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Advances in Modeling, Estimation, and Control of Intelligent Transportation Systems

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Message from the Guest Editors

This Special Issue aims to explore the modeling theories and methods for UAV and SDV in intelligent transportation systems. Further, the evolutionary mechanisms of the system are characterized by direct measurements versus indirect estimates and short-term predictions. Finally, advanced control algorithms are built based on models and data to enhance the safety and intelligence of transportation. Topics including but not limited to the following:

- Application of artificial intelligence, modeling, simulation, and dynamic analysis of the collaboration system for unmanned aerial vehicles and self-driving vehicles;
- Unmanned aerial vehicle and self-driving vehicle decision making in a complex urban traffic environment:
- Parameter identification and state estimation, coordinated control and fault-tolerant control of unmanned aerial vehicles and self-driving vehicles;
- Advanced control for critical components of selfdriving vehicles;
- Failure monitoring and protection of unmanned aerial vehicles and self-driving vehicles;
- Design of new sensors and novel estimation and data fusion algorithms for unmanned aerial vehicles and self-driving vehicles.











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Message from the Editor-in-Chief

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