

Article

The Entropy of a Discrete Real Variable

Scott Funkhouser

SPAWAR Systems Center Atlantic, Joint Base Charleston, North Charleston, SC 29406, USA;

E-Mail: scott.funkhouser@gmail.com

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Abstract: The discrete Shannon entropy H was formulated only to measure indeterminacy effected through a set of probabilities, but the indeterminacy in a real-valued discrete variable depends on both the allowed outcomes $\mathbf{x}$ and the corresponding probabilities $\mathbf{p}$. A fundamental measure that is sensitive to both $\mathbf{x}$ and $\mathbf{p}$ is derived here from the total differential entropy of a continuous real variable and its conjugate in the discrete limit, where the conjugate is universally eliminated. The asymptotic differential entropy recovers H plus the new measure, named Ξ , which provides a novel probe of intrinsic organization in sequences of real numbers.

Keywords: Shannon entropy; information entropy; information theory

1. Introduction

Let Y be a discrete variable with $n > 1$ generic outcomes $\mathbf{y} = \{y_1, \dots, y_n\}$ and corresponding probabilities $\mathbf{p} = \{p_1, \dots, p_n\}$ such that

$$\sum_{j=1}^n p_j = 1 \quad (1)$$

Expressed in terms of the natural logarithm, the Shannon entropy attributed to Y in connection with $\mathbf{p}$ is [1]

$$H(\mathbf{p}) = - \sum_{j=1}^n p_j \log(p_j) \quad (2)$$

For convenience let

$$H_2(\mathbf{p}) \equiv \frac{H(\mathbf{p})}{\log(2)} \quad (3)$$

represent the original form defined in terms of the base-2 logarithm. $H = H(\mathbf{p})$ is bound according to

$$0 \leq H \leq \log(n) \quad (4)$$

The maximum is generated only when all outcomes are equally probable. $H(\mathbf{p})$ vanishes in the limit as some $p_j \in \mathbf{p}$ approaches unity, which represents a completely predetermined outcome.

Because it emerges naturally from the basic principles of encoded compression, the discrete Shannon entropy is widely recognized as an informatic measure. Specifically, consider a message $\mathbf{m}$ consisting of $N \gg 1$ symbols from a generalized alphabet $\mathbf{s} = \{s_1, \dots, s_a\}$. Let N_j represent the total number of occurrences of a particular symbol $s_j \in \mathbf{s}$ within $\mathbf{m}$. In the limit as N becomes infinitely large suppose that each N_j/N approaches a certain constant w_j that is characteristic to the “language” in which $\mathbf{m}$ is composed. For sufficiently large N we therefore have $N_j \simeq w_j N$. The total number I of likely messages of length N is consequently fixed by $\mathbf{w} = \{w_1, \dots, w_a\}$ according to

$$I \simeq \prod_{j=1}^n w_j^{-N_j} \quad (5)$$

The right side of Equation (5) is simply the inverse of the probability for finding any one particular $\mathbf{m}$ among all messages of length N subject to $\mathbf{w}$. The inventory of likely messages could be encoded as I different integers. The number β of bits required to register the encoded inventory is given by $\beta = \lceil \log_2(I) \rceil$, and we therefore have the average compression rate

$$\frac{\beta}{N} \simeq H_2(\mathbf{w}) \quad (6)$$

Notwithstanding its significance, Equation (6) represents only a particular example of the expansive utility of the discrete Shannon entropy. Interpreted most broadly, and in accordance with the purpose for which it was derived, $H(\mathbf{p})$ measures the indeterminacy in a random selection from among n different options with corresponding probabilities $\mathbf{p}$ [1]. It is therefore appropriate to attribute a quantity of entropy $H(\mathbf{p})$ to a discrete variable with probabilities $\mathbf{p}$.

Consider a variable Y whose $n \gg 1$ allowed outcomes $\mathbf{y}$ are governed by some $\mathbf{p}$ such that $H(\mathbf{p})$ is near $\log(n)$. The nearly maximal entropy implies that Y exhibits no significant statistical preference toward any particular outcome or group of outcomes among $\mathbf{y}$. Consequently an ideal observer who studied the behavior of Y could develop a successful model only to predict the most trivial details about future outcomes. Stated alternatively, the degree to which Y behaves deterministically is minimal. In contrast suppose that $H(\mathbf{p})$ is much smaller than $\log(n)$. The nearly minimal entropy implies a strong statistical preference for some comparatively small number of $y_j \in \mathbf{y}$. As such Y would exhibit an appreciable degree of deterministic behavior. A successful, non-trivial predictive model could be therefore developed from observations of Y .

It is important to emphasize that H is a rigorous measure of indeterminacy in a variable only insofar as the indeterminacy depends on $\mathbf{p}$ alone. Let X be a discrete variable whose n allowed outcomes $\mathbf{x} = \{x_1, \dots, x_n\}$ are D -dimensional real vectors, *i.e.* $x_j \in \mathbb{R}^D$ for $j = 1, \dots, n$. The elements of every one-dimensional $\mathbf{x}$ are implicitly listed in ascending order throughout the following. Analogously to the real nature of $\mathbf{p}$, the real nature of $\mathbf{x}$ endows the outcomes of X with definite spatial attributes in which

non-trivial deterministic behaviors could manifest. Consequently, as illustrated in the following two examples, H is not generally sufficient as a measure of indeterminacy in real-valued discrete variables.

Consider two variables X_{ee} and X_{er} whose outcomes are confined to the real axis. Let the allowed outcomes of X_{ee} be *e*qually probable and *e*qually spaced, hence the subscript “*ee*”, and let the allowed outcomes of X_{er} be *e*qually probable but *r*andomly spaced, hence the subscript “*er*”. More formally, the allowed outcomes of X_{ee} are of the form $\mathbf{x}_e$, which is defined for $D = 1$ to be a set of n equally spaced points on the real axis. Let γ represent the arbitrary spacing in a given $\mathbf{x}_e$. For convenience we also define $\mathbf{p}_e \equiv \{1/n, \dots, 1/n\}$ for a given n to represent a set of equal probabilities. The allowed outcomes of X_{er} are of the form $\mathbf{x}_r$, which is defined for $D = 1$ to be indistinguishable from a set of n points distributed randomly over some simple finite segment $\mathfrak{X}_1$ of the real axis. The intrinsic spatial structure of $\mathbf{x}_e$ effects a commensurate degree of deterministic behavior in X_{ee} . For instance, the difference between successive outcomes of X_{ee} is always an integer multiple of γ , and is therefore significantly more predictable than the difference between successive outcomes of X_{er} . Because X_{ee} and X_{er} differ only in the spatial arrangement of their allowed outcomes, X_{ee} would behave more deterministically. By definition a smaller quantity of entropy should be therefore attributed to X_{ee} . The discrete Shannon entropy attributed to both variables, however, would be identically maximal.

Consider next a complementary scenario in which the allowed outcomes are identically valued but the respective probabilities differ. Let X_{re} and X_{ae} be two variables with $n \gg 1$ one-dimensional allowed outcomes of the form $\mathbf{x}_e$. The set of probabilities governing X_{re} is of the form $\mathbf{p}_r$, which is defined generally to be indistinguishable from n randomly selected positive real numbers, subsequently normalized to unity and listed in *r*andom order. The spatial assignment of $\mathbf{p}_r$ through $\mathbf{x}_e$ would be globally isotropic but locally irregular, despite the intrinsic structure of $\mathbf{x}_e$. The outcomes of X_{ae} are matched to a set of probabilities of the form $\mathbf{p}_a$, which is defined generally to be indistinguishable from n randomly selected positive real numbers, subsequently normalized to unity and listed in *a*scending order. The ordered arrangement of $\mathbf{p}_a$ effects a non-trivial deterministic bias favoring progressively larger outcomes in X_{ae} . Note that the specific form of $\mathbf{p}_a$ in this example could be constructed simply by sorting the elements of $\mathbf{p}_r$, in which case X_{ae} would behave more deterministically but $H(\mathbf{p}_r)$ and $H(\mathbf{p}_a)$ would be identical.

The problems raised in the previous two paragraphs do not imply any flaw in H . The discrete Shannon entropy was formulated only to measure indeterminacy effected by a given $\mathbf{p}$ in a generic discrete variable. The net indeterminacy in a real-valued discrete variable, however, depends on the respective intrinsic characteristics of $\mathbf{x}$ and $\mathbf{p}$, and on the manner in which $\mathbf{x}$ and $\mathbf{p}$ are matched. A special measure is therefore required for discrete real variables. Note that Equation (6) is insensitive to the nature of $\mathbf{s}$, and the present considerations are therefore irrelevant in the context of the coding theorems. To be precise, the role of H_2 in Equation (6) is not truly as a measure of indeterminacy.

Although it included no special provisions for discrete real variables, Shannon’s seminal paper introduced a separate formulation for the entropy of a continuous real variable. Let $\mathcal{X}$ be a probabilistically determined variable whose allowed outcomes span a continuum of real vectors within some region $\mathfrak{X} \in \mathbb{R}^D$. Let the probability density $\rho(x)$ be defined such that $\rho(x)dx$ gives the probability for an outcome of $\mathcal{X}$ to lie within an infinitesimal element dx centered on x , where $x \in \mathbb{R}^D$ is an independent variable and $dx = dx^{(1)} \dots dx^{(D)}$ represents implicitly the product of the differentials of each

vector component of $x = (x^{(1)}, \dots, x^{(D)})$. We therefore require $\rho = \rho(x)$ to vanish for all $x \notin \mathfrak{X}$. The normalization of ρ is accordingly

$$\int_{\mathbb{R}^D} \rho dx = \int_{\mathfrak{X}} \rho dx = 1 \quad (7)$$

Henceforth any integration is understood to span $\mathbb{R}^D$ in the absence of explicit limits. The entropy $\mathcal{H} = \mathcal{H}(\rho)$ attributed to $\mathcal{X}$ in connection with ρ is [1]

$$\mathcal{H} = - \int \rho \log(\rho) dx \quad (8)$$

where $\rho \log(\rho)$ is defined to vanish for $\rho = 0$. The measure in Equation (8) is known as the *differential (Shannon) entropy*.

In contrast to H a single quantity of $\mathcal{H}$ is subject to no finite bounds. Consequently a simple comparison between H and $\mathcal{H}$ is not meaningful. For instance, the differential entropy of a normalized Gaussian

$$\rho_G = \rho_G(\nu, x) \equiv \left(\frac{\nu}{\sqrt{\pi}} \right)^D e^{-\nu^2 x^2} \quad (9)$$

is $D \log(\sqrt{\pi e}/\nu)$. For ν equal to $\sqrt{\pi e}$ the entropy vanishes, which signifies a predetermined outcome in the context of discrete real variables. Furthermore in the limit as ν becomes infinitely large ρ_G behaves as a D -dimensional delta-distribution $\delta(x)$, which describes a single predetermined real outcome. $\mathcal{H}(\rho_G)$, however, decreases without bound as ν approaches infinity.

The apparent inconsistencies between H and $\mathcal{H}$ are reconciled in the following manner. As a generalization of ρ_G let $\rho_0 = \rho_0(\nu, x)$ be some well-behaved, unity-normalized function that becomes $\delta(x)$ in the limit as the positive, real parameter ν becomes infinitely large. In association with an arbitrary X , with n allowed outcomes $\mathbf{x}$ and corresponding probabilities $\mathbf{p}$, let the probability density $\rho_x = \rho_x(\nu, x)$ be defined such that

$$\rho_x(\nu, x) \sim B \sum_{j=1}^n p_j \rho_0(\nu, x - x_j) \quad (10)$$

and thus

$$\lim_{\nu \rightarrow \infty} \rho_x = \sum_{j=1}^n p_j \delta(x - x_j) \quad (11)$$

where $B = B(\nu)$ is the appropriate normalization coefficient for a given ν , and x_j and p_j span $\mathbf{x}$ and $\mathbf{p}$ respectively. The symbol “ $\sim$ ” is used in Equation (10) and throughout, where convenient, to signify asymptotic equality as ν approaches infinity. The right side of Equation (11) describes the probabilistic behavior of X . Consider an originally continuous test variable $\mathcal{X}_x$ whose outcomes are governed by ρ_x . The entropy attributed to $\mathcal{X}_x$ is $\mathcal{H}(\rho_x)$, which behaves asymptotically as

$$\mathcal{H}(\rho_x) \sim -B \sum_{j=1}^n p_j \int \rho_0 \log(B p_j \rho_0) dx \quad (12)$$

When ν is finite but very large the behavior of $\mathcal{X}_x$ is a hybrid of the continuous traits of ρ_0 and the discrete traits of $\mathbf{x}$ and $\mathbf{p}$. In the limit as $\nu \rightarrow \infty$ the two sets of traits become completely disassociated from one another, and $\mathcal{X}_x = X$ is characterized only by $\mathbf{x}$ and $\mathbf{p}$. The entropy associated with the probabilistic

behavior of X should be therefore given by the asymptote of $\mathcal{H}(\rho_x) - \mathcal{H}(\rho_0)$. From Equation (12) we readily obtain

$$\lim_{\nu \rightarrow \infty} (\mathcal{H}(\rho_x) - \mathcal{H}(\rho_0)) = - \sum_{j=1}^n p_j \log(p_j) \quad (13)$$

thereby recovering H from $\mathcal{H}$.

Although the analysis leading to Equation (13) may be instructive, $\mathcal{H}(\rho_x)$ is asymptotically independent of $\mathbf{x}$ and could not produce the desired new measure for discrete real variables. It is reasonable to suspect that some additional quantity of the form $\mathcal{H}$ could be considered in conjunction with $\mathcal{H}(\rho_x)$ to provide the required asymptotic sensitivity to both $\mathbf{x}$ and $\mathbf{p}$. In order to be meaningful, however, the additional measure should be intrinsically related to ρ_x .

Within the paradigm of wave mechanics two distinct quantities of differential entropy are naturally associated with a given ρ . More precisely, two separate probability density functions are naturally associated with a given probability amplitude $\psi = \psi(x)$, namely $\rho = |\psi|^2$ and the spectral density

$$\hat{\rho}(k) = |\hat{\psi}(k)|^2 \quad (14)$$

where

$$\hat{\psi} = \hat{\psi}(k) = \left(\frac{1}{\sqrt{2\pi}} \right)^D \int \psi e^{-ik \cdot x} dx \quad (15)$$

is the Fourier-conjugate of ψ and $k \in \mathbb{R}^D$ is an independent variable. We may interpret $\hat{\rho} = \hat{\rho}(k)$ as the probability density governing the outcomes of a variable $\mathcal{K}$ that is the conjugate of the variable $\mathcal{X}$ governed by ρ . The entropy attributed to $\mathcal{K}$ in connection with $\hat{\rho}$ is $\mathcal{H}(\hat{\rho})$. The total differential entropy attributed to the conjugated pair is therefore

$$S(\psi) \equiv \mathcal{H}(|\psi|^2) + \mathcal{H}(|\hat{\psi}|^2) \quad (16)$$

A more formal derivation of $S = S(\psi)$ follows from the total phase-space distribution [9]

$$f = f(x, k) \equiv \rho \hat{\rho} \quad (17)$$

which is subject to the normalization

$$\int f dr = 1, \quad (18)$$

where $r \equiv (x^{(1)}, \dots, x^{(D)}, k^{(1)}, \dots, k^{(D)})$ for any given x and k . Because f is simply a probability density in a $2D$ -dimensional vector space, it is appropriate to attribute a quantity of differential entropy

$$- \int f \log(f) dr = S \quad (19)$$

to the conjugated pair.

The total differential entropy S has been the subject of extensive research. (See, for instance, [2–8]). It is worthwhile to mention here two general characteristics that distinguish S as a fundamentally important measure. Because f is dimensionless S , like the relative entropy, is free from a potentially serious flaw to which the differential Shannon entropy is otherwise vulnerable [10]. Furthermore, whereas $\mathcal{H}(\rho)$ and $\mathcal{H}(\hat{\rho})$ may become infinitely negative, S is subject to the lower bound [2]

$$S \geq D \log(\pi e) \quad (20)$$

Perhaps uniquely, a Gaussian amplitude generates the minimal S allowed by Equation (20) [2].

The purpose of this article is to demonstrate that a measure of indeterminacy for discrete real variables that is sensitive to both $\mathbf{x}$ and $\mathbf{p}$ emerges from the total differential entropy of $\mathcal{X}_x$ and its conjugate in the limit as ν diverges. Specifically, the conjugated analogue of Equation (13) includes an additional measure $\Xi = \Xi(\mathbf{p}, \mathbf{x})$, expressed most generally in terms of an integral, that behaves naturally as a measure of indeterminacy in the spatial configuration of $\mathbf{x}$ and $\mathbf{p}$. Furthermore the conjugate is universally eliminated in the limit as $\mathcal{X}_x$ becomes discrete and the entire residual entropy $H + \Xi$, named η , is therefore attributed to X . Section 2 contains a derivation of η . The general characteristics of η are examined in Section 3. Section 4 presents a quantitative study demonstrating the basic behaviors of η as a measure of indeterminacy for discrete real variables. The primary conclusions are summarized and interpreted in Section 5.

2. Derivation of η

The terms defined in Section 1 retain their definitions throughout the following. Let $\mathcal{K}_x$ be the conjugate of a given $\mathcal{X}_x$. The probability density $\hat{\rho}_x = \hat{\rho}_x(\nu, k)$ governing the outcomes of $\mathcal{K}_x$ is formulated presently. Let $\psi_x = \psi_x(\nu, x)$ be defined such that $\rho_x = |\psi_x|^2$. The total differential entropy of the conjugated pair is thus $S(\psi_x) = \mathcal{H}(\rho_x) + \mathcal{H}(\hat{\rho}_x)$. This section contains a derivation of the asymptotic form of $S(\psi_x)$ expressed analogously to Equation (13).

The first step is to formulate ψ_x . Following the standard wave-mechanical prescription, and in accordance with natural law, we attribute to each allowed outcome a separate amplitude [11]. The total amplitude is simply the sum of the individual amplitude waveforms multiplied by an appropriate normalization coefficient. Let the probability amplitude $\phi_0 = \phi_0(\nu, x)$ be therefore defined such that $|\phi_0|^2 = \rho_0$, i.e.,

$$\lim_{\nu \rightarrow \infty} |\phi_0|^2 = \delta(x) \quad (21)$$

The waveform assigned to each $x_j \in \mathbf{x}$ is

$$\phi_j = \phi_j(\nu, x) \equiv \sqrt{p_j} \phi_0(\nu, x - x_j) \quad (22)$$

and the total amplitude is accordingly

$$\psi_x = A \sum_{j=1}^n \phi_j \quad (23)$$

where $A = A(\nu)$ is defined such that ρ_x is unity-normalized for all ν . Because the real part of ϕ_0 becomes ever more sharply peaked with increasing ν , the cross terms $|A|^2 \phi_j \phi_l^*$ in $|\psi_x|^2$ are negligible for sufficiently large ν and vanish asymptotically. We therefore have

$$\rho_x \sim |A|^2 \sum_{j=1}^n |\phi_j|^2 \quad (24)$$

which is equivalent to Equation (10). Note that

$$\lim_{\nu \rightarrow \infty} |A|^2 = \lim_{\nu \rightarrow \infty} B = 1 \quad (25)$$

The next step is to determine the respective forms of the conjugate amplitude $\hat{\psi}_x = \hat{\psi}_x(\nu, k)$ and density $\hat{\rho}_x = |\hat{\psi}_x|^2$. Let $\hat{\phi}_0 = \hat{\phi}_0(\nu, k)$ represent the conjugate of ϕ_0 , and let the associated density $|\hat{\phi}_0|^2$ be defined as $\hat{\rho}_0 = \hat{\rho}_0(\nu, k)$. It follows from Equation (15), with $x - x_j$ substituted for x , that

$$\hat{\phi}_j = \sqrt{p_j} e^{-ik \cdot x_j} \hat{\phi}_0 \quad (26)$$

where $\hat{\phi}_j = \hat{\phi}_j(\nu, k)$ is the conjugate of a given ϕ_j . We therefore have

$$\hat{\psi}_x = A \hat{\phi}_0 \sum_{j=1}^n \sqrt{p_j} e^{-ik \cdot x_j} \quad (27)$$

and thus

$$\hat{\rho}_x = |A|^2 \tau \hat{\rho}_0 \quad (28)$$

where

$$\tau \equiv \left| \sum_{j=1}^n \sqrt{p_j} e^{-ik \cdot x_j} \right|^2 \quad (29)$$

An equivalent expression for $\tau = \tau(k)$ following from the Euler identity is

$$\tau = 1 + 2 \sum_{j=1}^{n-1} \left\{ \sum_{l=j+1}^n \sqrt{p_j p_l} \cos((x_l - x_j) \cdot k) \right\} \quad (30)$$

For convenience we define $\zeta = \zeta(k)$ such that $\tau = 1 + 2\zeta$.

The asymptotic behavior of $\hat{\rho}_x$ is ascertained readily from the explicit form of $\hat{\phi}_0$ in Equation (15) with ϕ_0 expressed as ρ_0/ϕ_0^* for all non-vanishing ϕ_0^* . It follows from the behavior ascribed to ρ_0 that

$$\hat{\phi}_0 \sim \left(\frac{1}{\sqrt{2\pi}} \right)^D \frac{1}{\phi_0^*(0)} \quad (31)$$

which is independent of k . Because $\int \rho_0 dk$ must remain unity-normalized $\hat{\phi}_0$ must vanish everywhere asymptotically. As ρ_0 increasingly resembles $\delta(x)$ the real part of $\phi_0^*(0)$ must either increase or decrease without bound, which ensures that the right side of Equation (31) vanishes. Consequently $\hat{\psi}_x$ and $\hat{\rho}_x$ vanish asymptotically for all k .

It is also worthwhile to note that, because $\hat{\rho}_x$ and $\hat{\rho}_0$ are both unity-normalized for all ν , Equations (28) and (30) imply

$$\lim_{\nu \rightarrow \infty} \langle \zeta \rangle_0 = 0 \quad (32)$$

where

$$\langle \varepsilon \rangle_0 \equiv \int \hat{\rho}_0 \varepsilon dk \quad (33)$$

is the expected value of any $\varepsilon = \varepsilon(k)$ averaged against $\hat{\rho}_0$. Equation (32) may be understood as a consequence of the asymptotic uniformity of $\hat{\rho}_0$ in conjunction with the usual trigonometric property

$$\lim_{b \rightarrow \infty} \int_{-b}^b \cos(k) dk = 0 \quad (34)$$

In the limit as ν diverges $\langle \zeta \rangle_0$ becomes simply the average of ζ over all space, which we denote by $\bar{\zeta}$, and thus vanishes term-by-term in accordance with Equation (34). Expressed more generally,

$$\lim_{\nu \rightarrow \infty} \langle \varepsilon \rangle_0 = \bar{\varepsilon}. \quad (35)$$

Returning to the derivation proper, the next step is to evaluate $\mathcal{H}(\hat{\rho}_x)$ in the limit as ν approaches infinity. It follows from Equations (25) and (28) that

$$\mathcal{H}(\hat{\rho}_x) \sim -\langle \tau \log(\hat{\rho}_0) \rangle_0 - \langle \tau \log(\tau) \rangle_0 \quad (36)$$

Substituting $1 + 2\zeta$ for τ in the left-most term on the right side of Equation (36) produces

$$\mathcal{H}(\hat{\rho}_x) \sim \mathcal{H}(\hat{\rho}_0) - 2\langle \zeta \log(\hat{\rho}_0) \rangle_0 - \langle \tau \log(\tau) \rangle_0 \quad (37)$$

Although $\log(\hat{\rho}_0)$ decreases without bound it does so with asymptotic uniformity, hence

$$\langle \zeta \log(\hat{\rho}_0) \rangle_0 \sim \langle \zeta \rangle_0 \log(\hat{\rho}_0(k_0)) \quad (38)$$

for any $k_0 \in \mathfrak{R}^D$. The middle term on the right side of Equation (37) is therefore asymptotically proportional to $\bar{\zeta}$ and thus vanishes. Equation (37) accordingly becomes

$$\mathcal{H}(\hat{\rho}_x) \sim \mathcal{H}(\hat{\rho}_0) - \langle \tau \log(\tau) \rangle_0 \quad (39)$$

The asymptotic form of the right-most term in Equation (39) is

$$\Xi(\mathbf{p}, \mathbf{x}) \equiv -\overline{\tau \log(\tau)} \quad (40)$$

Because τ is periodic $\Xi = \Xi(\mathbf{p}, \mathbf{x})$ is identical to the average value of $-\tau \log(\tau)$ taken over some finite region $\mathfrak{R}_0 \in \mathfrak{R}^D$ spanning one period in each dimension. We therefore have

$$\Xi = -\frac{1}{\kappa_0} \int_{\mathfrak{R}_0} \tau \log(\tau) d\mathbf{k} \quad (41)$$

where

$$\kappa_0 \equiv \int_{\mathfrak{R}_0} d\mathbf{k} \quad (42)$$

An analytical expression for $\int \tau \log(\tau) d\mathbf{k}$ is possible only for a few rudimentary configurations of $\mathbf{x}$ and $\mathbf{p}$, and Equation (41) is thus critical for quantifying Ξ .

Finally, Equation (39) may be expressed in terms of a proper limit as

$$\lim_{\nu \rightarrow \infty} (\mathcal{H}(\hat{\rho}_x) - \mathcal{H}(\hat{\rho}_0)) = \Xi \quad (43)$$

analogously to Equation (13). Combining Equations (13) and (43) produces the central result

$$\lim_{\nu \rightarrow \infty} (S(\psi_x) - S(\phi_0)) = \eta(\mathbf{p}, \mathbf{x}) \quad (44)$$

where

$$\eta(\mathbf{p}, \mathbf{x}) \equiv H(\mathbf{p}) + \Xi(\mathbf{p}, \mathbf{x}) \quad (45)$$

The nature and behavior of $\eta = \eta(\mathbf{p}, \mathbf{x})$ are examined in the following Sections.

3. General Characteristics of η

By definition $S(\psi_x)$ measures the net indeterminacy in the conjugated pair $\mathcal{X}_x$ and $\mathcal{K}_x$. In the limit as ν becomes infinitely large, however, the pair is characterized completely by $\mathbf{x}$ and $\mathbf{p}$, independently of ϕ_0 . The entropy attributed asymptotically to the pair is therefore η . Furthermore as $\mathcal{X}_x$ becomes discrete $\hat{\rho}_x$ vanishes everywhere and $\mathcal{K}_x$ becomes therefore a “ghost” variable, doomed to exist without ever generating an outcome. The indeterminacy measured by η must be therefore evident in the probabilistic behaviors of X . Because X and its ghost conjugate together are indistinguishable from X alone we conclude that η is a generally valid measure of indeterminacy in discrete real variables.

Given that Ξ is the asymptotic form of $\mathcal{H}(\hat{\rho}_x) - \mathcal{H}(\hat{\rho}_0)$ its attribution to X is perhaps counterintuitive, despite the elimination of the conjugate. In particular $\mathcal{H}(\rho)$ and $\mathcal{H}(\hat{\rho})$ are typically anti-correlated among different ρ of a given generalized form. Recall, however, that $\mathcal{H}(\rho_x)$ is asymptotically insensitive to $\mathbf{x}$ and therefore is not generally correlated to $\mathcal{H}(\hat{\rho}_x)$ in any appreciable manner among different ρ_x . Not only is $\mathcal{H}(\hat{\rho}_x)$ sensitive to both $\mathbf{x}$ and $\mathbf{p}$, it is also naturally correlated to the intrinsic indeterminacy effected by the definite spatial attributes of $\mathbf{x}$. Stated most generally, greater spatial regularity in the configuration of $\mathbf{x}$ and $\mathbf{p}$ effects greater harmonic regularity in the spatial arrangement of the peaks in ρ_x , for $\nu \gg 1$. Greater harmonic regularity in ρ_x implies greater localization in the associated Fourier spectrum, which accordingly generates a smaller $\mathcal{H}(\hat{\rho}_x)$, for a given ϕ_0 . In order to isolate the effects associated with $\mathbf{x}$ and $\mathbf{p}$ we exclude the contribution from $\mathcal{H}(\hat{\rho}_0)$. In that manner Ξ measures the deterministic effects of real allowed outcomes.

Lower bounds on η and Ξ follow directly from the universal lower bound on S . Specifically, both $S(\psi_x)$ and $S(\phi_0)$ are subject to Equation (20) for all ν . We therefore have

$$\eta \geq 0 \quad (46)$$

and thus

$$\Xi \geq -H \quad (47)$$

Regardless of the degree of spatial structure in the configuration of $\mathbf{x}$ and $\mathbf{p}$, no variable could behave more deterministically than a fixed real number. Equation (46) is therefore consistent with the attribution of zero entropy to a predetermined outcome.

Upper bounds on η and Ξ may be obtained by writing Equation (41) as

$$\Xi = - \int_{\mathfrak{K}_0} \frac{\tau}{\kappa_0} \log \left(\frac{\tau}{\kappa_0} \right) dk - \log(\kappa_0) \quad (48)$$

where the right-most term has been reduced using

$$\bar{\tau} = \frac{1}{\kappa_0} \int_{\mathfrak{K}_0} \tau dk = 1, \quad (49)$$

which is a consequence of Equation (34). The integral on the right side of Equation (48) is simply the differential Shannon entropy associated with a normalized density τ/κ_0 defined over $\mathfrak{K}_0$. Furthermore $\log(\kappa_0)$ is the maximal differential Shannon entropy that could be associated with $\mathfrak{K}_0$. Equation (48) therefore implies

$$\Xi \leq 0 \quad (50)$$

hence

$$\eta \leq H \quad (51)$$

The upper bound on η is consistent with the basic expectations about the predictive utility of real outcomes. Consider some X that has been “disguised” by mapping the n allowed outcomes in $\mathbf{x}$ to a set of n generic outcomes, while keeping the corresponding probabilities $\mathbf{p}$ fixed. An ideal observer who studied only the generic outcomes could form a predictive model only to the extent allowed by $\mathbf{p}$. Suppose that such an observer were subsequently allowed to study the real outcomes. The numeric details could never detract from the observer’s capability to develop a predictive model because, at very least, the outcomes from any $\mathbf{x}$ could be interpreted simply as non-numeric symbols. The entropy attributed to X , therefore, should not be greater than the entropy attributed to the generic analogue, which is precisely what Equation (51) ensures.

For any $\mathbf{p}$, H and η should be similar when the degree of deterministic structure within $\mathbf{x}$ is negligible. We therefore expect

$$\eta(\mathbf{p}, \mathbf{x}_r) \simeq H(\mathbf{p}) \quad (52)$$

which is validated in the following section. Among variables with spatially randomized outcomes, indeterminacy depends primarily on the intrinsic characteristics of $\mathbf{p}$, hence Equation (52). Conversely, among variables with equally probable outcomes, indeterminacy depends only on $\mathbf{x}$. In that manner $\eta(\mathbf{p}_e, \mathbf{x})$ measures the intrinsic indeterminacy in the spatial configuration of $\mathbf{x}$. It is therefore fitting, as explicitly evident in Equation (30), that τ is sensitive to each of the $n(n-1)/2$ uniquely defined positive intervals $x_i - x_j$ within a given $\mathbf{x}$.

Because there is no preferred region within $\mathbb{R}^D$, any meaningful measure of indeterminacy for discrete real variables must be invariant under spatial transformations of the form $\mathbf{x} + \Delta x \equiv \{x_1 + \Delta x, \dots, x_n + \Delta x\}$ for any finite $\Delta x \in \mathbb{R}^D$. By inspecting either Equation (29) or Equation (30) we readily find that τ is translationally invariant, hence

$$\eta(\mathbf{p}, \mathbf{x} + \Delta x) = \eta(\mathbf{p}, \mathbf{x}) \quad (53)$$

Similarly transformations of the form $\mathbf{R}\mathbf{x} \equiv \{\mathbf{R}x_1, \dots, \mathbf{R}x_n\}$, where $\mathbf{R}$ is a D -dimensional unitary rotation matrix, could not change the indeterminacy in any X . Consequently the entropy attributed to X must be rotationally invariant as well. The effects of such a rotation would be equivalent to replacing the original $\tau(k)$ with $\tau'(k) = \tau(k\mathbf{R})$, which we may write as $\tau'(k) = \tau(k')$ after the variable substitution $k' = k\mathbf{R}$. The rotation therefore amounts to nothing more than a cosmetic change of variables, which does not affect the average value of $\tau \log(\tau)$ —whether taken over all space or taken over a finite region spanning a period in each dimension of k' . We therefore have

$$\eta(\mathbf{p}, \mathbf{R}\mathbf{x}) = \eta(\mathbf{p}, \mathbf{x}) \quad (54)$$

For the same reasons we also have

$$\eta(\mathbf{p}, \alpha\mathbf{x}) = \eta(\mathbf{p}, \mathbf{x}) \quad (55)$$

for any non-vanishing $\alpha \in \mathbb{R}$, where $\alpha\mathbf{x} \equiv \{\alpha x_1, \dots, \alpha x_n\}$. Contrary to Equation (55), suppose that the entropy of a real discrete variable were to increase under transformations of the form $\alpha\mathbf{x}$ for $|\alpha| > 1$. Consider applying such transformations successively to the allowed outcomes of some non-trivial X . Given that the entropy must never exceed H the effects of the transformations must

become negligible at some point, which would imply the existence of some preferred spatial scale for a given $\mathbf{x}$ and $\mathbf{p}$. The indeterminacy, however, could not be sensitive to such a scale. The scale-invariance expressed in Equation (55) is therefore necessary for any meaningful measure of indeterminacy in discrete real variables.

4. Quantitative Study

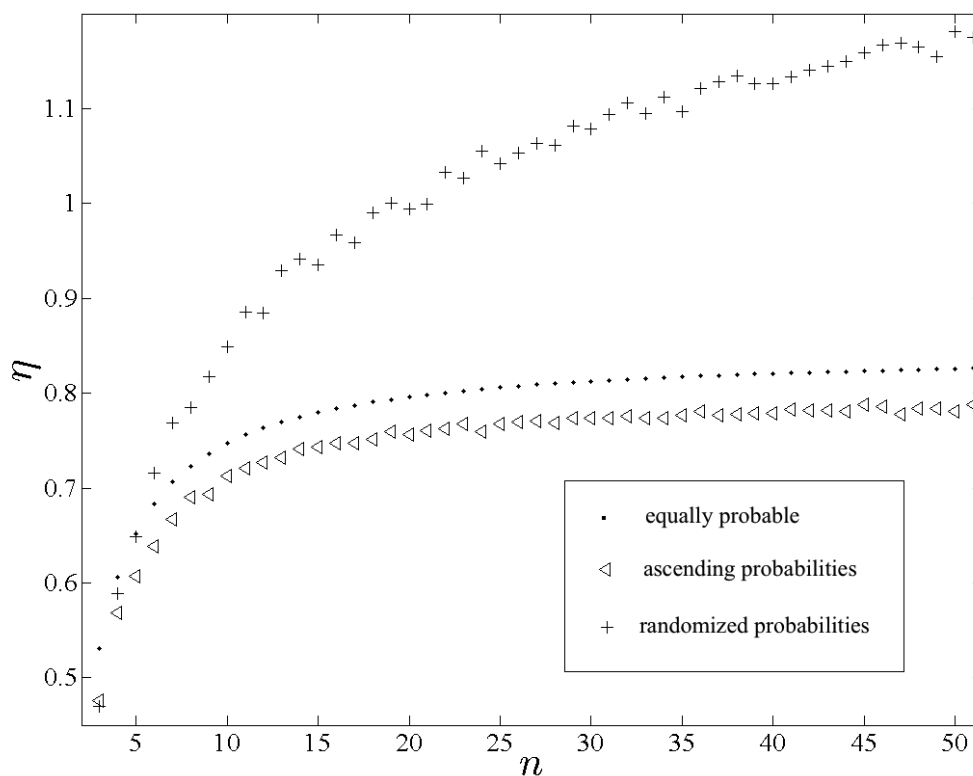
This section presents the results of numerical calculations of η chosen to validate the identification of η as the entropy of a discrete real variable and to demonstrate the utility of Ξ as a probe of deterministic structure in sequences of real numbers or non-numeric symbols. For convenience this introductory study is restricted to scenarios where $D = 1$; the conclusions are readily generalized to higher-dimensional spaces. In each calculation of η reported here the period-averaged value of $-\tau \log(\tau)$ was obtained from $2^5 \lfloor \kappa_0 / \kappa_* \rfloor$ samples, where $\kappa_* = 2\pi / (x_n - x_1)$ represents the finest periodicity in τ . Note that $x_n - x_1$ is always the largest positive interval within a one-dimensional $\mathbf{x}$. All computations were precise to 15 significant figures. The accuracy, in comparison to the “true” value of η produced by an infinite number of samples, is always better than $10^{-6}\eta$.

The first sets of calculations examined below involve the basic types of $\mathbf{x}$ and $\mathbf{p}$ introduced in Section 1, matched in various instructive combinations. Each $\mathbf{p}_r$ was constructed from n different real numbers with 15 significant figures selected randomly from $(0, 1)$, and subsequently normalized. Each $\mathbf{x}_r$ was constructed by randomly selecting n different integers from $[1, 100n]$. This produces approximately the same effect as using the full range available with 15 significant figures, but dramatically reduces processing requirements. For each calculation involving $\mathbf{p}_r$ a corresponding calculation involving $\mathbf{p}_a$ is performed, and each $\mathbf{p}_a$ is constructed by sorting the elements of the corresponding $\mathbf{p}_r$. Finally, each reported quantity of η involving a randomly generated parameter is the average of 100 separate calculations with different randomizations.

Let us begin by examining how η measures indeterminacy effected through different types of $\mathbf{p}$. Figure 1 displays calculations of $\eta(\mathbf{p}_e, \mathbf{x}_e)$, $\eta(\mathbf{p}_a, \mathbf{x}_e)$ and $\eta(\mathbf{p}_r, \mathbf{x}_e)$ plotted as functions of n . Recall that $\eta(\mathbf{p}_r, \mathbf{x}_e)$ and $\eta(\mathbf{p}_a, \mathbf{x}_e)$ should behave respectively as quantities of entropy attributed to the variables X_{re} and X_{ae} examined in Section 1. We find that $\eta(\mathbf{p}_r, \mathbf{x}_e)$ is appreciably greater than $\eta(\mathbf{p}_a, \mathbf{x}_e)$ for all but trivially small n , which is consistent with the expected result. Because the only difference between each $\mathbf{p}_a$ and $\mathbf{p}_r$ is the order of their respective terms, the differences between the associated quantities of entropy are entirely due to the contribution from Ξ .

Perhaps more importantly, and in opposition to the behavior of H alone, we find that $\eta(\mathbf{p}_r, \mathbf{x}_e)$ is also appreciably greater than $\eta(\mathbf{p}_e, \mathbf{x}_e)$ for all non-trivial n . Among generic discrete variables any non-uniformity in $\mathbf{p}$ is a benefit to predictability, hence $H(\mathbf{p}_r) \leq H(\mathbf{p}_e)$. Among real-valued discrete variables, however, the predictive benefit of non-uniformities in $\mathbf{p}$ depends on the manner in which the probabilities are spatially assigned. In the case of X_{re} the indeterminacy effected by the irregular spatial assignment of $\mathbf{p}_r$ evidently outweighs the intrinsic predictive benefit of $\mathbf{p}_r$, which implies that X_{ee} behaves more deterministically than X_{re} . Though not necessarily expected *a priori*, that implication is not surprising.

Figure 1. Plots of $\eta(\mathbf{p}_e, \mathbf{x}_e)$, $\eta(\mathbf{p}_a, \mathbf{x}_e)$ and $\eta(\mathbf{p}_r, \mathbf{x}_e)$ using the respective symbols “•”, “◁” and “+”.



As a complement to the previous scenario it is instructive to compare the effects of the three types of probabilities when matched to spatially randomized outcomes. Figure 2 displays calculations of $\eta(\mathbf{p}_e, \mathbf{x}_r)$, $\eta(\mathbf{p}_a, \mathbf{x}_r)$ and $\eta(\mathbf{p}_r, \mathbf{x}_r)$ plotted as functions of n . Note that $\eta(\mathbf{p}_a, \mathbf{x}_r)$ and $\eta(\mathbf{p}_r, \mathbf{x}_r)$ nearly coincide for each n , and the symbols “◊” and “*” are always superimposed in Figure 2. The entropy-difference $\eta(\mathbf{p}_r, \mathbf{x}_r) - \eta(\mathbf{p}_a, \mathbf{x}_r)$ is shown in Figure 3. In contrast to the previous scenario $\mathbf{p}_e$ consistently effects the largest entropy among the three, which is expected from Equation (52) given that $H(\mathbf{p}_e)$ is maximal. Note that $\eta(\mathbf{p}_e, \mathbf{x}_r)$ would be even closer to $H(\mathbf{p}_e)$ had the randomness of $\mathbf{x}_r$ not been restricted for the sake of computational feasibility. The similarity between $\eta(\mathbf{p}_r, \mathbf{x}_r)$ and $\eta(\mathbf{p}_a, \mathbf{x}_r)$ is also expected from Equation (52) given that $H(\mathbf{p}_r) = H(\mathbf{p}_a)$. Furthermore insofar as $\eta(\mathbf{p}_r, \mathbf{x}_r)$ and $\eta(\mathbf{p}_a, \mathbf{x}_r)$ differ the former should be typically greater for sufficiently large n , which is confirmed in Figure 3.

Let us next examine calculations demonstrating how η measures indeterminacy effected through $\mathbf{x}$, which is perhaps the most significant attribute of η . The most basic comparison corresponds to the scenario involving X_{ee} and X_{er} in Section 1. It is immediately evident from Figures 1 and 2 that $\eta(\mathbf{p}_e, \mathbf{x}_r)$ is considerably larger than $\eta(\mathbf{p}_e, \mathbf{x}_e)$ for all n , which is expected.

Figure 2. Plots of $\eta(\mathbf{p}_e, \mathbf{x}_r)$, $\eta(\mathbf{p}_a, \mathbf{x}_r)$ and $\eta(\mathbf{p}_r, \mathbf{x}_r)$, using the respective symbols “ $\times$ ”, “ $\diamond$ ” and “ $*$ ”. The solid line follows a plot of $\log(n)$ for reference.

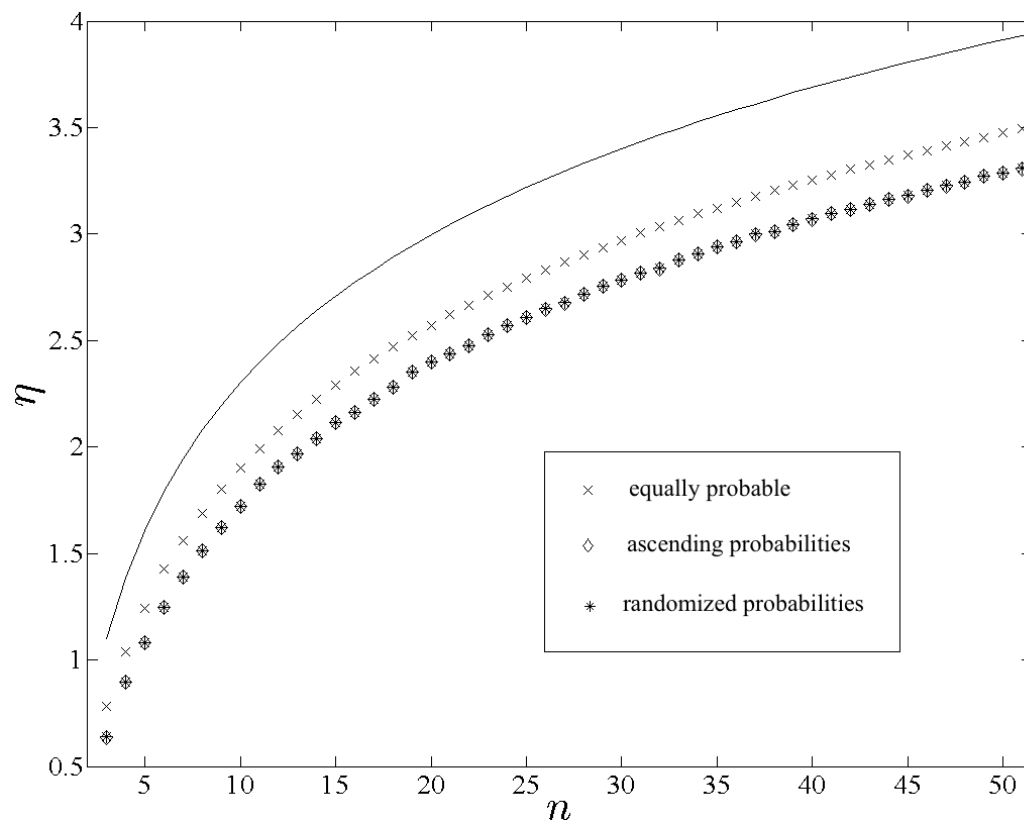
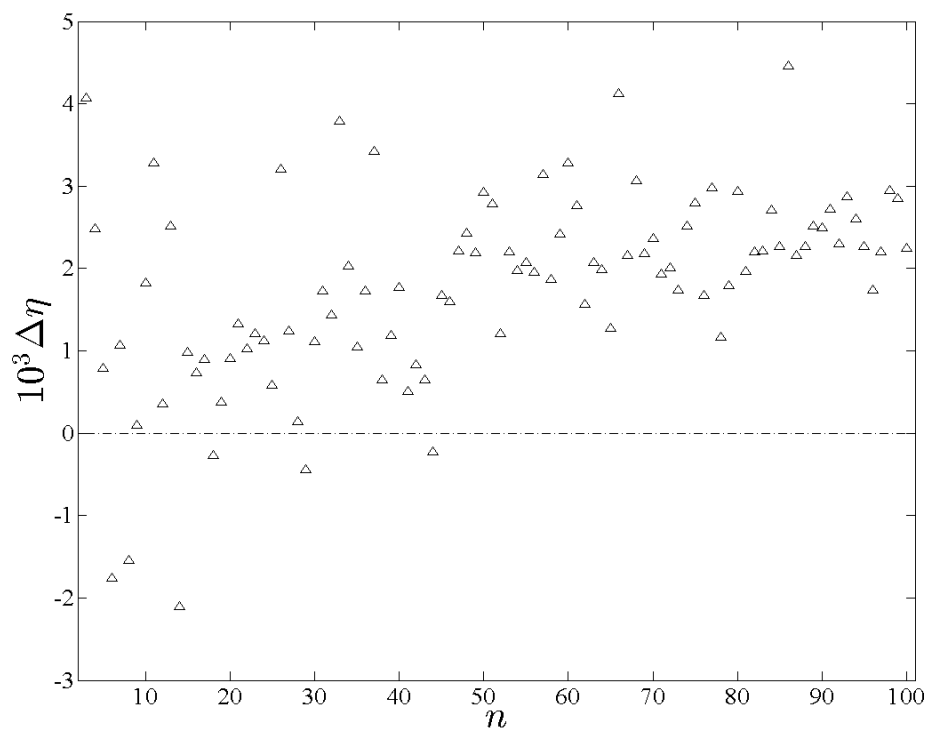


Figure 3. The entropy difference $\Delta\eta$ plotted here is $\eta(\mathbf{p}_r, \mathbf{x}_r) - \eta(\mathbf{p}_a, \mathbf{x}_r)$.



In order to test the sensitivity of η to more subtle differences in spatial structure the following additional sets of type $\mathbf{x}$ are defined. For a given n let $\mathbf{x}_p$ consist of the first n prime numbers. It follows from the Prime Number Theorem (PNT) that the local average gap in the vicinity of a given $x_j \in \mathbf{x}_p$ varies as $\log(j)$ for sufficiently large j . The term *gap* is used throughout in reference to a positive interval between consecutive terms in any given one-dimensional $\mathbf{x}$ and is defined such that the j -th gap is

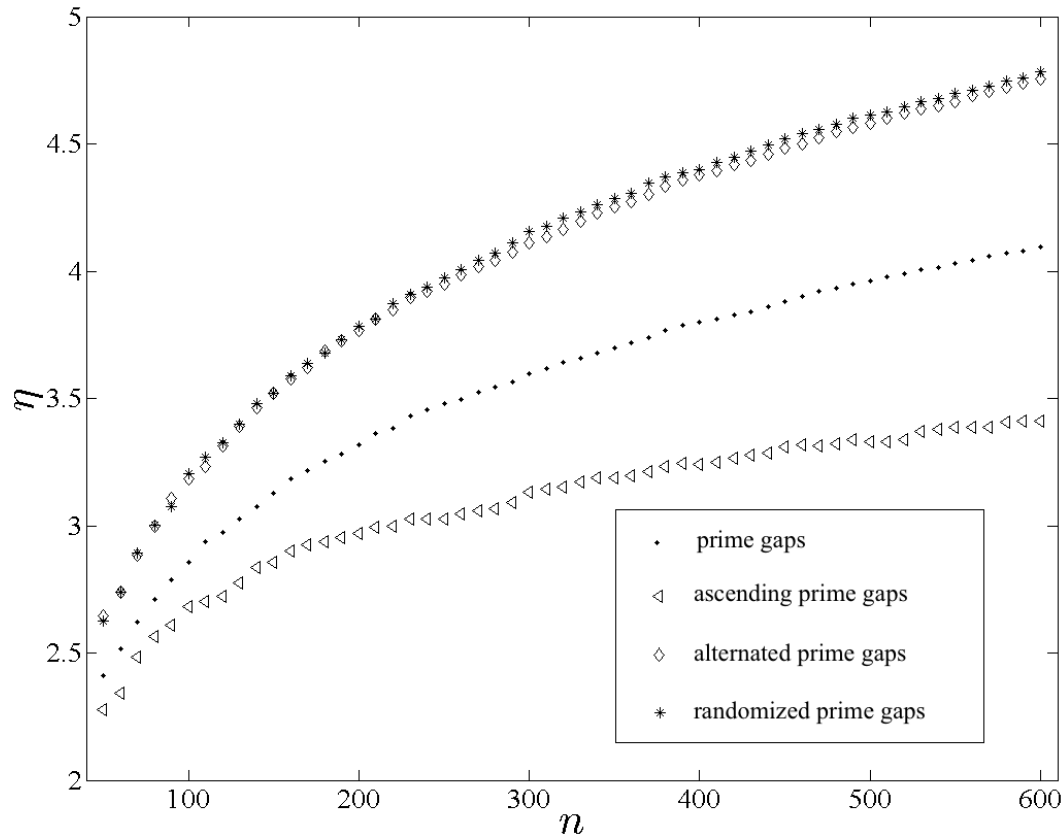
$$g_j \equiv x_{j+1} - x_j \quad (56)$$

The global anisotropy associated with the PNT constitutes an intrinsic deterministic spatial characteristic. For a more pronounced anisotropy of the same kind, let $\dot{\mathbf{x}}_p = \{2, 3, \dots\}$ be defined for a given n such that its sequence of gaps consists of the first $n - 1$ prime gaps arranged in ascending order. As an example, for $n = 6$ we have $\dot{\mathbf{x}}_p = \{2, 3, 5, 7, 9, 13\}$. Let $\tilde{\mathbf{x}}_p = \{2, 3, \dots\}$ be defined for a given n such that its sequence of gaps consists of the first $n - 1$ prime gaps ordered randomly, with the exception that the first gap in $\tilde{\mathbf{x}}_p$ is always 1. Finally let $\check{\mathbf{x}}_p = \{2, 3, \dots\}$ be defined such that its sequence of gaps is $\{g'_1, g'_3, g'_2, g'_5, g'_4, \dots\}$, where g'_j is the j -th prime gap. In other words, the sequence of gaps in $\check{\mathbf{x}}_p$ is constructed simply by alternating the order of g'_i and g'_{i+1} for all even i no greater than $n - 2$. Consequently every even-numbered element of $\check{\mathbf{x}}_p$ is guaranteed to be identical to the corresponding prime. As an example we have $\check{\mathbf{x}}_p = \{2, 3, 5, 7, 9, 13, 15, 19\}$ for $n = 8$. Note that the average gap in the vicinity of some $x_j \in \check{\mathbf{x}}_p$ differs only negligibly from the corresponding average gap in the primes, and $\check{\mathbf{x}}_p$ therefore exhibits the same global anisotropy inherent to $\mathbf{x}_p$.

Consider four variables with $n \gg 1$ allowed outcomes $\mathbf{x}_p$, $\dot{\mathbf{x}}_p$, $\tilde{\mathbf{x}}_p$ and $\check{\mathbf{x}}_p$, respectively, all of which are equally probable. As $\tilde{\mathbf{x}}_p$ is the least deterministically configured among the four, $\eta(\mathbf{p}_e, \tilde{\mathbf{x}}_p)$ should be largest. Furthermore, given that the sequence of gaps in $\dot{\mathbf{x}}_p$ ascends uniformly, the deterministic nature of the associated anisotropy is significantly greater than in $\mathbf{x}_p$ and $\check{\mathbf{x}}_p$. We therefore expect $\eta(\mathbf{p}_e, \dot{\mathbf{x}}_p)$ to be the smallest entropy among the four. Figure 4 shows $\eta(\mathbf{p}_e, \mathbf{x}_p)$, $\eta(\mathbf{p}_e, \dot{\mathbf{x}}_p)$, $\eta(\mathbf{p}_e, \tilde{\mathbf{x}}_p)$ and $\eta(\mathbf{p}_e, \check{\mathbf{x}}_p)$ plotted as functions of n . Although $\eta(\mathbf{p}_e, \tilde{\mathbf{x}}_p)$ and $\eta(\mathbf{p}_e, \check{\mathbf{x}}_p)$ differ only negligibly for n smaller than approximately 200, for all larger n the entropy due to $\tilde{\mathbf{x}}_p$ is the greatest among the four. The small but non-negligible difference between $\eta(\mathbf{p}_e, \tilde{\mathbf{x}}_p)$ and $\eta(\mathbf{p}_e, \check{\mathbf{x}}_p)$ for large n is attributed to the global anisotropy in $\check{\mathbf{x}}_p$. The entropy due to $\dot{\mathbf{x}}_p$ is the smallest among the four. The behavior of η in these calculations is therefore consistent with the stated expectations.

The dramatic difference between $\eta(\mathbf{p}_e, \mathbf{x}_p)$ and $\eta(\mathbf{p}_e, \check{\mathbf{x}}_p)$ is noteworthy and unexpected. The smaller entropy due to $\mathbf{x}_p$ implies a greater degree of intrinsic determinacy in the arrangement of $\mathbf{x}_p$ along the real axis. Note that the implied deterministic structure could not be associated with the PNT. A detailed analysis of this finding is beyond the present scope and has become the subject of a separate investigation [12]. For the present purposes it is sufficient to mention, as the reader may verify readily, that the number of positive intervals of a given size d among the first $n \gg 1$ primes is strongly correlated to the largest primordial factor of d [12]. That regularity could represent the deterministic property intimated by $\eta(\mathbf{p}_e, \mathbf{x}_p)$.

Figure 4. Plots of $\eta(\mathbf{p}_e, \mathbf{x}_p)$, $\eta(\mathbf{p}_e, \dot{\mathbf{x}}_p)$, $\eta(\mathbf{p}_e, \ddot{\mathbf{x}}_p)$ and $\eta(\mathbf{p}_e, \tilde{\mathbf{x}}_p)$, shown with “•”, “◁”, “◊” and “*”, respectively, measuring intrinsic structure in the primes $\mathbf{x}_p$ and in three variants constructed by changing the order of the first $n - 2$ even prime gaps.



5. Summary and Conclusions

For finite ν the entropy attributed to the variable $\mathcal{X}_\nu$ governed by $\rho_\nu(\nu, x)$ is simply $\mathcal{H}(\rho_\nu)$. In the limit as $\nu \rightarrow \infty$, however, $\mathcal{X}_\nu$ becomes a discrete variable X whose behavior is insensitive to the function ρ_0 from which ρ_ν is constructed. The entropy attributed asymptotically to X is therefore $\mathcal{H}(\rho_\infty) - \mathcal{H}(\rho_0)$, which recovers the discrete Shannon entropy. Similarly when ν is finite a quantity of entropy $S(\psi_\nu)$ is attributed to the conjugated pair $\mathcal{X}_\nu$ and $\mathcal{K}_\nu$. The nature of the pair, however, is asymptotically insensitive to ϕ_0 . The entropy attributed to the pair in the limit as ν diverges is therefore $S(\psi_\infty) - S(\phi_0)$, whose asymptotic form $H + \Xi$ is defined as η . Furthermore because the conjugate is asymptotically eliminated η must be attributed to X alone.

As H is a function only of $\mathbf{p}$, the existence of some $\mathbf{x}$ -dependent contribution to the entropy of a discrete real variable is expected independently of the introduction of Ξ . Whereas the form of H uniquely exhibits the properties required for a self-consistent measure of indeterminacy effected by $\mathbf{p}$ [1], the complete set of requirements for a measure of indeterminacy effected by $\mathbf{x}$ and $\mathbf{p}$ is not readily ascertained *a priori*. Among those required properties are certainly translational invariance, scale-invariance, rotational invariance, non-negativity and being bound from above by H , all of which were proven for η in Section 3. Furthermore the calculations presented in Section 4 demonstrate that η behaves in the expected manner over a broad range of different configurations of $\mathbf{x}$ and $\mathbf{p}$.

The somewhat counterintuitive role of Ξ is a natural consequence of the relationship between a given wave-mechanical probability density and the corresponding spectral density. More broadly interpreted, the wave-mechanical origin of η may be understood as a natural consequence of a fundamental unity between information theory and quantum theory. Such an interpretation is well-motivated given the profound connections already known. For instance, the bounds on S lead to an uncertainty relation that is stronger than the most general form of the Heisenberg Uncertainty Principle [2]. Even more striking, the basic precepts of quantum theory have been derived from informatic principles [13]. It is important to specify, however, that the validity of η is contingent upon no quantum-mechanical premise.

The distinctive feature of η is its dependence on $\mathbf{x}$, which is necessary for a complete measure of indeterminacy in discrete real variables. Because of the generality of its form, η can be readily manipulated to probe intrinsic organization in sequences of real numbers. Section 4 presented calculations demonstrating the novel capability of η in such applications. Future investigations will explore additional applications of η .

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