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Neuromechanical Principles of Perturbed and Unperturbed Motion Control

Guest Editors:

Prof. Dr. Adamantios Arampatzis

Department of Training and Movement Sciences, Humboldt-Universität zu Berlin, Philippstr. 13, 10115 Berlin, Germany

Dr. Sebastian Bohm

Department of Training and Movement Sciences, Humboldt-Universität zu Berlin, 10115 Berlin, Germany

Deadline for manuscript submissions:

30 June 2024

Message from the Guest Editors

Dear Colleagues,

Real-world environments rarely allow for stable and constant movement, and most often, unsteadiness and unpredictable disturbances are involved. Through an integration of analytical, computational, and experimental approaches, the various neuromechanical networks and mechanisms (e.g., proprioceptive feedback, sensorimotor integration, muscle-tendon interaction, reflexes, preflexes) that are involved in the control of movement can be explored. Promoting research in this field will improve our understanding of how vertebrate systems organize their movements and how wearable assistive devices may augment and assist human motion in both steady and unsteady conditions.

This Special Issue invites authors to contribute new knowledge about movement control in steady and unsteady conditions. A broad range of related topics is welcome, such as methodological innovations for the analysis of movements, assistive exoskeleton technology, or modeling and experimental studies investigating mechanisms of motor control and muscle-tendon mechanics.



mdpi.com/si/89039

Special Issue



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Editor-in-Chief

Prof. Dr. Vittorio M. N. Passaro

Dipartimento di Ingegneria
Elettrica e dell'Informazione
(Department of Electrical and
Information Engineering),
Politecnico di Bari, Via Edoardo
Orabona n. 4, 70125 Bari, Italy

Message from the Editor-in-Chief

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Sensors Editorial Office
MDPI, St. Alban-Anlage 66
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