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Interference, Robustness and Complementary Solutions for GNSS-Based Navigation for Aerial Vehicles

Guest Editors:

Dr. Elena Simona Lohan

Dr. Alberto De la Fuente

Prof. Dr. Fabio Dovis

Dr. Pau Closas

Deadline for manuscript
submissions:
closed (20 August 2019)

Message from the Guest Editors

Sensors welcomes submissions to this Special Issue on “Interference, Robustness and Complementary Solutions for GNSS-Based Navigation for Aerial Vehicles”.

The main themes and keywords to guide potential authors are as follows:

1. Interference detection, classification, mitigation, and localization in GNSS
2. Authentication mechanisms in GNSS
3. Novel navigation solutions for aerial vehicles

Keywords

- GNSS interferences
- Spoofing
- Meaconing
- Interference detection
- Interference mitigation
- Interference localization
- Interference classification
- Authentication mechanisms in GNSS
- Alternative/complementary tracking and navigation methods for aviation
- Drones
- Aviation
- UAV



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Special Issue



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Prof. Dr. Vittorio M. N. Passaro

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Elettrica e dell'Informazione
(Department of Electrical and
Information Engineering),
Politecnico di Bari, Via Edoardo
Orabona n. 4, 70125 Bari, Italy

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Sensors Editorial Office
MDPI, St. Alban-Anlage 66
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