

Turning Detection During Gait: Algorithm Validation and Influence of Sensor Location and Turning Characteristics in the Classification of Parkinson's Disease

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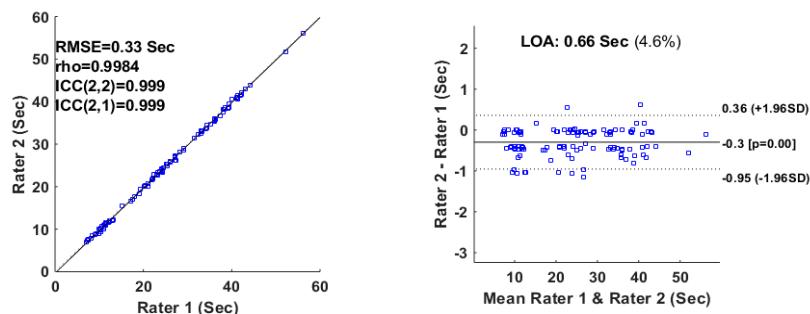
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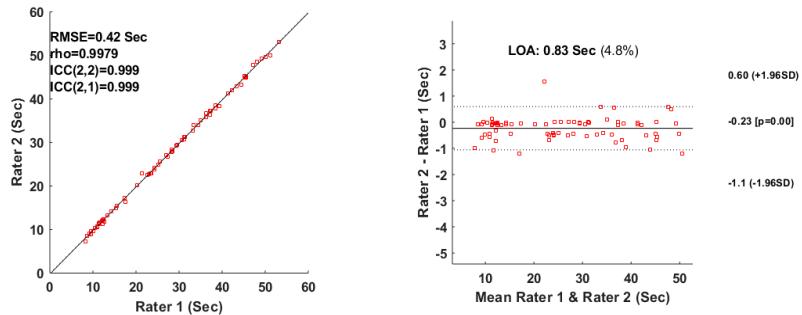
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Supplementary Material

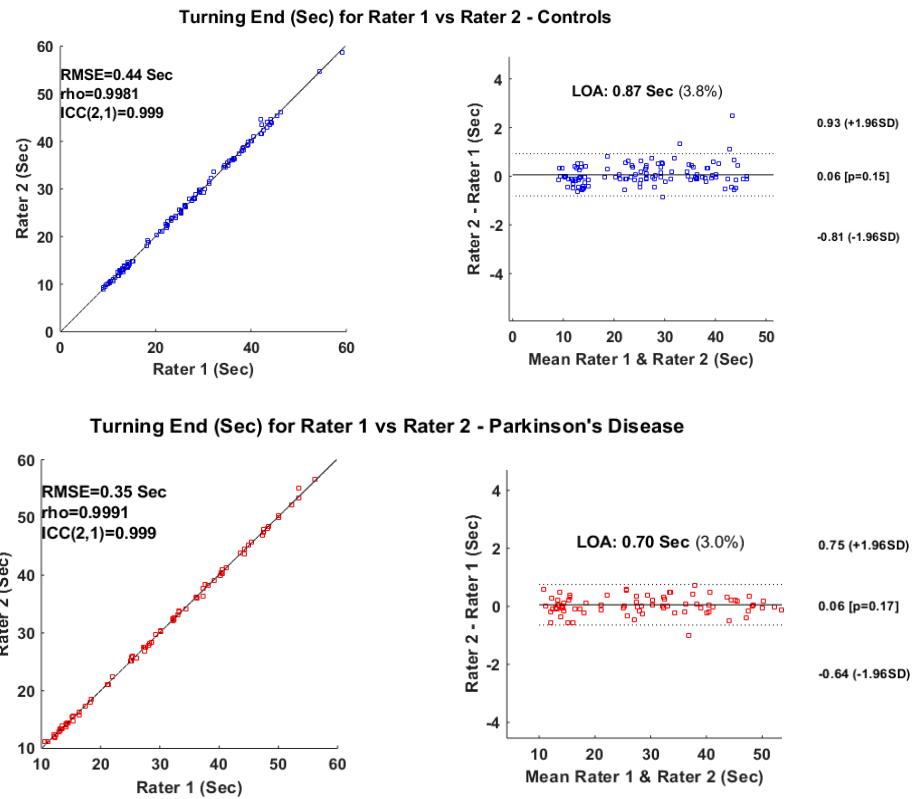
Turning Start (Sec) for Rater 1 vs Rater 2 - Controls



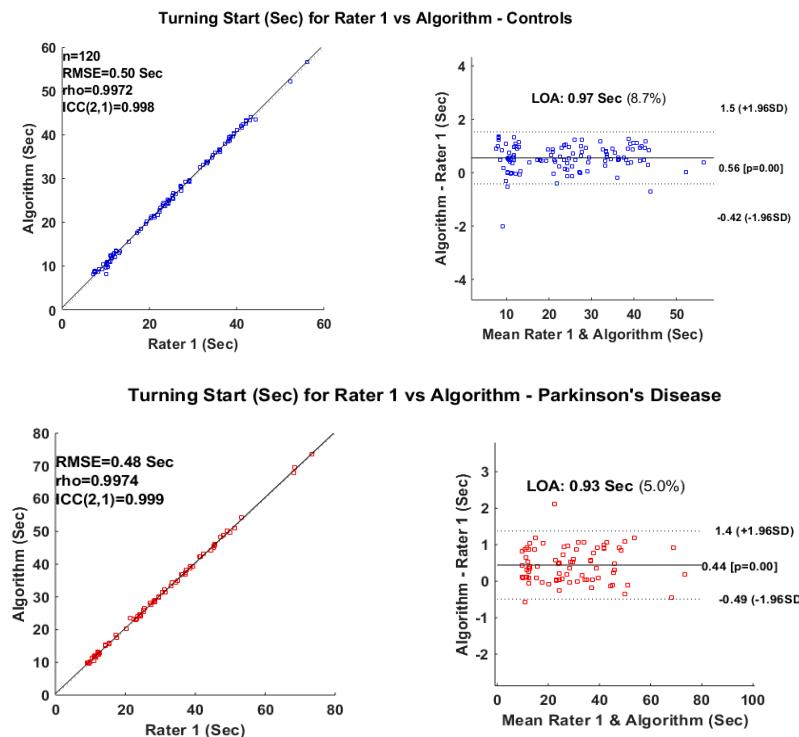
Turning Start (Sec) for Rater 1 vs Rater 2 - Parkinson's Disease



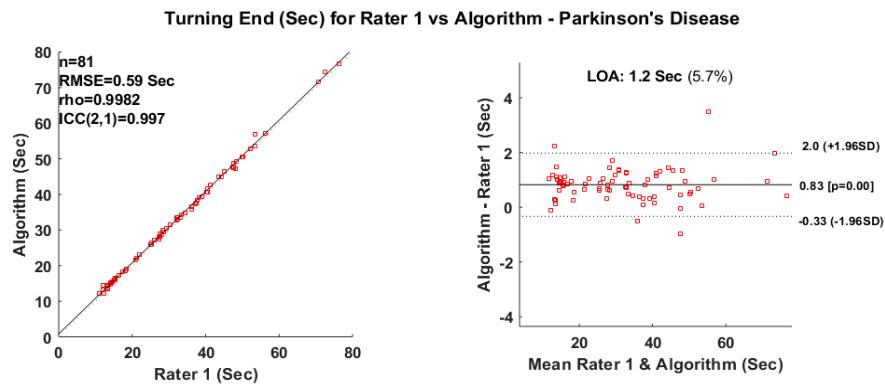
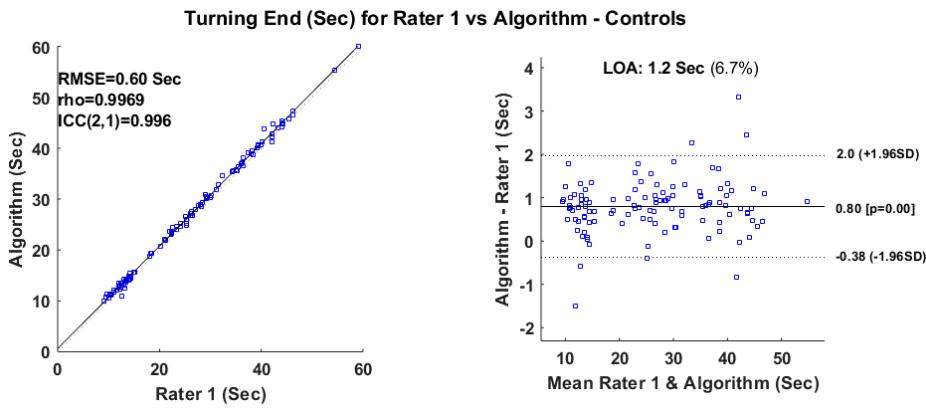
(a) Rater 1 vs. Rater 2—Turn Start.



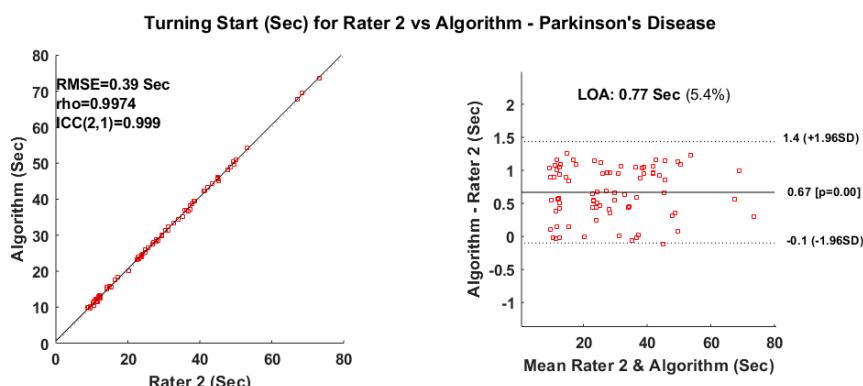
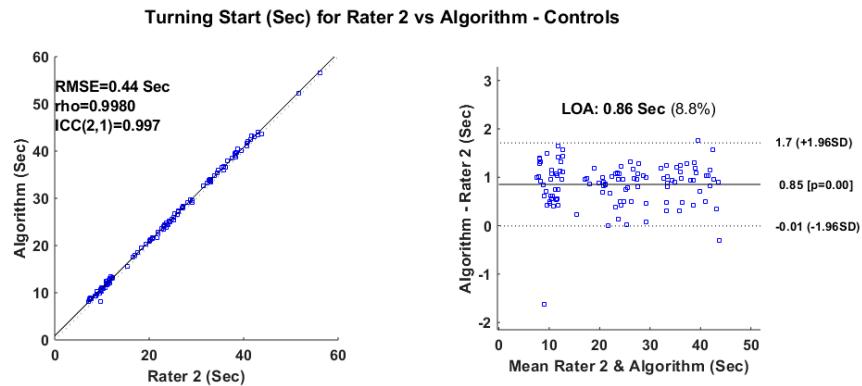
(b) Rater 1 vs. Rater 2—Turn End.



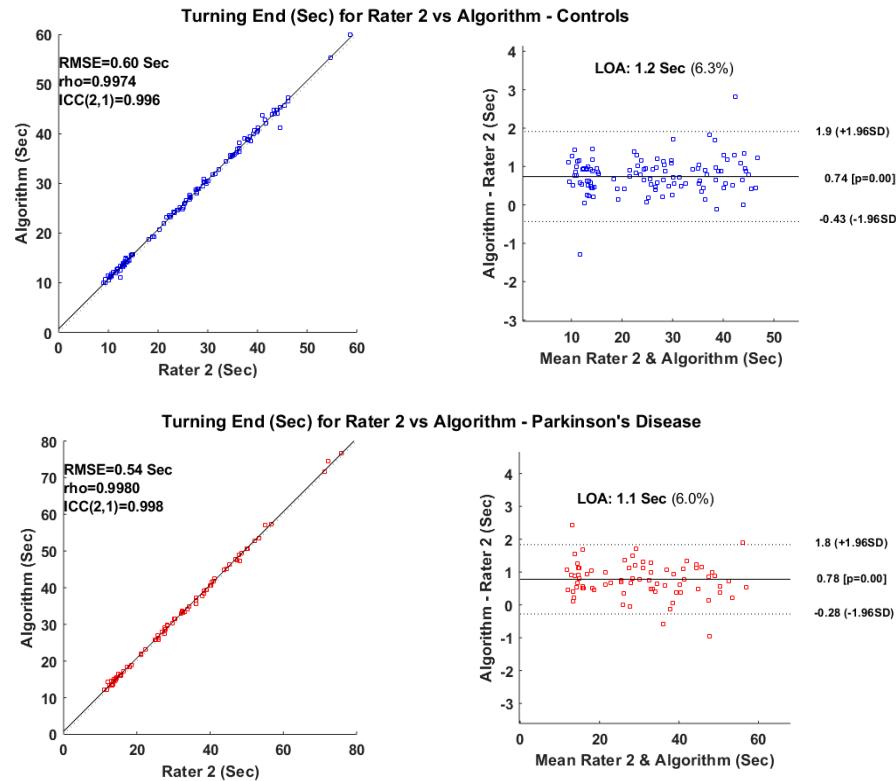
(c) Rater 1 vs. Algorithm—Turn Start.



(d) Rater 1 vs. Algorithm—Turn End.



(e) Rater 2 vs. Algorithm—Turn Start.



(f) Rater 2 vs. Algorithm—Turn End.

Figure S1. Scatter plots and Bland Altman plots for validation of the turning start and turning end.

Table S1. Statistical analysis of turning characteristics from the lower back (L5), neck (C7), head (HD), inner ankle (inner), outer ankle (outer).

| Turning Characteristics | Control Group | PD Group | Student t-test | Mann Whitney |
|---|--------------------|--------------------|----------------|--------------|
| Turning Characteristics from Lower Back (L5) | | | | |
| Number of Turns | 3.48 ± 0.54 | 3.22 ± 0.82 | 0.062 | 0.043 |
| Angle of Turn-Max | 188.15 ± 45.69 | 176.93 ± 29.30 | 0.189 | 0.004 |
| Angle of Turn-Min | 154.61 ± 21.49 | 157.61 ± 32.06 | 0.591 | 0.553 |
| Angle of Turn-Average | 172.59 ± 22.99 | 168.37 ± 29.33 | 0.440 | 0.056 |
| Angle of Turn-Variability | 15.99 ± 22.75 | 9.56 ± 8.02 | 0.102 | 0.034 |
| No. of Direction of Turns-Right | 2.30 ± 1.11 | 2.49 ± 1.15 | 0.445 | 0.471 |
| No. of Direction of Turns-Left | 1.18 ± 1.03 | 0.73 ± 1.12 | 0.050 | 0.020 |
| Duration of Turn-Max | 3.04 ± 1.05 | 3.88 ± 1.41 | 0.001 | 0.001 |
| Duration of Turn-Min | 1.94 ± 0.54 | 2.70 ± 1.04 | < 0.0001 | < 0.0001 |
| Duration of Turn-Average | 2.46 ± 0.64 | 3.25 ± 1.03 | < 0.0001 | < 0.0001 |
| Duration of Turn-Variability | 0.53 ± 0.47 | 0.58 ± 0.63 | 0.629 | 0.854 |
| Angular Velocity-Average | 75.85 ± 17.53 | 56.74 ± 14.43 | < 0.0001 | < 0.0001 |
| Angular Velocity-Variability | 13.46 ± 8.24 | 8.98 ± 7.47 | 0.009 | 0.003 |
| Peak Angular Velocity-Average | 175.72 ± 38.44 | 136.68 ± 34.04 | < 0.0001 | < 0.0001 |
| Peak Angular Velocity-Variability | 24.47 ± 13.12 | 16.30 ± 11.79 | 0.003 | 0.002 |
| Angular Velocity Start-Average | 31.84 ± 16.08 | 24.63 ± 11.09 | 0.020 | 0.030 |
| Angular Velocity Start-Variability | 15.66 ± 9.51 | 10.11 ± 6.56 | 0.003 | 0.002 |

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|--------------------------------------|--------------------|-------------------|--------------|--------------|
| Angular Velocity End-Average | 13.67 ± 7.48 | 10.39 ± 9.01 | 0.060 | 0.001 |
| Angular Velocity End-Variability | 7.93 ± 5.39 | 4.80 ± 6.20 | 0.012 | 0.000 |
| Angular Velocity Middle-Average | 107.62 ± 37.82 | 72.77 ± 30.48 | < 0.0001 | < 0.0001 |
| Angular Velocity Middle-Variability | 38.55 ± 24.35 | 25.85 ± 16.91 | 0.007 | 0.016 |
| RMS-Acceleration-ML | 0.14 ± 0.03 | 0.12 ± 0.03 | 0.000 | 0.000 |
| RMS-Acceleration-Start-ML | 0.16 ± 0.09 | 0.16 ± 0.08 | 0.989 | 0.751 |
| RMS-Acceleration-Mid-ML | 0.14 ± 0.04 | 0.12 ± 0.07 | 0.044 | 0.004 |
| RMS-Acceleration-End-ML | 0.11 ± 0.04 | 0.08 ± 0.05 | 0.013 | 0.002 |
| RMS-Angular Velocity-ML | 0.25 ± 0.07 | 0.21 ± 0.06 | 0.003 | 0.001 |
| RMS-Angular Velocity-Start-ML | 0.26 ± 0.14 | 0.22 ± 0.12 | 0.114 | 0.121 |
| RMS-Angular Velocity-Mid-ML | 0.23 ± 0.10 | 0.19 ± 0.13 | 0.095 | 0.006 |
| RMS-Angular Velocity-End-ML | 0.15 ± 0.06 | 0.12 ± 0.07 | 0.009 | 0.000 |
| RMS of Jerk-ML | 3.92 ± 1.55 | 3.25 ± 1.29 | 0.031 | 0.029 |
| Max of Jerk-ML | 16.14 ± 7.61 | 14.79 ± 5.96 | 0.364 | 0.538 |
| Min of Jerk-ML | 16.43 ± 7.75 | 15.00 ± 6.79 | 0.363 | 0.403 |
| Range of Jerk-ML | 32.58 ± 15.07 | 29.79 ± 12.19 | 0.351 | 0.522 |
| RMS of Jerk-Start-ML | 6.00 ± 4.46 | 5.54 ± 3.40 | 0.596 | 0.860 |
| RMS of Jerk-Mid-ML | 2.83 ± 1.45 | 3.06 ± 3.80 | 0.677 | 0.072 |
| RMS of Jerk-End-ML | 2.11 ± 1.86 | 1.77 ± 1.80 | 0.380 | 0.077 |
| RMS of Angular Acceleration-ML | 6.62 ± 3.17 | 4.89 ± 2.92 | 0.009 | 0.003 |
| Max of Angular Acceleration-ML | 29.22 ± 16.03 | 22.70 ± 18.94 | 0.078 | 0.019 |
| Min of Angular Acceleration-ML | 30.21 ± 16.62 | 24.40 ± 16.52 | 0.102 | 0.051 |
| Range of Angular Acceleration-ML | 59.44 ± 31.78 | 47.11 ± 34.98 | 0.082 | 0.026 |
| RMS of Angular Acceleration-Start-ML | 11.13 ± 8.39 | 8.08 ± 6.29 | 0.063 | 0.037 |
| RMS of Angular Acceleration-Mid-ML | 4.61 ± 3.15 | 3.89 ± 4.73 | 0.381 | 0.021 |
| RMS of Angular Acceleration-End-ML | 3.21 ± 1.95 | 2.71 ± 3.05 | 0.338 | 0.024 |
| RMS-Acceleration-VT | 0.11 ± 0.04 | 0.09 ± 0.04 | 0.018 | 0.003 |
| RMS-Acceleration-Start-VT | 0.18 ± 0.10 | 0.15 ± 0.08 | 0.223 | 0.421 |
| RMS-Acceleration-Mid-VT | 0.07 ± 0.04 | 0.07 ± 0.07 | 0.924 | 0.030 |
| RMS-Acceleration-End-VT | 0.07 ± 0.04 | 0.06 ± 0.08 | 0.542 | 0.020 |
| RMS-Angular Velocity-VT | 1.49 ± 0.36 | 1.07 ± 0.32 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-Start-VT | 0.49 ± 0.26 | 0.36 ± 0.18 | 0.009 | 0.018 |
| RMS-Angular Velocity-Mid-VT | 1.81 ± 0.66 | 1.17 ± 0.55 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-End-VT | 0.24 ± 0.13 | 0.18 ± 0.14 | 0.039 | 0.002 |
| RMS of Jerk-VT | 4.38 ± 2.31 | 3.22 ± 1.49 | 0.008 | 0.004 |
| Max of Jerk-VT | 21.90 ± 12.25 | 17.94 ± 9.81 | 0.103 | 0.054 |
| Min of Jerk-VT | 20.36 ± 12.81 | 16.31 ± 8.73 | 0.097 | 0.066 |
| Range of Jerk-VT | 42.25 ± 24.67 | 34.25 ± 18.06 | 0.094 | 0.056 |
| RMS of Jerk-Start-VT | 7.11 ± 6.25 | 5.65 ± 4.07 | 0.214 | 0.458 |
| RMS of Jerk-Mid-VT | 2.49 ± 1.74 | 2.51 ± 2.68 | 0.964 | 0.263 |
| RMS of Jerk-End-VT | 2.27 ± 2.26 | 2.22 ± 4.77 | 0.943 | 0.094 |
| RMS of Angular Acceleration-VT | 9.28 ± 3.17 | 6.89 ± 3.44 | 0.001 | < 0.0001 |
| Max of Angular Acceleration-VT | 38.95 ± 18.93 | 31.69 ± 18.49 | 0.071 | 0.030 |
| Min of Angular Acceleration-VT | 36.95 ± 14.31 | 27.07 ± 16.63 | 0.003 | < 0.0001 |

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| Range of Angular Acceleration-VT | 75.89 ± 30.52 | 58.76 ± 34.36 | 0.013 | 0.001 |
| RMS of Angular Acceleration-Start-VT | 17.19 ± 9.19 | 13.44 ± 7.25 | 0.040 | 0.033 |
| RMS of Angular Acceleration-Mid-VT | 6.98 ± 3.93 | 7.01 ± 9.75 | 0.986 | 0.018 |
| RMS of Angular Acceleration-End-VT | 6.22 ± 3.52 | 4.72 ± 4.06 | 0.063 | 0.001 |
| RMS-Acceleration-AP | 0.09 ± 0.03 | 0.08 ± 0.03 | 0.062 | 0.002 |
| RMS-Acceleration-Start-AP | 0.15 ± 0.07 | 0.12 ± 0.06 | 0.013 | 0.011 |
| RMS-Acceleration-Mid-AP | 0.07 ± 0.05 | 0.06 ± 0.05 | 0.378 | 0.048 |
| RMS-Acceleration-End-AP | 0.06 ± 0.03 | 0.07 ± 0.07 | 0.276 | 0.817 |
| RMS-Angular Velocity-AP | 0.41 ± 0.23 | 0.27 ± 0.14 | 0.002 | 0.000 |
| RMS-Angular Velocity-Start-AP | 0.31 ± 0.16 | 0.26 ± 0.12 | 0.129 | 0.189 |
| RMS-Angular Velocity-Mid-AP | 0.50 ± 0.36 | 0.28 ± 0.17 | 0.001 | 0.000 |
| RMS-Angular Velocity-End-AP | 0.15 ± 0.08 | 0.10 ± 0.09 | 0.007 | 0.000 |
| RMS of Jerk-AP | 3.22 ± 1.44 | 2.34 ± 1.05 | 0.002 | 0.000 |
| Max of Jerk-AP | 15.65 ± 8.24 | 11.88 ± 7.98 | 0.031 | 0.004 |
| Min of Jerk-AP | 16.23 ± 7.87 | 12.99 ± 7.00 | 0.046 | 0.009 |
| Range of Jerk-AP | 31.88 ± 15.57 | 24.87 ± 14.54 | 0.032 | 0.003 |
| RMS of Jerk-Start-AP | 5.63 ± 4.27 | 3.96 ± 2.91 | 0.040 | 0.023 |
| RMS of Jerk-Mid-AP | 1.87 ± 1.44 | 1.72 ± 2.00 | 0.677 | 0.072 |
| RMS of Jerk-End-AP | 1.54 ± 1.26 | 1.81 ± 4.91 | 0.686 | 0.029 |
| RMS of Angular Acceleration-AP | 6.08 ± 2.36 | 4.45 ± 1.76 | 0.001 | 0.000 |
| Max of Angular Acceleration-AP | 25.35 ± 11.19 | 19.55 ± 8.41 | 0.008 | 0.009 |
| Min of Angular Acceleration-AP | 23.80 ± 10.03 | 19.26 ± 8.24 | 0.024 | 0.017 |
| Range of Angular Acceleration-AP | 49.15 ± 20.57 | 38.80 ± 15.91 | 0.011 | 0.009 |
| RMS of Angular Acceleration-Start-AP | 10.14 ± 5.80 | 8.00 ± 4.32 | 0.057 | 0.129 |
| RMS of Angular Acceleration-Mid-AP | 4.46 ± 2.53 | 3.50 ± 3.19 | 0.112 | 0.005 |
| RMS of Angular Acceleration-End-AP | 3.25 ± 2.52 | 2.37 ± 2.68 | 0.112 | 0.001 |
| RMS-Acceleration-R | 0.21 ± 0.05 | 0.17 ± 0.05 | 0.003 | 0.001 |
| RMS-Acceleration-Start-R | 0.30 ± 0.13 | 0.27 ± 0.10 | 0.234 | 0.317 |
| RMS-Acceleration-Mid-R | 0.19 ± 0.06 | 0.17 ± 0.10 | 0.177 | 0.002 |
| RMS-Acceleration-End-R | 0.15 ± 0.05 | 0.14 ± 0.11 | 0.394 | 0.010 |
| RMS-Angular Velocity-R | 1.58 ± 0.37 | 1.13 ± 0.33 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-Start-R | 0.69 ± 0.29 | 0.54 ± 0.19 | 0.008 | 0.020 |
| RMS-Angular Velocity-Mid-R | 1.93 ± 0.68 | 1.25 ± 0.55 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-End-R | 0.35 ± 0.14 | 0.26 ± 0.17 | 0.006 | 0.000 |
| RMS of Jerk-R | 4.47 ± 2.06 | 3.31 ± 1.35 | 0.003 | 0.002 |
| Max of Jerk-R | 22.84 ± 13.41 | 18.43 ± 10.18 | 0.093 | 0.078 |
| Min of Jerk-R | 23.31 ± 10.98 | 19.45 ± 9.60 | 0.084 | 0.045 |
| Range of Jerk-R | 46.15 ± 23.92 | 37.88 ± 19.35 | 0.082 | 0.047 |
| RMS of Jerk-Start-R | 6.83 ± 4.93 | 5.89 ± 3.97 | 0.332 | 0.394 |
| RMS of Jerk-Mid-R | 2.63 ± 1.50 | 2.79 ± 3.29 | 0.739 | 0.173 |
| RMS of Jerk-End-R | 2.18 ± 1.91 | 2.42 ± 5.53 | 0.767 | 0.039 |
| RMS of Angular Acceleration-R | 8.73 ± 2.74 | 6.44 ± 2.71 | 0.000 | < 0.0001 |
| Max of Angular Acceleration-R | 38.93 ± 16.37 | 29.34 ± 15.59 | 0.006 | 0.001 |

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|---|--------------------|--------------------|--------------|--------------|
| Min of Angular Acceleration-R | 34.98 ± 12.95 | 28.00 ± 15.22 | 0.020 | 0.002 |
| Range of Angular Acceleration-R | 73.91 ± 26.96 | 57.34 ± 29.71 | 0.007 | 0.001 |
| RMS of Angular Acceleration-Start-R | 14.30 ± 7.35 | 10.86 ± 5.50 | 0.017 | 0.020 |
| RMS of Angular Acceleration-Mid-R | 6.68 ± 3.72 | 6.12 ± 7.02 | 0.621 | 0.010 |
| RMS of Angular Acceleration-End-R | 4.78 ± 2.60 | 3.72 ± 3.23 | 0.084 | 0.001 |
| Turning Characteristics from Neck (C7) | | | | |
| Number of Turns | 3.84 ± 1.06 | 4.24 ± 2.17 | 0.234 | 0.539 |
| Angle of Turn-Max | 118.55 ± 23.34 | 106.88 ± 27.47 | 0.030 | 0.047 |
| Angle of Turn-Min | 88.74 ± 35.01 | 77.50 ± 39.77 | 0.155 | 0.216 |
| Angle of Turn-Average | 105.35 ± 25.05 | 92.65 ± 31.50 | 0.034 | 0.065 |
| Angle of Turn-Variability | 13.51 ± 11.68 | 12.87 ± 12.76 | 0.803 | 0.231 |
| No. of Direction of Turns-Right | 2.52 ± 1.18 | 3.11 ± 1.68 | 0.049 | 0.092 |
| No. of Direction of Turns-Left | 1.32 ± 1.18 | 1.14 ± 1.62 | 0.522 | 0.170 |
| Duration of Turn-Max | 3.03 ± 0.75 | 3.82 ± 1.56 | 0.002 | 0.009 |
| Duration of Turn-Min | 1.80 ± 0.59 | 2.17 ± 0.82 | 0.012 | 0.012 |
| Duration of Turn-Average | 2.37 ± 0.54 | 2.86 ± 0.80 | 0.001 | 0.000 |
| Duration of Turn-Variability | 0.57 ± 0.33 | 0.73 ± 0.55 | 0.073 | 0.348 |
| Angular Velocity-Average | 47.31 ± 12.71 | 34.06 ± 10.57 | < 0.0001 | < 0.0001 |
| Angular Velocity-Variability | 9.25 ± 6.01 | 6.86 ± 4.57 | 0.042 | 0.047 |
| Peak Angular Velocity-Average | 109.48 ± 26.93 | 82.82 ± 25.83 | < 0.0001 | < 0.0001 |
| Peak Angular Velocity-Variability | 16.18 ± 9.26 | 15.11 ± 10.39 | 0.603 | 0.538 |
| Angular Velocity Start-Average | 11.95 ± 6.50 | 10.48 ± 4.92 | 0.242 | 0.352 |
| Angular Velocity Start-Variability | 6.07 ± 4.18 | 4.97 ± 3.76 | 0.199 | 0.143 |
| Angular Velocity End-Average | 7.13 ± 3.73 | 6.58 ± 3.91 | 0.498 | 0.241 |
| Angular Velocity End-Variability | 3.90 ± 4.53 | 3.55 ± 2.57 | 0.676 | 0.984 |
| Angular Velocity Middle-Average | 70.25 ± 25.66 | 49.45 ± 23.15 | 0.000 | 0.000 |
| Angular Velocity Middle-Variability | 27.48 ± 12.84 | 19.56 ± 11.41 | 0.003 | 0.003 |
| RMS-Acceleration-ML | 0.15 ± 0.03 | 0.13 ± 0.04 | 0.011 | 0.001 |
| RMS-Acceleration-Start-ML | 0.16 ± 0.07 | 0.15 ± 0.06 | 0.608 | 0.811 |
| RMS-Acceleration-Mid-ML | 0.14 ± 0.06 | 0.13 ± 0.05 | 0.285 | 0.507 |
| RMS-Acceleration-End-ML | 0.12 ± 0.05 | 0.11 ± 0.06 | 0.449 | 0.280 |
| RMS-Angular Velocity-ML | 0.25 ± 0.08 | 0.20 ± 0.09 | 0.009 | 0.000 |
| RMS-Angular Velocity-Start-ML | 0.18 ± 0.07 | 0.16 ± 0.09 | 0.209 | 0.070 |
| RMS-Angular Velocity-Mid-ML | 0.23 ± 0.11 | 0.17 ± 0.08 | 0.009 | 0.004 |
| RMS-Angular Velocity-End-ML | 0.15 ± 0.06 | 0.12 ± 0.07 | 0.041 | 0.007 |
| RMS of Jerk-ML | 2.16 ± 0.85 | 1.81 ± 0.75 | 0.041 | 0.020 |
| Max of Jerk-ML | 8.98 ± 3.94 | 7.80 ± 3.50 | 0.142 | 0.079 |
| Min of Jerk-ML | 8.34 ± 4.14 | 7.18 ± 3.36 | 0.160 | 0.139 |
| Range of Jerk-ML | 17.32 ± 7.67 | 14.98 ± 6.39 | 0.128 | 0.094 |
| RMS of Jerk-Start-ML | 2.34 ± 2.22 | 2.09 ± 0.83 | 0.512 | 0.497 |
| RMS of Jerk-Mid-ML | 1.85 ± 1.36 | 1.42 ± 0.95 | 0.097 | 0.039 |
| RMS of Jerk-End-ML | 1.08 ± 0.76 | 0.99 ± 0.54 | 0.532 | 0.698 |
| RMS of Angular Acceleration-ML | 5.27 ± 2.76 | 4.16 ± 2.59 | 0.056 | 0.020 |

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|--------------------------------------|-------------------|-------------------|--------------|--------------|
| Max of Angular Acceleration-ML | 20.48 ± 13.78 | 16.73 ± 12.06 | 0.181 | 0.154 |
| Min of Angular Acceleration-ML | 23.06 ± 13.49 | 19.08 ± 12.53 | 0.156 | 0.103 |
| Range of Angular Acceleration-ML | 43.54 ± 26.72 | 35.81 ± 23.83 | 0.158 | 0.154 |
| RMS of Angular Acceleration-Start-ML | 5.70 ± 3.96 | 4.75 ± 2.91 | 0.212 | 0.277 |
| RMS of Angular Acceleration-Mid-ML | 4.35 ± 3.58 | 2.98 ± 2.93 | 0.055 | 0.011 |
| RMS of Angular Acceleration-End-ML | 2.98 ± 2.95 | 2.41 ± 1.78 | 0.289 | 0.231 |
| RMS-Acceleration-VT | 0.12 ± 0.03 | 0.11 ± 0.04 | 0.280 | 0.040 |
| RMS-Acceleration-Start-VT | 0.13 ± 0.06 | 0.13 ± 0.06 | 0.765 | 0.757 |
| RMS-Acceleration-Mid-VT | 0.09 ± 0.04 | 0.09 ± 0.04 | 0.973 | 0.793 |
| RMS-Acceleration-End-VT | 0.09 ± 0.06 | 0.07 ± 0.05 | 0.103 | 0.024 |
| RMS-Angular Velocity-VT | 0.94 ± 0.25 | 0.65 ± 0.20 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-Start-VT | 0.18 ± 0.10 | 0.16 ± 0.07 | 0.184 | 0.274 |
| RMS-Angular Velocity-Mid-VT | 1.17 ± 0.44 | 0.79 ± 0.38 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-End-VT | 0.12 ± 0.06 | 0.12 ± 0.06 | 0.652 | 0.463 |
| RMS of Jerk-VT | 3.73 ± 1.80 | 2.84 ± 1.15 | 0.009 | 0.004 |
| Max of Jerk-VT | 17.81 ± 9.61 | 15.01 ± 6.97 | 0.130 | 0.168 |
| Min of Jerk-VT | 15.37 ± 8.64 | 12.46 ± 5.54 | 0.073 | 0.069 |
| Range of Jerk-VT | 33.18 ± 17.94 | 27.47 ± 12.17 | 0.094 | 0.097 |
| RMS of Jerk-Start-VT | 3.99 ± 3.18 | 3.55 ± 1.81 | 0.453 | 0.953 |
| RMS of Jerk-Mid-VT | 2.64 ± 1.76 | 1.79 ± 1.19 | 0.012 | 0.005 |
| RMS of Jerk-End-VT | 1.89 ± 2.61 | 1.22 ± 0.62 | 0.131 | 0.291 |
| RMS of Angular Acceleration-VT | 4.35 ± 1.70 | 3.57 ± 1.77 | 0.035 | 0.008 |
| Max of Angular Acceleration-VT | 14.69 ± 7.44 | 13.71 ± 7.18 | 0.527 | 0.548 |
| Min of Angular Acceleration-VT | 13.15 ± 6.10 | 11.31 ± 6.07 | 0.157 | 0.061 |
| Range of Angular Acceleration-VT | 27.84 ± 12.83 | 25.01 ± 12.90 | 0.302 | 0.186 |
| RMS of Angular Acceleration-Start-VT | 5.94 ± 3.31 | 5.26 ± 2.60 | 0.301 | 0.522 |
| RMS of Angular Acceleration-Mid-VT | 3.94 ± 2.14 | 3.15 ± 1.82 | 0.070 | 0.027 |
| RMS of Angular Acceleration-End-VT | 3.26 ± 1.74 | 3.01 ± 1.78 | 0.513 | 0.194 |
| RMS-Acceleration-AP | 0.09 ± 0.03 | 0.08 ± 0.03 | 0.176 | 0.078 |
| RMS-Acceleration-Start-AP | 0.12 ± 0.06 | 0.12 ± 0.05 | 0.824 | 0.997 |
| RMS-Acceleration-Mid-AP | 0.07 ± 0.03 | 0.07 ± 0.03 | 0.295 | 0.183 |
| RMS-Acceleration-End-AP | 0.06 ± 0.04 | 0.06 ± 0.04 | 0.557 | 0.377 |
| RMS-Angular Velocity-AP | 1.11 ± 0.32 | 0.86 ± 0.36 | 0.001 | < 0.0001 |
| RMS-Angular Velocity-Start-AP | 0.35 ± 0.19 | 0.32 ± 0.14 | 0.369 | 0.817 |
| RMS-Angular Velocity-Mid-AP | 1.40 ± 0.48 | 1.08 ± 0.45 | 0.002 | 0.002 |
| RMS-Angular Velocity-End-AP | 0.30 ± 0.19 | 0.27 ± 0.34 | 0.574 | 0.058 |
| RMS of Jerk-AP | 2.15 ± 0.93 | 1.62 ± 0.65 | 0.004 | 0.001 |
| Max of Jerk-AP | 8.08 ± 3.79 | 6.50 ± 2.86 | 0.034 | 0.040 |
| Min of Jerk-AP | 9.53 ± 5.50 | 6.99 ± 3.27 | 0.013 | 0.006 |
| Range of Jerk-AP | 17.62 ± 8.98 | 13.50 ± 5.95 | 0.016 | 0.009 |
| RMS of Jerk-Start-AP | 2.49 ± 1.70 | 1.95 ± 0.83 | 0.077 | 0.159 |
| RMS of Jerk-Mid-AP | 1.60 ± 0.87 | 1.18 ± 0.75 | 0.016 | 0.005 |
| RMS of Jerk-End-AP | 1.33 ± 1.53 | 0.91 ± 0.43 | 0.102 | 0.105 |

| RMS of Angular Acceleration-AP | 4.49 ± 1.66 | 3.55 ± 1.44 | 0.006 | 0.003 |
|---|--------------------|--------------------|--------------|--------------|
| Max of Angular Acceleration-AP | 13.78 ± 6.06 | 11.50 ± 4.94 | 0.060 | 0.060 |
| Min of Angular Acceleration-AP | 14.50 ± 7.10 | 12.21 ± 5.16 | 0.094 | 0.139 |
| Range of Angular Acceleration-AP | 28.28 ± 12.69 | 23.71 ± 9.86 | 0.067 | 0.075 |
| RMS of Angular Acceleration-Start-AP | 5.36 ± 3.64 | 4.49 ± 2.31 | 0.202 | 0.133 |
| RMS of Angular Acceleration-Mid-AP | 3.97 ± 1.87 | 3.00 ± 1.65 | 0.012 | 0.001 |
| RMS of Angular Acceleration-End-AP | 2.93 ± 1.42 | 2.55 ± 1.74 | 0.262 | 0.054 |
| RMS-Acceleration-R | 0.22 ± 0.04 | 0.20 ± 0.06 | 0.064 | 0.003 |
| RMS-Acceleration-Start-R | 0.25 ± 0.09 | 0.25 ± 0.08 | 0.937 | 0.928 |
| RMS-Acceleration-Mid-R | 0.20 ± 0.06 | 0.19 ± 0.06 | 0.316 | 0.284 |
| RMS-Acceleration-End-R | 0.17 ± 0.07 | 0.15 ± 0.08 | 0.173 | 0.026 |
| RMS-Angular Velocity-R | 1.49 ± 0.34 | 1.12 ± 0.35 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-Start-R | 0.47 ± 0.19 | 0.42 ± 0.15 | 0.191 | 0.463 |
| RMS-Angular Velocity-Mid-R | 1.89 ± 0.57 | 1.40 ± 0.51 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-End-R | 0.38 ± 0.19 | 0.35 ± 0.34 | 0.548 | 0.036 |
| RMS of Jerk-R | 2.84 ± 1.39 | 2.18 ± 0.84 | 0.012 | 0.005 |
| Max of Jerk-R | 13.42 ± 7.81 | 10.78 ± 4.52 | 0.066 | 0.097 |
| Min of Jerk-R | 13.22 ± 7.65 | 10.97 ± 5.16 | 0.121 | 0.168 |
| Range of Jerk-R | 26.64 ± 15.20 | 21.75 ± 9.50 | 0.085 | 0.139 |
| RMS of Jerk-Start-R | 2.96 ± 2.14 | 2.55 ± 1.21 | 0.299 | 0.781 |
| RMS of Jerk-Mid-R | 2.09 ± 1.27 | 1.43 ± 0.86 | 0.007 | 0.003 |
| RMS of Jerk-End-R | 1.53 ± 2.42 | 1.00 ± 0.53 | 0.194 | 0.112 |
| RMS of Angular Acceleration-R | 5.29 ± 1.90 | 4.28 ± 1.92 | 0.014 | 0.004 |
| Max of Angular Acceleration-R | 17.97 ± 8.90 | 16.03 ± 9.11 | 0.311 | 0.234 |
| Min of Angular Acceleration-R | 16.44 ± 7.07 | 15.14 ± 8.52 | 0.427 | 0.139 |
| Range of Angular Acceleration-R | 34.41 ± 15.34 | 31.17 ± 17.29 | 0.346 | 0.194 |
| RMS of Angular Acceleration-Start-R | 5.85 ± 3.53 | 5.01 ± 2.32 | 0.200 | 0.267 |
| RMS of Angular Acceleration-Mid-R | 4.76 ± 2.12 | 3.65 ± 1.84 | 0.011 | 0.003 |
| RMS of Angular Acceleration-End-R | 3.27 ± 1.63 | 2.98 ± 1.85 | 0.423 | 0.105 |
| Turning Characteristics from Head (HD) | | | | |
| Number of Turns | 5.07 ± 1.70 | 5.78 ± 6.00 | 0.403 | 0.304 |
| Angle of Turn-Max | 178.71 ± 25.28 | 176.57 ± 13.78 | 0.639 | 0.463 |
| Angle of Turn-Min | 77.77 ± 54.36 | 92.00 ± 60.39 | 0.241 | 0.317 |
| Angle of Turn-Average | 134.51 ± 29.76 | 138.32 ± 32.34 | 0.561 | 0.477 |
| Angle of Turn-Variability | 45.52 ± 25.76 | 37.21 ± 27.57 | 0.142 | 0.082 |
| No. of Direction of Turns-Right | 3.38 ± 1.48 | 4.08 ± 2.81 | 0.118 | 0.344 |
| No. of Direction of Turns-Left | 1.70 ± 1.26 | 1.70 ± 3.49 | 0.990 | 0.084 |
| Duration of Turn-Max | 3.42 ± 0.94 | 4.15 ± 1.13 | 0.001 | 0.001 |
| Duration of Turn-Min | 1.50 ± 0.76 | 2.07 ± 1.02 | 0.002 | 0.004 |
| Duration of Turn-Average | 2.37 ± 0.60 | 3.02 ± 0.83 | < 0.0001 | < 0.0001 |
| Duration of Turn-Variability | 0.79 ± 0.41 | 0.87 ± 0.56 | 0.388 | 0.675 |
| Angular Velocity-Average | 58.27 ± 9.96 | 47.67 ± 10.40 | < 0.0001 | < 0.0001 |
| Angular Velocity-Variability | 16.67 ± 9.57 | 10.95 ± 5.98 | 0.002 | 0.002 |
| Peak Angular Velocity-Average | 165.01 ± 27.47 | 133.63 ± 28.37 | < 0.0001 | < 0.0001 |

| | | | | |
|--------------------------------------|-------------------|-------------------|--------------|--------------|
| Peak Angular Velocity-Variability | 41.56 ± 19.02 | 35.38 ± 20.23 | 0.138 | 0.125 |
| Angular Velocity Start-Average | 11.15 ± 5.30 | 9.73 ± 6.13 | 0.238 | 0.079 |
| Angular Velocity Start-Variability | 8.20 ± 6.21 | 5.63 ± 4.34 | 0.031 | 0.033 |
| Angular Velocity End-Average | 8.09 ± 3.91 | 7.28 ± 5.28 | 0.398 | 0.127 |
| Angular Velocity End-Variability | 5.28 ± 3.80 | 4.33 ± 3.88 | 0.242 | 0.072 |
| Angular Velocity Middle-Average | 92.68 ± 29.75 | 81.63 ± 27.67 | 0.075 | 0.088 |
| Angular Velocity Middle-Variability | 50.59 ± 21.39 | 41.43 ± 21.04 | 0.045 | 0.039 |
| RMS-Acceleration-ML | 0.15 ± 0.03 | 0.13 ± 0.05 | 0.078 | 0.004 |
| RMS-Acceleration-Start-ML | 0.14 ± 0.05 | 0.12 ± 0.07 | 0.181 | 0.047 |
| RMS-Acceleration-Mid-ML | 0.14 ± 0.05 | 0.13 ± 0.06 | 0.638 | 0.328 |
| RMS-Acceleration-End-ML | 0.10 ± 0.03 | 0.09 ± 0.06 | 0.444 | 0.039 |
| RMS-Angular Velocity-ML | 0.37 ± 0.12 | 0.27 ± 0.15 | 0.000 | < 0.0001 |
| RMS-Angular Velocity-Start-ML | 0.24 ± 0.12 | 0.20 ± 0.17 | 0.197 | 0.009 |
| RMS-Angular Velocity-Mid-ML | 0.35 ± 0.18 | 0.26 ± 0.18 | 0.027 | 0.010 |
| RMS-Angular Velocity-End-ML | 0.29 ± 0.17 | 0.18 ± 0.15 | 0.004 | < 0.0001 |
| RMS of Jerk-ML | 1.93 ± 0.54 | 1.80 ± 0.83 | 0.377 | 0.023 |
| Max of Jerk-ML | 7.15 ± 2.78 | 6.68 ± 3.50 | 0.473 | 0.148 |
| Min of Jerk-ML | 6.20 ± 2.16 | 6.18 ± 3.27 | 0.969 | 0.538 |
| Range of Jerk-ML | 13.35 ± 4.63 | 12.86 ± 6.60 | 0.673 | 0.219 |
| RMS of Jerk-Start-ML | 1.72 ± 0.86 | 1.72 ± 1.06 | 0.997 | 0.468 |
| RMS of Jerk-Mid-ML | 1.73 ± 0.72 | 1.77 ± 0.91 | 0.792 | 0.885 |
| RMS of Jerk-End-ML | 1.14 ± 0.76 | 1.07 ± 0.70 | 0.650 | 0.250 |
| RMS of Angular Acceleration-ML | 4.91 ± 2.14 | 4.23 ± 1.73 | 0.109 | 0.078 |
| Max of Angular Acceleration-ML | 15.12 ± 7.66 | 14.13 ± 5.69 | 0.502 | 0.635 |
| Min of Angular Acceleration-ML | 16.40 ± 9.40 | 16.44 ± 6.73 | 0.982 | 0.473 |
| Range of Angular Acceleration-ML | 31.52 ± 16.84 | 30.57 ± 12.00 | 0.767 | 0.762 |
| RMS of Angular Acceleration-Start-ML | 4.86 ± 2.47 | 4.34 ± 2.39 | 0.316 | 0.365 |
| RMS of Angular Acceleration-Mid-ML | 4.19 ± 2.73 | 2.99 ± 1.45 | 0.016 | 0.008 |
| RMS of Angular Acceleration-End-ML | 3.70 ± 2.77 | 2.90 ± 1.69 | 0.118 | 0.058 |
| RMS-Acceleration-VT | 0.12 ± 0.04 | 0.10 ± 0.03 | 0.010 | 0.014 |
| RMS-Acceleration-Start-VT | 0.14 ± 0.07 | 0.12 ± 0.04 | 0.065 | 0.194 |
| RMS-Acceleration-Mid-VT | 0.09 ± 0.05 | 0.08 ± 0.04 | 0.104 | 0.148 |
| RMS-Acceleration-End-VT | 0.09 ± 0.05 | 0.07 ± 0.03 | 0.021 | 0.053 |
| RMS-Angular Velocity-VT | 1.27 ± 0.21 | 0.99 ± 0.23 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-Start-VT | 0.21 ± 0.14 | 0.17 ± 0.10 | 0.086 | 0.016 |
| RMS-Angular Velocity-Mid-VT | 1.56 ± 0.47 | 1.33 ± 0.46 | 0.024 | 0.036 |
| RMS-Angular Velocity-End-VT | 0.19 ± 0.16 | 0.16 ± 0.10 | 0.336 | 0.152 |
| RMS of Jerk-VT | 3.81 ± 1.51 | 3.27 ± 1.05 | 0.064 | 0.121 |
| Max of Jerk-VT | 16.30 ± 7.47 | 16.38 ± 6.64 | 0.960 | 0.721 |
| Min of Jerk-VT | 16.10 ± 7.26 | 14.57 ± 4.81 | 0.261 | 0.580 |
| Range of Jerk-VT | 32.40 ± 14.52 | 30.95 ± 11.07 | 0.605 | 0.978 |
| RMS of Jerk-Start-VT | 3.84 ± 2.40 | 3.35 ± 2.00 | 0.309 | 0.247 |

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|--------------------------------------|-------------------|------------------|--------------|--------------|
| RMS of Jerk-Mid-VT | 2.79 ± 1.72 | 2.14 ± 1.14 | 0.045 | 0.054 |
| RMS of Jerk-End-VT | 2.40 ± 1.71 | 1.80 ± 0.87 | 0.051 | 0.030 |
| RMS of Angular Acceleration-VT | 5.61 ± 1.47 | 4.34 ± 1.91 | 0.000 | < 0.0001 |
| Max of Angular Acceleration-VT | 16.08 ± 4.59 | 13.61 ± 4.63 | 0.013 | 0.008 |
| Min of Angular Acceleration-VT | 14.23 ± 3.83 | 11.57 ± 3.48 | 0.001 | 0.001 |
| Range of Angular Acceleration-VT | 30.30 ± 7.89 | 25.17 ± 7.78 | 0.003 | 0.002 |
| RMS of Angular Acceleration-Start-VT | 5.24 ± 2.48 | 4.56 ± 2.76 | 0.218 | 0.100 |
| RMS of Angular Acceleration-Mid-VT | 5.23 ± 2.25 | 4.26 ± 1.79 | 0.030 | 0.012 |
| RMS of Angular Acceleration-End-VT | 3.50 ± 1.71 | 3.19 ± 2.31 | 0.458 | 0.108 |
| RMS-Acceleration-AP | 0.19 ± 0.06 | 0.16 ± 0.07 | 0.023 | 0.003 |
| RMS-Acceleration-Start-AP | 0.16 ± 0.07 | 0.15 ± 0.08 | 0.486 | 0.260 |
| RMS-Acceleration-Mid-AP | 0.15 ± 0.07 | 0.14 ± 0.07 | 0.351 | 0.328 |
| RMS-Acceleration-End-AP | 0.18 ± 0.09 | 0.14 ± 0.08 | 0.022 | 0.009 |
| RMS-Angular Velocity-AP | 0.36 ± 0.18 | 0.29 ± 0.14 | 0.046 | 0.010 |
| RMS-Angular Velocity-Start-AP | 0.19 ± 0.12 | 0.17 ± 0.15 | 0.369 | 0.089 |
| RMS-Angular Velocity-Mid-AP | 0.41 ± 0.24 | 0.32 ± 0.17 | 0.065 | 0.052 |
| RMS-Angular Velocity-End-AP | 0.14 ± 0.07 | 0.12 ± 0.11 | 0.296 | 0.006 |
| RMS of Jerk-AP | 1.78 ± 0.65 | 1.57 ± 0.45 | 0.090 | 0.121 |
| Max of Jerk-AP | 6.03 ± 3.16 | 5.76 ± 1.94 | 0.645 | 0.891 |
| Min of Jerk-AP | 6.98 ± 3.22 | 6.61 ± 2.46 | 0.554 | 0.602 |
| Range of Jerk-AP | 13.01 ± 6.22 | 12.37 ± 4.12 | 0.583 | 0.841 |
| RMS of Jerk-Start-AP | 1.61 ± 0.75 | 1.62 ± 0.75 | 0.944 | 0.959 |
| RMS of Jerk-Mid-AP | 1.42 ± 0.70 | 1.19 ± 0.47 | 0.093 | 0.241 |
| RMS of Jerk-End-AP | 1.24 ± 1.03 | 0.95 ± 0.41 | 0.117 | 0.116 |
| RMS of Angular Acceleration-AP | 3.56 ± 1.22 | 2.97 ± 1.41 | 0.034 | 0.001 |
| Max of Angular Acceleration-AP | 11.39 ± 5.05 | 10.07 ± 4.74 | 0.209 | 0.123 |
| Min of Angular Acceleration-AP | 11.07 ± 4.89 | 9.70 ± 4.27 | 0.170 | 0.069 |
| Range of Angular Acceleration-AP | 22.46 ± 9.65 | 19.78 ± 8.60 | 0.174 | 0.110 |
| RMS of Angular Acceleration-Start-AP | 3.33 ± 1.43 | 2.99 ± 2.06 | 0.347 | 0.061 |
| RMS of Angular Acceleration-Mid-AP | 3.36 ± 1.57 | 2.46 ± 1.29 | 0.005 | 0.000 |
| RMS of Angular Acceleration-End-AP | 2.17 ± 1.14 | 1.83 ± 1.20 | 0.172 | 0.023 |
| RMS-Acceleration-R | 0.28 ± 0.06 | 0.24 ± 0.08 | 0.007 | 0.000 |
| RMS-Acceleration-Start-R | 0.29 ± 0.08 | 0.26 ± 0.09 | 0.052 | 0.008 |
| RMS-Acceleration-Mid-R | 0.25 ± 0.07 | 0.23 ± 0.08 | 0.202 | 0.069 |
| RMS-Acceleration-End-R | 0.25 ± 0.09 | 0.20 ± 0.10 | 0.033 | 0.006 |
| RMS-Angular Velocity-R | 1.39 ± 0.23 | 1.08 ± 0.27 | < 0.0001 | < 0.0001 |
| RMS-Angular Velocity-Start-R | 0.42 ± 0.19 | 0.34 ± 0.24 | 0.067 | 0.001 |
| RMS-Angular Velocity-Mid-R | 1.71 ± 0.49 | 1.44 ± 0.47 | 0.010 | 0.010 |
| RMS-Angular Velocity-End-R | 0.42 ± 0.21 | 0.30 ± 0.22 | 0.012 | < 0.0001 |
| RMS of Jerk-R | 2.80 ± 1.05 | 2.40 ± 0.81 | 0.056 | 0.058 |
| Max of Jerk-R | 13.45 ± 5.80 | 12.14 ± 4.12 | 0.238 | 0.527 |
| Min of Jerk-R | 12.66 ± 6.08 | 11.89 ± 4.38 | 0.504 | 0.885 |
| Range of Jerk-R | 26.11 ± 11.66 | 24.03 ± 8.23 | 0.348 | 0.698 |

| RMS of Jerk-Start-R | 2.71 ± 1.60 | 2.30 ± 1.19 | 0.190 | 0.298 |
|---|--------------------------|--------------------------|--------------|--------------------|
| RMS of Jerk-Mid-R | 2.13 ± 1.20 | 1.77 ± 0.74 | 0.113 | 0.250 |
| RMS of Jerk-End-R | 1.68 ± 1.39 | 1.43 ± 0.78 | 0.319 | 0.340 |
| RMS of Angular Acceleration-R | 6.18 ± 1.77 | 4.72 ± 2.08 | 0.001 | < 0.0001 |
| Max of Angular Acceleration-R | 19.68 ± 6.61 | 15.74 ± 5.71 | 0.004 | 0.002 |
| Min of Angular Acceleration-R | 15.85 ± 6.12 | 14.12 ± 5.24 | 0.162 | 0.068 |
| Range of Angular Acceleration-R | 35.53 ± 12.19 | 29.85 ± 10.66 | 0.023 | 0.009 |
| RMS of Angular Acceleration-Start-R | 5.44 ± 2.45 | 4.36 ± 2.72 | 0.051 | 0.008 |
| RMS of Angular Acceleration-Mid-R | 5.51 ± 2.56 | 4.30 ± 2.03 | 0.018 | 0.010 |
| RMS of Angular Acceleration-End-R | 3.79 ± 2.21 | 2.95 ± 1.84 | 0.059 | 0.037 |
| Turning Characteristics from Inner Turning Ankle | | | | |
| Number of Transitions/Steps | 2.85 ± 1.61 | 3.51 ± 2.31 | 0.106 | 0.079 |
| Angle of Turn-Average | 145.97 ± 35.78 | 127.97 ± 44.38 | 0.034 | 0.040 |
| Angle of Turn-Variability | 47.92 ± 24.64 | 44.47 ± 28.63 | 0.537 | 0.527 |
| Duration of Turn-Average | 0.69 ± 0.19 | 0.63 ± 0.19 | 0.125 | 0.152 |
| Duration of Turn-Variability | 0.24 ± 0.12 | 0.22 ± 0.13 | 0.551 | 0.602 |
| Angular Velocity-Average | 382.37 ± 407.35 | 365.59 ± 264.36 | 0.825 | 0.613 |
| Angular Velocity-Variability | 264.91 ± 431.29 | 306.24 ± 422.94 | 0.650 | 0.234 |
| Peak Angular Velocity-Average | $16,671.21 \pm 9,437.05$ | $11,924.05 \pm 9,287.73$ | 0.019 | 0.014 |
| Peak Angular Velocity-Variability | $12,290.51 \pm 7,040.74$ | $10,213.44 \pm 7,179.51$ | 0.170 | 0.313 |
| RMS-Acceleration-ML | 0.39 ± 0.12 | 0.32 ± 0.10 | 0.009 | 0.013 |
| RMS-Angular Velocity-ML | 0.81 ± 0.34 | 0.72 ± 0.44 | 0.266 | 0.036 |
| RMS of Jerk-ML | 15.30 ± 5.87 | 13.36 ± 5.19 | 0.105 | 0.079 |
| Max of Jerk-ML | 46.79 ± 19.58 | 38.40 ± 17.44 | 0.038 | 0.020 |
| Min of Jerk-ML | 41.56 ± 17.08 | 35.43 ± 12.40 | 0.063 | 0.056 |
| Range of Jerk-ML | 88.35 ± 32.77 | 73.84 ± 23.39 | 0.022 | 0.020 |
| RMS of Angular Acceleration-ML | 11.20 ± 4.21 | 9.75 ± 4.56 | 0.120 | 0.073 |
| Max of Angular Acceleration-ML | 22.35 ± 7.68 | 18.57 ± 7.79 | 0.023 | 0.012 |
| Min of Angular Acceleration-ML | 28.34 ± 10.90 | 23.89 ± 9.87 | 0.048 | 0.028 |
| Range of Angular Acceleration-ML | 50.70 ± 16.53 | 42.46 ± 15.95 | 0.019 | 0.004 |
| RMS-Acceleration-VT | 0.29 ± 0.10 | 0.29 ± 0.11 | 0.764 | 0.799 |
| RMS-Angular Velocity-VT | 2.24 ± 0.57 | 1.79 ± 0.48 | 0.000 | < 0.0001 |
| RMS of Jerk-VT | 8.20 ± 3.11 | 8.11 ± 3.93 | 0.904 | 0.473 |
| Max of Jerk-VT | 20.28 ± 8.44 | 19.22 ± 7.92 | 0.543 | 0.569 |
| Min of Jerk-VT | 23.91 ± 13.59 | 21.71 ± 9.14 | 0.390 | 0.348 |
| Range of Jerk-VT | 44.19 ± 20.47 | 40.92 ± 15.85 | 0.413 | 0.263 |
| RMS of Angular Acceleration-VT | 33.48 ± 8.93 | 29.62 ± 13.19 | 0.096 | 0.001 |
| Max of Angular Acceleration-VT | 74.49 ± 18.12 | 64.16 ± 24.85 | 0.023 | 0.004 |
| Min of Angular Acceleration-VT | 92.33 ± 26.14 | 75.17 ± 32.69 | 0.006 | 0.000 |
| Range of Angular Acceleration-VT | 166.81 ± 36.87 | 139.33 ± 49.67 | 0.003 | 0.000 |
| RMS-Acceleration-AP | 0.32 ± 0.10 | 0.27 ± 0.10 | 0.023 | 0.006 |

| RMS-Angular Velocity-AP | 1.62 ± 0.50 | 1.60 ± 0.61 | 0.881 | 0.984 |
|---|--------------------------|---------------------------|--------------|--------------|
| RMS of Jerk-AP | 10.20 ± 3.78 | 8.81 ± 4.56 | 0.114 | 0.010 |
| Max of Jerk-AP | 26.46 ± 9.74 | 22.43 ± 10.78 | 0.064 | 0.020 |
| Min of Jerk-AP | 30.54 ± 11.58 | 24.45 ± 11.67 | 0.015 | 0.004 |
| Range of Jerk-AP | 57.01 ± 18.93 | 46.88 ± 21.11 | 0.018 | 0.004 |
| RMS of Angular Acceleration-AP | 18.64 ± 6.22 | 17.24 ± 6.48 | 0.298 | 0.348 |
| Max of Angular Acceleration-AP | 34.92 ± 12.23 | 31.69 ± 10.40 | 0.191 | 0.194 |
| Min of Angular Acceleration-AP | 37.71 ± 13.18 | 32.41 ± 11.37 | 0.048 | 0.086 |
| Range of Angular Acceleration-AP | 72.63 ± 20.67 | 64.10 ± 18.17 | 0.044 | 0.082 |
| RMS-Acceleration-R | 0.61 ± 0.17 | 0.54 ± 0.16 | 0.039 | 0.036 |
| RMS-Angular Velocity-R | 3.17 ± 0.60 | 2.78 ± 0.58 | 0.003 | 0.005 |
| RMS of Jerk-R | 13.68 ± 4.69 | 12.00 ± 4.40 | 0.086 | 0.055 |
| Max of Jerk-R | 46.68 ± 20.00 | 38.46 ± 14.45 | 0.034 | 0.012 |
| Min of Jerk-R | 37.21 ± 14.13 | 30.98 ± 9.87 | 0.022 | 0.028 |
| Range of Jerk-R | 83.90 ± 31.67 | 69.43 ± 20.79 | 0.016 | 0.008 |
| RMS of Angular Acceleration-R | 29.91 ± 8.24 | 26.69 ± 11.01 | 0.111 | 0.005 |
| Max of Angular Acceleration-R | 61.08 ± 16.44 | 50.40 ± 20.55 | 0.007 | 0.003 |
| Min of Angular Acceleration-R | 82.62 ± 24.03 | 69.23 ± 25.73 | 0.012 | 0.002 |
| Range of Angular Acceleration-R | 143.70 ± 33.86 | 119.63 ± 42.25 | 0.003 | 0.000 |
| Turning Characteristics from Outer Turning Ankle | | | | |
| Number of Transitions/Steps | 3.10 ± 1.53 | 2.81 ± 1.52 | 0.372 | 0.295 |
| Angle of Turn-Average | 140.06 ± 40.00 | 137.70 ± 49.96 | 0.802 | 0.885 |
| Angle of Turn-Variability | 54.87 ± 29.61 | 48.12 ± 30.10 | 0.288 | 0.348 |
| Duration of Turn-Average | 0.50 ± 0.13 | 0.51 ± 0.17 | 0.802 | 0.811 |
| Duration of Turn-Variability | 0.16 ± 0.11 | 0.17 ± 0.13 | 0.893 | 0.903 |
| Angular Velocity-Average | 429.60 ± 257.77 | 462.34 ± 330.44 | 0.594 | 0.745 |
| Angular Velocity-Variability | 316.77 ± 379.81 | 387.75 ± 506.03 | 0.442 | 0.774 |
| Peak Angular Velocity-Average | $15,597.38 \pm 9,765.84$ | $15,511.74 \pm 12,573.28$ | 0.971 | 0.781 |
| Peak Angular Velocity-Variability | $13,735.79 \pm 7,822.24$ | $11,264.82 \pm 9,263.51$ | 0.169 | 0.178 |
| RMS-Acceleration-ML | 0.48 ± 0.11 | 0.45 ± 0.15 | 0.306 | 0.332 |
| RMS-Angular Velocity-ML | 1.03 ± 0.35 | 0.91 ± 0.45 | 0.171 | 0.052 |
| RMS of Jerk-ML | 21.24 ± 6.58 | 17.68 ± 7.00 | 0.015 | 0.041 |
| Max of Jerk-ML | 60.78 ± 23.21 | 48.96 ± 19.41 | 0.012 | 0.025 |
| Min of Jerk-ML | 57.90 ± 19.34 | 48.54 ± 21.96 | 0.033 | 0.031 |
| Range of Jerk-ML | 118.68 ± 35.66 | 97.51 ± 37.32 | 0.007 | 0.021 |
| RMS of Angular Acceleration-ML | 13.70 ± 4.51 | 11.79 ± 5.07 | 0.061 | 0.037 |
| Max of Angular Acceleration-ML | 33.69 ± 10.66 | 26.95 ± 12.85 | 0.007 | 0.002 |
| Min of Angular Acceleration-ML | 24.97 ± 8.64 | 21.90 ± 9.30 | 0.107 | 0.082 |
| Range of Angular Acceleration-ML | 58.66 ± 17.37 | 48.85 ± 20.40 | 0.015 | 0.007 |
| RMS-Acceleration-VT | 0.35 ± 0.09 | 0.32 ± 0.11 | 0.253 | 0.373 |
| RMS-Angular Velocity-VT | 2.49 ± 0.64 | 2.19 ± 0.83 | 0.052 | 0.017 |
| RMS of Jerk-VT | 10.22 ± 3.59 | 8.93 ± 3.78 | 0.101 | 0.094 |
| Max of Jerk-VT | 25.86 ± 9.88 | 21.68 ± 9.33 | 0.044 | 0.058 |
| Min of Jerk-VT | 24.15 ± 11.35 | 19.60 ± 7.46 | 0.034 | 0.029 |

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|----------------------------------|--------------------|--------------------|--------------|--------------|
| Range of Jerk-VT | 50.01 ± 19.72 | 41.28 ± 15.76 | 0.026 | 0.046 |
| RMS of Angular Acceleration-VT | 41.91 ± 11.31 | 37.86 ± 16.54 | 0.164 | 0.047 |
| Max of Angular Acceleration-VT | 89.38 ± 23.28 | 82.53 ± 34.59 | 0.256 | 0.121 |
| Min of Angular Acceleration-VT | 98.72 ± 28.34 | 86.98 ± 32.11 | 0.067 | 0.074 |
| Range of Angular Acceleration-VT | 188.10 ± 46.29 | 169.51 ± 61.86 | 0.101 | 0.068 |
| RMS-Acceleration-AP | 0.38 ± 0.11 | 0.32 ± 0.12 | 0.011 | 0.010 |
| RMS-Angular Velocity-AP | 1.84 ± 0.48 | 1.83 ± 0.64 | 0.970 | 0.872 |
| RMS of Jerk-AP | 11.18 ± 3.69 | 9.32 ± 3.11 | 0.013 | 0.037 |
| Max of Jerk-AP | 27.39 ± 9.92 | 22.29 ± 7.25 | 0.008 | 0.025 |
| Min of Jerk-AP | 31.91 ± 12.99 | 25.04 ± 10.72 | 0.009 | 0.006 |
| Range of Jerk-AP | 59.30 ± 21.82 | 47.32 ± 16.62 | 0.006 | 0.007 |
| RMS of Angular Acceleration-AP | 23.17 ± 6.51 | 21.90 ± 8.01 | 0.403 | 0.602 |
| Max of Angular Acceleration-AP | 48.06 ± 16.57 | 42.97 ± 16.37 | 0.149 | 0.222 |
| Min of Angular Acceleration-AP | 44.60 ± 11.40 | 39.85 ± 16.66 | 0.106 | 0.157 |
| Range of Angular Acceleration-AP | 92.66 ± 23.80 | 82.81 ± 29.20 | 0.078 | 0.148 |
| RMS-Acceleration-R | 0.74 ± 0.16 | 0.66 ± 0.20 | 0.058 | 0.127 |
| RMS-Angular Velocity-R | 3.48 ± 0.64 | 3.22 ± 0.85 | 0.093 | 0.131 |
| RMS of Jerk-R | 17.95 ± 5.46 | 15.21 ± 5.18 | 0.018 | 0.061 |
| Max of Jerk-R | 56.67 ± 20.17 | 42.94 ± 15.48 | 0.001 | 0.002 |
| Min of Jerk-R | 50.11 ± 20.09 | 45.07 ± 19.22 | 0.232 | 0.336 |
| Range of Jerk-R | 106.77 ± 34.74 | 88.01 ± 30.66 | 0.009 | 0.039 |
| RMS of Angular Acceleration-R | 36.19 ± 8.94 | 33.35 ± 13.04 | 0.215 | 0.148 |
| Max of Angular Acceleration-R | 66.38 ± 20.38 | 56.74 ± 22.76 | 0.036 | 0.027 |
| Min of Angular Acceleration-R | 94.31 ± 25.52 | 86.80 ± 31.34 | 0.209 | 0.274 |
| Range of Angular Acceleration-R | 160.68 ± 40.54 | 143.54 ± 50.19 | 0.073 | 0.068 |

Table S2. Partial least square discriminant analysis (PLS-DA) model parameters trained on turning characteristics.

| Model Trained On | Spatiotemporal Characteristics | | | | Signal-based Characteristics | | | | Combined Characteristics | | | |
|----------------------|--------------------------------|----------------|------------------|------------------|------------------------------|----------------|------------------|------------------|--------------------------|----------------|------------------|------------------|
| | Components | Q ² | R ² Y | R ² X | Components | Q ² | R ² Y | R ² X | Components | Q ² | R ² Y | R ² X |
| Head (HD) | 5 | 0.074 | 0.429 | 0.757 | 2 | 0.069 | 0.309 | 0.476 | 2 | 0.127 | 0.374 | 0.416 |
| Neck (C7) | 3 | 0.089 | 0.379 | 0.535 | 2 | 0.107 | 0.348 | 0.473 | 4 | 0.033 | 0.532 | 0.558 |
| Lower back (L5) | 4 | 0.008 | 0.398 | 0.595 | 3 | 0.077 | 0.393 | 0.551 | 3 | 0.166 | 0.428 | 0.501 |
| HD + C7 | 5 | 0.054 | 0.576 | 0.580 | 2 | 0.119 | 0.424 | 0.415 | 2 | 0.204 | 0.463 | 0.374 |
| HD + L5 | 5 | 0.115 | 0.541 | 0.477 | 2 | 0.134 | 0.470 | 0.378 | 2 | 0.219 | 0.486 | 0.343 |
| C7 + L5 | 3 | 0.105 | 0.491 | 0.383 | 2 | 0.137 | 0.436 | 0.415 | 3 | 0.154 | 0.555 | 0.426 |
| Upper Body | 4 | 0.212 | 0.620 | 0.445 | 2 | 0.134 | 0.505 | 0.380 | 3 | 0.059 | 0.670 | 0.378 |
| Inner Turning Ankle | 1 | -0.009 | 0.071 | 0.225 | 3 | 0.065 | 0.351 | 0.592 | 3 | 0.033 | 0.385 | 0.528 |
| Outer Turning Ankle | 1 | -0.231 | 0.072 | 0.102 | 1 | 0.031 | 0.081 | 0.433 | 1 | 0.023 | 0.086 | 0.363 |
| Lower Body | 1 | -0.089 | 0.099 | 0.115 | 1 | 0.050 | 0.120 | 0.337 | 1 | 0.051 | 0.133 | 0.282 |
| HD + Inner | 2 | 0.154 | 0.382 | 0.304 | 2 | 0.070 | 0.418 | 0.361 | 4 | 0.013 | 0.665 | 0.452 |
| HD + Outer | 2 | 0.109 | 0.375 | 0.270 | 1 | 0.053 | 0.145 | 0.302 | 1 | 0.066 | 0.176 | 0.254 |
| HD + Lower Body | 2 | 0.050 | 0.424 | 0.205 | 1 | 0.070 | 0.157 | 0.282 | 2 | 0.051 | 0.470 | 0.294 |
| C7 + Inner | 2 | 0.047 | 0.395 | 0.247 | 4 | 0.002 | 0.590 | 0.519 | 4 | 0.065 | 0.641 | 0.466 |
| C7 + Outer | 1 | 0.165 | 0.279 | 0.143 | 1 | 0.060 | 0.126 | 0.328 | 1 | 0.075 | 0.154 | 0.281 |
| C7 + Lower Body | 1 | 0.157 | 0.308 | 0.107 | 1 | 0.070 | 0.143 | 0.297 | 2 | 0.038 | 0.487 | 0.298 |
| L5 + Inner | 3 | 0.065 | 0.417 | 0.400 | 3 | 0.023 | 0.499 | 0.435 | 4 | 0.026 | 0.626 | 0.456 |
| L5 + Outer | 3 | 0.113 | 0.453 | 0.379 | 1 | 0.091 | 0.162 | 0.304 | 2 | 0.079 | 0.471 | 0.311 |
| L5 + Lower Body | 2 | 0.153 | 0.425 | 0.225 | 1 | 0.095 | 0.168 | 0.286 | 2 | 0.108 | 0.445 | 0.301 |
| HD + C7 + Inner | 4 | 0.094 | 0.583 | 0.432 | 2 | 0.102 | 0.491 | 0.344 | 3 | 0.044 | 0.695 | 0.337 |
| HD + C7 + Outer | 3 | 0.078 | 0.563 | 0.342 | 1 | 0.063 | 0.150 | 0.303 | 2 | 0.071 | 0.510 | 0.307 |
| HD + C7 + Lower Body | 3 | 0.014 | 0.594 | 0.274 | 1 | 0.076 | 0.161 | 0.281 | 2 | 0.123 | 0.565 | 0.281 |
| HD + L5 + Inner | 3 | 0.119 | 0.528 | 0.319 | 2 | 0.119 | 0.496 | 0.330 | 3 | 0.089 | 0.652 | 0.341 |
| HD + L5 + Outer | 3 | 0.034 | 0.594 | 0.275 | 1 | 0.088 | 0.181 | 0.280 | 2 | 0.090 | 0.529 | 0.288 |
| HD + L5 + Lower Body | 2 | 0.163 | 0.504 | 0.199 | 2 | 0.006 | 0.512 | 0.307 | 2 | 0.128 | 0.535 | 0.276 |
| C7 + L5 + Inner | 3 | 0.055 | 0.505 | 0.324 | 2 | 0.113 | 0.474 | 0.352 | 4 | 0.001 | 0.713 | 0.415 |
| C7 + L5 + Outer | 3 | 0.031 | 0.551 | 0.317 | 1 | 0.090 | 0.158 | 0.307 | 2 | 0.123 | 0.541 | 0.308 |
| C7 + L5 + Lower Body | 2 | 0.137 | 0.474 | 0.213 | 1 | 0.095 | 0.166 | 0.286 | 3 | 0.036 | 0.671 | 0.332 |
| Upper Body + Inner | 4 | 0.065 | 0.628 | 0.379 | 2 | 0.131 | 0.535 | 0.336 | 3 | 0.118 | 0.719 | 0.334 |
| Upper Body + Outer | 4 | 0.066 | 0.696 | 0.372 | 2 | 0.013 | 0.527 | 0.333 | 2 | 0.148 | 0.563 | 0.300 |
| Full Body | 3 | 0.059 | 0.648 | 0.257 | 2 | 0.027 | 0.555 | 0.311 | 2 | 0.180 | 0.587 | 0.279 |

Table S3: Demographic characteristics of the subjects in the algorithm development set

| Demographics | CL (n = 16) | PD (n = 10) | p |
|--------------------------------|--------------------|----------------------|----------|
| Age (years) | 70.03 ± 8.15 | 73.04 ± 9.74 | 0.261 |
| Height (m) | 1.74 ± 0.08 | 1.67 ± 0.08 | 0.052 |
| Mass (Kg) | 83.99 ± 11.71 | 72.61 ± 10.41 | 0.048 |
| BMI (kg/m^2) | 27.70 ± 4.22 | 26.29 ± 4.25 | 0.682 |
| ABCs (0–100)% | 89.77 ± 11.50 | 73.36 ± 23.32 | 0.030 |
| MMSE (0–30) | 28.60 ± 2.10 | 28.70 ± 1.83 | 0.994 |
| LEDD, mg/day | | 587.70 ± 365.08 | |
| Hoehn and Yahr (n) | | HY I: 8 HY III: 2 | |
| MDS-UPDRS III | | 41.10 ± 9.89 | |

ACRONYMS: BMI, Body mass index; MMSE, Mini-Mental State Examination; ABCs, Activity balance score; LEDD, Levodopa equivalent medical dosage; MDS-UPDRS, Movement disorders-Unified Parkinson's disease rating scale.