [16–20].

After the above important discussion, the aim of this work is to introduce a different version of the co-variational inequality problem, which involves two generalized Yosida approximation operators. We obtain the solution of our problem as well as discuss the convergence criteria for the sequences achieved by the iterative method.

2. Preliminaries

Throughout this document, we denote the real Banach space by E and its dual space by E^* . Let $\langle \dot{a}, \dot{b} \rangle$ be the duality pairing between $\dot{a} \in E$ and $\dot{b} \in E^*$. The usual norm on E is denoted by $\|\cdot\|$, the class of nonempty subsets of E by 2^E and the class of nonempty compact subsets of E by $\widehat{C}(E)$.

Definition 1. The Hausdörff metric on $\widehat{C}(E)$ is defined by

$$D(P, Q) = \max \left\{ \sup_{x \in P} d(x, Q), \sup_{y \in Q} d(P, y) \right\},$$

where $d(x, Q) = \inf_{y \in Q} d(x, y)$ and $d(P, y) = \inf_{x \in P} d(x, y)$,

where d is the metric induced by the norm $\|\cdot\|$.

Definition 2. The normalized duality operator $J : E \rightarrow E^*$ is defined by

$$J(\dot{a}) = \left\{ \dot{b} \in E^* : \langle \dot{a}, \dot{b} \rangle = \|\dot{a}\|^2 = \|\dot{b}\|^2 \right\}, \quad \forall \dot{a} \in E.$$

Some characteristics of the normalized duality operator can be discovered in [21].

Definition 3. The modulus of smoothness for the space E is given by the function:

$$\rho_E(t) = \sup_E \left\{ \frac{\|\dot{c} + \dot{d}\| + \|\dot{c} - \dot{d}\|}{2} - 1 : \|\dot{c}\| = 1, \|\dot{d}\| = t \right\}.$$

Definition 4. The Banach space E is uniformly smooth if and only if

$$\lim_{t \rightarrow 0} t^{-1} \rho_E(t) = 0.$$

The following result is instrumental for our main result.

Proposition 1 ([13]). Let E be a uniformly smooth Banach space and J be the normalized duality operator. Then, for any $\dot{a}, \dot{b} \in E$, we have

- (i) $\|\dot{a} + \dot{b}\|^2 \leq \|\dot{a}\|^2 + 2\langle \dot{b}, J(\dot{a} + \dot{b}) \rangle$.
- (ii) $\langle \dot{a} - \dot{b}, J(\dot{a}) - J(\dot{b}) \rangle \leq 2d^2 \rho_E(4\|\dot{a} - \dot{b}\|/d)$, where $d = \sqrt{\|\dot{a}\|^2 + \|\dot{b}\|^2/2}$.

Definition 5. The operator $h_1 : E \rightarrow E$ is called:

- (i) Accretive, if

$$\langle h_1(\dot{a}) - h_1(\dot{b}), J(\dot{a} - \dot{b}) \rangle \geq 0, \quad \forall \dot{a}, \dot{b} \in E;$$

- (ii) Strongly accretive, if

$$\langle h_1(\dot{a}) - h_1(\dot{b}), J(\dot{a} - \dot{b}) \rangle \geq r_1 \|\dot{a} - \dot{b}\|^2, \quad \forall \dot{a}, \dot{b} \in E,$$

where $r_1 > 0$ is a constant;

- (iii) Lipschitz continuous, if

$$\|h_1(\dot{a}) - h_1(\dot{b})\| \leq \lambda_{h_1} \|\dot{a} - \dot{b}\|, \quad \forall \dot{a}, \dot{b} \in E,$$

where $\lambda_{h_1} > 0$ is a constant.

(iv) *Expansive, if*

$$\|h_1(\dot{a}) - h_1(\dot{b})\| \geq \beta_{h_1} \|\dot{a} - \dot{b}\|, \quad \forall \dot{a}, \dot{b} \in E,$$

where $\beta_{h_1} > 0$ is a constant.

Remark 1. If E is a Hilbert space then the definitions of the accretive operator and the strongly accretive operator become the definitions of the monotone operator and the strongly monotone operator, respectively. For more literature on different types of operators, see [22–24].

Definition 6. Let $\tilde{A} : E \rightarrow E$ be an operator. The operator $S : E \times E \times E \rightarrow E$ is said to be:

(i) *Lipschitz continuous in the first slot, if*

$$\|S(u_1, \cdot, \cdot) - S(u_2, \cdot, \cdot)\| \leq \delta_{S_1} \|u_1 - u_2\|, \quad \forall \dot{a}, \dot{b} \in E \text{ and for some } u_1 \in \tilde{A}(\dot{a}), u_2 \in \tilde{A}(\dot{b}),$$

where $\delta_{S_1} > 0$ is a constant.

Similarly, we can obtain Lipschitz continuity of S in other slots;

(ii) *Strongly accretive in the first slot with respect to \tilde{A} , if*

$$\langle S(u_1, \cdot, \cdot) - S(u_2, \cdot, \cdot), J(\dot{a} - \dot{b}) \rangle \geq \lambda_{S_1} \|\dot{a} - \dot{b}\|^2, \quad \forall \dot{a}, \dot{b} \in E \text{ and for some } u_1 \in \tilde{A}(\dot{a}), u_2 \in \tilde{A}(\dot{b}),$$

where $\lambda_{S_1} > 0$ is a constant.

Similarly strong accretivity of S in other slots and with respect to other operators can be obtained.

Definition 7. The operator $\tilde{A} : E \rightarrow \hat{C}(E)$ is called D -Lipschitz continuous if

$$D(\tilde{A}(\dot{a}), \tilde{A}(\dot{b})) \leq \alpha_{\tilde{A}} \|\dot{a} - \dot{b}\|, \quad \forall \dot{a}, \dot{b} \in E,$$

where $\alpha_{\tilde{A}} > 0$ is a constant and $D(\cdot, \cdot)$ denotes the Hausdorff metric.

Definition 8 ([13]). Suppose that Ω is the nonempty closed convex subset of E . Then an operator $Q_\Omega : E \rightarrow \Omega$ is called:

(i) *Retraction on Ω , if $Q_\Omega^2 = Q_\Omega$;*

(ii) *Nonexpansive retraction on Ω , if it satisfies the inequality:*

$$\|Q_\Omega(\dot{a}) - Q_\Omega(\dot{b})\| \leq \|\dot{a} - \dot{b}\|, \quad \forall \dot{a}, \dot{b} \in E;$$

(iii) *Nonexpansive sunny retraction on Ω , if*

$$Q_\Omega(Q_\Omega(\dot{a}) + \hat{t}(\dot{a} - Q_\Omega(\dot{a}))) = Q_\Omega(\dot{a}),$$

for all $\dot{a} \in E$ and for $0 \leq \hat{t} < +\infty$.

Nonexpansive sunny retraction operators are characterized as follows, which can be found in [25–27].

Proposition 2. The operator Q_Ω is a nonexpansive sunny retraction, if and only if

$$\langle \dot{a} - Q_\Omega(\dot{a}), J(Q_\Omega(\dot{a}) - \dot{b}) \rangle \geq 0,$$

for all $\dot{a} \in E$ and $\dot{b} \in \Omega$.

Remark 2. If E is a Hilbert space, then operator Q_Ω is a nonexpansive sunny retraction, if and only if

$$\langle \dot{a} - Q_\Omega(\dot{a}), Q_\Omega(\dot{a}) - \dot{b} \rangle \geq 0,$$

for all $\dot{a} \in E$ and $\dot{b} \in \Omega$.

Proposition 3. Suppose $\tilde{m} = \tilde{m}(\dot{a}) : E \rightarrow E$ and $Q_\Omega : E \rightarrow \Omega$ is a nonexpansive sunny retraction. Then, for all $\dot{a} \in E$, we have

$$Q_{\Omega + \tilde{m}(\dot{a})}(\dot{a}) = \tilde{m}(\dot{a}) + Q_\Omega(\dot{a} - \tilde{m}(\dot{a})).$$

Remark 3. Let us take E to be a Hilbert space and Ω to be a nonempty closed convex subset of E . Then, an example of nonexpansive sunny retraction of E onto Ω is the nearest point projection P_Ω from E onto Ω . But this fact does not hold for all Banach spaces because, outside a Hilbert space, nearest point projections are sunny but not nonexpansive. In view of Proposition 2, it is observed that a nonexpansive retraction behaves similarly in a Banach space to how the nearest point projection behaves in a Hilbert space. Bruck [28] has shown that, for a nonexpansive retraction, there is a nonexpansive sunny retraction if the Banach space is uniformly smooth.

Definition 9. The multi-valued operator $\widehat{M} : E \rightarrow 2^E$ is called accretive, if

$$\langle u - v, J(\dot{a} - \dot{b}) \rangle \geq 0, \quad \forall \dot{a}, \dot{b} \in E \text{ and for some } u \in \widehat{M}(\dot{a}), v \in \widehat{M}(\dot{b}).$$

Definition 10. Let $h_1 : E \rightarrow E$ be an operator. The multi-valued operator $\widehat{M} : E \rightarrow 2^E$ is said to be h_1 -accretive if \widehat{M} is accretive and the range of $[h_1 + \lambda \widehat{M}]$ is E , where $\lambda > 0$ is a constant.

Definition 11. Let $\widehat{M} : E \rightarrow 2^E$ be a multi-valued operator. The operator $R_{I,\lambda}^{\widehat{M}} : E \rightarrow E$ defined by

$$R_{I,\lambda}^{\widehat{M}}(\dot{a}) = [I + \lambda \widehat{M}]^{-1}(\dot{a}), \text{ for all } \dot{a} \in E,$$

is called a classical resolvent operator, where I is the identity operator and $\lambda > 0$ is a constant.

Definition 12. We define $R_{h_1,\lambda}^{\widehat{M}} : E \rightarrow E$ such that

$$R_{h_1,\lambda}^{\widehat{M}}(\dot{a}) = [h_1 + \lambda \widehat{M}]^{-1}(\dot{a}), \quad \forall \dot{a} \in E, \text{ where } \lambda > 0 \text{ is a constant.}$$

We call it a generalized resolvent operator.

Definition 13. The classical Yosida approximation operator is defined by

$$Y_{I,\lambda}^{\widehat{M}}(\dot{a}) = \frac{1}{\lambda} [I - R_{I,\lambda}^{\widehat{M}}](\dot{a}), \text{ for all } \dot{a} \in E,$$

where I is the identity operator and $\lambda > 0$ is a constant.

Definition 14. We define $Y_{h_1,\lambda}^{\widehat{M}} : E \rightarrow E$ such that

$$Y_{h_1,\lambda}^{\widehat{M}}(\dot{a}) = \frac{1}{\lambda} [h_1 - R_{h_1,\lambda}^{\widehat{M}}](\dot{a}), \quad \forall \dot{a} \in E, \text{ where } \lambda > 0 \text{ is a constant.}$$

We call it a generalized Yosida approximation operator.

Proposition 4 ([29]). Let $h_1 : E \rightarrow E$ be r_1 -strongly accretive and $\widehat{M} : E \rightarrow 2^E$ be an h_1 -accretive multi-valued operator. Then, the operator $R_{h_1, \lambda}^{\widehat{M}} : E \rightarrow E$ satisfies the following condition:

$$\|R_{h_1, \lambda}^{\widehat{M}}(\dot{a}) - R_{h_1, \lambda}^{\widehat{M}}(\dot{b})\| \leq \frac{1}{r_1} \|\dot{a} - \dot{b}\|, \quad \forall \dot{a}, \dot{b} \in E.$$

That is, $R_{h_1, \lambda}^{\widehat{M}}$ is $\frac{1}{r_1}$ -Lipschitz continuous.

Proposition 5. If $h_1 : E \rightarrow E$ is r_1 -strongly accretive, β_{h_1} -expansive, λ_{h_1} -Lipschitz continuous operator, and $R_{h_1, \lambda}^{\widehat{M}} : E \rightarrow E$ is $\frac{1}{r_1}$ -Lipschitz continuous operator, then the operator $Y_{h_1, \lambda}^{\widehat{M}} : E \rightarrow E$ satisfies the following condition:

$$\langle Y_{h_1, \lambda}^{\widehat{M}}(\dot{a}) - Y_{h_1, \lambda}^{\widehat{M}}(\dot{b}), J(h_1(\dot{a}) - h_1(\dot{b})) \rangle \geq \delta_{Y_{h_1}} \|\dot{a} - \dot{b}\|^2, \quad \forall \dot{a}, \dot{b} \in E,$$

where $\delta_{Y_{h_1}} = \frac{\beta_{h_1}^2 r_1 - \lambda_{h_1}}{\lambda r_1}$, $\beta_{h_1}^2 r_1 > \lambda_{h_1}$, $\lambda r_1 \neq 0$ and all the constants involved are positive. That is, $Y_{h_1, \lambda}^{\widehat{M}}$ is $\delta_{Y_{h_1}}$ -strongly accretive with respect to the operator h_1 .

Proof. Since $Y_{h_1, \lambda}^{\widehat{M}} = \frac{1}{\lambda} [h_1 - R_{h_1, \lambda}^{\widehat{M}}]$, we evaluate

$$\begin{aligned} & \langle Y_{h_1, \lambda}^{\widehat{M}}(\dot{a}) - Y_{h_1, \lambda}^{\widehat{M}}(\dot{b}), J(h_1(\dot{a}) - h_1(\dot{b})) \rangle \\ &= \frac{1}{\lambda} \langle h_1(\dot{a}) - R_{h_1, \lambda}^{\widehat{M}}(\dot{a}) - [h_1(\dot{b}) - R_{h_1, \lambda}^{\widehat{M}}(\dot{b})], J(h_1(\dot{a}) - h_1(\dot{b})) \rangle \\ &= \frac{1}{\lambda} \langle h_1(\dot{a}) - h_1(\dot{b}), J(h_1(\dot{a}) - h_1(\dot{b})) \rangle \\ &\quad - \frac{1}{\lambda} \langle R_{h_1, \lambda}^{\widehat{M}}(\dot{a}) - R_{h_1, \lambda}^{\widehat{M}}(\dot{b}), J(h_1(\dot{a}) - h_1(\dot{b})) \rangle. \end{aligned}$$

Using the expansiveness of h_1 , Lipschitz continuity of h_1 , and Lipschitz continuity of the generalized resolvent operator $R_{h_1, \lambda}^{\widehat{M}}$, we obtain

$$\begin{aligned} & \langle Y_{h_1, \lambda}^{\widehat{M}}(\dot{a}) - Y_{h_1, \lambda}^{\widehat{M}}(\dot{b}), J(h_1(\dot{a}) - h_1(\dot{b})) \rangle \\ &\geq \frac{1}{\lambda} \|h_1(\dot{a}) - h_1(\dot{b})\|^2 - \frac{1}{\lambda} \|R_{h_1, \lambda}^{\widehat{M}}(\dot{a}) - R_{h_1, \lambda}^{\widehat{M}}(\dot{b})\| \|h_1(\dot{a}) - h_1(\dot{b})\| \\ &\geq \frac{1}{\lambda} \|h_1(\dot{a}) - h_1(\dot{b})\|^2 - \frac{1}{\lambda} \frac{1}{r_1} \|\dot{a} - \dot{b}\| \|h_1(\dot{a}) - h_1(\dot{b})\| \\ &\geq \frac{1}{\lambda} \beta_{h_1}^2 \|\dot{a} - \dot{b}\|^2 - \frac{1}{\lambda} \frac{1}{r_1} \lambda_{h_1} \|\dot{a} - \dot{b}\| \|\dot{a} - \dot{b}\| \\ &\geq \frac{\beta_{h_1}^2}{\lambda} \|\dot{a} - \dot{b}\|^2 - \frac{\lambda_{h_1}}{\lambda r_1} \|\dot{a} - \dot{b}\|^2 \\ &\geq \frac{\beta_{h_1}^2 r_1 - \lambda_{h_1}}{\lambda r_1} \|\dot{a} - \dot{b}\|^2 \\ &= \delta_{Y_{h_1}} \|\dot{a} - \dot{b}\|^2. \end{aligned}$$

That is,

$$\langle Y_{h_1, \lambda}^{\widehat{M}}(\dot{a}) - Y_{h_1, \lambda}^{\widehat{M}}(\dot{b}), J(h_1(\dot{a}) - h_1(\dot{b})) \rangle \geq \delta_{Y_{h_1}} \|\dot{a} - \dot{b}\|^2.$$

That is, $Y_{h_1, \lambda}^{\widehat{M}}$ is $\delta_{Y_{h_1}}$ -strongly accretive with respect to h_1 . \square

Proposition 6. Let $h_1 : E \rightarrow E$ be λ_{h_1} -Lipschitz continuous, r_1 -strongly accretive operator and $R_{h_1, \lambda}^{\hat{M}} : E \rightarrow E$ is $\frac{1}{r_1}$ -Lipschitz continuous operator, then the operator $Y_{h_1, \lambda}^{\hat{M}} : E \rightarrow E$ satisfies the following condition:

$$\left\| Y_{h_1, \lambda}^{\hat{M}}(\dot{a}) - Y_{h_1, \lambda}^{\hat{M}}(\dot{b}) \right\| \leq \lambda_{Y_{h_1}} \|\dot{a} - \dot{b}\|, \quad \forall \dot{a}, \dot{b} \in E,$$

where $\lambda_{Y_{h_1}} = \frac{\lambda_{h_1} r_1 + 1}{\lambda r_1}$, $\lambda r_1 \neq 0$. That is, $Y_{h_1, \lambda}^{\hat{M}}$ is $\lambda_{Y_{h_1}}$ -Lipschitz continuous.

Proof. Since h_1 and the generalized resolvent operator $R_{h_1, \lambda}^{\hat{M}}$ are Lipschitz continuous, we obtain

$$\begin{aligned} \left\| Y_{h_1, \lambda}^{\hat{M}}(\dot{a}) - Y_{h_1, \lambda}^{\hat{M}}(\dot{b}) \right\| &= \left\| \frac{1}{\lambda} \left[h_1(\dot{a}) - R_{h_1, \lambda}^{\hat{M}}(\dot{a}) \right] - \frac{1}{\lambda} \left[h_1(\dot{b}) - R_{h_1, \lambda}^{\hat{M}}(\dot{b}) \right] \right\| \\ &= \frac{1}{\lambda} \|h_1(\dot{a}) - h_1(\dot{b})\| + \frac{1}{\lambda} \|R_{h_1, \lambda}^{\hat{M}}(\dot{a}) - R_{h_1, \lambda}^{\hat{M}}(\dot{b})\| \\ &\leq \frac{1}{\lambda} \lambda_{h_1} \|\dot{a} - \dot{b}\| + \frac{1}{\lambda} \frac{1}{r_1} \|\dot{a} - \dot{b}\| \\ &= \left(\frac{\lambda_{h_1} r_1 + 1}{\lambda r_1} \right) \|\dot{a} - \dot{b}\| \\ &= \lambda_{Y_{h_1}} \|\dot{a} - \dot{b}\|. \end{aligned}$$

That is,

$$\left\| Y_{h_1, \lambda}^{\hat{M}}(\dot{a}) - Y_{h_1, \lambda}^{\hat{M}}(\dot{b}) \right\| \leq \lambda_{Y_{h_1}} \|\dot{a} - \dot{b}\|, \quad \forall \dot{a}, \dot{b} \in E.$$

Thus, the operator $Y_{h_1, \lambda}^{\hat{M}}$ is $\lambda_{Y_{h_1}}$ -Lipschitz continuous. \square

3. Problem Formation and Iterative Method

Suppose $S : E \times E \times E \rightarrow E$ is a nonlinear operator, $\tilde{A}, \tilde{B}, \tilde{C} : E \rightarrow \hat{C}(E)$ are multi-valued operators, and $\tilde{K} : E \rightarrow 2^E$ is a multi-valued operator such that $\tilde{K}(\dot{a})$ is a nonempty, closed, and convex set for all $\dot{a} \in E$. Let $h_1, h_2 : E \rightarrow E$ be the single-valued operators, $\hat{M} : E \rightarrow 2^E$ be an h_1 -accretive multi-valued operator and $\hat{N} : E \rightarrow 2^E$ be an h_2 -accretive multi-valued operator, $Y_{h_1, \lambda}^{\hat{M}} : E \rightarrow E$ and $Y_{h_2, \lambda}^{\hat{N}} : E \rightarrow E$ be the generalized Yosida approximation operators, where $\lambda > 0$ is a constant.

We consider the problem of finding $\dot{a} \in E$, $u \in \tilde{A}(\dot{a})$, $v \in \tilde{B}(\dot{a})$, and $w \in \tilde{C}(\dot{a})$ such that

$$\left\langle Y_{h_1, \lambda}^{\hat{M}}(\dot{a}) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a}), J(S(u, v, w)) \right\rangle \geq 0, \quad \forall S(u, v, w) \in \tilde{K}(\dot{a}). \quad (1)$$

We call problem (1) a co-variational inequality problem involving two generalized Yosida approximation operators.

Clearly for problem (1), it is easily accessible to obtain co-variational inequalities studied by Alber and Yao [13] and Ahmad and Irfan [14].

We provide few characterizations of a solution of problem (1).

Theorem 1. Let $\tilde{A}, \tilde{B}, \tilde{C} : E \rightarrow \hat{C}(E)$ be the multi-valued operators, $S : E \times E \times E \rightarrow E$ be the nonlinear operator, and $\tilde{K} : E \rightarrow 2^E$ be a multi-valued operator such that $\tilde{K}(\dot{a})$ is a nonempty, closed, and convex set for all $\dot{a} \in E$. Let $h_1, h_2 : E \rightarrow E$ be the single-valued operators, $\hat{M} : E \rightarrow 2^E$ be the h_1 -accretive multi-valued operator, and $\hat{N} : E \rightarrow 2^E$ be the h_2 -accretive multi-valued operator, $Y_{h_1, \lambda}^{\hat{M}} : E \rightarrow E$ and $Y_{h_2, \lambda}^{\hat{N}} : E \rightarrow E$ be the generalized Yosida approximation operators, where $\lambda > 0$ is a constant. Then, the following assertions are similar:

- (i) $\dot{a} \in E, u \in \tilde{A}(\dot{a}), v \in \tilde{B}(\dot{a}), w \in \tilde{C}(\dot{a})$ constitute the solution of problem (1);
- (ii) $\dot{a} \in E, u \in \tilde{A}(\dot{a}), v \in \tilde{B}(\dot{a}), w \in \tilde{C}(\dot{a})$ such that

$$S(u, v, w) = Q_{\tilde{K}(\dot{a})}[S(u, v, w) - \lambda(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a}))].$$

Proof. For proof, see [7,21]. \square

Combining Proposition 3 and Theorem 1, we obtain the theorem mentioned below.

Theorem 2. Suppose all the conditions of Theorem 1 are fulfilled and, additionally, $\tilde{K}(\dot{a}) = \tilde{m}(\dot{a}) + F$, for all $\dot{a} \in E$, where F is a nonempty closed convex subset of E and $Q_F : E \rightarrow F$ is a nonexpansive sunny retraction. Then, $\dot{a} \in E, u \in \tilde{A}(\dot{a}), v \in \tilde{B}(\dot{a}),$ and $w \in \tilde{C}(\dot{a})$ constitute the solution of problem (1), if and only if

$$\dot{a} = \dot{a} + \tilde{m}(\dot{a}) - S(u, v, w) + Q_F[S(u, v, w) - \lambda(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a})) - \tilde{m}(\dot{a})], \quad (2)$$

where $\lambda > 0$ is a constant.

Using Theorem 2, we construct the following iterative method.

Iterative Method 1. For initial points $\dot{a}_0 \in E, u_0 \in \tilde{A}(\dot{a}_0), v_0 \in \tilde{B}(\dot{a}_0), w_0 \in \tilde{C}(\dot{a}_0)$, let

$$\dot{a}_1 = \dot{a}_0 + \tilde{m}(\dot{a}_0) - S(u_0, v_0, w_0) + Q_F[S(u_0, v_0, w_0) - \lambda(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_0) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a}_0)) - \tilde{m}(\dot{a}_0)].$$

Since $\tilde{A}(\dot{a}_0), \tilde{B}(\dot{a}_0),$ and $\tilde{C}(\dot{a}_0)$ are nonempty convex sets, by Nadler [30], there exists $u_1 \in \tilde{A}(\dot{a}_1), v_1 \in \tilde{B}(\dot{a}_1),$ and $w_1 \in \tilde{C}(\dot{a}_1)$ such that

$$\begin{aligned} \|u_1 - u_0\| &\leq D(\tilde{A}(\dot{a}_1), \tilde{A}(\dot{a}_0)), \\ \|v_1 - v_0\| &\leq D(\tilde{B}(\dot{a}_1), \tilde{B}(\dot{a}_0)), \\ \text{and } \|w_1 - w_0\| &\leq D(\tilde{C}(\dot{a}_1), \tilde{C}(\dot{a}_0)), \end{aligned}$$

where $D(\cdot, \cdot)$ denotes the Hausdorff metric.

Proceeding in a similar manner, we can find the sequences $\{\dot{a}_n\}, \{u_n\}, \{v_n\}$ and $\{w_n\}$ using the following method:

$$\dot{a}_{n+1} = \dot{a}_n + \tilde{m}(\dot{a}_n) - S(u_n, v_n, w_n) + Q_F[S(u_n, v_n, w_n) - \lambda(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a}_n)) - \tilde{m}(\dot{a}_n)], \quad (3)$$

$$u_n \in \tilde{A}(\dot{a}_n), \|u_{n+1} - u_n\| \leq D(\tilde{A}(\dot{a}_{n+1}), \tilde{A}(\dot{a}_n)), \quad (4)$$

$$v_n \in \tilde{B}(\dot{a}_n), \|v_{n+1} - v_n\| \leq D(\tilde{B}(\dot{a}_{n+1}), \tilde{B}(\dot{a}_n)), \quad (5)$$

$$w_n \in \tilde{C}(\dot{a}_n), \|w_{n+1} - w_n\| \leq D(\tilde{C}(\dot{a}_{n+1}), \tilde{C}(\dot{a}_n)), \quad (6)$$

for $n = 0, 1, 2, 3, \dots$, where $\lambda > 0$ is a constant.

4. Convergence Result

Theorem 3. Suppose E is real uniformly smooth Banach space and $\rho_E(t) \leq Ct^2$, for some $C > 0$, is the modulus of smoothness. Suppose F is a closed convex subset of $E, S(\cdot, \cdot, \cdot) : E \times E \times E \rightarrow E$ is an operator, $\tilde{A}, \tilde{B}, \tilde{C} : E \rightarrow \tilde{C}(E)$ are the multi-valued operators, $\tilde{m} : E \rightarrow E$ is an operator. Let $Q_F : E \rightarrow F$ be a nonexpansive sunny retraction operator and $\tilde{K} : E \rightarrow 2^E$ be a multi-valued operator such that $\tilde{K}(\dot{a}) = \tilde{m}(\dot{a}) + F$, for all $\dot{a} \in E$. Let $\hat{M}, \hat{N} : E \rightarrow 2^E$ be the multi-valued operators, and $h_1, h_2 : E \rightarrow E$ be the operators. Let $Y_{h_1, \lambda}^{\hat{M}}$ be the generalized Yosida approximation operator associated with the generalized resolvent operator $R_{h_1, \lambda}^{\hat{M}}$ and $Y_{h_2, \lambda}^{\hat{N}}$ be the generalized Yosida approximation operator associated with the generalized resolvent operator $R_{h_2, \lambda}^{\hat{N}}$. Suppose that the following assertions are satisfied:

- (i) $S(\cdot, \cdot, \cdot)$ is λ_{S_1} -strongly accretive with respect to \tilde{A} in the first slot, λ_{S_2} -strongly accretive with respect to \tilde{B} in the second slot, λ_{S_3} -strongly accretive with respect to \tilde{C} in the third slot

- and δ_{S_1} -Lipschitz continuous in the first slot, δ_{S_2} -Lipschitz continuous in the second slot, δ_{S_3} -Lipschitz continuous in the third slot;
- (ii) \tilde{A} is $\alpha_{\tilde{A}}$ -D-Lipschitz continuous, \tilde{B} is $\alpha_{\tilde{B}}$ -D-Lipschitz continuous and \tilde{C} is $\alpha_{\tilde{C}}$ -D-Lipschitz continuous;
- (iii) \tilde{m} is λ_m -Lipschitz continuous;
- (iv) h_1 is r_1 -strongly accretive, β_{h_1} -expansive and λ_{h_1} -Lipschitz continuous; h_2 is r_2 -strongly accretive, β_{h_2} -expansive, and λ_{h_2} -Lipschitz continuous;
- (v) $R_{h_1, \lambda}^{\hat{M}}$ is $\frac{1}{r_1}$ -Lipschitz continuous and $R_{h_2, \lambda}^{\hat{N}}$ is $\frac{1}{r_2}$ -Lipschitz continuous;
- (vi) $Y_{h_1, \lambda}^{\hat{M}}$ is $\delta_{Y_{h_1}}$ -strongly accretive, $\lambda_{Y_{h_1}}$ -Lipschitz continuous and $Y_{h_2, \lambda}^{\hat{N}}$ is $\delta_{Y_{h_2}}$ -strongly accretive, $\lambda_{Y_{h_2}}$ -Lipschitz continuous;
- (vii) Suppose that

$$0 < \left[\sqrt{\left[(1 - 2(\lambda_{S_1} + \lambda_{S_2} + \lambda_{S_3})) + 64C(\delta_{S_1}^2 \alpha_{\tilde{A}}^2 + \delta_{S_2}^2 \alpha_{\tilde{B}}^2 + \delta_{S_3}^2 \alpha_{\tilde{C}}^2) \right]} \right. \\ \left. + 2\lambda_m + (\delta_{S_1} \alpha_{\tilde{A}} + \delta_{S_2} \alpha_{\tilde{B}} + \delta_{S_3} \alpha_{\tilde{C}}) + \sqrt{1 - 2\lambda \delta_{Y_{h_1}} + 64C\lambda^4 \lambda_{Y_{h_1}}^2} \right. \\ \left. + \sqrt{1 - 2\lambda \delta_{Y_{h_2}} + 64C\lambda^4 \lambda_{Y_{h_2}}^2} \right] < 1,$$

where

$$\delta_{Y_{h_1}} = \frac{\beta_{h_1}^2 r_1 - \lambda_{h_1}}{\lambda r_1}, \quad \delta_{Y_{h_2}} = \frac{\beta_{h_2}^2 r_2 - \lambda_{h_2}}{\lambda r_2}, \\ \lambda_{Y_{h_1}} = \frac{\lambda_{h_1} r_1 + 1}{\lambda r_1}, \quad \lambda_{Y_{h_2}} = \frac{\lambda_{h_2} r_2 + 1}{\lambda r_2}, \\ \beta_{h_1}^2 r_1 > \lambda_{h_1} \quad \text{and} \quad \beta_{h_2}^2 r_2 > \lambda_{h_2}.$$

Then, there exist $\dot{a} \in E, u \in \tilde{A}(\dot{a}), v \in \tilde{B}(\dot{a})$ and $w \in \tilde{C}(\dot{a})$, the solution of problem (1). Also, sequences $\{\dot{a}_n\}, \{u_n\}, \{v_n\}$ and $\{w_n\}$ converge strongly to \dot{a}, u, v and w , respectively.

Proof. Using (3) of iterative method 1 and the nonexpansive retraction property of Q_F , we estimate

$$\begin{aligned} \|\dot{a}_{n+1} - \dot{a}_n\| &= \left\| \left[\dot{a}_n + \tilde{m}(\dot{a}_n) - S(u_n, v_n, w_n) + Q_F[S(u_n, v_n, w_n) \right. \right. \\ &\quad \left. \left. - \lambda \left(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a}_n) \right) - \tilde{m}(\dot{a}_n) \right] \right. \\ &\quad \left. - \left[\dot{a}_{n-1} + \tilde{m}(\dot{a}_{n-1}) - S(u_{n-1}, v_{n-1}, w_{n-1}) + Q_F[S(u_{n-1}, v_{n-1}, w_{n-1}) \right. \right. \\ &\quad \left. \left. - \lambda \left(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1}) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a}_{n-1}) \right) - \tilde{m}(\dot{a}_{n-1}) \right] \right\| \\ &\leq \|\dot{a}_n - \dot{a}_{n-1} - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))\| + \|\tilde{m}(\dot{a}_n) - \tilde{m}(\dot{a}_{n-1})\| \\ &\quad + \|Q_F[S(u_n, v_n, w_n) - \lambda \left(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a}_n) \right) - \tilde{m}(\dot{a}_n)] \\ &\quad - Q_F[S(u_{n-1}, v_{n-1}, w_{n-1}) - \lambda \left(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1}) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a}_{n-1}) \right) - \tilde{m}(\dot{a}_{n-1})]\| \\ &\leq \|\dot{a}_n - \dot{a}_{n-1} - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))\| \\ &\quad + 2\|\tilde{m}(\dot{a}_n) - \tilde{m}(\dot{a}_{n-1})\| + \|S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1})\| \\ &\quad + \|\dot{a}_n - \dot{a}_{n-1} - \lambda \left(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1}) \right)\| \end{aligned}$$

$$+\|\dot{a}_n - \dot{a}_{n-1} - \lambda \left(Y_{h_2, \lambda}^{\hat{N}}(\dot{a}_n) - Y_{h_2, \lambda}^{\hat{N}}(\dot{a}_{n-1}) \right)\|. \quad (7)$$

Applying Proposition 1, we evaluate

$$\begin{aligned} & \|\dot{a}_n - \dot{a}_{n-1} - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))\|^2 \\ & \leq \|\dot{a}_n - \dot{a}_{n-1}\|^2 \\ & \quad - 2\langle S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), J(\dot{a}_n - \dot{a}_{n-1} - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))) \rangle \\ & = \|\dot{a}_n - \dot{a}_{n-1}\|^2 - 2\langle S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\ & \quad - 2\langle S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), \\ & \quad \quad J(\dot{a}_n - \dot{a}_{n-1} - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))) - J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\ & = \|\dot{a}_n - \dot{a}_{n-1}\|^2 - 2\langle S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\ & \quad + S(u_{n-1}, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_n) + S(u_{n-1}, v_{n-1}, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\ & \quad - 2\langle S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), J(\dot{a}_n - \dot{a}_{n-1} \\ & \quad \quad - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))) - J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\ & = \|\dot{a}_n - \dot{a}_{n-1}\|^2 - 2\langle S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\ & \quad - 2\langle S(u_{n-1}, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_n), J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\ & \quad - 2\langle S(u_{n-1}, v_{n-1}, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\ & \quad - 2\langle S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), \\ & \quad \quad J(\dot{a}_n - \dot{a}_{n-1} - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))) - J(\dot{a}_n - \dot{a}_{n-1}) \rangle. \end{aligned} \quad (8)$$

Since $S(\cdot, \cdot, \cdot)$ is λ_{S_1} -strongly accretive with respect to \tilde{A} in the first slot, λ_{S_2} -strongly accretive with respect to \tilde{B} in the second slot, λ_{S_3} -strongly accretive with respect to \tilde{C} in the third slot and applying (ii) of Proposition 1, (8) becomes

$$\begin{aligned} & \|(\dot{a}_n - \dot{a}_{n-1}) - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))\|^2 \\ & \leq \|\dot{a}_n - \dot{a}_{n-1}\|^2 - 2(\lambda_{S_1} + \lambda_{S_2} + \lambda_{S_3})\|\dot{a}_n - \dot{a}_{n-1}\|^2 \\ & \quad - 2\langle S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}), \\ & \quad \quad J(\dot{a}_n - \dot{a}_{n-1} - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))) - J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\ & \leq (1 - 2(\lambda_{S_1} + \lambda_{S_2} + \lambda_{S_3}))\|\dot{a}_n - \dot{a}_{n-1}\|^2 \\ & \quad + 4d^2\rho_E \left(\frac{4\|S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1})\|}{d} \right). \end{aligned} \quad (9)$$

As $S(\cdot, \cdot, \cdot)$ is δ_{S_1} -Lipschitz continuous in the first slot, δ_{S_2} -Lipschitz continuous in the second slot, δ_{S_3} -Lipschitz continuous in the third slot, and \tilde{A} is $\alpha_{\tilde{A}}$ -D-Lipschitz continuous, \tilde{B} is $\alpha_{\tilde{B}}$ -D-Lipschitz continuous, and \tilde{C} is $\alpha_{\tilde{C}}$ -D-Lipschitz continuous, we have

$$\begin{aligned} & \|S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1})\| \\ & = \|S(u_n, v_n, w_n) - S(u_{n-1}, v_n, w_n) + S(u_{n-1}, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_n) \\ & \quad + S(u_{n-1}, v_{n-1}, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1})\| \\ & \leq \delta_{S_1}\|u_n - u_{n-1}\| + \delta_{S_2}\|v_n - v_{n-1}\| + \delta_{S_3}\|w_n - w_{n-1}\| \\ & \leq \delta_{S_1}D(\tilde{A}(\dot{a}_n), \tilde{A}(\dot{a}_{n-1})) + \delta_{S_2}D(\tilde{B}(\dot{a}_n), \tilde{B}(\dot{a}_{n-1})) + \delta_{S_3}D(\tilde{C}(\dot{a}_n), \tilde{C}(\dot{a}_{n-1})) \\ & \leq \delta_{S_1}\alpha_{\tilde{A}}\|\dot{a}_n - \dot{a}_{n-1}\| + \delta_{S_2}\alpha_{\tilde{B}}\|\dot{a}_n - \dot{a}_{n-1}\| + \delta_{S_3}\alpha_{\tilde{C}}\|\dot{a}_n - \dot{a}_{n-1}\| \\ & \leq (\delta_{S_1}\alpha_{\tilde{A}} + \delta_{S_2}\alpha_{\tilde{B}} + \delta_{S_3}\alpha_{\tilde{C}})\|\dot{a}_n - \dot{a}_{n-1}\|. \end{aligned} \quad (10)$$

Using Equation (10) and (ii) of Proposition 1, we evaluate

$$4d^2\rho_E \left(\frac{4\|S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1})\|}{d} \right)$$

$$\begin{aligned}
&= 4d^2\rho_E \left(\frac{4}{d} (\|S(u_n, v_n, w_n) - S(u_{n-1}, v_n, w_n) + S(u_{n-1}, v_n, w_n) \right. \\
&\quad \left. - S(u_{n-1}, v_{n-1}, w_n) + S(u_{n-1}, v_{n-1}, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1})\|) \right) \\
&\leq 64C \left(\|S(u_n, v_n, w_n) - S(u_{n-1}, v_n, w_n)\|^2 + \|S(u_{n-1}, v_n, w_n) \right. \\
&\quad \left. - S(u_{n-1}, v_{n-1}, w_n)\|^2 + \|S(u_{n-1}, v_{n-1}, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1})\|^2 \right) \\
&\leq 64C(\delta_{S_1}^2 \|u_n - u_{n-1}\|^2 + \delta_{S_2}^2 \|v_n - v_{n-1}\|^2 + \delta_{S_3}^2 \|w_n - w_{n-1}\|^2) \\
&\leq 64C(\delta_{S_1}^2 D^2(\tilde{A}(\dot{a}_n), \tilde{A}(\dot{a}_{n-1})) + \delta_{S_2}^2 D^2(\tilde{B}(\dot{a}_n), \tilde{B}(\dot{a}_{n-1})) + \delta_{S_3}^2 D^2(\tilde{C}(\dot{a}_n), \tilde{C}(\dot{a}_{n-1}))) \\
&\leq 64C(\delta_{S_1}^2 \alpha_{\tilde{A}}^2 \|\dot{a}_n - \dot{a}_{n-1}\|^2 + \delta_{S_2}^2 \alpha_{\tilde{B}}^2 \|\dot{a}_n - \dot{a}_{n-1}\|^2 + \delta_{S_3}^2 \alpha_{\tilde{C}}^2 \|\dot{a}_n - \dot{a}_{n-1}\|^2) \\
&= 64C(\delta_{S_1}^2 \alpha_{\tilde{A}}^2 + \delta_{S_2}^2 \alpha_{\tilde{B}}^2 + \delta_{S_3}^2 \alpha_{\tilde{C}}^2) \|\dot{a}_n - \dot{a}_{n-1}\|^2. \tag{11}
\end{aligned}$$

Combining (9) and (11), we have

$$\begin{aligned}
\|(\dot{a}_n - \dot{a}_{n-1}) - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))\|^2 &\leq \left[(1 - 2(\lambda_{S_1} + \lambda_{S_2} + \lambda_{S_3})) \right. \\
&\quad \left. + 64C(\delta_{S_1}^2 \alpha_{\tilde{A}}^2 + \delta_{S_2}^2 \alpha_{\tilde{B}}^2 + \delta_{S_3}^2 \alpha_{\tilde{C}}^2) \right] \|\dot{a}_n - \dot{a}_{n-1}\|^2,
\end{aligned}$$

which implies that

$$\begin{aligned}
&\|(\dot{a}_n - \dot{a}_{n-1}) - (S(u_n, v_n, w_n) - S(u_{n-1}, v_{n-1}, w_{n-1}))\| \\
&\leq \sqrt{\left[(1 - 2(\lambda_{S_1} + \lambda_{S_2} + \lambda_{S_3})) + 64C(\delta_{S_1}^2 \alpha_{\tilde{A}}^2 + \delta_{S_2}^2 \alpha_{\tilde{B}}^2 + \delta_{S_3}^2 \alpha_{\tilde{C}}^2) \right]} \|\dot{a}_n - \dot{a}_{n-1}\|. \tag{12}
\end{aligned}$$

Since \tilde{m} is λ_m -Lipschitz continuous, we have

$$\|\tilde{m}(\dot{a}_n) - \tilde{m}(\dot{a}_{n-1})\| \leq \lambda_m \|\dot{a}_n - \dot{a}_{n-1}\|. \tag{13}$$

As Yosida approximation operator $Y_{h_1, \lambda}^{\hat{M}}$ is $\delta_{Y_{h_1}}$ -strongly accretive, $\lambda_{Y_{h_1}}$ -Lipschitz continuous, and applying Proposition 1, we evaluate

$$\begin{aligned}
&\left\| (\dot{a}_n - \dot{a}_{n-1}) - \lambda \left(Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1}) \right) \right\|^2 \\
&\leq \|\dot{a}_n - \dot{a}_{n-1}\|^2 - 2\lambda \left\langle Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1}), J(\dot{a}_n - \dot{a}_{n-1} - \lambda (Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1}))) \right\rangle \\
&= \|\dot{a}_n - \dot{a}_{n-1}\|^2 - 2\lambda \langle Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1}), J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\
&\quad - 2\lambda \langle Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1}), J(\dot{a}_n - \dot{a}_{n-1} - (Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1}))) - J(\dot{a}_n - \dot{a}_{n-1}) \rangle \\
&\leq \|\dot{a}_n - \dot{a}_{n-1}\|^2 - 2\lambda \delta_{Y_{h_1}} \|\dot{a}_n - \dot{a}_{n-1}\|^2 + 4d^2\rho_E \left(\frac{4\lambda^2 \|Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1})\|}{d} \right) \\
&= \|\dot{a}_n - \dot{a}_{n-1}\|^2 - 2\lambda \delta_{Y_{h_1}} \|\dot{a}_n - \dot{a}_{n-1}\|^2 + 64C\lambda^4 \|Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1, \lambda}^{\hat{M}}(\dot{a}_{n-1})\|^2 \\
&= \|\dot{a}_n - \dot{a}_{n-1}\|^2 - 2\lambda \delta_{Y_{h_1}} \|\dot{a}_n - \dot{a}_{n-1}\|^2 + 64C\lambda^4 \lambda_{Y_{h_1}}^2 \|\dot{a}_n - \dot{a}_{n-1}\|^2
\end{aligned}$$

$$= (1 - 2\lambda\delta_{Y_{h_1}} + 64C\lambda^4\lambda_{Y_{h_1}}^2)\|\dot{a}_n - \dot{a}_{n-1}\|^2,$$

that is,

$$\|(\dot{a}_n - \dot{a}_{n-1}) - \lambda(Y_{h_1,\lambda}^{\hat{M}}(\dot{a}_n) - Y_{h_1,\lambda}^{\hat{M}}(\dot{a}_{n-1}))\| \leq \sqrt{1 - 2\lambda\delta_{Y_{h_1}} + 64C\lambda^4\lambda_{Y_{h_1}}^2}\|\dot{a}_n - \dot{a}_{n-1}\|. \quad (14)$$

Using the same arguments as for (14), we have

$$\|(\dot{a}_n - \dot{a}_{n-1}) - \lambda(Y_{h_2,\lambda}^{\hat{N}}(\dot{a}_n) - Y_{h_2,\lambda}^{\hat{N}}(\dot{a}_{n-1}))\| \leq \sqrt{1 - 2\lambda\delta_{Y_{h_2}} + 64C\lambda^4\lambda_{Y_{h_2}}^2}\|\dot{a}_n - \dot{a}_{n-1}\|. \quad (15)$$

Using (7), (10) and (12)–(15) becomes

$$\begin{aligned} \|\dot{a}_{n+1} - \dot{a}_n\| &\leq \sqrt{\left[(1 - 2(\lambda_{S_1} + \lambda_{S_2} + \lambda_{S_3})) + 64C(\delta_{S_1}^2\alpha_{\tilde{A}}^2 + \delta_{S_2}^2\alpha_{\tilde{B}}^2 + \delta_{S_3}^2\alpha_{\tilde{C}}^2)\right]}\|\dot{a}_n - \dot{a}_{n-1}\| \\ &\quad + 2\lambda_m\|\dot{a}_n - \dot{a}_{n-1}\| + (\delta_{S_1}\alpha_{\tilde{A}} + \delta_{S_2}\alpha_{\tilde{B}} + \delta_{S_3}\alpha_{\tilde{C}})\|\dot{a}_n - \dot{a}_{n-1}\| \\ &\quad + \sqrt{1 - 2\lambda\delta_{Y_{h_1}} + 64C\lambda^4\lambda_{Y_{h_1}}^2}\|\dot{a}_n - \dot{a}_{n-1}\| \\ &\quad + \sqrt{1 - 2\lambda\delta_{Y_{h_2}} + 64C\lambda^4\lambda_{Y_{h_2}}^2}\|\dot{a}_n - \dot{a}_{n-1}\| \\ &= \theta\|\dot{a}_n - \dot{a}_{n-1}\|, \end{aligned} \quad (16)$$

$$\begin{aligned} \text{where } \theta &= \sqrt{\left[(1 - 2(\lambda_{S_1} + \lambda_{S_2} + \lambda_{S_3})) + 64C(\delta_{S_1}^2\alpha_{\tilde{A}}^2 + \delta_{S_2}^2\alpha_{\tilde{B}}^2 + \delta_{S_3}^2\alpha_{\tilde{C}}^2)\right]} \\ &\quad + 2\lambda_m + (\delta_{S_1}\alpha_{\tilde{A}} + \delta_{S_2}\alpha_{\tilde{B}} + \delta_{S_3}\alpha_{\tilde{C}}) + \sqrt{1 - 2\lambda\delta_{Y_{h_1}} + 64C\lambda^4\lambda_{Y_{h_1}}^2} \\ &\quad + \sqrt{1 - 2\lambda\delta_{Y_{h_2}} + 64C\lambda^4\lambda_{Y_{h_2}}^2}. \end{aligned} \quad (17)$$

In view of the assumption (vii), $0 < \theta < 1$ and clearly $\{\dot{a}_n\}$ is a Cauchy sequence in E such that $\dot{a}_n \rightarrow \dot{a} \in E$. Using (4)–(6) of iterative method 1, D -Lipschitz continuity of \tilde{A} , \tilde{B} , \tilde{C} and the techniques of Ahmad and Irfan [14], it is clear that $\{u_n\}$, $\{v_n\}$ and $\{w_n\}$ are all Cauchy sequences in E . Thus, $u_n \rightarrow u \in E$, $v_n \rightarrow v \in E$ and $w_n \rightarrow w \in E$. Since $Q_F, S(\cdot, \cdot, \cdot)$, $\tilde{A}, \tilde{B}, \tilde{C}, h_1, h_2, \hat{M}, N, Y_{h_1,\lambda}^{\hat{M}}$ and $Y_{h_2,\lambda}^{\hat{N}}$ are all continuous operators in E , we have

$$\dot{a} = \dot{a} + \tilde{m}(\dot{a}) - S(u, v, w) + Q_F[S(u, v, w) - \lambda(Y_{h_1,\lambda}^{\hat{M}}(\dot{a}) - Y_{h_2,\lambda}^{\hat{N}}(\dot{a}))].$$

It remains to be shown that $u \in \tilde{A}(\dot{a})$, $v \in \tilde{B}(\dot{a})$ and $w_n \rightarrow w \in \tilde{C}(\dot{a})$. In fact,

$$\begin{aligned} d(u, \tilde{A}(\dot{a})) &= \inf\{\|u - h\| : h \in \tilde{A}(\dot{a})\} \\ &\leq \|u - u_n\| + d(u_n, \tilde{A}(\dot{a})) \\ &\leq \|u - u_n\| + D(\tilde{A}(\dot{a}_n), \tilde{A}(\dot{a})) \\ &\leq \|u - u_n\| + \alpha_{\tilde{A}}\|\dot{a}_n - \dot{a}\| \rightarrow 0. \end{aligned}$$

Hence, $d(u, \tilde{A}(\dot{a})) = 0$ and thus $u \in \tilde{A}(\dot{a})$. Similarly, we have $v \in \tilde{B}(\dot{a})$ and $w \in \tilde{C}(\dot{a})$. From Theorem 2, the result follows. \square

5. Conclusions

In this work, we consider a different version of co-variational inequalities existing in the available literature. We call it the co-variational inequality problem, which involves two generalized Yosida approximation operators depending on different generalized resolvent operators. Some properties of generalized Yosida approximation operators are proved. Us-

ing the concept of nonexpansive sunny retraction, we prove an existence and convergence result for problem (1).

Our results may be used for further generalizations and experimental purposes.

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