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# Advanced Sensing and Safety Control for Connected and Automated Vehicles

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### **Message from the Guest Editors**

Connected and automated vehicle (CAV) transformative technology that is expected to change and improve the safety and efficiency of the mobilities. As main functional components of CAVs, advanced sensing technologies and control algorithms, which gather environmental information, process data, and control vehicle motion, are of great importance. The development of novel sensing technologies for CAVs has become a hot spot in recent years. Thanks to the improved sensing technologies, CAVs are able to interpret sensory information to further detect obstacles, localize their positions, and navigate themselves and interact with other surrounding vehicles in the dynamic environment. Further, leveraging computer vision and other sensing methods, incabin humans' body activities, facial emotions, and even their mental states can also be recognized.

The objective of this SI is to compile recent research and development efforts contributing to advances in sensing and control for CAVs. The Special Issue will also welcome contributions addressing the state-of-the-art in associated developments and methodologies, and the perspectives on future developments and applications.













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