



Application and Optimal Control of Vision Robot System

Guest Editor:

Dr. Cosmin Copot

Department of
Electromechanics, University of
Antwerp, Antwerp, Belgium

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Message from the Guest Editor

Dear Colleague,

Recent research in the field of robotics aims to use auxiliary sensors to help improve the robustness, flexibility, and accuracy of the control system. The information obtained from sensors is used as feedback in the system control loop. In recent years, a manifold of sensor types has been developed to perform specific tasks which vary in their features and operation design. Due the fact that industrial systems are becoming increasingly more interconnected, the current control schemes need to be updated in order to deal with the system dynamics, system faults, etc. In recent years, there has been increased research attempting to make steps toward the design and development of high-performance and autonomous robotic systems by means of control strategies able to achieve optimal performance at all times and in all circumstances with minimum user interaction. We welcome any contributions within the general scope of the Special Issue theme “Applications and Optimal Control of Vision Robot Systems”.

Dr. Cosmin Copot

Guest Editor





Editor-in-Chief

Prof. Dr. Marco Ceccarelli

LARM2: Laboratory of Robot
Mechatronics, Department of
Industrial Engineering, University
of Rome Tor Vergata, Via del
Politecnico 1, 00133 Roma, Italy

Message from the Editor-in-Chief

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It is great fun to create intelligent robots and imagine their practical applications. *Robotics* is now ready to serve you in the long journey towards such a goal.

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Robotics Editorial Office
MDPI, St. Alban-Anlage 66
4052 Basel, Switzerland

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