



Article

A New Approach to Multiroot Vectorial Problems: Highly Efficient Parallel Computing Schemes

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Abstract: In this article, we construct an efficient family of simultaneous methods for finding all the distinct as well as multiple roots of polynomial equations. Convergence analysis proves that the order of convergence of newly constructed family of simultaneous methods is seventeen. Fractal-based simultaneous iterative algorithms are thoroughly examined. Using self-similar features, fractal-based simultaneous schemes can converge to solutions faster, saving computational time and resources necessary for solving nonlinear equations. Fractals analysis illustrates the newly developed method's global convergence behavior when compared to single root-finding procedures for solving fractional order polynomials that arise in complex engineering applications. Some real problems from various branches of engineering along with some higher degree polynomials are considered as test examples to show the global convergence property of simultaneous methods, performance and efficiency of the proposed family of methods. Further computational efficiencies, CPU time and residual graphs are also drawn to validate the efficiency, robustness of the newly introduced family of methods as compared to the existing methods in the literature.

Keywords: parallel scheme; fractal analysis; local convergence; dynamical analysis; error graph



Citation: Shams, M.; Rafiq, N.; Carpentieri, B.; Ahmad Mir, N. A New Approach to Multiroot Vectorial Problems: Highly Efficient Parallel Computing Schemes. *Fractal Fract.* **2024**, *8*, 162. <https://doi.org/10.3390/fractalfract8030162>

Academic Editors: Christoph Bandt and Riccardo Caponetto

Received: 1 December 2023

Revised: 8 February 2024

Accepted: 22 February 2024

Published: 12 March 2024



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1. Introduction

Consider nonlinear polynomial equation of degree m

$$f(\zeta) = \prod_{i=1}^n (\zeta - \zeta_i)^{\sigma_i} \quad (1)$$

with multiple real or complex exact roots $\zeta_1, \dots, \zeta_n$ of respective unknown multiplicities $\sigma_1, \dots, \sigma_n$ ($\sigma_1 + \dots + \sigma_n = m$). Generally, the multiplicity of roots is not given in advance. However, researchers are working on numerical methods which approximate the unknown multiplicity of roots; see, e.g., [1–7]. To solve (1), is one of the primal problems of sciences in general and in applied and computational mathematics, in particular. Nonlinear equations play a crucial role in providing more realistic and precise descriptions of phenomena, enabling scientists and engineers to understand, simulate, and predict the behavior of diverse systems. From the microscopic world of quantum mechanics to the macroscopic scale of climate modeling, nonlinear equations serve as the foundation for capturing the dynamic and non-trivial relationships that characterize the behavior of materials, physical processes, and complex systems. Their application extends to optimization problems [8], signal processing [9], and the modeling of population dynamics [10], emphasizing their pervasive role in advancing our understanding and facilitating the design and optimization of systems in science and engineering [11,12]. In essence, the importance of nonlinear equations lies in their ability to bridge the gap between theoretical models and the intricate realities of the natural and engineered world, providing a powerful tool for analysis, simulation,

and innovation. The numerical iterative methods which approximate the roots of (1) may be classified into two main groups: iterative methods which estimate one root at a time; see, e.g., Chicharro et al. [13], Kung and Trub [14], King et al. [15], Cordero et al. [16], Chun et al. [17], Behl [18], Kou et al. [19], Chun and Ham [20], Jarrat [21], Chicharro and Cordero [22], Ostrowski [23], Cordero and Garcia-Maimo [24], and the iterative techniques which find all roots of (1) simultaneously.

Simultaneous iterative methods are more precise, stable, and consistent than single root finding methods, and they can also be used for parallel computation. Karl Weierstrass developed a derivative-free simultaneous technique [25] known as the Weierstrass method in the literature, which was rediscovered by Kerner [26], Durand [27], Dochev [28], and Presic [29] to estimate all roots of nonlinear equations. In 1962, Dochev shows that the Weierstrass iterative technique converged locally with convergence order two. Later, Dochev and Byrnev [30] and Börsch-Supan [31] developed a derivative-free simultaneous technique of convergence order three, whereas Ehrlich [32] developed a simultaneous method with derivative. Based on Ehrlich and Börsch-Supan's approaches, Norein [33,34] developed two fourth-order simultaneous schemes in 1977. In the literature, Norein techniques are obtained by combining two approaches, namely Ehrlich methods with Newton's corrections and Brouck-Supan methods with Weierstrass' correction. Sakurai, Torii, and Sugiura [35] developed and study a fifth-order simultaneous method with derivative in 1991 using the Padé approximation. In 2019, Proinov et al. [36] presented the detailed convergence of the Sakurai–Torii–Sugiura method, followed by local and semi local convergence [37]. Petkovic et al [38] use Halley's single root finding method as a correction to accelerate the Sakurai–Torii–Sugiura method up to convergence order 6. There have been numerous implementations of Norein's method to construct simultaneous methods with accelerated convergence, including [39–44] and references therein.

Motivated by the aforementioned work, the primary goal of this study is to develop a family of simultaneous methods that are both more efficient and have a higher convergence order. Using appropriate corrections allows us to achieve seventeenth-order convergence with the fewest functional evaluations required in each step, resulting in very high computational efficiency for the newly constructed family of numerical schemes for finding distinct as well as multiple roots. So far, only the Midrog Petkovic method [45] of order 10 and the Gargantini–Farmer–Loizou method of $2N + 1$ convergence order (where N is a positive integer) [46,47] exist in the literature, but their efficiency is low and abbreviated as NN. The main contributions of this study are as follows.

- Three novel simultaneous methods are proposed to find all the distinct and multiple roots of (1).
- A local convergence analysis demonstrates that the newly developed methods rate seventeenth in terms of convergence order.
- We provide an in-depth complexity analysis to illustrate how effective the new approach is as compared to existing methods.
- Using fractal behavior, the newly developed methods are numerically evaluated for stability and efficiency.
- Utilizing a variety of stopping criteria, the method's general applicability to a wide range of nonlinear engineering problems is thoroughly investigated.

Global convergence behavior of simultaneous iterative methods is characterized by analyzing their basins of attractions and taking initial guesses away from the roots. The most frequently used classical approach for finding single roots of (1) of the first category is Newton's method:

$$\zeta^{(\vartheta+1)} = \zeta^{(\vartheta)} - \frac{f(\zeta^{(\vartheta)})}{f'(\zeta^{(\vartheta)})}, (\vartheta = 1, 2, \dots). \quad (2)$$

Method (2) is of optimal convergence order 2 with efficiency index 1.41. If we use Weierstrass' Correction [48–50]

$$\frac{f(\zeta_i^{(\theta)})}{f'(\zeta_i^{(\theta)})} = w(\zeta_i^{(\theta)}) = \frac{f(\zeta_i^{(\theta)})}{\prod_{\substack{j=1 \\ j \neq i}}^n (\zeta_i^{(\theta)} - \zeta_j^{(\theta)})}, \quad (3)$$

in (2), we get Weierstrass method to estimate all distinct roots of (1) as:

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{f(\zeta_i^{(\theta)})}{\prod_{\substack{j=1 \\ j \neq i}}^n (\zeta_i^{(\theta)} - \zeta_j^{(\theta)})}. \quad (4)$$

Method (4) has convergence order two. Later, in 1973 Ehrlich [51] and Alefeld and Herzberger proposed the following third order convergent method [52] as below:

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{1}{\frac{1}{N(\zeta_i^{(\theta)})} - \sum_{\substack{j=1 \\ j \neq i}}^n \left(\frac{1}{(\zeta_i^{(\theta)} - \zeta_j^{(\theta)})} \right)}, \quad (5)$$

and

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{1}{\frac{1}{N_i(\zeta_i^{(\theta)})} - \sum_{i=1}^{j-1} \frac{1}{\zeta_i^{(\theta)} - \zeta_j^{(\theta)}} - \sum_{j=i+1}^n \frac{1}{\zeta_i^{(\theta)} - \zeta_j^{(\theta)}}}, \quad (6)$$

where $N(\zeta_i^{(\theta)}) = \frac{f(\zeta_i^{(\theta)})}{f'(\zeta_i^{(\theta)})}$. Nourein accelerated the convergence order of (5) from three to four [33] as:

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{1}{\frac{1}{N_i(\zeta_i^{(\theta)})} - \sum_{\substack{j \neq i \\ j=1}}^n \frac{1}{\zeta_i^{(\theta)} - \zeta_j^{(\theta)} + \frac{f(\zeta_j^{(\theta)})}{f'(\zeta_j^{(\theta)})}}}, \quad (7)$$

Milovanovic et al. [53] proposed the following 4th-order convergent method:

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{1}{\frac{1}{N_i(\zeta_i^{(\theta)})} - \sum_{i=1}^{j-1} \frac{1}{\zeta_i^{(\theta)} - \zeta_j^{(\theta)}} - \sum_{j=i+1}^n \frac{1}{\zeta_i^{(\theta)} - \zeta_j^{(\theta)} + N_j(\zeta_j^{(\theta)})}}. \quad (8)$$

Petkovic et al. [54] accelerated the convergence order of (5) from three to six:

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{1}{\frac{1}{N_i(\zeta_i^{(\theta)})} - \sum_{\substack{j=1 \\ j \neq i}}^n \frac{1}{(\zeta_i^{(\theta)} - Z_j^{(\theta)})}}, \quad (9)$$

where $Z_j^{(\theta)} = \zeta_j^{(\theta)} - \frac{f(y_j^{(\theta)}) - f(\zeta_j^{(\theta)})}{2 * f(y_j^{(\theta)}) - f(\zeta_j^{(\theta)})} \frac{f(\zeta_j^{(\theta)})}{f'(\zeta_j^{(\theta)})}$ and $y_j^{(\theta)} = \zeta_j^{(\theta)} - \frac{f(\zeta_j^{(\theta)})}{f'(\zeta_j^{(\theta)})}$.

Petkovic et al. [45] accelerated the convergence order of (5) from three to ten as:

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{1}{\frac{1}{N_i(\zeta_i^{(\theta)})} - \sum_{\substack{j=1 \\ j \neq i}}^n \frac{1}{(\zeta_i^{(\theta)} - v_j^{(\theta)})}}, \quad (10)$$

$$\text{where } v_j^{(\theta)} = u_j^{(\theta)} - \frac{(y_j^{(\theta)} - u_j^{(\theta)})f(u_j^{(\theta)})\left(\frac{f(\zeta_j^{(\theta)})}{f'(\zeta_j^{(\theta)})}\right)}{(f(\zeta_j^{(\theta)}) - f(u_j^{(\theta)}))^2} \left[f(y_j^{(\theta)}) - \frac{f(\zeta_j^{(\theta)})}{f(y_j^{(\theta)}) - f(u_j^{(\theta)})} \right], u_j^{(\theta)} = y_j^{(\theta)} - \frac{f(\zeta_j^{(\theta)})f(y_j^{(\theta)})\left(\frac{f(\zeta_j^{(\theta)})}{f'(\zeta_j^{(\theta)})}\right)}{(f(\zeta_j^{(\theta)}) - f(y_j^{(\theta)}))^2}, y_j^{(\theta)} = \zeta_j^{(\theta)} - \frac{f(\zeta_j^{(\theta)})}{f'(\zeta_j^{(\theta)})}.$$

To our knowledge, this contribution is unique. A review of the literature reveals that not much work has been done on higher-order, consistent, efficient, and reliable simultaneous methods for finding all distinct and multiple roots of (1). The paper is organized in the following way: In Section 2, fractal behavior—a representation of the global convergence behavior of the proposed methods—and the development and analysis of simultaneous methods are covered. A detailed discussion of the computational cost analysis of the simultaneous methods are provided in Section 3. Section 4 deals with numerical test problems and engineering applications. Section 5 concludes the study and discusses future research directions.

2. Family of Simultaneous Methods, Its Construction and Convergence Framework

Using the technique of the weight function, Rafiq [55] proposed the following family of fifteenth-order iterative methods for finding single root of (1):

$$z^{(\theta+1)} = w^{(\theta)} - \frac{f(w^{(\theta)})}{f[\zeta^{(\theta)}, w^{(\theta)}] + \left(\frac{f[y^{(\theta)}, \zeta^{(\theta)}, y^{(\theta)}] - f[y^{(\theta)}, \zeta^{(\theta)}, w^{(\theta)}]}{f[h^{(\theta)}, \zeta^{(\theta)}, w^{(\theta)}]} \right) [\zeta^{(\theta)} - w^{(\theta)}]}, \quad (11)$$

$$\text{where } w^{(\theta)} = h^{(\theta)} - G(v^{(\theta)}) \frac{f(h^{(\theta)})}{f[\zeta^{(\theta)}, h^{(\theta)}] - f[\zeta^{(\theta)}, y^{(\theta)}, h^{(\theta)}] (\zeta^{(\theta)} - h^{(\theta)})},$$

$$h^{(\theta)} = y^{(\theta)} - \frac{1}{2} \left(\frac{f(\zeta^{(\theta)}) + \beta f(y^{(\theta)})}{f(\zeta^{(\theta)}) + (\beta - 2)f(y^{(\theta)})} \frac{f(y^{(\theta)})}{f'(\zeta^{(\theta)})} + \frac{f(y^{(\theta)})}{2 \left[\frac{f(y^{(\theta)}) - f(\zeta^{(\theta)})}{y^{(\theta)} - \zeta^{(\theta)}} \right] - f'(\zeta^{(\theta)})} \right),$$

$$y^{(\theta)} = \zeta^{(\theta)} - \frac{f(\zeta^{(\theta)})}{f'(\zeta^{(\theta)})} \text{ and } v^{(\theta)} = \frac{f(h^{(\theta)})}{f(\zeta^{(\theta)})}.$$

In (11), $f[\zeta^{(\theta)}, w^{(\theta)}]$ and $f[y^{(\theta)}, \zeta^{(\theta)}, w^{(\theta)}]$ are the divided difference and defined as:

$$f[\zeta^{(\theta)}, w^{(\theta)}] = \frac{f(\zeta^{(\theta)}) - f(w^{(\theta)})}{(\zeta^{(\theta)} - w^{(\theta)})},$$

and

$$f[y^{(\theta)}, \zeta^{(\theta)}, w^{(\theta)}] = \frac{f[y^{(\theta)}, \zeta^{(\theta)}] - f[\zeta^{(\theta)}, w^{(\theta)}]}{(y^{(\theta)} - w^{(\theta)})}.$$

If $G(v^{(\theta)})$ is real valued function defined on $v^{(\theta)} = \frac{f(h^{(\theta)})}{f(\zeta^{(\theta)})}$ such that $G(0) = G'(0) = 1$ and $|G''(0)| < \infty$, then the family of methods (11) has convergence order fifteen, if ζ is simple root of (1) and $\epsilon = \zeta - \zeta$ and error equation is given by:

$$\frac{\zeta^{(\theta+1)} - \zeta}{(\zeta^{(\theta)} - \zeta)^{15}} \rightarrow -C_2^2 C_3 C_4 (C_3 C_2^5 + 2C_3^2 C_2^3 - C_3 C_4 C_2^2); \quad (12)$$

$$C_k(\zeta) = \frac{f^{(k)}(\zeta)}{k! f'(\zeta)}, k = 2, 3, \dots \quad (13)$$

or

$$\zeta^{(\theta+1)} - \zeta = O(\epsilon^{15}). \quad (14)$$

We consider here, three concrete fifteenth order family of iterative methods as presented in [55]:

Method-1: (N1)

Selecting $G(v^{(\vartheta)}) = 1 + v^{(\vartheta)} + \alpha(v^{(\vartheta)})^2$, $\alpha \in \mathbb{R}$ the family of iterative schemes becomes:

$$z_1^{(\vartheta)} = w_1^{(\vartheta)} - \frac{f(w^{(\vartheta)})}{f[\zeta^{(\vartheta)}, w^{(\vartheta)}] + \left(\frac{f[y^{(\vartheta)}, \zeta^{(\vartheta)}, y^{(\vartheta)}] - f[y^{(\vartheta)}, \zeta^{(\vartheta)}, w^{(\vartheta)}]}{f[h^{(\vartheta)}, \zeta^{(\vartheta)}, w^{(\vartheta)}]} \right) [\zeta^{(\vartheta)} - w^{(\vartheta)}]}, \quad (15)$$

$$\text{where } w_1^{(\vartheta)} = h^{(\vartheta)} - \left(\frac{1 + \frac{f(h^{(\vartheta)})}{f(\zeta^{(\vartheta)})} + \alpha \left(\frac{f(h^{(\vartheta)})}{f(\zeta^{(\vartheta)})} \right)^2}{\frac{f(h^{(\vartheta)})}{f(\zeta^{(\vartheta)})}} \right) \left(\frac{\frac{f(h^{(\vartheta)})}{f[\zeta^{(\vartheta)}, h^{(\vartheta)}] - f[\zeta^{(\vartheta)}, y^{(\vartheta)}, h^{(\vartheta)}](\zeta^{(\vartheta)} - h^{(\vartheta)})}}{f[\zeta^{(\vartheta)}, y^{(\vartheta)}, h^{(\vartheta)}](\zeta^{(\vartheta)} - h^{(\vartheta)})} \right),$$

$$h^{(\vartheta)} = y^{(\vartheta)} - \frac{1}{2} \left(\frac{\frac{f(\zeta^{(\vartheta)}) + \beta f(y^{(\vartheta)})}{f(\zeta^{(\vartheta)}) + (\beta - 2)f(y^{(\vartheta)})} \frac{f(y^{(\vartheta)})}{f'(\zeta^{(\vartheta)})} + \frac{\frac{f(y^{(\vartheta)})}{2 \left[\frac{f(y^{(\vartheta)}) - f(\zeta^{(\vartheta)})}{y^{(\vartheta)} - \zeta^{(\vartheta)}} \right] - f'(\zeta^{(\vartheta)})}}{f'(\zeta^{(\vartheta)})} \right),$$

$$y^{(\vartheta)} = \zeta^{(\vartheta)} - \frac{f(\zeta^{(\vartheta)})}{f'(\zeta^{(\vartheta)})} \text{ and } v^{(\vartheta)} = \frac{f(h^{(\vartheta)})}{f(\zeta^{(\vartheta)})}.$$

Method-2: (N2)

Choosing $G(v^{(\vartheta)}) = (1 - \alpha v^{(\vartheta)})^{\frac{1}{\alpha}}$, $\alpha \neq 0$, $\alpha \in \mathbb{R}$ the family of iterative schemes is given by:

$$z_2^{(\vartheta)} = w_2^{(\vartheta)} - \frac{f(w^{(\vartheta)})}{f[\zeta^{(\vartheta)}, w^{(\vartheta)}] + \left(\frac{f[y^{(\vartheta)}, \zeta^{(\vartheta)}, y^{(\vartheta)}] - f[y^{(\vartheta)}, \zeta^{(\vartheta)}, w^{(\vartheta)}]}{f[h^{(\vartheta)}, \zeta^{(\vartheta)}, w^{(\vartheta)}]} \right) [\zeta^{(\vartheta)} - w^{(\vartheta)}]}, \quad (16)$$

$$\text{where } w_2^{(\vartheta)} = h^{(\vartheta)} - \left(\left(1 - \alpha \frac{f(h^{(\vartheta)})}{f(\zeta^{(\vartheta)})} \right)^{\frac{1}{\alpha}} \right) \left(\frac{\frac{f(h^{(\vartheta)})}{f[\zeta^{(\vartheta)}, h^{(\vartheta)}] - f[\zeta^{(\vartheta)}, y^{(\vartheta)}, h^{(\vartheta)}](\zeta^{(\vartheta)} - h^{(\vartheta)})}}{f[\zeta^{(\vartheta)}, y^{(\vartheta)}, h^{(\vartheta)}](\zeta^{(\vartheta)} - h^{(\vartheta)})} \right),$$

$$h^{(\vartheta)} = y^{(\vartheta)} - \frac{1}{2} \left(\frac{\frac{f(\zeta^{(\vartheta)}) + \beta f(y^{(\vartheta)})}{f(\zeta^{(\vartheta)}) + (\beta - 2)f(y^{(\vartheta)})} \frac{f(y^{(\vartheta)})}{f'(\zeta^{(\vartheta)})} + \frac{\frac{f(y^{(\vartheta)})}{2 \left[\frac{f(y^{(\vartheta)}) - f(\zeta^{(\vartheta)})}{y^{(\vartheta)} - \zeta^{(\vartheta)}} \right] - f'(\zeta^{(\vartheta)})}}{f'(\zeta^{(\vartheta)})} \right),$$

$$y^{(\vartheta)} = \zeta^{(\vartheta)} - \frac{f(\zeta^{(\vartheta)})}{f'(\zeta^{(\vartheta)})} \text{ and } v^{(\vartheta)} = \frac{f(h^{(\vartheta)})}{f(\zeta^{(\vartheta)})}.$$

Method-3: (N3)

Considering $G(v^{(\vartheta)}) = 1 + v^{(\vartheta)} + \alpha(v^{(\vartheta)})^2 + \gamma(v^{(\vartheta)})^3$, $\alpha, \gamma \in \mathbb{R}$ the family of iterative schemes is given as follows:

$$z_3^{(\vartheta)} = w_3^{(\vartheta)} - \frac{f(w^{(\vartheta)})}{f[\zeta^{(\vartheta)}, w^{(\vartheta)}] + \left(\frac{f[y^{(\vartheta)}, \zeta^{(\vartheta)}, y^{(\vartheta)}] - f[y^{(\vartheta)}, \zeta^{(\vartheta)}, w^{(\vartheta)}]}{f[h^{(\vartheta)}, \zeta^{(\vartheta)}, w^{(\vartheta)}]} \right) [\zeta^{(\vartheta)} - w^{(\vartheta)}]}, \quad (17)$$

$$\text{where } w_3^{(\vartheta)} = h^{(\vartheta)} - \left(\begin{array}{c} 1 + \frac{f(h^{(\vartheta)})}{f(\zeta^{(\vartheta)})} + \\ \alpha \left(\frac{f(h^{(\vartheta)})}{f(\zeta^{(\vartheta)})} \right)^2 + \\ \gamma \left(\frac{f(h^{(\vartheta)})}{f(\zeta^{(\vartheta)})} \right)^3 \end{array} \right) \left(\frac{\frac{f(z^{(\vartheta)})}{f[\zeta^{(\vartheta)}, h^{(\vartheta)}] - f[\zeta^{(\vartheta)}, y^{(\vartheta)}, h^{(\vartheta)}](\zeta^{(\vartheta)} - h^{(\vartheta)})}}{f[\zeta^{(\vartheta)}, y^{(\vartheta)}, h^{(\vartheta)}](\zeta^{(\vartheta)} - h^{(\vartheta)})} \right),$$

$$h^{(\theta)} = y^{(\theta)} - \frac{1}{2} \left(\frac{f(\zeta^{(\theta)}) + \beta f(y^{(\theta)})}{f(\zeta^{(\theta)}) + (\beta - 2)f(y^{(\theta)})} \frac{f(y^{(\theta)})}{f'(\zeta^{(\theta)})} + \frac{f(y^{(\theta)})}{2 \left[\frac{f(y^{(\theta)}) - f(\zeta^{(\theta)})}{y^{(\theta)} - \zeta^{(\theta)}} \right] - f'(\zeta^{(\theta)})} \right),$$

$$y^{(\theta)} = \zeta^{(\theta)} - \frac{f(\zeta^{(\theta)})}{f'(\zeta^{(\theta)})} \text{ and } v^{(\theta)} = \frac{f(h^{(\theta)})}{f'(\zeta^{(\theta)})}.$$

Suppose, (1) has m distinct roots. Then $f(\zeta)$ and $f'(\zeta)$ can be approximated as:

$$f(\zeta) = \prod_{j=1}^m (\zeta - \zeta_j) \text{ and } f'(\zeta) = \sum_{k=1}^n \prod_{\substack{j=1 \\ j \neq k}}^m (\zeta - \zeta_j) \text{ or } f'(\zeta_k) = \sum_{k=1}^n \prod_{\substack{j=1 \\ j \neq k}}^m (\zeta_k - \zeta_j). \quad (18)$$

This implies,

$$\frac{f'(\zeta)}{f(\zeta)} = \sum_{j=1}^m \left(\frac{1}{(\zeta - \zeta_j)} \right) = \frac{1}{\frac{1}{\zeta - \zeta_i} - \sum_{\substack{j=1 \\ j \neq i}}^m \left(\frac{1}{(\zeta - \zeta_j)} \right)}. \quad (19)$$

This provides the Aberth Ehrlich method (5).

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{1}{\frac{1}{N(\zeta_i^{(\theta)})} - \sum_{\substack{j=1 \\ j \neq i}}^m \left(\frac{1}{(\zeta_i^{(\theta)} - \zeta_j^{(\theta)})} \right)}, \text{ where } N(\zeta_i^{(\theta)}) = \frac{f(\zeta_i^{(\theta)})}{f'(\zeta_i^{(\theta)})}. \quad (20)$$

Now from (25), an approximation of $\frac{f(\zeta_i^{(\theta)})}{f'(\zeta_i^{(\theta)})}$ is formed by replacing $\zeta_j^{(\theta)}$ with $z_{vj}^{(\theta)}$ as follows:

$$\frac{f(\zeta_i^{(\theta)})}{f'(\zeta_i^{(\theta)})} = \frac{1}{\frac{1}{N(\zeta_i^{(\theta)})} - \sum_{\substack{j=1 \\ j \neq i}}^m \left(\frac{1}{(\zeta_i^{(\theta)} - z_{vj}^{(\theta)})} \right)}, v = 1, 2, 3 \quad (21)$$

Using (21) in (5), we have:

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{1}{\frac{1}{N(\zeta_i^{(\theta)})} - \sum_{\substack{j=1 \\ j \neq i}}^m \left(\frac{1}{(\zeta_i^{(\theta)} - z_{vj}^{(\theta)})} \right)}. \quad (22)$$

In case of multiple roots:

$$\zeta_i^{(\theta+1)} = \zeta_i^{(\theta)} - \frac{\sigma_i}{\frac{1}{N(\zeta_i^{(\theta)})} - \sum_{\substack{j=1 \\ j \neq i}}^n \left(\frac{\sigma_j}{(\zeta_i^{(\theta)} - z_{vj}^{(\theta)})} \right)}, \quad (23)$$

where $\zeta_1, \dots, \zeta_n$ are now multiple roots of respective unknown multiplicities $\sigma_1, \dots, \sigma_n$ ($\sigma_1 + \dots + \sigma_n = m$) and

$$z_{1j}^{(\theta)} = w_{1j}^{(\theta)} - \frac{f(w_j^{(\theta)})}{f[\zeta_j^{(\theta)}, w_j^{(\theta)}] + \left(\frac{f[y_j^{(\theta)}, \zeta_j^{(\theta)}, y_j^{(\theta)}] - f[y_j^{(\theta)}, \zeta_j^{(\theta)}, w_j^{(\theta)}] - f[h_j^{(\theta)}, \zeta_j^{(\theta)}, w_j^{(\theta)}]}{f[y_j^{(\theta)}, \zeta_j^{(\theta)}, y_j^{(\theta)}] - f[y_j^{(\theta)}, \zeta_j^{(\theta)}, w_j^{(\theta)}]} \right) [\zeta_j^{(\theta)} - w_j^{(\theta)}]},$$

$$\begin{aligned}
\text{where } w_{1j} &= h_j^{(\theta)} - \left(\begin{array}{c} 1 + \frac{f(h_j^{(\theta)})}{f(\varsigma_j^{(\theta)})} \\ + \alpha \left(\frac{f(h_j^{(\theta)})}{f(\varsigma_j^{(\theta)})} \right)^2 \end{array} \right) \left(\frac{f(h_j^{(\theta)})}{f[\varsigma_j^{(\theta)}, h_j^{(\theta)}] - f[\varsigma_j^{(\theta)}, y_j^{(\theta)}, h_j^{(\theta)}](\varsigma_j^{(\theta)} - h_j^{(\theta)})} \right), \\
h_j^{(\theta)} &= y_j^{(\theta)} - \frac{1}{2} \left(\frac{f(\varsigma_j^{(\theta)}) + \beta f(y_j^{(\theta)})}{f(\varsigma_j^{(\theta)}) + (\beta - 2)f(y_j^{(\theta)})} \frac{f(y_j^{(\theta)})}{f'(\varsigma_j^{(\theta)})} + \frac{f(y_j^{(\theta)})}{2 \left[\frac{f(y_j^{(\theta)}) - f(\varsigma_j^{(\theta)})}{y_j^{(\theta)} - \varsigma_j^{(\theta)}} \right] - f'(\varsigma_j^{(\theta)})} \right), \\
y_j^{(\theta)} &= \varsigma_j^{(\theta)} - \frac{f(\varsigma_j^{(\theta)})}{f'(\varsigma_j^{(\theta)})}, v_j^{(\theta)} = \frac{f(h_j^{(\theta)})}{f(\varsigma_j^{(\theta)})}, \\
z_{2j}^{(\theta)} &= w_{2j}^{(\theta)} - \frac{f(w_j^{(\theta)})}{f[\varsigma_j^{(\theta)}, w_j^{(\theta)}] + \left(\frac{f[y_j^{(\theta)}, \varsigma_j^{(\theta)}, y_j^{(\theta)}] - f[y_j^{(\theta)}, \varsigma_j^{(\theta)}, w_j^{(\theta)}] - f[h_j^{(\theta)}, \varsigma_j^{(\theta)}, w_j^{(\theta)}]}{f[\varsigma_j^{(\theta)}, w_j^{(\theta)}]} \right) [\varsigma_j^{(\theta)} - w_j^{(\theta)}]}, \\
w_{2j}^{(\theta)} &= h_j^{(\theta)} - \left(\left(1 - \alpha \frac{f(h_j^{(\theta)})}{f(\varsigma_j^{(\theta)})} \right)^{\frac{1}{\alpha}} \right) \left(\frac{f(h_j^{(\theta)})}{f[\varsigma_j^{(\theta)}, h_j^{(\theta)}] - f[\varsigma_j^{(\theta)}, y_j^{(\theta)}, h_j^{(\theta)}](\varsigma_j^{(\theta)} - h_j^{(\theta)})} \right), \\
h_j^{(\theta)} &= y_j^{(\theta)} - \frac{1}{2} \left(\frac{f(\varsigma_j^{(\theta)}) + \beta f(y_j^{(\theta)})}{f(\varsigma_j^{(\theta)}) + (\beta - 2)f(y_j^{(\theta)})} \frac{f(y_j^{(\theta)})}{f'(\varsigma_j^{(\theta)})} + \frac{f(y_j^{(\theta)})}{2 \left[\frac{f(y_j^{(\theta)}) - f(\varsigma_j^{(\theta)})}{y_j^{(\theta)} - \varsigma_j^{(\theta)}} \right] - f'(\varsigma_j^{(\theta)})} \right), \\
y_j^{(\theta)} &= \varsigma_j^{(\theta)} - \frac{f(\varsigma_j^{(\theta)})}{f'(\varsigma_j^{(\theta)})}, v_j^{(\theta)} = \frac{f(h_j^{(\theta)})}{f(\varsigma_j^{(\theta)})}, \\
z_{3j}^{(\theta)} &= w_{3j}^{(\theta)} - \frac{f(w_j^{(\theta)})}{f[\varsigma_j^{(\theta)}, w_j^{(\theta)}] + \left(\frac{f[y_j^{(\theta)}, \varsigma_j^{(\theta)}, y_j^{(\theta)}] - f[y_j^{(\theta)}, \varsigma_j^{(\theta)}, w_j^{(\theta)}] - f[h_j^{(\theta)}, \varsigma_j^{(\theta)}, w_j^{(\theta)}]}{f[\varsigma_j^{(\theta)}, w_j^{(\theta)}]} \right) [\varsigma_j^{(\theta)} - w_j^{(\theta)}]}, \\
w_{3j}^{(\theta)} &= h_j^{(\theta)} - \left(\begin{array}{c} 1 + \frac{f(h_j^{(\theta)})}{f(\varsigma_j^{(\theta)})} + \\ \alpha \left(\frac{f(h_j^{(\theta)})}{f(\varsigma_j^{(\theta)})} \right)^2 \\ + \gamma \left(\frac{f(h_j^{(\theta)})}{f(\varsigma_j^{(\theta)})} \right)^3 \end{array} \right) \left(\frac{f(h_j^{(\theta)})}{f[\varsigma_j^{(\theta)}, h_j^{(\theta)}] - f[\varsigma_j^{(\theta)}, y_j^{(\theta)}, h_j^{(\theta)}](\varsigma_j^{(\theta)} - h_j^{(\theta)})} \right), \\
h_j^{(\theta)} &= y_j^{(\theta)} - \frac{1}{2} \left(\frac{f(\varsigma_j^{(\theta)}) + \beta f(y_j^{(\theta)})}{f(\varsigma_j^{(\theta)}) + (\beta - 2)f(y_j^{(\theta)})} \frac{f(y_j^{(\theta)})}{f'(\varsigma_j^{(\theta)})} + \frac{f(y_j^{(\theta)})}{2 \left[\frac{f(y_j^{(\theta)}) - f(\varsigma_j^{(\theta)})}{y_j^{(\theta)} - \varsigma_j^{(\theta)}} \right] - f'(\varsigma_j^{(\theta)})} \right), \\
y_j^{(\theta)} &= \varsigma_j^{(\theta)} - \frac{f(\varsigma_j^{(\theta)})}{f'(\varsigma_j^{(\theta)})}, v_j^{(\theta)} = \frac{f(h_j^{(\theta)})}{f(\varsigma_j^{(\theta)})}.
\end{aligned}$$

Thus, we have constructed family of three simultaneous methods of seventeenth order for finding all the distinct roots of nonlinear polynomial equations, abbreviated as MN₁–MN₃.

Convergence Analysis

Here, we prove convergence order of simultaneous methods MN₁–MN₃ using following convergence theorem.

Theorem 1. Let $\xi_1, \xi_2, \dots, \xi_n$ be simple roots of (1) with multiplicity $\sigma_1, \dots, \sigma_n$ ($\sigma_1 + \dots + \sigma_n = m$) and if $\varsigma_1^{(0)}, \dots, \varsigma_n^{(0)}$ be sufficiently close initial guessed estimates of the roots, then MN₁–MN₃ has seventeenth order convergence.

Proof. Let $\epsilon_i = \varsigma_i^{(\theta)} - \xi_i$ and $\epsilon'_i = \varsigma_i^{(\theta+1)} - \xi_i$ be the errors in $\varsigma_i^{(\theta)}$ and $\varsigma_i^{(\theta+1)}$ estimates correspondingly. Considering MN₁–MN₃, we have:

$$\varsigma_i^{(\theta+1)} = \varsigma_i^{(\theta)} - \frac{1}{\frac{\sigma_i}{N(\varsigma_i^{(\theta)})} - \sum_{\substack{j=1 \\ j \neq i}}^n \left(\frac{1}{(\varsigma_i^{(\theta)} - \xi_j)} \right)}, \quad (v = 1, 2, 3). \quad (24)$$

where $N(\varsigma_i^{(\theta)}) = \left(\frac{f(\varsigma_i^{(\theta)})}{f'(\varsigma_i^{(\theta)})} \right)$. Then, obviously for distinct roots:

$$\frac{1}{N(\varsigma_i^{(\theta)})} = \left(\frac{f'(\varsigma_i^{(\theta)})}{f(\varsigma_i^{(\theta)})} \right) = \sum_{j=1}^n \left(\frac{1}{(\varsigma_i^{(\theta)} - \xi_j)} \right) = \frac{1}{(\varsigma_i^{(\theta)} - \xi_i)} + \sum_{\substack{j=1 \\ j \neq i}}^n \left(\frac{1}{(\varsigma_i^{(\theta)} - \xi_j)} \right). \quad (25)$$

Thus, for multiple roots we have from MN₁ to MN₃:

$$\varsigma_i^{(\theta+1)} = \varsigma_i^{(\theta)} - \frac{\sigma_i}{\frac{\sigma_i}{(\varsigma_i^{(\theta)} - \xi_i)} + \sum_{\substack{j=1 \\ j \neq i}}^n \left(\frac{\sigma_j}{(\varsigma_i^{(\theta)} - \xi_j)} \right) - \sum_{\substack{j=1 \\ j \neq i}}^n \left(\frac{\sigma_j}{(\varsigma_i^{(\theta)} - \xi_j)} \right)}, \quad (26)$$

$$\varsigma_i^{(\theta+1)} - \xi_i = \varsigma_i^{(\theta)} - \xi_i - \frac{\sigma_i}{\frac{\sigma_i}{(\varsigma_i^{(\theta)} - \xi_i)} + \sum_{\substack{j=1 \\ j \neq i}}^n \left(\frac{\sigma_j(\varsigma_i^{(\theta)} - \xi_j - \xi_i + \xi_j)}{(\varsigma_i^{(\theta)} - \xi_j)(\varsigma_i^{(\theta)} - \xi_j)} \right)}, \quad (27)$$

$$\epsilon'_i = \epsilon_i - \frac{\sigma_i}{\frac{\sigma_i}{\epsilon_i} + \sum_{\substack{j=1 \\ j \neq i}}^n \left(\frac{-\sigma_j(z_{vj}^{(\theta)} - \xi_j)}{(\varsigma_i^{(\theta)} - \xi_j)(\varsigma_i^{(\theta)} - z_{vj}^{(\theta)})} \right)}, \quad (28)$$

$$\epsilon'_i = \epsilon_i - \frac{\sigma_i \epsilon_i}{\sigma_i + \epsilon_i \sum_{\substack{j=1 \\ j \neq i}}^n \left(\frac{-\sigma_j(z_{vj}^{(\theta)} - \xi_j)}{(\varsigma_i^{(\theta)} - \xi_j)(\varsigma_i^{(\theta)} - z_{vj}^{(\theta)})} \right)}, \quad (29)$$

$$= \epsilon_i - \frac{\sigma_i \epsilon_i}{\sigma_i + \epsilon_i \sum_{\substack{j=1 \\ j \neq i}}^n (E_i \epsilon_j^4)}, \quad (30)$$

where $z_{vj}^{(\theta)} - \xi_j = \epsilon_j^{15}$. Using (29) and $E_i = \left(\frac{-\sigma_j}{(\varsigma_i^{(\theta)} - \xi_j)(\varsigma_i^{(\theta)} - z_{vj}^{(\theta)})} \right)$, we have

$$\epsilon'_i = \frac{\epsilon_i^2 \sum_{\substack{j=1 \\ j \neq i}}^n (E_i \epsilon_j^{15})}{\sigma_i + \epsilon_i \sum_{\substack{j=1 \\ j \neq i}}^n (E_i \epsilon_j^{15})}. \quad (31)$$

Assuming $|\epsilon_i| = |\epsilon_j| = O|\epsilon|$, from (31), we have:

$$\epsilon'_i = O(\epsilon_i)^{17}. \quad (32)$$

hence the theorem. $\square$

Fractal Analysis of Simultaneous Scheme: To provoke the fractal-basin of attractions of iterative schemes N_1 – N_3 , MN_1 – MN_3 , and NN for the determining the roots of nonlinear equation, we execute the real and imaginary parts of the starting approximations represented as two axes over a mesh of 250×250 in complex plane. Use $|\zeta^{(\theta+1)} - \zeta^{(\theta)}| < 10^{-3}$ as a stopping criteria and consider maximum 3 iterations. We allow different colors to mark to which root the iterative scheme converges and black in other cases. Color brightness in basins shows less number of iterations. Figures 1a–g and 2a–g illustrate the fractal behavior of N_1 – N_3 , MN_1 – MN_3 and NN for fractional-order nonlinear polynomials.

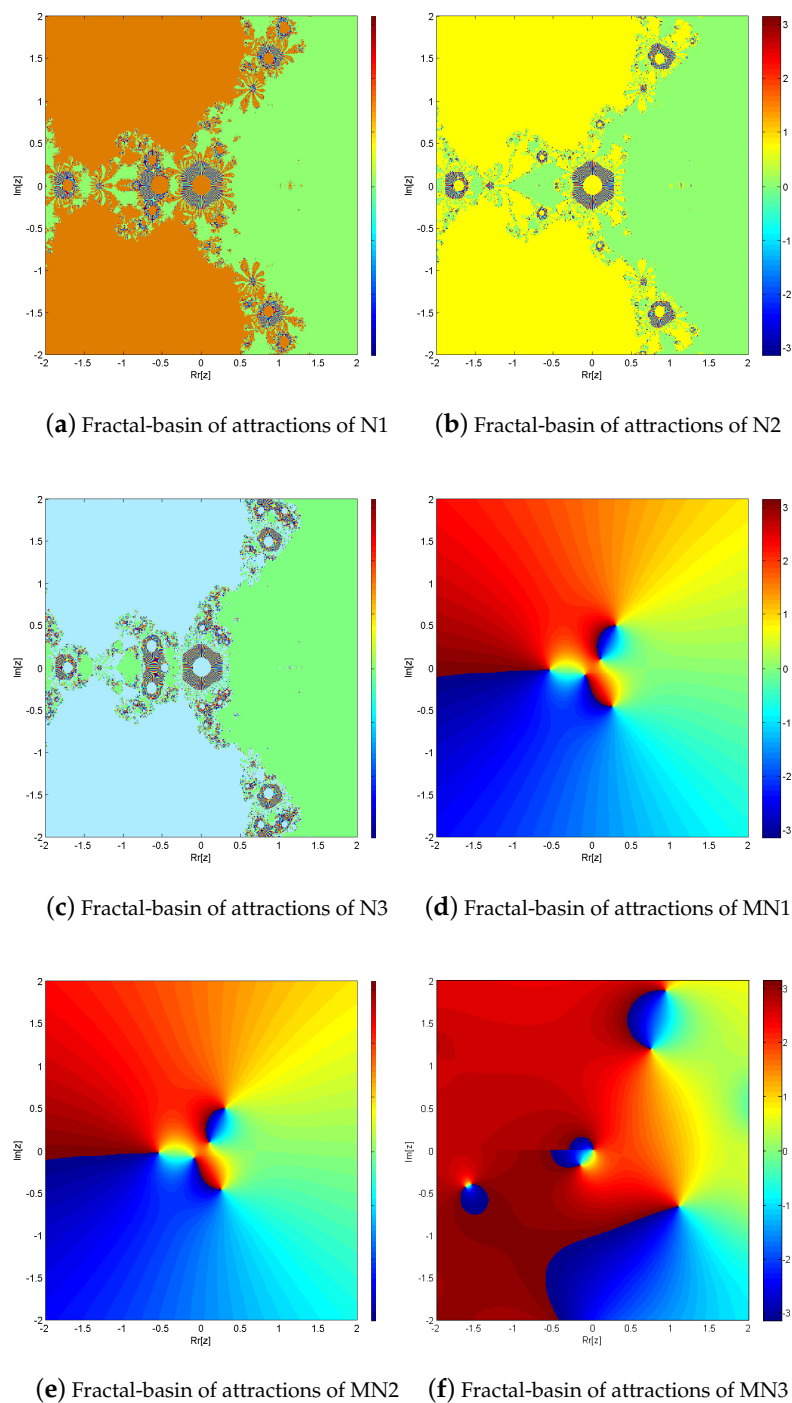
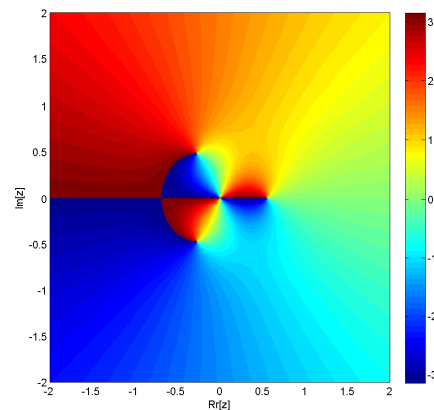


Figure 1. Cont.

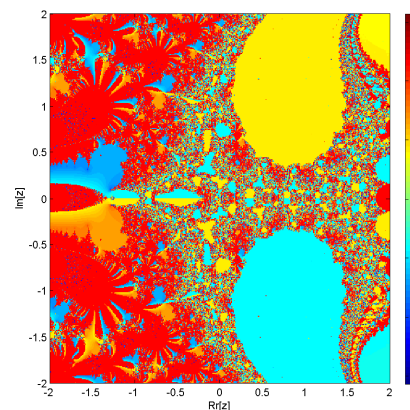


(g) Fractal-basin of attractions of NN

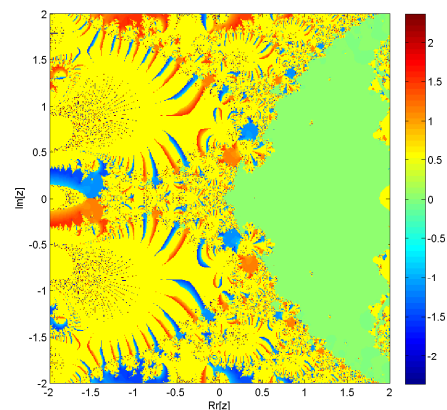
Figure 1. (a–g) shows basins of attraction for nonlinear function $f(\zeta) = \zeta^{312/99} - \frac{1}{3}$ of iterative methods N1–N3, MN₁–MN₃, and NN, respectively.

Figure 1a–g, shows basins of attraction for nonlinear function $f(\zeta) = \zeta^{312/99} - \frac{1}{3}$ of iterative methods N1–N3, MN₁–MN₃, and NN, respectively.

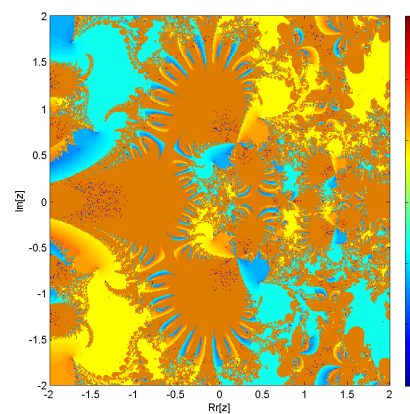
Figure 2a–g, shows basins of attraction for nonlinear function $f(\zeta) = e^{\zeta^{210/99}} - \log(\zeta)$ of iterative methods N1–N3, MN₁–MN₃, and NN, respectively.



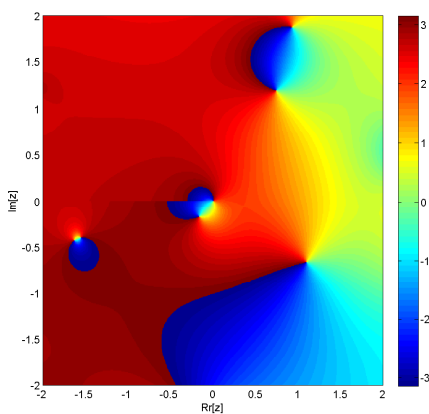
(a) Fractal-basin of attractions of N1



(b) Fractal-basin of attractions of N2



(c) Fractal-basin of attractions of N3



(d) Fractal-basin of attractions of MN1

Figure 2. Cont.

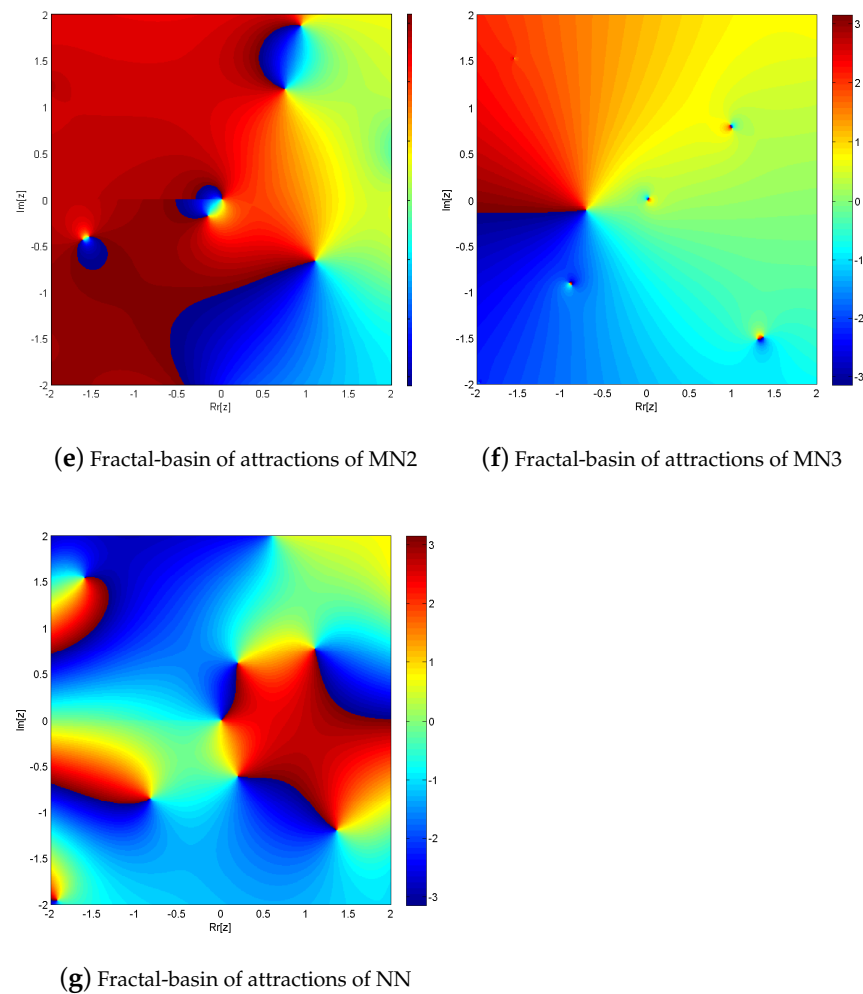


Figure 2. (a–g) shows basins of attraction for nonlinear function $f(\zeta) = e^{\zeta^{210/99}} - \log(\zeta)$ of iterative methods N1–N3, MN₁–MN₃, and NN, respectively.

From the elapsed time in Table 1 and brightness in color in Figures 1a–g and 2a–g, shows the dominance behavior of MN₁–MN₃ over N1–N3 and NN, respectively.

Table 1. Elapsed time in seconds.

Method	N1	N2	N3	MN ₁	MN ₂	MN ₃	NN
$f(\zeta) = \zeta^{312/99} - \frac{1}{3}$	5.1293	6.1422	4.3231	0.0714	0.0152	0.0142	0.1235
$f(\zeta) = e^{\zeta^{210/99}} - \log(\zeta)$	4.1609	5.2382	3.4319	0.0124	0.0193	0.0147	0.2145

The iterative schemes N1–N3, MN₁–MN₃, and NN for solving $f(\zeta) = \zeta^{312/99} - \frac{1}{3}$, $f(\zeta) = e^{\zeta^{210/99}} - \log(\zeta)$, exhibit fractal behavior, as seen in Figures 1a–g and 2a–g, respectively. In comparison to solving fractional order nonlinear equations $f(\zeta) = \zeta^{312/99} - \frac{1}{3}$ with N1–N3, MN₁–MN₃, and NN converge to 510,003, 534,673, 507,432, 618,654, 638,765, 632,154, and 588,975 points out of a total of 640,000, respectively. While generating the fractal of $f(\zeta) = e^{\zeta^{210/99}} - \log(\zeta)$, with N1–N3, MN₁–MN₃, and NN converge to 543,254, 543,565, 546,754, 632,455, 63,765, 638,765, and 523,451 points out of a total of 640,000, respectively. Furthermore, MN₁–MN₃ has a far higher convergence rate than NN. In the complex plane, MN₁–MN₃ converges to more points than NN due to global convergence.

3. Computational Aspect

We compare the percentage cost of computation of Midrog Petkovic method (NN-method) [45] and the new family of methods MN_1 – MN_3 , the computation efficiencies (CE) are computed as:

$$CE(m) = \frac{\log u}{D}, \quad (33)$$

where D and u are cost of computation order of convergence of MN_1 – MN_3 , NN, respectively. Applying (33) and data given in Table 2, we calculate the percentage computational cost as $\rho(MN_1$ – MN_2 , NN) [56] given by:

$$\rho(MN_1 - MN_3, NN) = \left(\frac{CE(MN_1 - MN_3)}{CE(NN)} - 1 \right) \times 100. \quad (34)$$

Figure 3a–d graphically clarifies these percentage costs of computation. It is obvious from Figure 3b–d, that MN_1 – MN_3 are more efficient as compared to NN.

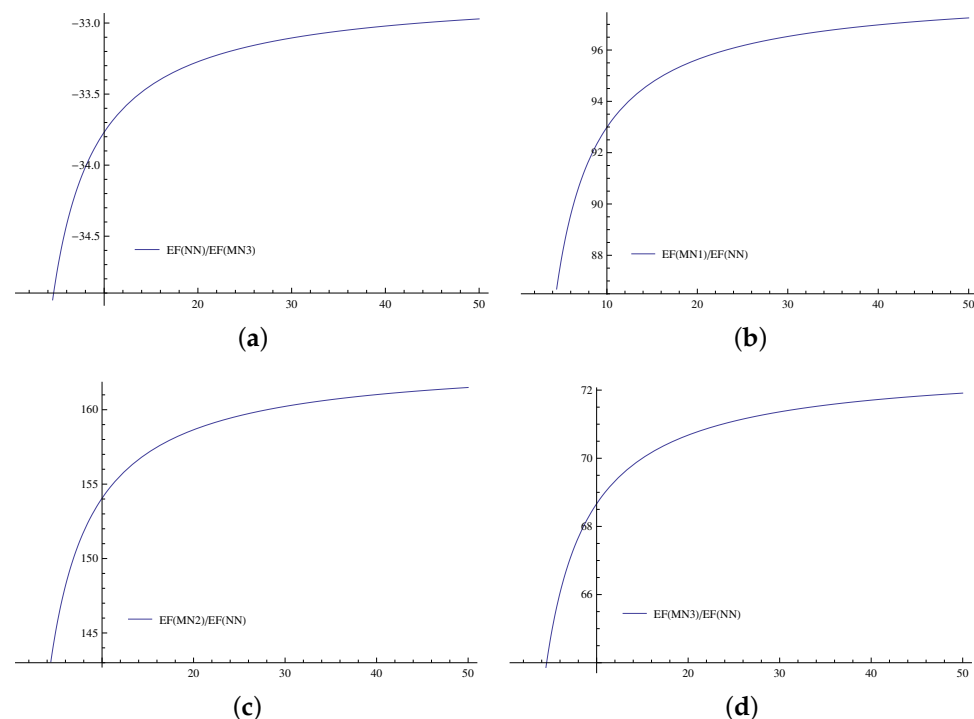


Figure 3. (a–d): Graphically clarifies these percentage costs of computation. It is obvious from (b–d), that MN_1 – MN_3 are more efficient as compared to NN.

Table 2. Basic operations per iterations.

	MN_1	MN_2	MN_3	NN
Addition and subtraction	$6\oslash$	$7\oslash$	$9\oslash$	$8\oslash$
Multiplications	$1\oslash$	$1\oslash$	$1\oslash$	$6\oslash$
Divisions	$2\oslash$	$1\oslash$	$2\oslash$	$2\oslash$

where $\oslash = \oslash_1 + \oslash_2$; $\oslash_1 = m^2$; $\oslash_2 = O(m)$.

4. Numerical Results

We use CAS Maple 18 with 64-Digits-Floating-Point arithmetic for all numerical calculations with stopping criteria as follows:

$$e_i^{(\vartheta)} = \left\| \zeta_i^{(\vartheta+1)} - \rho_i \right\|_2 < \epsilon = 10^{-30},$$

where $e_i^{(\vartheta)}$ represents the absolute error of norm-2. In all numerical calculations we take $\alpha = 0.008$, $\beta = -0.001$, $\gamma = 1.5$.

Numerical tests problems from [57–60] are provided in Tables 3–13 and Algorithm 1.

Algorithm 1: For simultaneous scheme MN_1 to approximate all distinct and multiple root of (1).

For the preliminary computations $\zeta_i^{(0)}$ ($ii = 1, \dots, N$),
tolerance $\epsilon > 0$ and set $jj = 0$ for tt -iterations

Calculate

$$\begin{aligned} y_j^{(\theta)} &= \zeta_j^{(\theta)} - \frac{f(\zeta_j^{(\theta)})}{f'(\zeta_j^{(\theta)})}, v_j^{(\theta)} = \frac{f(h_j^{(\theta)})}{f(\zeta_j^{(\theta)})}. \\ h_i^{(\theta)} &= y_i^{(\theta)} - \frac{1}{2} \left(\frac{\frac{f(\zeta_j^{(\theta)}) + \beta f(y_j^{(\theta)})}{f(\zeta_j^{(\theta)}) + (\beta - 2)f(y_j^{(\theta)})} \frac{f(y_j^{(\theta)})}{f'(\zeta_j^{(\theta)})} + \frac{f(y_j^{(\theta)})}{2 \left[\frac{f(y_j^{(\theta)}) - f(\zeta_j^{(\theta)})}{y_j^{(\theta)} - \zeta_j^{(\theta)}} \right] - f'(\zeta_j^{(\theta)})} \right), \\ w_{1j} &= h_j^{(\theta)} - \left(\frac{1 + \frac{f(h_j^{(\theta)})}{f(\zeta_j^{(\theta)})}}{+\alpha \left(\frac{f(h_j^{(\theta)})}{f(\zeta_j^{(\theta)})} \right)^2} \right) \left(\frac{f(h_j^{(\theta)})}{f[\zeta_j^{(\theta)}, h_j^{(\theta)}] - f[\zeta_j^{(\theta)}, y_j^{(\theta)}, h_j^{(\theta)}] * (\zeta_j^{(\theta)} - h_j^{(\theta)})} \right), \\ z_{1j}^{(\theta)} &= w_{1j}^{(\theta)} - \frac{f(w_{1j}^{(\theta)})}{f[\zeta_j^{(\theta)}, w_{1j}^{(\theta)}] + \left(\frac{f[y_j^{(\theta)}, \zeta_j^{(\theta)}, y_j^{(\theta)}] - f[y_j^{(\theta)}, \zeta_j^{(\theta)}, w_{1j}^{(\theta)}] - f[h_j^{(\theta)}, \zeta_j^{(\theta)}, w_{1j}^{(\theta)}]}{f[y_j^{(\theta)}, \zeta_j^{(\theta)}, y_j^{(\theta)}] - f[y_j^{(\theta)}, \zeta_j^{(\theta)}, w_{1j}^{(\theta)}] - f[h_j^{(\theta)}, \zeta_j^{(\theta)}, w_{1j}^{(\theta)}]} \right) [\zeta_j^{(\theta)} - w_{1j}^{(\theta)}]}, \\ \text{Update } \zeta_i^{(\theta+1)} &= \zeta_i^{(\theta)} - \frac{\sigma_i}{\frac{1}{N(\zeta_i^{(\theta)})} - \sum_{j=1, j \neq i}^n \left(\frac{\sigma_j}{(\zeta_i^{(\theta)} - \zeta_j^{(\theta)})} \right)}, \\ \text{where } N(\zeta_i^{(\theta)}) &= \left(\frac{f(\zeta_i^{(\theta)})}{f'(\zeta_i^{(\theta)})} \right). \\ \zeta_i^{(\theta+1)} &= \zeta_i^{(\theta)} \quad (ii = 1, \dots, n). \\ \text{if } e_i^{(\theta)} &= \left| \zeta_i^{(\theta+1)} - \zeta_i^{(\theta)} \right| < \epsilon = 10^{-30} \text{ or } \sigma > tt, \text{ then break.} \\ \text{Set } jj &= jj + 1 \text{ and go to } 1^{st} \text{-iteration.} \\ \text{End do.} \end{aligned}$$

Table 3. Parallel numerical scheme residual error comparison NN, MN_1 – MN_3 .

Method	CPU-Time	$e_1^{(2)}$	$e_2^{(2)}$	$e_3^{(2)}$	$e_4^{(2)}$	$e_5^{(2)}$	$e_6^{(2)}$	$e_7^{(2)}$	$e_8^{(2)}$	$e_9^{(2)}$
NN	0.406	0.0	0.0	0.0	5.7×10^{-17}	3.2×10^{-21}	0.0	0.0	0.0	0.0
MN_1	0.016	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
MN_2	0.156	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
MN_3	0.159	0.0	0.0	0.0	6.0×10^{-37}	0.9×10^{-45}	0.0	0.0	0.0	0.0

Table 4. Approximate roots of the $f_2(\zeta)$ utilising MN_1 – MN_3 up-to 25 decimal places.

Roots	Approximate Roots after Second Iteration Using Simultaneous Methods MN_1 – MN_3
$\zeta_1^{(2)}$	$-59,696.70991140727878983742649 - 17,330.45629984850327806571946 \times i$
$\zeta_2^{(2)}$	$-59,696.70991140727878983742649 + 17,330.45629984850327806571946 \times i$
$\zeta_3^{(2)}$	$-35,422.49261941473703632706384 - 41,931.87069228758403349587288 \times i$
$\zeta_4^{(2)}$	$-35,422.49261941473703632706384 + 41,931.87069228758403349587288 \times i$
$\zeta_5^{(2)}$	$-1235.689293801075002171094064 - 42,268.27946411286842679890715 \times i$
$\zeta_6^{(2)}$	$-1235.689293801075002171094064 + 42,268.27946411286842679890715 \times i$
$\zeta_7^{(2)}$	$10,470.78502392132516903681496 + 0 \times i$
$\zeta_8^{(2)}$	$22,153.98207243945655027389363 - 18,201.65072991473532250086939 \times i$
$\zeta_9^{(2)}$	$22,153.98207243945655027389363 + 18,201.65072991473532250086939 \times i$

Table 5. Parallel numerical scheme residual error comparison NN, MN₁–MN₃.

Method	CPU-Time	$e_1^{(2)}$	$e_2^{(2)}$	$e_3^{(2)}$	$e_4^{(2)}$	$e_5^{(2)}$	$e_6^{(2)}$	$e_7^{(2)}$	
NN	4.547	0.1×10^{-11}	3.6×10^{-12}	3.9×10^{-10}	3.3×10^{-12}	1.0×10^{-10}	3.0×10^{-11}	3.0×10^{-11}	
MN ₁	1.547	1.1×10^{-114}	3.2×10^{-85}	3.3×10^{-113}	3.6×10^{-114}	3.0×10^{-110}	3.6×10^{-98}	0.0	
MN ₂	1.320	1.3×10^{-224}	1.0×10^{-115}	3.0×10^{-114}	1.6×10^{-118}	0.1×10^{-117}	6.9×10^{-115}	0.0	
MN ₃	1.016	1.0×10^{-214}	3.0×10^{-115}	1.0×10^{-123}	3.5×10^{-117}	3.0×10^{-114}	2.0×10^{-101}	0.0	
Residual errors for finding of all multiple roots of polynomial of degree 10200 with 21 multiple roots									
NN	41.406	3.0×10^{-3}	3.6×10^{-3}	1.0×10^{-9}	3.0×10^{-3}	3.1×10^{-2}	2.0×10^{-3}	4.8×10^{-7}	
MN ₁	12.510	5.5×10^{-18511}	3.7×10^{-3661}	3.0×10^{-3224}	3.0×10^{-1192}	2.0×10^{-498}	1.1×10^{-1518}	2.5×10^{-3866}	
MN ₂	11.320	3.3×10^{-17588}	3.8×10^{-2661}	3.6×10^{-3224}	0.9×10^{-1214}	5.5×10^{-385}	1.0×10^{-1517}	5.0×10^{-3513}	
MN ₃	13.033	3.6×10^{-14561}	3.9×10^{-4125}	3.6×10^{-3112}	0.8×10^{-2112}	2.6×10^{-396}	3.6×10^{-1311}	3.6×10^{-1501}	
$e_8^{(2)}$	$e_9^{(2)}$	$e_{10}^{(2)}$	$e_{11}^{(2)}$	$e_{12}^{(2)}$	$e_{13}^{(2)}$	$e_{14}^{(2)}$	$e_{15}^{(2)}$	$e_{16}^{(2)}$	$e_{17}^{(2)}$
2.0×10^{-12}	2.3×10^{-12}	1.3×10^{-101}	0.0	0.0	0.0	0.0	0.2×10^{-102}	9.3×10^{-90}	8.9×10^{-112}
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	9.5×10^{-201}
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	2.2×10^{-121}
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	3.1×10^{-131}
using MN1-3, NN									
1.0×10^{-3}	3.9×10^{-2}	9.3×10^{-1014}	3.6×10^{-3145}	9.1×10^{-1112}	0.0	0.0	0.0	6.0×10^{-1103}	7.8×10^{-330}
0.0	0.0	9.0×10^{-3215}	4.9×10^{-4120}	7.8×10^{-1125}	0.0	0.0	0.0	0.0	8.2×10^{-1205}
0.0	0.0	5.6×10^{-5125}	0.5×10^{-4412}	8.1×10^{-1225}	0.0	0.0	0.0	0.0	3.6×10^{-1225}
0.0	0.0	1.2×10^{-6132}	5.9×10^{-4}	4.5×10^{-4255}	0.0	0.0	0.0	0.0	4.6×10^{-1135}
		$e_{18}^{(2)}$			$e_{19}^{(2)}$			$e_{20}^{(2)}$	$e_{21}^{(2)}$
		7.8×10^{-91}			1.0×10^{-107}			9.8×10^{-112}	9.2×10^{-111}
		8.7×10^{-108}			3.5×10^{-158}			9.6×10^{-319}	3.2×10^{-113}
		1.2×10^{-228}			1.0×10^{-118}			3.2×10^{-319}	1.3×10^{-103}
		1.0×10^{-128}			9.0×10^{-128}			1.2×10^{-219}	1.1×10^{-123}
respectively.									
		6.3×10^{-2001}			3.6×10^{-1152}			6.3×10^{-3011}	3.6×10^{-1222}
		0.0			9.8×10^{-50122}			7.2×10^{-4513}	4.5×10^{-4135}
		0.0			8.0×10^{-50145}			3.3×10^{-4873}	1.2×10^{-4014}
		0.0			9.8×10^{-50143}			0.3×10^{-4713}	3.2×10^{-4781}

Table 6. Approximate roots of the $f_3(\zeta)$ utilising MN₁–MN₃ up-to 25 decimal places.

Roots	Approximate Roots after Second Iteration Using Simultaneous Methods MN₁-MN₃
$\zeta_1^{(2)}$	$3.9999999999999999999999862205 - 2.534958216275585934291378436 \times 10^{-22} \times i$
$\zeta_2^{(2)}$	$- 0.999999999999999999999999893629 - 5.690633353809298633369220348 \times 10^{-26} \times i$
$\zeta_3^{(2)}$	$1.999999999999999999999989781561 + 2.614467550760436593548580136 \times 10^{-20} \times i$
$\zeta_4^{(2)}$	$- 1.9999999999999999999999930336 + 3.160564818685589784758770362 \times 10^{-23} \times i$
$\zeta_5^{(2)}$	$- 2.323214931157996872628855725 \times 10^{-21} + 2.000000000000000000000342 \times i$
$\zeta_6^{(2)}$	$- 2.529298089824518863489277124 \times 10^{-22} - 1.99999999999999999999938556 \times i$
$\zeta_7^{(2)}$	$1.023976376364266788722524957 \times 10^{-21} + 3.00000000000000000000005376510 \times i$
$\zeta_8^{(2)}$	$- 2.840865161134075189641229891 \times 10^{-24} - 2.99999999999999999999993380 \times i$
$\zeta_9^{(2)}$	$- 1.0011529 + 2.0000000000000000000000000000280 \times i$
$\zeta_{10}^{(2)}$	$- 0.999999999999999999999999997808790 - 2.000000000000000000000000000105176 \times i$
$\zeta_{11}^{(2)}$	$- 1.0003310 + 0.999999999999999999999999960241 \times i$
$\zeta_{12}^{(2)}$	$- 1.0005614 - 1.00000000000000000000000000001786 \times i$
$\zeta_{13}^{(2)}$	$0.9999999999999999999999998888888966375 + 0.9999999999999999999999997438242 \times i$
$\zeta_{14}^{(2)}$	$1.0004082 - 0.999999999999999999999999976687 \times i$
$\zeta_{15}^{(2)}$	$2.000304411 + 1.00000000000000000000000000001584937 \times i$
$\zeta_{16}^{(2)}$	$2.00050095 - 0.9999999999999999999999999538760 \times i$
$\zeta_{17}^{(2)}$	$1.007480959 + 3.000000000000000000000000000012531548 \times i$
$\zeta_{18}^{(2)}$	$0.99999999999999999999999999676240 - 3.00014860 \times i$
$\zeta_{19}^{(2)}$	$6.7038343474826752003668885234 \times 10^{-21} + 4.00000000000000000000000000005924627 \times i$
$\zeta_{20}^{(2)}$	$10.593133679422746292651200009402 - 3.19174226899999915825206220041498 \times i$
$\zeta_{21}^{(2)}$	$1.00032127 - 5.51392157952973235574917078 \times 10^{-24} \times i$

Table 7. Parallel numerical scheme residual error comparison NN, MN₁–MN₃.

Method	CPU-Time	$\mathbf{e}_1^{(2)}$	$\mathbf{e}_2^{(2)}$	$\mathbf{e}_3^{(2)}$	$\mathbf{e}_4^{(2)}$
NN	0.235	3.1×10^{-27}	0.0	2.1×10^{-41}	0.0
MN ₁	0.201	0.0	0.0	0.0	0.0
MN ₂	0.211	0.0	0.0	0.0	0.0
MN ₃	0.191	0.0	0.0	0.0	0.0
Simultaneous finding of all multiple roots					
NN	0.335	1.2×10^{-1105}	0.0	1.2×10^{-1613}	0.0
MN ₁	0.101	7.2×10^{-2114}	1.2×10^{-3801}	1.2×10^{-5305}	5.2×10^{-6662}
MN ₂	0.121	5.2×10^{-2100}	4.2×10^{-3710}	3.2×10^{-5211}	6.2×10^{-6653}
MN ₃	0.311	9.2×10^{-2100}	7.2×10^{-3601}	1.9×10^{-5305}	8.2×10^{-6714}

Table 8. Approximate roots of the $f_4(\zeta)$ utilising MN₁–MN₃ up-to 25 decimal places.

[illegible]

Table 9. Parallel numerical scheme residual error comparison NN, MN₁–MN₃.

Method	CPU-Time	$e_1^{(2)}$	$e_2^{(2)}$	$e_3^{(2)}$	$e_4^{(2)}$	$e_5^{(2)}$	$e_6^{(2)}$	$e_7^{(2)}$
NN	0.235	0.3×10^{-87}	3.0×10^{-91}	1.0×10^{-90}	4.3×10^{-93}	5.0×10^{-83}	2.1×10^{-12}	2.1×10^{-72}
MN ₁	0.201	7.3×10^{-101}	3.2×10^{-101}	2.0×10^{-110}	1.3×10^{-125}	3.4×10^{-137}	6.0×10^{-112}	0.3×10^{-101}
MN ₂	0.211	1.7×10^{-111}	0.1×10^{-101}	1.2×10^{-101}	5.5×10^{-225}	7.6×10^{-134}	8.0×10^{-112}	9.3×10^{-104}
MN ₃	0.191	8.3×10^{-111}	9.0×10^{-111}	2.1×10^{-101}	4.3×10^{-125}	3.0×10^{-132}	2.8×10^{-112}	8.3×10^{-101}
	$e_8^{(2)}$	$e_9^{(2)}$	$e_{10}^{(2)}$	$e_{11}^{(2)}$	$e_{12}^{(2)}$	$e_{13}^{(2)}$	$e_{14}^{(2)}$	$e_{15}^{(2)}$
	2.1×10^{-82}	2.5×10^{-73}	9.3×10^{-74}	3.0×10^{-77}	2.1×10^{-73}	1.3×10^{-112}	3.0×10^{-98}	2.0×10^{-85}
	6.1×10^{-114}	7.0×10^{-113}	8.3×10^{-115}	3.5×10^{-117}	2.2×10^{-114}	9.3×10^{-117}	9.0×10^{-111}	2.9×10^{-135}
	3.3×10^{-131}	5.8×10^{-101}	1.5×10^{-110}	3.3×10^{-118}	0.6×10^{-115}	6.3×10^{-119}	0.9×10^{-112}	5.0×10^{-131}
	9.0×10^{-120}	7.6×10^{-100}	7.3×10^{-115}	6.0×10^{-120}	1.7×10^{-116}	7.3×10^{-121}	4.4×10^{-115}	2.5×10^{-117}
	$e_{16}^{(2)}$			$e_{17}^{(2)}$			$e_{18}^{(2)}$	
	1.3×10^{-95}			3.0×10^{-95}			5.0×10^{-91}	
	2.3×10^{-111}			9.0×10^{-102}			0.1×10^{-119}	
	1.3×10^{-115}			5.8×10^{-113}			2.9×10^{-203}	
	5.3×10^{-101}			3.9×10^{-114}			8.0×10^{-117}	

Table 10. Approximate roots of the $f_5(\zeta)$ utilising MN₁–MN₃ up-to 25 decimal places.

Roots	Approximate Roots after Second Iteration Using Simultaneous Methods MN ₁ –MN ₃
$\zeta_1^{(2)}$	$0.8603435385822107751310968108 + 1.854362078138018927197345307 \times i$
$\zeta_2^{(2)}$	$0.8603435385824826826164634926 - 1.854362078137389759121145467 \times i$
$\zeta_3^{(2)}$	$-0.8603435385824826826191976484 + 1.854362078137389759116467203 \times i$
$\zeta_4^{(2)}$	$-0.8603435385824826826250491509 - 1.854362078137389758498169291 \times i$
$\zeta_5^{(2)}$	$2.099515617155402337664929826 + 2.0018942089444809594275 \times 10^{-25} \times i$
$\zeta_6^{(2)}$	$-2.099515617155402337664930488 + 8.500261481816581859095 \times 10^{-65} \times i$
$\zeta_7^{(2)}$	$-0.1153355754810685747732055498 - 0.9452308584818627592298044050 \times i$
$\zeta_8^{(2)}$	$5.735924944438839111033359624 + 9.9691958921656837672916427681 \times i$
$\zeta_9^{(2)}$	$2.780333195217222311406266628 + 1.5314159752240276458048625411 \times i$
$\zeta_{10}^{(2)}$	$10.38458363502628061602412598 - 2.2689074595992585372659252860 \times i$
$\zeta_{11}^{(2)}$	$-2.889237782026642801550622077 + 1.387876808887673226733098622 \times i$
$\zeta_{12}^{(2)}$	$-2.889237274653490024449890492 - 1.387876796309858631439562289 \times i$
$\zeta_{13}^{(2)}$	$2.378876612988062257880708956 + 3.4667457639218525242487229114 \times i$
$\zeta_{14}^{(2)}$	$2.378876612988074253739225478 - 3.4667457639218476882627822682 \times i$
$\zeta_{15}^{(2)}$	$-2.378876612988074361358332472 + 3.466745763921847828159258028 \times i$
$\zeta_{16}^{(2)}$	$-2.378876615468194672405838207 - 3.466745742882904234182513076 \times i$
$\zeta_{17}^{(2)}$	$-1.705508831120901418129885320 \times 10^{-50} + 3.1838193018332206021608 \times i$
$\zeta_{18}^{(2)}$	$2.684827765525257608577503573 \times 10^{-34} - 3.18381930183322060216087 \times i$

Table 11. Parallel numerical scheme residual error comparison NN, MN₁–MN₃.

Method	CPU-Time	$e_1^{(2)}$	$e_2^{(2)}$	$e_3^{(2)}$	$e_4^{(2)}$	$e_5^{(2)}$	$e_6^{(2)}$	$e_7^{(2)}$	$e_8^{(2)}$
NN	3.547	1.0×10^{-57}	3.1×10^{-40}	8.4×10^{-51}	6.6×10^{-52}	1.1×10^{-47}	0.1×10^{-51}	3.1×10^{-47}	0.1×10^{-59}
MN ₁	1.201	0.0	8.4×10^{-61}	8.4×10^{-62}	9.6×10^{-62}	1.6×10^{-62}	0.1×10^{-62}	3.1×10^{-63}	6.1×10^{-62}
MN ₂	2.201	1.5×10^{-61}	5.2×10^{-64}	5.5×10^{-61}	0.9×10^{-62}	0.1×10^{-62}	9.1×10^{-62}	6.1×10^{-65}	7.1×10^{-62}
MN ₃	2.101	0.0	7.1×10^{-60}	54×10^{-64}	0.6×10^{-62}	7.1×10^{-62}	9.1×10^{-62}	3.8×10^{-62}	8.1×10^{-62}
	$e_9^{(2)}$			$e_{10}^{(2)}$		$e_{11}^{(2)}$		$e_{12}^{(2)}$	
	3.5×10^{-41}			4.1×10^{-52}		3.4×10^{-57}		3.7×10^{-59}	
	9.5×10^{-63}			9.1×10^{-61}		7.7×10^{-60}		0.7×10^{-63}	
	3.5×10^{-65}			8.1×10^{-62}		3.4×10^{-64}		9.1×10^{-61}	
	1.0×10^{-64}			4.8×10^{-65}		6.4×10^{-67}		6.7×10^{-67}	

KK_D , The ligand-molecule binding in solution to cells dissociation constant in all three directions (M),
 RR_{eq} , the balance quantity of liberated receptors that are on the outside of the cell (# receptors/cell),
 RR_T , the whole amount of receptors on the surface of platelets.

Binding of a multivalent ligand in solution to monovalent receptors on a cell surface.

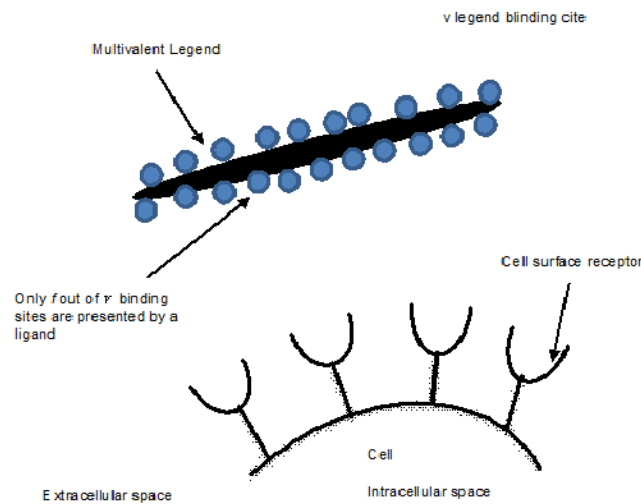


Figure 4. Building of multi-valent legend in solution to univalent receptors on a cell surface.

In order to bind blood platelets cells, a plasma protein known as von Willebrand factor [57] engages in multiple receptor-ligand interactions. The following elements for the von Willebrand factor platelet system are projected:

- (i) $v = 18.00$
- (ii) $f = 9.00$
- (iii) $KK_0 = 7.73 \times 10^{-5} M$,
- (iv) $KK_\zeta = 5.80 \times 10^{-5}$ cell per number of ligands
- (v) $LL_0 = 2.0 \times 10^{-9} M$
- (vi) $RR_T = 10,688.00$ number of receptor per cell

By replacing R_{eq} with ζ in a platelet, we want to find the equilibrium concentration RR_{eq} of unbound or free receptors as:

$$f_1(\zeta) = \zeta \left[1 + v \left(\frac{LL_0}{KK_0} \right) (1 + \zeta KK_\zeta)^{f-1} \right] - RR_T = 0,$$

Substituting values of $v, f, KK_D, KK_\zeta, LL_0, RR_T$ in $f_1(\zeta)$ and by simplifying we obtain a nonlinear polynomial of degree 9.0 as:

$$f_2(\zeta) = \zeta \left[1 + 18 \left(\frac{2 \times 10^{-9}}{7.73 \times 10^{-5}} \right) (1 + 5.8 \times 10^{-5} \zeta)^{9-1} \right] - 10688 = 0,$$

or

$$\begin{aligned} f_2(\zeta) = & 5.964127997 \times 10^{-38} \zeta^9 + 8.226383444 \times 10^{-33} \zeta^8 + 4.964196905 \times 10^{-28} \zeta^7 + \\ & 1.711792037 \times 10^{-23} \zeta^6 + 3.689206976 \times 10^{-19} \zeta^5 + 5.088561346 \times 10^{-15} \zeta^4 + \\ & 4.386690815 \times 10^{-11} \zeta^3 + 2.160931436 \times 10^{-7} \zeta^2 + 1.000465718x - 10688. \end{aligned}$$

we take the following initial Gaussed values:

$$\begin{aligned}
\zeta_1^{(0)} &= -69696 - 17330i, \zeta_2^{(0)} = -69696 + 17330i, \zeta_3^{(0)} = -45422 - 41931i, \zeta_4^{(0)} = -45422 + 41931i, \\
\zeta_5^{(0)} &= -2235 - 42268i, \zeta_6^{(0)} = -2235 + 42268i, \zeta_7^{(0)} = 10470, \zeta_8^{(0)} = 22153 - 18201i, \\
\zeta_9^{(0)} &= 22153 + 18201i.
\end{aligned}$$

For the nonlinear problem $f_1(\zeta)$, the numerical results of the iterative schemes MN_1 – MN_3 and NN are shown in Tables 3 and 4, respectively.

The simultaneous NN and MN_1 for solving $f_2(\zeta)$ exhibit fractal behavior, as seen in Figure 5a,b. In comparison to solving fractional order polynomial equations, solving $f_2(\zeta)$ with NN and MN_1 takes 0.016774 s and 0.0145 s, respectively. Furthermore, MN_1 has a far higher convergence rate than NN. In the complex plane, NN converges to 512,412 points while MN_1 converges to 631,243 points out of a total of 640,000. Due to global convergence, MN_2 and MN_3 exhibit the same fractal behavior as MN_1 .

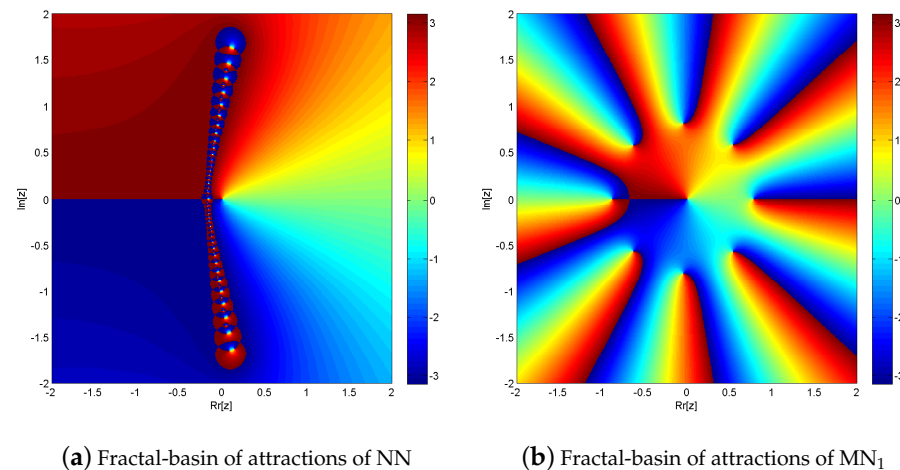


Figure 5. (a,b) shows fractal behavior of NN and MN_1 for solving $f_2(\zeta)$.

Example 2: [58] Standard polynomial of degree 10,000 with 21 multiple roots of multiplicities 600, 100, 100, 200, 200, 200, 200, 300, 300, 400, 400, 500, 500, 600, 600, 700, 700, 800, 800, 900, and 900, respectively.

Consider

$$\begin{aligned}
f_3(\zeta) &= (\zeta - 4)^{600}(\zeta^2 - 1)^{100}(\zeta^4 - 16)^{200}(\zeta^2 + 9)^{300}(\zeta^2 + 16)^{400}(\zeta^2 + 2\zeta + 5)^{500}(\zeta^2 + 2\zeta + 2)^{600} \\
&\quad (\zeta^2 - 2\zeta + 2)^{700}(\zeta^2 - 4\zeta + 5)^{800}(\zeta^2 - 2\zeta + 10)^{900},
\end{aligned}$$

with exact real and complex roots:

$$\begin{aligned}
\zeta_1 &= 4, \zeta_{2,3} = \pm 1, \zeta_{4,5,6,7} = \pm 2, \zeta_{8,9} = \pm 3i, \zeta_{10,11} = \pm 4i, \\
\zeta_{12,13} &= -1 \pm 2i, \zeta_{14,15} = -1 \pm i, \zeta_{16,17} = 1.0 \pm i, -\zeta_{18,19} = 2.0 \pm 1i, \zeta_{20,21} = 1.0 \pm 3.0i.
\end{aligned}$$

The initial guessed values below were randomly selected for global convergence:

$$\begin{aligned}
\zeta_1^{(0)} &= 4.2 + 0.1i, \quad \zeta_2^{(0)} = -1.2 + 0.1i, \quad \zeta_3^{(0)} = 2.2 + 0.1i, \quad \zeta_4^{(0)} = -2.2 - 0.1i, \quad \zeta_5^{(0)} = 0.2 + 2.1i. \\
\zeta_6^{(0)} &= 0.2 + 3.1i, \quad \zeta_7^{(0)} = 0.2 - 3.1i, \quad \zeta_8^{(0)} = -1.2 + 2.1i, \quad \zeta_9^{(0)} = -1.2 - 2.1i, \quad \zeta_{10}^{(0)} = -1.2 - 2.1i. \\
\zeta_{11}^{(0)} &= -1.2 + 1.1i, \quad \zeta_{12}^{(0)} = -1.2 - 1.1i, \quad \zeta_{13}^{(0)} = 1.2 + 1.1i, \quad \zeta_{14}^{(0)} = 1.2 - 1.1i, \quad \zeta_{15}^{(0)} = 2.2 + 1.1i. \\
\zeta_{16}^{(0)} &= 2.2 - 1.1i, \quad \zeta_{17}^{(0)} = 1.2 + 3.1i, \quad \zeta_{18}^{(0)} = 1.2 - 3.1i, \quad \zeta_{19}^{(0)} = 0.2 + 4.1i, \quad \zeta_{20}^{(0)} = 1.2 - 4.1i. \\
\zeta_{21}^{(0)} &= 1.1 + 0.2i,
\end{aligned}$$

For distinct roots:

$$\begin{aligned}
f_{3*}(\zeta) &= (\zeta - 4)^{600}(\zeta^2 - 1)^{100}(\zeta^4 - 16)^{200}(\zeta^2 + 9)^{300}(\zeta^2 + 16)^{400}(\zeta^2 + 2\zeta + 5)^{500}(\zeta^2 + 2\zeta + 2)^{600} \\
&\quad (\zeta^2 - 2\zeta + 2)^{700}(\zeta^2 - 4\zeta + 5)^{800}(\zeta^2 - 2\zeta + 10)^{900}.
\end{aligned}$$

Tables 5 and 6, shows numerical results of iterative schemes MN_1 – MN_3 and NN for nonlinear equation $f_3(\zeta)$, $f_{3*}(\zeta)$, respectively.

The simultaneous NN and MN_1 for solving $f_3(\zeta)$ exhibit fractal behavior, as seen in Figure 6a,b. In comparison to solving fractional order polynomial equations, solving $f_3(\zeta)$ with NN and MN_1 takes 0.008774 s and 0.00135 s, respectively. Furthermore, MN_1 has a far higher convergence rate than NN. In the complex plane, NN converges to 212,413 points while MN_1 converges to 621,345 points out of a total of 640,000. Due to global convergence, MN_2 and MN_3 exhibit the same fractal behavior as MN_1 .

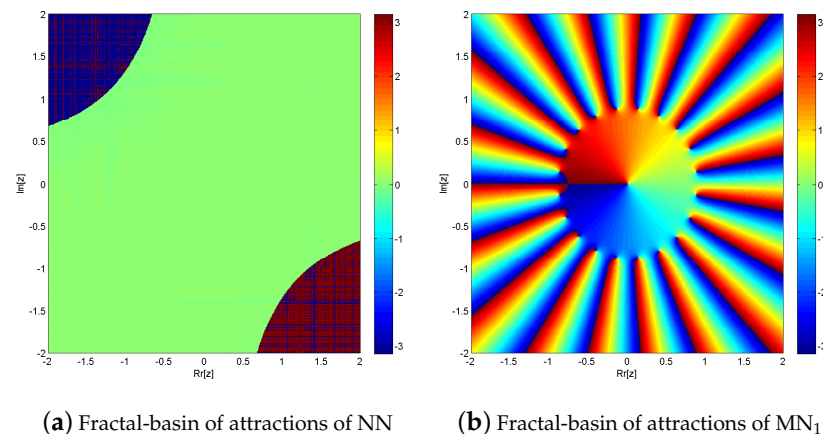


Figure 6. (a,b) shows fractal behavior of NN and MN for solving $f_3(\zeta)$.

Example 3: [58] Standard polynomial of degree 1000 with four multiple roots with multiplicities 100, 200, 300, and 400, respectively.

Consider a problem of beam positioning, resulting a nonlinear polynomial equation given as:

$$f_4(\zeta) = (\zeta - (0.3 + 0.6i))^{100}(\zeta - (0.1 + 0.7i))^{200}(\zeta - (0.7 + 0.5i))^{300}(\zeta - (0.3 + 0.4i))^{400}. \quad (35)$$

The exact roots of (35) are $\xi_1 = 0.3 + 0.6i$, $\xi_2 = 0.1 + 0.7i$, $\xi_3 = 0.7 + 0.5i$, $\xi_4 = 0.3 + 0.4i$. The initial estimates for $f_4(\zeta)$ are:

$$\zeta_1^{(0)} = 0.301 + 0.601i, \quad \zeta_2^{(0)} = 0.100 + 0.702i, \quad \zeta_3^{(0)} = 0.702 + 0.498i, \quad \zeta_4^{(0)} = 0.289 + 0.400i$$

$$f_{4*}(\zeta) = (\zeta - (0.3 + 0.6i))(\zeta - (0.1 + 0.7i))(\zeta - (0.7 + 0.5i))(\zeta - (0.3 + 0.4i)).$$

Tables 7 and 8, presents the computational outcomes of MN_1 – MN_3 and NN for nonlinear equation $f_4(\zeta)$, $f_{4*}(\zeta)$, respectively.

The simultaneous NN and MN_1 for solving $f_4(\zeta)$ exhibit fractal behavior, as seen in Figure 7a,b. In comparison to solving fractional order polynomial equations, solving $f_4(\zeta)$ with NN and MN_1 takes 0.036774 s and 0.0245 s, respectively. Furthermore, MN_1 has a far higher convergence rate than NN. In the complex plane, NN converges to 610,115 points while MN_1 converges to 637,017 points out of a total of 640,000. Due to global convergence, MN_2 and MN_3 exhibit the same fractal behavior as MN_1 .

Example 4: [58] Standard polynomial of degree 18 with four multiple roots.

A nonlinear polynomial equation for a beam alignment problem is as follows:

$$f_5(\zeta) = \zeta^{18} + 12\zeta^{16} + 268\zeta^{14} + 278\zeta^{12} + 3471\zeta^{10} + 324696\zeta^8 + 620972\zeta^6 - 2270592\zeta^4 - 28303951\zeta^2 - 25704900. \quad (36)$$

The exact roots of (36) are $\xi_{1,2} = -3.06 \pm 1.2i$, $\xi_{3,4} = -2.4 \pm 3.4i$, $\xi_5 = -1.7$, $\xi_{6,7} = -0.6 \pm 2.7i$,

$\xi_{8,9} = \pm 1.8i$, $\xi_{10,11} = \pm 0.9i$, $\xi_{12,13} = -0.6 \pm 2.7i$, $\xi_{14} = 1.7$, $\xi_{15,16} = 2.4 \pm 3.4i$, $\xi_{17,18} = 3.0 \pm 1.2i$.

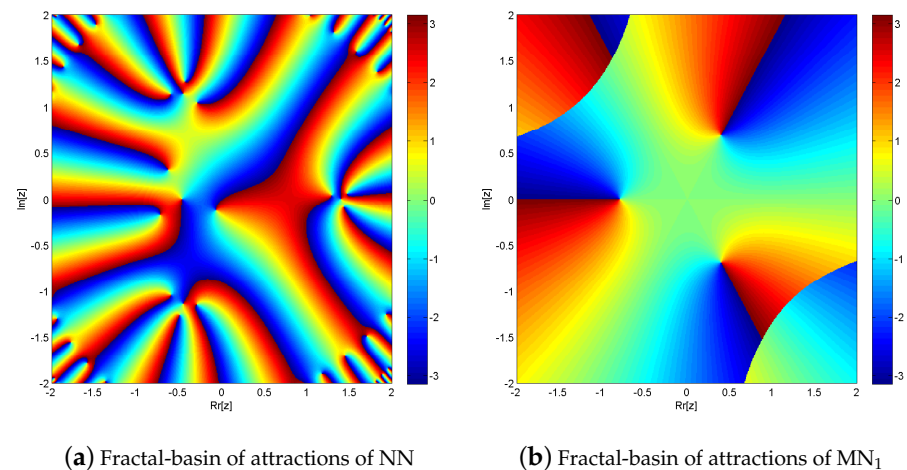


Figure 7. (a,b) shows fractal behavior of NN and MN_1 for solving $f_4(\zeta)$.

The initial estimates for $f_5(\zeta)$ are:

$$\begin{aligned} \zeta_1^{(0)} &= 1.1 + 2.1i, & \zeta_2^{(0)} &= 1.1 - 2.1i, & \zeta_3^{(0)} &= -1.1 + 2.1i, & \zeta_4^{(0)} &= -1.1 - 2.1i, & \zeta_5^{(0)} &= 2.2 + 0.1i. \\ \zeta_6^{(0)} &= -2.1 + 0.1i, & \zeta_7^{(0)} &= -0.2 + 0.9i, & \zeta_8^{(0)} &= 0.2 + 1.1i, & \zeta_9^{(0)} &= 3.1 + 1.9i, & \zeta_{10}^{(0)} &= 3.2 - 1.9i. \\ \zeta_{11}^{(0)} &= -3.2 + 1.9i, & \zeta_{12}^{(0)} &= -3.2 - 1.9i, & \zeta_{13}^{(0)} &= 2.1 + 2.9i, & \zeta_{14}^{(0)} &= 2.1 - 2.9i, & \zeta_{15}^{(0)} &= -2.1 + 2.9i. \\ \zeta_{16}^{(0)} &= -2.1 - 2.9i, & \zeta_{17}^{(0)} &= 0.1 + 3.1i, & \zeta_{18}^{(0)} &= -0.1 - 2.9i. \end{aligned}$$

Tables 9 and 10, shows numerical results of iterative schemes MN_1 – MN_3 and NN for nonlinear equation $f_5(\zeta)$, respectively.

The simultaneous NN and MN_1 for solving $f_5(\zeta)$ exhibit fractal behavior, as seen in Figure 8a,b. In comparison to solving fractional order polynomial equations, solving $f_5(\zeta)$ with NN and MN_1 takes 0.041294 s and 0.0215445 s, respectively. Furthermore, MN_1 has a far higher convergence rate than NN. In the complex plane, NN converges to 217,615 points while MN_1 converges to 621,971 points out of a total of 640,000. Due to global convergence, MN_2 and MN_3 exhibit the same fractal behavior as MN_1 .

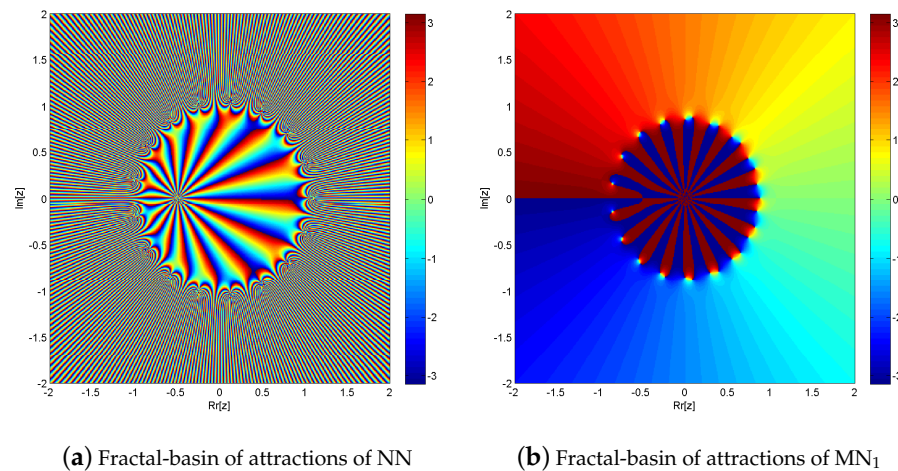


Figure 8. (a,b) shows fractal behavior of NN and MN₁ for solving $f_5(\zeta)$.

Example 5: [58] Standard polynomial of degree 12 with two multiple roots with multiplicity 2 and 8 distinct roots.

Consider the nonlinear polynomial equation:

$$f_6(\zeta) = \zeta^{12} - (2 + 5i)\zeta^{11} - (1 - 10i)\zeta^{10} + (12 - 25i)\zeta^9 - 30\zeta^8 - \zeta^4 + (2 + 5i)\zeta^3 + (1 - 10i)\zeta^2 - (12 - 25i)\zeta + 30. \quad (37)$$

The exact roots of (37) are $\zeta_{1,2} = \frac{\sqrt{2}}{2} \pm \frac{\sqrt{2}}{2}i$, $\zeta_{3,4} = -\frac{\sqrt{2}}{2} \pm \frac{\sqrt{2}}{2}i$, $\zeta_{5,6} = 1 \pm 2i$, $\zeta_{7,8} = \pm i$, $\zeta_9 = 2i$, $\zeta_{10} = 3i$, $\zeta_{11,12} = \pm 1$.

The initial estimates for $f_6(\zeta)$ are:

$$\begin{aligned} \zeta_1^{(0)} &= 1.30 + 0.2i, \quad \zeta_2^{(0)} = -1.3 + 0.2i, \quad \zeta_3^{(0)} = -0.30 - 1.20i, \quad \zeta_4^{(0)} = -0.30 + 1.20i, \quad \zeta_5^{(0)} = 0.5 + 0.5i, \\ \zeta_6^{(0)} &= 0.50 - 0.5i, \quad \zeta_7^{(0)} = -0.5 + 0.5i, \quad \zeta_8^{(0)} = -0.5 - 0.50i, \quad \zeta_9^{(0)} = 0.2 + 2.2i, \quad \zeta_{10}^{(0)} = 0.20 + 2.30i, \\ \zeta_{11}^{(0)} &= 1.30 + 2.20i, \quad \zeta_{12}^{(0)} = 1.3 - 2.20i, \end{aligned}$$

Tables 11 and 12, shows numerical results of iterative schemes MN₁–MN₃ and NN for nonlinear equation $f_6(\zeta)$, respectively.

The simultaneous NN and MN₁ for solving $f_6(\zeta)$ exhibit fractal behavior, as seen in Figure 9a,b. In comparison to solving fractional order polynomial equations, solving $f_6(\zeta)$ with NN and MN₁ takes 0.0745321 s and 0.0349 s, respectively. Furthermore, MN₁ has a far higher convergence rate than NN. In the complex plane, NN converges to 572,416 points while MN₁ converges to 635,097 points out of a total of 640,000. Due to global convergence, MN₂ and MN₃ exhibit the same fractal behavior as MN₁.

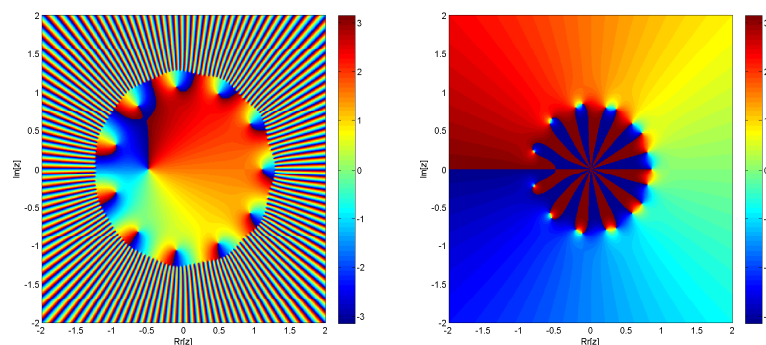
Example 6. Model of Blood Rheology [59,60] Blood, a non-Newtonian fluid, is modeled using the Casson Fluid. Based to the Casson fluid model, an elementary fluid, like bloodstream, is going to move through a tube so that the gradient in velocity happens near the wall and the center portion of the fluid goes as a lump with little deformation.

We developed the plug flow of Casson fluids [60] using the following nonlinear polynomial equation, where flow rate reduction is measured by

$$G = 1 - \frac{16}{7}\sqrt{\zeta} + \frac{4}{3}\zeta - \frac{1}{21}\zeta^4, \quad (38)$$

or where reduction in flow rate is measured by G . Using $G = 0.40$ in (38), we have:

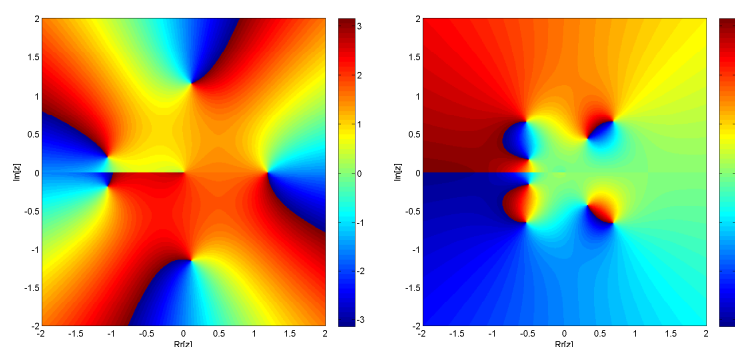
$$f_7(\zeta) = \frac{1}{441}\zeta^8 - \frac{8}{63}\zeta^5 - 0.05714285714\zeta^4 + \frac{16}{9}\zeta^2 - 3.624489796\zeta + 0.36. \quad (39)$$



(a) Fractal-basin of attractions of NN (b) Fractal-basin of attractions of MN₁

Figure 9. (a,b) shows fractal behavior of NN and MN₁ for solving $f_6(\zeta)$.

The simultaneous NN and MN₁ for solving $f_7(\zeta)$ exhibit fractal behavior, as seen in Figure 10a,b. In comparison to solving fractional order polynomial equations, solving $f_7(\zeta)$ with NN and MN₁ takes 0.016774 s and 0.0145 s, respectively. Furthermore, MN₁ has a far higher convergence rate than NN. In the complex plane, NN converges to 630,819 points while MN₁ converges to 639,514 points out of a total of 640,000. Due to global convergence, MN₂ and MN₃ exhibit the same fractal behavior as MN₁.



(a) Fractal-basin of attractions of NN (b) Fractal-basin of attractions of MN₁

Figure 10. (a,b) shows fractal behavior of NN and MN₁ for solving $f_7(\zeta)$.

The exact roots of (38) are:

$$\begin{aligned}\zeta_1 &= 0.1046986515, \zeta_2 = 3.822389235, \zeta_3 = 1.553919850 + 0.9404149899i, \\ \zeta_4 &= -1.238769105 + 3.408523568i, \zeta_5 = -2.278694688 + 1.987476450i \\ \zeta_6 &= -2.278694688 - 1.987476450i, \zeta_7 = -1.238769105 - 3.408523568, \\ \zeta_8 &= 1.553919850 - 0.9404149899.\end{aligned}$$

we take the following initial guesses:

$$\begin{aligned}\zeta_1^{(0)} &= 0.1, \zeta_2^{(0)} = 3.8, \zeta_3^{(0)} = 1.5 + 0.9i, \zeta_4^{(0)} = 1.2 + 3.4i, \\ \zeta_5^{(0)} &= -2.2 + 1.9i, \zeta_6^{(0)} = -2.2 - 1.9i, \zeta_7^{(0)} = -1.2 - 3.4i, \zeta_8^{(0)} = 1.5 + 0.9i.\end{aligned}$$

Table 13, shows numerical results of iterative schemes MN₁–MN₃ and NN for nonlinear equation $f_7(\zeta)$, respectively.

Figure 11a–f, shows the residual error graph of the simultaneous method MN₁–MN₃ and NN for polynomial equations used in examples 1–6, respectively.

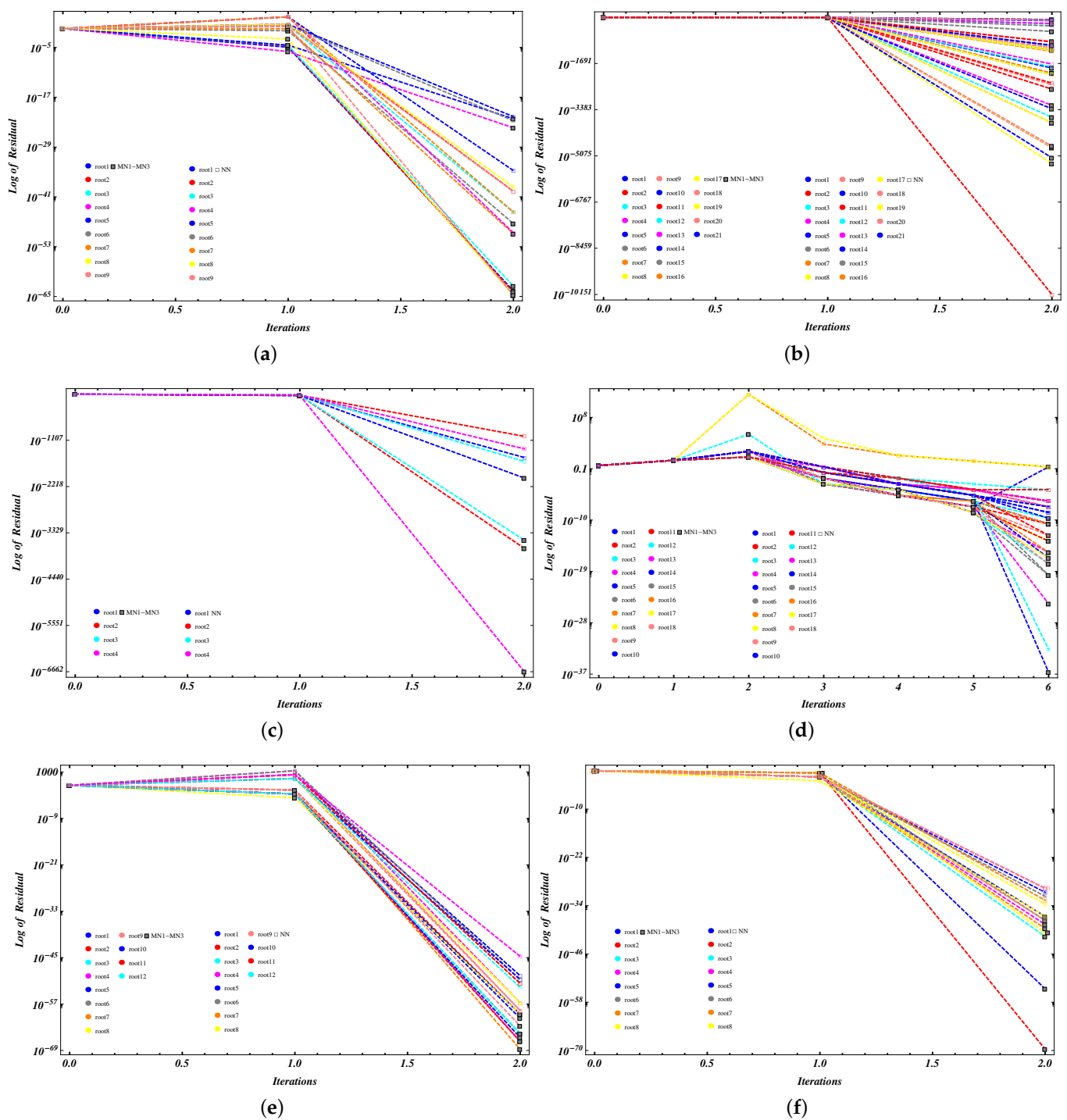


Figure 11. (a–f) shows the residual error graph of the simultaneous method MN₁-MN₃ and NN for polynomial equations used in examples 1–6, respectively.

5. Conclusions

Here, we have developed three families of simultaneous methods of convergence order seventeenth for finding all the real, complex, distinct, and multiple roots of (1). Fractal behavior from Figures 1–10 of simultaneous schemes is explored in detail, and it is discovered that in terms of convergence divergence region, our newly created methods MN₁-MN₃ converge to more points than NN methods while using less elapsed time. The fractal behavior of simultaneous techniques clearly indicated that the newly developed methods are more stable, consistent, and reliable than existing methods N1–N3 and NN for solving

nonlinear complex engineering problems. The numerical results from Tables 1–13, and Figure 11a–f, show that the newly developed technique MN_1 – MN_3 outperforms existing method NN in terms of computational cost, efficiency, CPU-time, and residual errors. In the future, we construct higher order efficient, optimal, and stable iterative methods for finding simple as well as all distinct and multiple roots of (1).

In the future, we will develop and generalize higher-order simultaneous methods for solving linear and nonlinear systems of equations. We may also explore the applications of these results in other areas. For example, the dynamics nonlinear inventory management system, numerical solution of fractional SIR epidemiological model, stability and optimal control strategies for a novel epidemic model [61,62] of COVID-19.

Author Contributions: Conceptualization, M.S. and B.C.; methodology, M.S. and N.R.; software, M.S.; validation, M.S.; formal analysis, B.C. and N.A.M.; investigation, M.S.; resources, B.C.; writing—original draft preparation, M.S. and B.C.; writing—review and editing, B.C.; visualization, M.S. and B.C.; supervision, B.C.; project administration, B.C.; funding acquisition, B.C. All authors have read and agreed to the published version of the manuscript.

Funding: The work is supported by Provincia autonoma di Bolzano/Alto Adigeà euro Ripartizione Innovazione, Ricerca, Università e Musei (contract nr. 19/34). Bruno Carpentieri is a member of the Gruppo Nazionale per il Calcolo Scientifico (GNCS) of the Istituto Nazionale di Alta Matematica (INdAM) and this work was partially supported by INdAM-GNCS under Progetti di Ricerca 2022.

Data Availability Statement: Data are contained within the article.

Conflicts of Interest: The authors declare that there are no conflicts of interest regarding the publication of this article.

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