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Grain-Size Effects on Multi-Wire Slurry Sawing of Translucent Alumina Ceramics

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Abstract: The technology of multi-wire sawing is well established in the production of silicon wafers but can also be applied in the production of ceramic substrates. In this study, the influence of the Al_2O_3 -grain size of the alumina ceramic on the efficiency of the multi-wire slurry process was investigated. The grain size of HIPed alumina ceramics was changed by heat treatment processes at 1350 °C and 1400 °C. A B₄C slurry was used for the investigation of the cutting of high purity alumina ceramic. With increasing grain size of the ceramic, the efficiency of the sawing process increases. The analysis of the as-cut surface morphology of the substrates shows a change in material removal from trans- to intergranular micro-fracture with increasing grain size. Furthermore, grain coarsening leads to substrates with increased roughness values and reduced biaxial strength.

Keywords: multi-wire sawing; translucent alumina ceramics; microstructure; mechanical properties; material removal; bow of wire web

1. Introduction

Multi-wire sawing has become the leading technology in wafer production for semiconductor materials. Substrates of other materials such as ceramics are also required. Alumina ceramic substrates are used for sensor applications, energy storage technology, and applications in power electronics [1,2]. Therefore, multi-wire sawing is a potential technology to produce such components. The main advantages of multi-wire slurry sawing are the low heat dissipation during machining, resulting in a low surface damage depth and the small material kerf width due to wire diameters ≤ 0.3 mm. In analogy to lapping or polishing, low surface roughness can be achieved with properly adjusted machining parameters [3]. A schematic drawing of a multi-wire slurry saw is shown in Figure 1. The rotation of the wire guide rollers accelerates the wire as the top plate presses the workpiece onto the wire field. The mixture adheres to the wires, is carried along by the wire speed, and is fed into the workpiece. The forced movement of the abrasive particles in the sawing channel causes the chipping of the material. The sawing channel, which is constantly deepened by the material removal, leads to separate ceramic substrates at the end of a sawing process [4].



Figure 1. Wire guide rollers; 2: Fresh wire; 3: Wire web; 4: Workpiece; 5: Top plate; 6: Slurry nozzles; 7: Used wire [5].

A detailed parameter study on the most important machine process and workpiece geometry parameters for multi-wire sawing of translucent, fine-grained high-density alumina ceramics is published in [6]. It was observed that a larger workpiece length, a higher number of wafers, and the abrasive particle size reduction lead to a decreased cutting rate in the sawing process and therefor longer process times. A maximum feed rate of 18 μ m/min could be applied under the investigated conditions, which are much lower than typical (feed rates for Silicon >700 μ m/min [7]). The substrates showed a high surface quality (roughness values R_a 0.2–0.3 μ m, biaxial strength >1000 MPa). The results show that translucent alumina ceramics with extreme hardness and wear resistance represent a major challenge for the multi-wire sawing process. However, no data concerning the influence of the microstructure on the cutting process exist. Therefore, the aim of this study was the investigation of the influence of the alumina grain size on the multi-wire slurry sawing process.

2. Materials and Methods

2.1. Materials and Characterization Methods

To determine the influence of the ceramic grain size on the multi-wire sawing process, heat treatments were conducted to coarsen the grain size of the alumina ceramic. The heat treatment processes were run in a tube furnace (RHT08/17, Nabertherm, Lilienthal, Germany). The original material was post-sintered at 1350 °C and 1400 °C in an air atmosphere with a holding time of 1 h and a heating and cooling rate of 3 K/min. The density of the samples was measured with the Archimedes method and the hardness by Vicker's indentation tests (according to DIN EN 843-4). K_{IC} was estimated by the Vicker's indentation fracture toughness test using the formula of Niihara (HP) [8]. The microstructure, chemical composition, and surface texture were examined using a scanning electron microscope (NVision 40, Carl Zeiss Microscopy GmbH, Oberkochen, Germany) with a field emission cathode (FESEM) and an energy dispersive detector of characteristic X-rays (EDX). The mean grain diameter was measured by the linear intercept method on images of polished cross-the sections (>300 grains, 4 SEM-micrographs at a magnification of 7500×). The biaxial strength was tested on the cut substrates with ball on three balls testing [9,10] with a loading rate of 0.5 mm/min, the radius of the ball of 3.175 mm, the radius of supporting balls of 5 mm and a sample size of 20 × 20 × thickness of the substrate (approx.: 0.23 mm). The Weibull modulus was determined according to DIN EN 843-5.

2.2. Experimental Multi-Wire Sawing Procedure

The multi-wire sawing processes were conducted on a multi-wire slurry saw (DS265, Meyer and Burger, Thun, Switzerland). The sawing parameters of the experiment are listed in Table 1. A standard structured steel wire (coating: copper, zinc) with a nominal diameter of 115 μ m was used. Boron-carbide grains with the size F-400 were used as a cutting agent in the loose abrasive slurry. The B₄C abrasive size and distribution were measured with a laser diffraction particle size analyzer (LS 13 320, Beckman Coulter, Brea, CA, USA).

Sawing Parameters	
Wire condition	New
Wire speed (m/s)	14
Wire tension (N)	25
Pitch (mm)	0.425
Number of substrates cut in one process	17
Wire nominal diameter (mm)	0.115
Nominal B_4C abrasive size (µm)	8-32
Table feed rate (mm/min)	0.02
B/F ratio	0.64

Table 1. Common process parameter	Table 1.	1. Common	process	parameter
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In the DS265 a multi-component dynamometer is used to determine the force profile during the process (sensor is mounted between the beam and the traversing unit). The force sensor provides reliable data for a feed speed >0.1 mm/min. The alumina ceramic was cut with a feed speed of 0.02 mm/min due to the high hardness and wear resistance. Therefore, it could not be used to characterize the cutting processes. The bow of the wire web was used instead to analyze the cutting behavior, as already described in [6]. If the wire is in contact with the workpiece and the cutting speed is lower than the feed speed (constant control parameter), a bow of the wire web will form under the workpiece (Figure 2). The size of the wire bow is an indicator of the cutting rate of a material. The smaller the bow, the better the cutting ability.



Figure 2. Wire bow (length); 2: Feed direction; 3: Compact part of the workpiece; 4: Processed part of the workpiece [6].

In this study, the influence of ceramic grain size on the wire bow was tested. Therefore, alumina ceramic blocks with a d_{50} -grain size of 0.44, 0.64, and 0.90 µm were used for cutting. After a feed length of 25 mm, the process is stopped, and the workpiece is moved out of the wire web. A feed length of 25 mm is needed to guarantee a constant material removal rate with a stable size of the bow (steady-state level). The length of the repositioning movement of the workpiece against the feed direction, until the wire web is strait (measuring error: $\pm 50 \text{ µm}$) represents the bow of the wire web. The experimental routine and the sawing parameters are previously described in [6].

The surface roughness and thickness of the ceramic substrates (17 substrates per sample) were characterized by an optical profilometer (MicroProf R 300, FRT GmbH, Bergisch Gladbach, Germany). The optical profilometer has a lateral resolution of 2 μ m and a vertical resolution of 6 nm. The roughness values were calculated according to the standard DIN EN ISO 4287. To efficiently characterize the surface morphology, roughness measurements along lines with a length of 5.6 mm were carried out per substrate. One line was measured parallel to the wire movement direction (Ra ||) and one perpendicular to it (Ra \perp).

3. Results

3.1. Microstructure and Properties of the Alumina Ceramic

The main properties of the original and grain coarsened Al_2O_3 -ceramics samples are listed in Table 2.

	Original	Heat Treatment 1	Heat Treatment 2
Process	HIP Al ₂ O ₃	HIP Al ₂ O ₃	HIP Al ₂ O ₃
Sample name	O1	HT1350	HT1400
Additional heat treatment temperature (°C)	-	1350	1400
Density (g/cm ³)	3.98 ± 0.01	3.98 ± 0.01	3.98 ± 0.01
Grain size d_{50} -value (µm)	0.44 ± 0.03	0.64 ± 0.06	0.90 ± 0.05
Vicker's hardness			
HV _{0.5}	2279 ± 1	2139 ± 23	2142 ± 23
HV_1	2220 ± 5	2060 ± 18	2027 ± 25
HV ₂	2168 ± 13	2059 ± 23	1980 ± 15
K _{IC} (Niihara HP; HV ₁) (MPa*m ^{0.5})	3.5 ± 0.2	3.4 ± 0.1	2.8 ± 0.2
Characteristic biaxial strength of the cut substrates (Mpa)	1356 (1328-1386)	1144 (1116-1173)	1033 (1008–1059)
Weibull modulus	16.3 ± 3.5	14.2 ± 4.0	14.0 ± 3.0
Surface roughness of the cut substrates			
$Ra \perp (\mu m)$	0.23 ± 0.01	0.32 ± 0.03	0.33 ± 0.02
Ra (μm)	0.23 ± 0.01	0.36 ± 0.08	0.33 ± 0.02
$Rz \perp (\mu m)$	1.70 ± 0.09	2.04 ± 0.53	3.00 ± 0.54
Rz (μm)	1.62 ± 0.09	2.18 ± 0.50	2.84 ± 0.62

Table 2. Mechanical properties of the original and grain coarsened Al₂O₃-ceramics.

Figures 3 and 4 show the SEM-micrographs of the polished cross-sections and Figure 5 summarizes the results of the grain size analysis. The d_{50} -grain size of the HT1400 sample is doubled by the heat treatment temperature of 1400 °C for 1 h in comparison to the O1 material, from 0.44–0.90 µm. To inhibit discontinuous grain growths in the manufacturing process of fine-grained, translucent alumina ceramics, magnesium oxide (<1 wt.%) as a sintering additive is used [11]. EDX- measurements show a slightly increased size of MgO-rich-precipitations at grain junctions and triple points with grain coarsening (Figure 4). The MgO-rich-precipitations are found sporadically in the O1 sample and have a size <0.1 µm. In the samples with grain coarsening HT1350 and HT1400 the size of the Mg-rich-precipitations increases to 0.3–0.4 µm.



Figure 3. Field emission scanning electron microscopy (FESEM) images of the polished cross section of the sample: (**a**) O1 [6]; (**b**) HT1350; (**c**) HT1400.

A decrease in the Vicker's hardness of about 10% was measured with increasing grain size in the investigated range of 0.44–0.90 μ m (Figure 6). The hardness measurements for the HV₁ and HV₂ load follow the Hall-Patch relation. The measurement error at a load of HV_{0.5} is increased due to the small indentation size, which limits the accuracy of the measurement. The phenomenon of an increase in hardness with the reciprocal root of the grain size is known as a Hall-Petch-type-relation and is

described in the literature for alumina ceramics with a grain size >0.2 μ m and a load of HV_{0.4-10} [12]. The increasing hardness is based on the increasing dislocation blocking at the grain boundaries with decreasing grain size [13]. The K_{IC}-value decreases from 3.5–2.8 MPa*m^{0.5} with increasing grain size.



Figure 4. Overlay of Mg distribution (EDX, violet color) and electron image of the polished cross section of the sample: (**a**) O1; (**b**) HT1400 (different magnifications were used due to the different grain sizes of the samples).



Figure 5. Influence of the heat treatment temperature on the grain size of alumina ceramic.



Figure 6. Influence of the alumina grain size on the hardness of the sample.

3.2. Influence of the Ceramic Grain Size on the Size of the Wire Bow

The sawing rate was evaluated using the wire bow as described in the experimental section. The original values of the sizes of the wire bows are displayed in Figure 7. The values were measured

after a constant time of 1250 min. These values include not only the influence of the ceramic structure but also the dependence on the B_4C grain size in the slurry since the B_4C wears out during the sawing process. Therefore, the mean grain sizes of the B₄C grits in the slurry differ in the individual experiments. In earlier work, a linear decrease of the $B_4C d_{50}$ -grit size of $-10.2 \mu m$ per sawn m² of O1-material was observed [6]. In this study, an area of 0.032 m^2 is cut in each process, resulting in a decrease of the B₄C d_{50} -grit size of 0.3 µm per sawing process. Due to the small change in grit size, a constant $B_4C d_{50}$ -grit size is assumed during one cut. However, the experiments shown here were not performed directly one after the other resulting in larger deviations of the mean grain sizes of B₄C in the slurry. Therefore, the influence of the grain size must be corrected for a clearer analysis of the data. The grit size of O1 was measured before the process (d_{50} -value of 21.6) and the values at the end of the process of cutting O1 can be estimated at a d_{50} -value of 21.3 µm. After cut #2 (HT1400) a d_{50} -grit size of 15.7 μ m was measured. The decrease in the d₅₀-value of -5.6 μ m is caused by cutting 0.55 m² of O1 material in further processes and cut #2 (HT1400) carried out with the slurry-tank. The degree of wear of the B_4C abrasives required a re-dosing of fresh abrasives into the slurry-tank bevor the cut #3 to ensure process stability. The addition of fresh abrasive grits results in a wider grain size distribution compared to cut #1 and #2 and an increased d₅₀-grit size compared to cut #2. A d₅₀-grit size of 20.8 µm was measured after cut #3 (HT1350). Based on these measurements the following $B_4C d_{50}$ -grit sizes were used for the bow correction:

- d50 = 21.3 μm for cut #1 (O1, d₅₀ alumina grain size: 0.44 μm)
- $d50 = 15.7 \mu m$ for cut #2 (HT1400, d_{50} alumina grain size: 0.90 μm) and
- d50 = 20.8 μm for cut #3 (HT1350, d₅₀ alumina grain size: 0.64 μm).



Figure 7. Influence of the alumina ceramic grain size on the size of the wire bow; regression of original data: $-4.09 (\pm 0.48) \times +4.38 (\pm 0.33)$; COD (r²): 0.98; regression of the corrected data = $-6.60 (\pm 0.48) \times +5.63 (\pm 0.33)$; COD (r²): 0.99).

In our previous experiments with the O1 material [6], it was shown that an increase of the size of the wire bow of 0.2 (\pm 0.1) mm per 1 µm shift of the d₅₀-value B₄C abrasive size occurs. This dependency was used to estimate the bowing caused by the changed abrasive grit size. However, it is not completely clear if this dependency holds also for the other alumina grain sizes but as a simplified estimate, a linear relationship is assumed. The normalized data in Figure 7 are calculated for the constant d₅₀-values of B₄C of 21.3 µm. The correction resulted in bow values of 2.65 mm, 1.53 mm, and -0.37 mm. A negative bow value has no direct physical meaning. However, it does imply that the cutting process can be done at a higher feed rate by using the slurry with the normalized grain size than used in the experiment. The resulting corrected bow of the wire reveals a much stronger dependence of the cutting behavior on the grain size than the original data. The increase of the mean ceramic grain size value by 1 µm reduces the wire bow by 6.60 (\pm 0.48) mm.

At the given feed rate of 20 μ m/min, this corresponds to an increase in the cutting rate from approximately 17.9 μ m/min for the fine-grained material (mean grain size 0.44 μ m) to more than 20 μ m/min for the HT1400 material (mean grain size 0.90 μ m).

3.3. Characterization of the Alumina Ceramic Substrates

Figure 8 shows images of the as-cut surfaces of the O1, HT1350, and HT1400 substrates. The surface morphology of the O1 sample is characterized by smooth areas, caused by trans-crystalline fracture (Figure 8a). With increasing grain size of the ceramic, the surface morphology of the sawn substrate surface changes. With increasing grain size, the area of inter-crystalline fracture or grain breakout increases (Figure 8b,c).



Figure 8. Field emission scanning electron microscopy (FESEM) images of the as-cut substrate surfaces of the sample: (**a**) O1; (**b**) HT1350; (**c**) HT1400.

The changed surface morphology of the substrates is also documented in the increased roughness values (Table 2, Figure 8a,b) and the decreased biaxial strength (Table 2). The roughness measurements parallel (R ||) and perpendicular to the wire movement direction (R \perp) show no significant differences (Table 2). Therefore, the mean values include the values of both directions. The O1 substrates have a R_a-value of 0.23 ± 0.01 µm whereas the HT1350 substrates have a R_a-value of 0.33 ± 0.06 and HT1400 0.33 ± 0.02 µm (Figure 9a). The R_z -value increases from 1.65 ± 0.09 µm (O1) to 2.92 ± 0.58 µm (HT1400) (Figure 9b).

The substrates of O1 (cut #1, d_{50} alumina grain size: 0.44 µm) have a thickness variation of 237 ± 15 µm, the substrates of HT1350 (cut #3, d_{50} alumina grain size: 0.64 µm), have a thickness variation of 235 ± 38 µm and the HT1400 substrates (cut #2, d_{50} alumina grain size: 0.90 µm) have a thickness variation of 229 ± 25 µm (Figure 10). The increasing thickness variation with the number of cuts is caused by the wear of the abrasive grains and increasing portion of debris and the wider grain size distribution of the B₄C abrasives after the re-dosing of fresh abrasives into the slurry-tank bevor cut #3.



Figure 9. Surface roughness parameters measured on the substrates of O1, HT1350 and HT1400 with different d_{50} -grain sizes (**a**) R_a ; (**b**) R_z .



Figure 10. Thickness variation of the substrates of O1, HT1350 and HT1400 for different d₅₀-grain sizes.

4. Discussion

4.1. Relationship of Grain Coarsening and Efficiency of the Multi-Wire Sawing Process

The cutting mechanism of multi-wire slurry sawing has been studied for silicon [14] and other hard and brittle materials such as quartz, glass, and ceramics [15] and can be described with the rolling indenting model. It states that the rolling abrasive particles in the sawing channel press onto the workpiece and cause elastic plowing (saw marks) or micro-fracture (chipping), schematically shown in Figure 11. The material properties such as the elastic modulus, hardness, and fracture toughness of the workpiece determine the elastic plowing or the chipping volume/shape, and thus the surface morphology of the substrates and the cutting rate.

The FESEM-analysis of the as-cut surface morphology of the substrates shows a transition from dominantly trans- to intergranular material removal with grain coarsening (Figure 8). The substrate surface of the original material is characterized by areas of trans-granular micro-fractures (saw marks) caused by elastic plowing (Figure 11a). This wear mechanism is also referred to as deformation-controlled material removal in other wear studies of alumina [16,17]. In contrast, the substrate surface of grain coarsened substrates is characterized by areas of inter-crystalline micro-fractures (grain boundary fracture) caused by chipping. This wear/cutting mechanism is referred to as fracture-controlled material removal (Figure 11b). A shift in the cutting mechanism is not analyzed in detail, but the surface morphology of the O1-substrates (Figure 8a) appears to be generated by ductile material removal [18]. The surface morphology of HT1350- and HT1400-substrates corresponds to brittle material removal.



Figure 11. Cutting mechanisms in the multi-wire slurry process for Al₂O₃-ceramics; (a) deformation-controlled material removal (trans-granular) for fine grained Al₂O₃; (b) fracture-controlled material removal (inter-granular) for coarse grained Al₂O₃.

The transition from deformation- to fracture-controlled wear of alumina ceramics, is characterized by an increased wear rate [16–19]. A simplistic fracture mechanics model, describes the phenomenon, that the wear-damage-induced stress levels required to cause intergranular micro-fracture in alumina ceramics decrease with increasing grain size [19], which reduces the wear resistance of the material. The wear experiments (reversing sliding abrasion performed with a rotating sphere on flat specimen) on which this model is based were conducted at local loads of approx. 3 GPa (the Hertzian stresses were estimated by the material and geometrical data given in the publication). The stresses of contact in slurry wire-sawing (free abrasive machining with third body particles) were modeled for cutting silicon with SiC abrasives [20] and the compression stresses underneath the indentation point are about 1–3 GPa depending on the exact shape of the indenting grain. Because of the comparable local stresses, the analogous wear behavior of the alumina ceramic is assumed for the multi-wire slurry sawing process. The fracture mechanics model [19] states that the reason for the reduced wear resistance of the grain coarsened samples is linked to the residual stresses in individual grains induced by the anisotropic thermal expansion. The micro-fracture from anisotropic thermal expansion of Al_2O_3 -single-phase polycrystals is described in detail [17,19,21,22]. The c-axes of the alumina grains are under tensile stresses and the axes perpendicular to the c-axis are under compression stresses. Some silicate grain boundary phase reduces these stresses. The influence of the grain size on the residual stresses is marginal, but due to the grain size-dependent creep behavior, a different relaxation behavior can be observed during cooling.

An increase in the cutting efficiency results from the grain coarsening of the alumina ceramic and the resulting change in the removal mechanism from dominantly trans- to intergranular. The efficiency of the multi-wire sawing process can be described by the size of the wire bow, the smaller the wire bow, the higher the sawing rate. Correction of the measured wire bow values was carried out, as the d_{50} -B₄C abrasive grain size varies due to wear in the sawing channel. The corrected data show a decrease in

the wire bow size of $-6.60 (\pm 0.48)$ mm per μ m increase of the d₅₀-grain size of the alumina ceramic. This represents a significant improvement in the cutting rate of alumina ceramic substrates because the nominal cutting speed can be increased (>20 μ m/min) to shorten the processing time. By decreasing the size of the wire bow, it has been shown that fracture-controlled material removal during multi-wire sawing is more efficient than deformation-controlled material removal. However, the surface damage by the process is not very pronounced. This can be proven by the slight change of strength.

Further studies on slurry wire-sawing of alumina ceramics have shown that increasing the sawing angle θ from 0° to 25° and the use of ultrasound, perpendicular to the feed direction, increases the material removal rate [3]. In the field of diamond wire-sawing of alumina ceramics, it was found that an increased wire tension from 13.3 to 26.3 N (no influence on R_a-values), and an increased wire speed from 1.3 to 3.5 m/s (decrease in the R_a-values of 1.5–1.2 µm) increase the material removal rate and therefore reduce the size of the wire bow [23]. The results from both studies refer to single-wire sawing experiments. In the field of multi-wire silicon cutting with SiC abrasives similar results were made. A decrease in the feed rate and the working length reduce the size of the wire bow. A reduction of the size of the wire bow by increasing the material removal rate can be achieved by increasing the wire speed from 8 to 20 m/s, increasing the wire tension from 10 to 25 N, and increasing the slurry viscosity to 0.4 Ns/m² [24].

4.2. Quality of the Ceramic Substrates

Due to the microstructural modification of grain coarsening and the varied grit size distribution of the $B_4C d_{50}$ -abrasives in the slurry-tank, the substrate properties change. With grain coarsening a transition from trans- to intergranular material removal is visible in an increase of the Ra- and Rz-values by 0.1 and 1.5 μ m (Figure 9). In contrast to the measured roughness values, the variation in substrate thickness remains unaffected by the grain coarsening. A decrease in the biaxial strength from 1356 MPa (O1) to 1033 MPa (HT1400) and a decrease in the fracture toughness from 3.5 (O1) to 2.8 MPa*m^{0.5} (HT1400) is observed (Table 2). This is can be caused by various reasons. EDX-measurements show an increased size of MgO-rich-precipitations (size: $0.3-0.4 \mu m$) at grain junctions and triple points with grain coarsening. Inhomogeneities in the microstructure can act as fracture initiating defects. Furthermore, an increase in the Ra- and Rz-values is measured, indicating the possibility of larger surface defects. Further B3B tests were performed to answer the question of whether the decrease in substrate strength is due to the different damages caused by the sawing process or the change in microstructure. O1- and HT1400-substrates were additionally polished to generate similar surfaces. 9 O1-substrates and 12 HT1400-substrates were tested. Due to the small number of samples, no Weibull analysis was conducted, and the mean value and standard deviation of the strength values are given. The polished O1 substrates have a strength of 1336 ± 234 MPa and the HT1400 substrates have a strength of 1453 ± 250 MPa. The strength of the polished O1 substrates is almost constant compared to the as-cut substrates, while the strength of polished HT1400 substrates is increased by about 400 MPa. It can be stated that the strength of the as-cut substrates is determined by the severity of surface damage caused by sawing.

5. Conclusions

The grain size of the HIPed alumina ceramics was changed by heat treatment processes at 1350 $^{\circ}$ C and 1400 $^{\circ}$ C from an initial d₅₀-value of 0.44 μ m to 0.64 μ m and 0.90 μ m. It was found that the Vicker's hardness decreases by about 10% with increasing grain size. However, the sawing processes are significantly changed.

The efficiency of the multi-wire slurry process increases with increasing grain size of the alumina ceramics. The increasing sawing efficiency is visible by the decrease in the size of the wire bow of -6.60 (±0.48) mm per µm d₅₀ alumina grain size in the investigated range of 0.44–0.90 µm. It was found that multi-wire slurry sawing of alumina with a d₅₀ grain size \geq 0.90 µm and without glassy phase can be performed at a feed rate >20 µm/min.

The increase in efficiency of the multi-wire slurry process is linked to a transition in the material removal mechanism. Field emission scanning electron microscopy (FESEM) analysis of the as-cut surface morphology shows a transition from trans- to intergranular material removal with grain coarsening. The transition from deformation controlled to fracture controlled wear is characterized by an increased wear rate. However, this results only in a moderate change in the properties of the substrate.

An increase of the R_a - and R_z -value by 0.1 and 1.5 µm of the substrates is observed due to the grain coarsening. The biaxial strength changes from 1356–1033 MPa. To answer the question of whether the decrease in substrate strength is due to sawing or the change in microstructure, further B3B tests on polished O1 and HT1400 substrates were performed. The strength of the polished O1 substrates is almost constant compared to the as-cut substrates, while the strength of polished HT1400 substrates is determined by the severity of surface damage caused by sawing.

In summarizing the experiments, it can be concluded that the multi-wire sawing is an interesting technology for cutting high-performance ceramics. However, the process depends on the cutting parameter and the microstructure. Further detailed investigations of the influence of residual porosity, amount, and nature of the glassy phase under the different cutting conditions have to be performed to establish this method. A compromise between the sawing performance and the quality requirements of the substrates can be freely adjusted according to the application.

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