

## Article

# SAMIRA-Satellite Based Monitoring Initiative for Regional Air Quality

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**Abstract:** The satellite based monitoring initiative for regional air quality (SAMIRA) initiative was set up to demonstrate the exploitation of existing satellite data for monitoring regional and urban scale air quality. The project was carried out between May 2016 and December 2019 and focused on aerosol optical depth (AOD), particulate matter (PM), nitrogen dioxide (NO<sub>2</sub>), and sulfur dioxide (SO<sub>2</sub>). SAMIRA was built around several research tasks: 1. The spinning enhanced visible and infrared imager (SEVIRI) AOD optimal estimation algorithm was improved and geographically extended from Poland to Romania, the Czech Republic and Southern Norway. A near real-time retrieval was implemented and is currently operational. Correlation coefficients of 0.61 and 0.62 were found between SEVIRI AOD and ground-based sun-photometer for Romania and Poland, respectively. 2. A retrieval for ground-level concentrations of PM<sub>2.5</sub> was implemented using the SEVIRI AOD in combination with WRF-Chem output. For representative sites a correlation of 0.56 and 0.49 between satellite-based PM<sub>2.5</sub> and in situ PM<sub>2.5</sub> was found for Poland and the Czech Republic, respectively. 3. An operational algorithm for data fusion was extended to make use of various satellite-based air quality products (NO<sub>2</sub>, SO<sub>2</sub>, AOD, PM<sub>2.5</sub> and PM<sub>10</sub>). For the Czech Republic inclusion of satellite data improved mapping of NO<sub>2</sub> in rural areas and on an annual basis in urban background areas. It slightly improved mapping of rural and urban background SO<sub>2</sub>. The use of satellites based AOD or PM<sub>2.5</sub> improved mapping results for PM<sub>2.5</sub> and PM<sub>10</sub>. 4. A geostatistical downscaling algorithm for satellite-based air quality products was developed to bridge the gap towards urban-scale applications. Initial testing using synthetic data was followed by applying the algorithm to OMI NO<sub>2</sub> data with a direct comparison against high-resolution TROPOMI NO<sub>2</sub> as a reference, thus allowing for a quantitative assessment of the algorithm performance and demonstrating significant accuracy improvements after downscaling. We can conclude that SAMIRA demonstrated the added value of using satellite data for regional- and urban-scale air quality monitoring.

**Keywords:** air quality; aerosols; remote sensing; SEVIRI; Sentinel-5P; data fusion; downscaling

## 1. Introduction

Despite positive developments in emission reductions, air quality is still of concern in Europe. Particulate matter (PM), nitrogen dioxide (NO<sub>2</sub>), and ground-level ozone (O<sub>3</sub>) are Europe's most problematic pollutants negatively affecting human health. The European Environment Agency (EEA) estimated that in 2018 in the 28 European Union member states 379,000 premature deaths could have been caused by long-term exposure to particles with a diameter of 2.5 µm or less (PM<sub>2.5</sub>), 54,000 to NO<sub>2</sub>, and 19,400 to O<sub>3</sub> [1]. According to the EEA, in 2018 48% and 74% of the urban population in Europe (EU-28) was exposed to concentrations above the World Health Organization (WHO) air quality guidelines (AQG) for particles with a diameter of 10 µm or less (PM<sub>10</sub>) (annual mean 20 µg m<sup>-3</sup>) and PM<sub>2.5</sub> (annual mean 10 µg m<sup>-3</sup>), respectively. Fortunately in most European countries NO<sub>2</sub> concentrations steadily decreased between 2009 and 2018. Only 4% of the European population were exposed to NO<sub>2</sub> concentrations above the EU annual limit value, which is equal to the AQG (40 µg m<sup>-3</sup> in a calendar year) in 2018 [1]. SO<sub>2</sub> pollution plays only a minor role in Europe these days, although, for example in vicinities of large power plants infrequent exceedances of limit values do occur (daily 20 µg m<sup>-3</sup>) and in 2018, based on the WHO AQGs, 19% of the urban population in Europe was affected [1].

Air quality maps are generated to inform the public about air pollution levels in the region they are living in. They serve as visualization of the actual situation and as a basis for air quality assessments. In situ observations, satellite measurements, and output from chemical transport modeling (CTM) are three mutually complimentary sources for generating air quality maps. In situ measurements provide accurate actual levels of concentrations, satellite data provide observations of spatial and temporal patterns (but not concentrations directly) and modeling outputs provide spatially continuous coverage of given area. The satellite based monitoring initiative for regional air quality (SAMIRA) project was set up to explore the added value of satellite data for air quality mapping through their synergistic use together with in situ air quality and modeling data. Satellite observations used in the project were acquired by the geostationary spinning enhanced visible and infrared imager (SEVIRI) onboard Meteosat second generation (MSG) [2], the ozone monitoring instrument (OMI) onboard NASA's Aura platform [3] and the TROPospheric monitoring instrument (TROPOMI) on the Sentinel-5 Precursor (S5P) satellite [4].

For estimating human exposure to air pollution the knowledge of PM concentration is essential. Ground-level concentration of PM<sub>2.5</sub> can be estimated from satellite observations of total-column aerosol optical depth (AOD) utilizing various approaches (see e.g., [5–7], and references therein). Geostationary satellites instruments like SEVIRI allow for the retrieval of AOD (e.g., [8–10]) at high temporal frequency and are, therefore, particularly interesting for air quality applications. Therefore, the SEVIRI near-real-time (NRT) AOD retrieval was a first task within SAMIRA. Satellite AOD is a convolution of the contribution from within the planetary boundary layer (PBL) and the free troposphere, locally-produced, and long range transported aerosols. Due to the complex spatial and temporal relationship between the total column aerosol optical depth and ground-level particulate matter, AOD-to-PM conversion, the second activity within SAMIRA, is a rather complex challenge. A multitude of methods for the AOD-to-PM conversion were developed throughout the years, for example using empirical and multivariate relations (e.g., [11,12]), scaling of the satellite AOD with the PM<sub>2.5</sub>/AOD ratio from a CTM [13], synergistic satellite and ground-based AOD [14], spectral and synergistic satellite information [15,16], fused satellite and model-calibrated PM<sub>2.5</sub> [17], and machine learning [18–20]. For SAMIRA we chose a physical based AOD-to-PM conversion method, the foundation of which goes back to work of [21].

SAMIRA dealt also with NO<sub>2</sub> and SO<sub>2</sub>, which was of particular interesting due to the improvement in spatial resolution and sensitivity introduced by TROPOMI. Whereas

OMI pixels have a spatial resolution of up to  $13 \times 24 \text{ km}^2$  at nadir, TROPOMI has a footprint of  $3.5 \times 5.5 \text{ km}^2$  at nadir (since August 2019). For OMI, the QA4ECV  $\text{NO}_2$  is one of the most recent  $\text{NO}_2$  retrieval products [22]; for TROPOMI  $\text{NO}_2$  see [23]. For Romania, which was one of our study regions, [24] reported that annual  $\text{SO}_2$  from power plants decreased between 2005 and 2015, while  $\text{NO}_2$  emissions were more or less stable during that time period. TROPOMI led to a new area of top-down  $\text{NO}_2$  emission monitoring from space [25,26], as well as bringing advances for surface  $\text{NO}_2$  concentration estimates (e.g., [27]). For  $\text{SO}_2$ , despite the increased sensitivity of TROPOMI, in 2018/2019 only the largest  $\text{SO}_2$  emitters in Europe, e.g., the Polish Bełchatów coal power plant, were visible from space, due to the installation of flue gas desulfurization systems in the European Union [28].

An essential goal of SAMIRA was to improve the societal relevance of air quality data measured from space. This can be done by combining ground-based in situ data with model output and satellite data products. For the combination of different data sources, a range of methods can be used to create spatial concentration fields. Such methods are often referred to as data assimilation and data fusion [29], the latter being a subset of data assimilation methods in a wider sense [30]. Therefore, within the SAMIRA initiative, an operational algorithm for data fusion of multiple heterogeneous datasets was extended to make use of various NRT satellite-based air quality products.

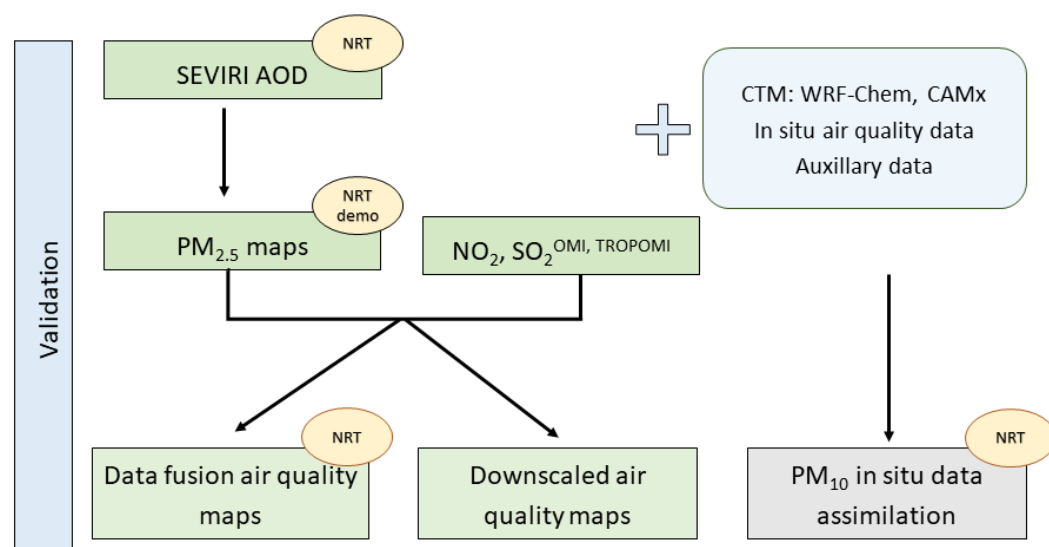
Although with the launch of the TROPOMI instrument the spatial resolution of air quality-related satellite products has significantly improved, the available resolution is still relatively coarse for urban- and local-scale applications, where air pollution tends to have the most significant consequences for the human population. Therefore, we investigated the feasibility of statistical downscaling of OMI and TROPOMI data with the help of geostatistics and a fine-scale proxy datasets. The proposed technique builds upon extensive previous research in geostatistics [31–34]. In geostatistical terms, downscaling is essentially a change of support problem (with support denoting the area of an observation, e.g., a point, a pixel, a grid cell, or a polygon), where the coarse spatial support of the original dataset is seen as an areal support and the fine spatial support of the target resolution is seen as a point support.

Finally, a pre-operational in situ  $\text{PM}_{10}$  data assimilation system was developed within SAMIRA. This development did not include satellite data yet. Therefore, it is only briefly described for completeness, being the first step towards a full air quality data assimilation system for Romania.

With this paper we want to give an overview and share lessons learned within the SAMIRA initiative. Following this introduction, in Section 2 we present the general methodology used in the project. Example results from the data product development are shown in Section 3. In Section 4 the validation of the datasets is presented. Section 5 illustrates the visualization system of the data. A discussion of the results, conclusions, and outlooks are summarized in Section 6.

## 2. SAMIRA Methodology

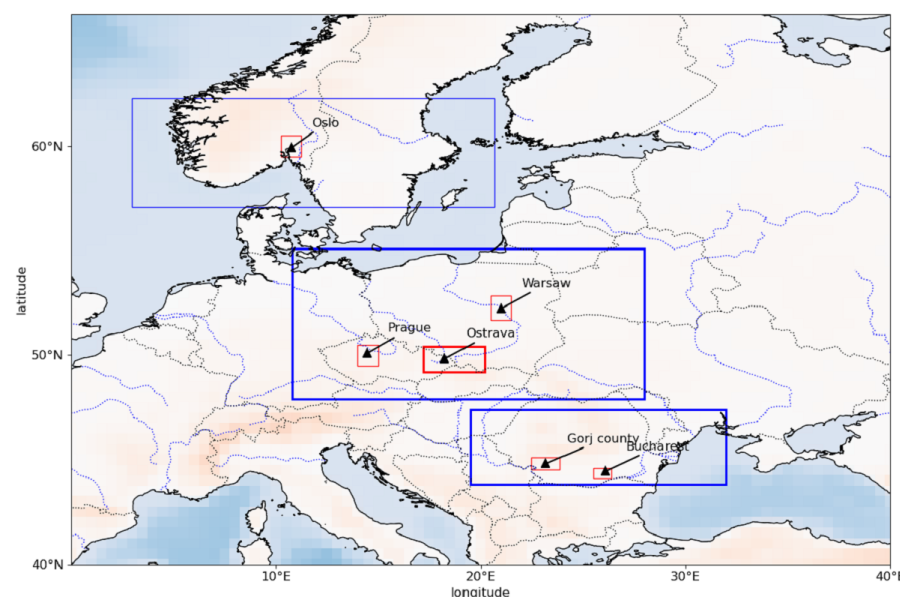
The overall approach, the activities and the logical flow of the SAMIRA project are illustrated in Figure 1. SAMIRA evolved around five primary research tasks: a. the SEVIRI AOD retrieval, b. the  $\text{PM}_{2.5}$  retrieval, i.e., the AOD to  $\text{PM}_{2.5}$  conversion, c. the data fusion methodology, which means the integration of satellite-based datasets with in situ monitoring and modeling data, d. the downscaling methodology, i.e., the development of algorithms for increasing the spatial resolution of satellite-based air quality products, and e. the in situ  $\text{PM}_{10}$  data assimilation. All activities marked in green in Figure 1 made use of satellite data, which were to various extents combined with ground-based in situ, model data and auxiliary datasets.



**Figure 1.** SAMIRA overview work-flow diagram. Activities marked in green made use of satellite data. For more details see Sections 2.1–2.5.

The SAMIRA data product development took place in two subsequent steps: a. the retrieval of historical data (June–September 2014) and their validation, and b. the demonstration and development of the products in near-real-time. The SEVIRI NRT AOD retrieval was developed based on an existing optimal estimation algorithm to provide up-to-date high-frequency AOD maps for Poland, Romania, the Czech Republic, and southern Norway (see Section 2.1). SEVIRI AOD and output from the weather research and forecasting (WRF) model coupled with chemistry (WRF-Chem) [35–37] was combined to calculate near-surface hourly  $PM_{2.5}$  (see Section 2.2). WRF-Chem was run on the Babeş-Bolyai University (UBB) high performance computer for June–September 2014 in multiple configurations. The WRF-Chem model was integrated for the entire European area at two horizontal resolutions: 15 km and 5 km. From the model integration at 15 km horizontal resolution, nested domains were run for each country and region of interest, at 5 km (country) and 1 km (region) horizontal resolution, respectively (see Figure 2). For areas marked in bold, we show exemplary results in the following. We combined in situ with satellite data and output from a chemistry transport model (CTM), either WRF-Chem or the comprehensive air quality model with extensions (CAMx) using data fusion techniques (see Section 2.3); the methodology was demonstrated for Europe and the Czech Republic. In the current paper we focus on regional and local air quality matters, therefore, we show results from the latter only. Finally, to make the coarse spatial resolution of satellite observations more suitable for local applications, satellite data were downscaled with the help of the high-resolution CTM output and alternative time-invariant proxies using geostatistics (see Section 2.4). The methodology was demonstrated for  $NO_2$ ,  $SO_2$ , and AOD/PM using OMI and TROPOMI data for the capitals of the four countries and areas, which are known for their bad air quality, e.g., the Ostrava/Katowice area. Finally, preparatory work for the development of an operational PM air quality forecast system in Romania was done by assimilation of in situ  $PM_{10}$  into the WRF-Chem model (see Section 2.5). In the following all retrievals are described briefly.





**Figure 2.** WRF-Chem model domains at 5 km (blue) and 1 km (red) horizontal resolution. Bold marked areas indicate regions for which exemplary results are discussed in this text.

### 2.1. SEVIRI AOD Retrieval

The first step in the SAMIRA air quality product development was the SEVIRI NRT AOD retrieval. A prototype algorithm was initially developed for Poland [38] and within SAMIRA it was improved and extended to the Czech Republic, Romania, and Southern Norway. The algorithm was modified based on case studies presented in [39–41]. Improvements that were made are related to the surface reflectance estimation, the improved cloud screening, and the uncertainty calculation. For a full description of the final version of the algorithm, we refer the interested readers to [42]. In short, the computation consists of a few steps. At first, a reference day with a low AOD and low cloud cover is chosen, for which the surface reflectance is calculated from SEVIRI data utilizing the operational global-scale Copernicus atmosphere monitoring service (CAMS) AOD forecast product (<https://atmosphere.copernicus.eu/>) as background information on the spatial AOD distribution. CAMS AOD is corrected using sun-photometer measurements from several aerosol robotic network (AERONET) [43] stations in the respective country using an optimal interpolation method [38]. Then the surface reflectance is estimated with the use of corrected CAMS AOD. The AOD is calculated for several days around the reference day. Finally, the AOD at 635 nm is interpolated to a regular grid of  $0.07^\circ \times 0.045^\circ$ , corresponding approximately to  $5.5 \times 5.5 \text{ km}^2$  for Poland. Besides AOD, AOD pixel-level uncertainties are estimated.

For the NRT retrieval, each day at 00:21 UTC surface reflectances are calculated. This is done for each country separately. At 7:00 UTC the following conditions are checked: a. the mean AOD, which is calculated using CAMS data, is below or equal to 0.15 and b. the cloud cover is less or equal to 65% (SEVIRI cloud mask). If fulfilled, surface reflectances are calculated for the previous day using data from SEVIRI, AERONET (both automatically downloaded), and CAMS AOD forecast data (downloaded every day at around 03:00 UTC). The SEVIRI AOD retrieval starts at the 7th, 23rd, 38th, and 53rd minute of each hour (within the time period between 5:00 and 9:45 UTC, and 13:00 and 16:45 UTC). There is about 20 to 23 min delay in receiving the data, which means that, e.g., the calculation for 7:00 UTC starts at 7:23 UTC. AOD computations take a few minutes, depending on the number of valid pixels (cloud-free and containing a surface reflectance). For each time the following is checked: the mean AOD (CAMS) is  $>0.15$  and the cloud cover is  $\leq 65\%$ . If these conditions are fulfilled, AOD and its uncertainties are calculated from SEVIRI data and surface reflectances (for the reference day, being one of the previous days). The choice

of the reference day for the surface reflectance calculation is done with a constraint that the span between the day for which the AOD map is derived and the closest available reference day cannot be more than 15 days.

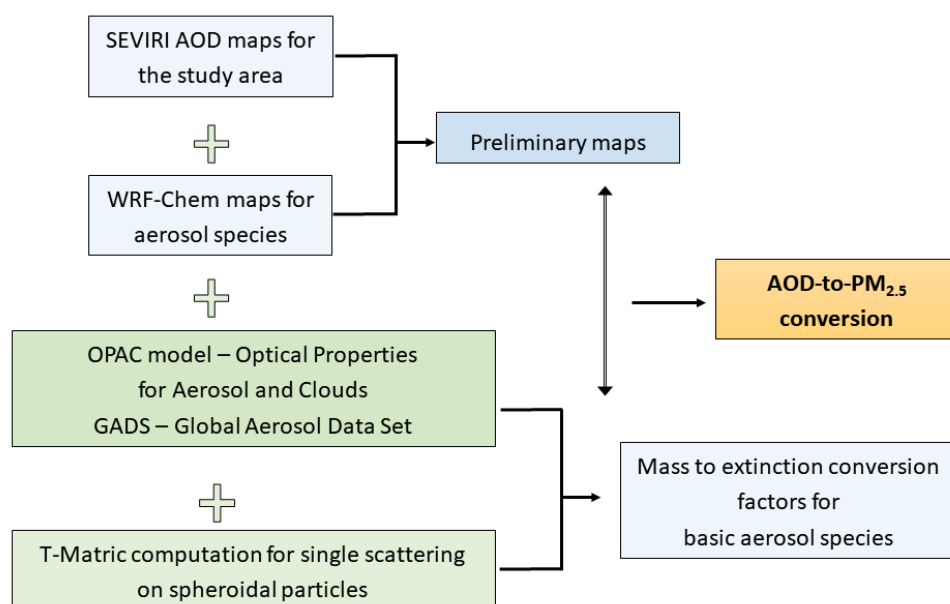
## 2.2. $PM_{2.5}$ Retrieval: AOD to $PM_{2.5}$ Conversion

The near-surface hourly  $PM_{2.5}$  concentrations were retrieved from temporally averaged SEVIRI AOD data [44]. Estimating  $PM_{2.5}$  from satellite observations of total-column AOD requires knowledge of the aerosol properties (microphysical and optical), their vertical distribution (PBL height and fraction of AOD in the PBL), and AOD. More specific, see Equation (1) from [21].

$$PM = \frac{4\rho r_{eff}}{3Q_{ext}} \times \frac{f_{PBL}}{h_{PBL}} \times AOD \quad (1)$$

with  $\rho$  being the density and  $r_{eff}$  the effective radius of the aerosol mixture,  $Q_{ext}$  the extinction coefficient,  $f_{PBL}$  the fraction of AOD in the PBL, and  $h_{PBL}$  the height of the PBL.

The workflow for our  $PM_{2.5}$  retrieval is illustrated in Figure 3. The most computationally intensive part is obtaining the optical and microphysical properties of aerosols in an online fashion. This was handled by creating a look-up table of properties for a range of aerosol mixtures at a number of relative humidity levels. Using the algorithm developed in [45] for aerosol typing a synthetic database was generated by simulating the optical properties of various aerosol types based on available information on the microphysics.



**Figure 3.** Methodology used in SAMIRA for AOD to  $PM_{2.5}$  conversion: data flow of the algorithm.

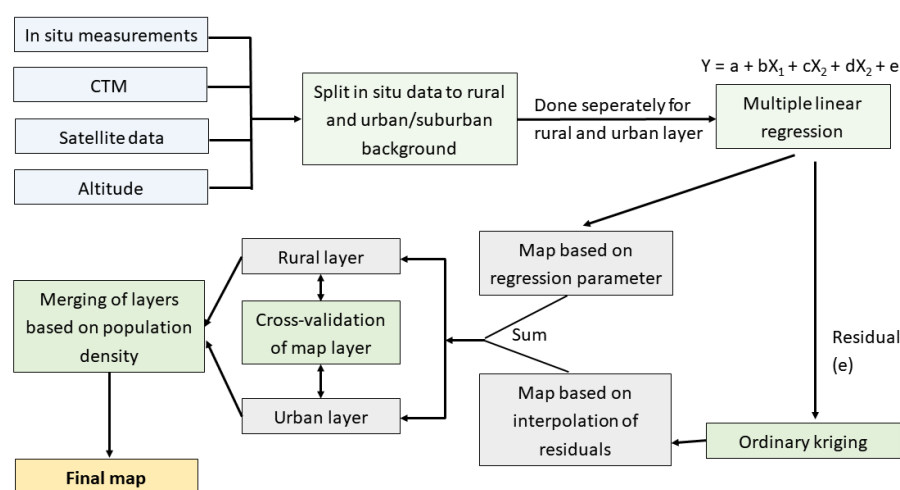
The algorithm combines the global aerosol dataset (GADS) database [46], the optical properties of aerosol and clouds (OPAC model) [47] and T-Matrix code for light scattering by non-spherical particles [48] in order to compute in an iterative way the optical properties of different aerosol classes in various humidity conditions and mass proportions starting from the microphysical properties. From GDAS we used the extinction, scattering and absorption coefficients, the single scattering albedo and the asymmetry parameter. From OPAC microphysical properties used are the density of aerosol particles, the aerosol mass per cubic meter, and the mode radius. Information from the CTM is used to compute the mass mixing ratios of the aerosols which are part of  $PM_{2.5}$ . Using the model we computed the relative humidity, mass mixing ratios for four major aerosol types (soot, water soluble, insoluble, sulfates), and the PBL height. The AOD fraction in the PBL was computed using WRF-Chem and the same aerosol type was assumed at all levels. Uncertainties due to the use of WRF-Chem cross-sections and the assumption of a unique aerosol type in the

column were evaluated in post-processing mode by comparisons with the cloud–aerosol LIDAR with orthogonal polarization (CALIOP) onboard the CALIPSO mission [49] and ground-based LIDAR data.

T-matrix calculations are very time consuming (approximately 3 s per mixture/grid point). This would have taken about a day of computation to get results ( $150 \times 200$  grid point), therefore, look-up tables were pre-computed. A master-script handled the inputs and errors, e.g., caused by missing input variables. It could run in automated or manual mode; the latter plotted all intermediate steps for debugging and quality control. Within SAMIRA we could demonstrate the NRT capability of our AOD-to-PM<sub>2.5</sub> retrieval, with PM<sub>2.5</sub> maps being ready within 5 min after the AOD maps became available on a server.

### 2.3. Data Fusion Methodology

The data fusion methodology used for SAMIRA is illustrated in Figure 4. It is a variant of the regression–interpolation–merging mapping [50,51], which is an improved residual kriging method. Residual kriging is a frequently used data fusion method [52]. In residual kriging, monitoring, modeling and other supplementary data are combined in multiple linear regression and subsequent spatial interpolation of its residuals is done by ordinary kriging [53]. Separate map layers were created for rural and urban background areas on a grid at a  $1 \times 1$  km<sup>2</sup> spatial resolution. The rural layer was based on the rural background stations, while the urban layer was based on the urban and suburban background stations. Residual kriging was applied separately for the rural and urban background areas with the subsequent merging of these map layers by population density.



**Figure 4.** Data fusion process used in SAMIRA: regression-interpolation-merging mapping.

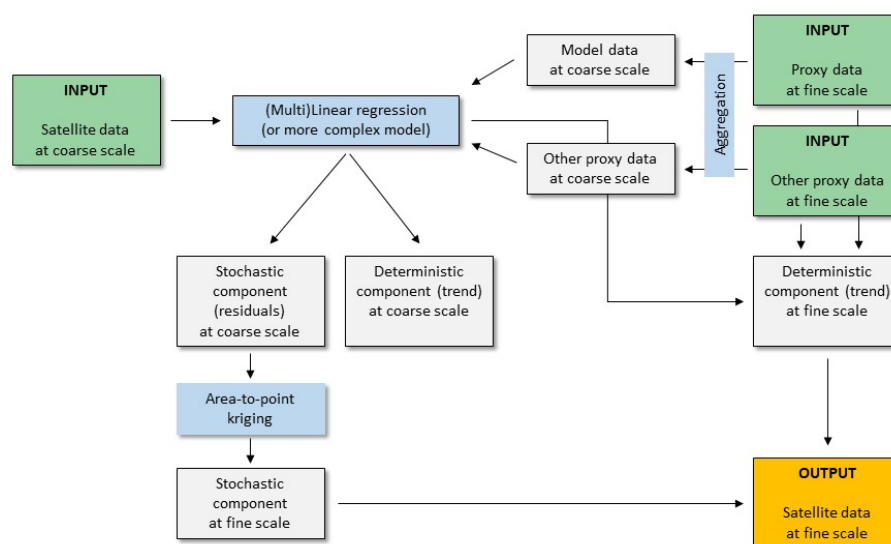
Air quality in situ data were acquired from the Czech national air pollution database, the air quality information system (AQIS) [54] and the EEA's air quality e-reporting database [55]. Model data were acquired from three models: CAMx for the Czech domain at  $4.7 \times 4.7$  km<sup>2</sup> spatial resolution, WRF-Chem for the European domain (hourly and daily time steps) at  $5 \times 5$  km<sup>2</sup> spatial resolution and the European Monitoring and Evaluation Programme (EMEP) model [56] for the European domain (annual averages) at  $10 \times 10$  km<sup>2</sup> spatial resolution. Various satellite datasets were used. SEVIRI AOD from SAMIRA (temporally aggregated into hourly and daily time averages) was used for the creation of data-fused PM<sub>2.5</sub> and PM<sub>10</sub> maps. The PM<sub>2.5</sub> product from SAMIRA was used for data-fused PM<sub>2.5</sub> maps. NO<sub>2</sub> and SO<sub>2</sub> from OMI, complemented by data from the Global Ozone Monitoring Experiment-2 (GOME-2), were used for the development of historical test data for 2014. NRT NO<sub>2</sub> and SO<sub>2</sub> data were obtained from TROPOMI. Supplementary datasets needed were altitudes from the database ZAGABED prepared by the Czech Office for Surveying, Mapping and Cadastre (<https://geoportal.cuzk.cz/>) and Global Multi-resolution Terrain Elevation Data 2010 (GMTED2010) [57]. Merging of the

rural and urban map layers was done using population density based on Geostat 2011 grid dataset [58] and data from the Czech Office for Surveying, Mapping, and Cadastre.

#### 2.4. Downscaling Methodology

The downscaling methodology used for SAMIRA is, just like many other downscaling techniques, essentially based on increasing the spatial resolution of a coarse source dataset (in our case satellite data of air quality) with the help of spatial proxy or auxiliary datasets that are available at a fine spatial resolution and that are, to some extent, correlated with the source dataset. As such, the technique makes use of the assumption that the spatial patterns of the unknown fine-scale field of the source variable will be similar to the spatial patterns of the fine-scale proxy datasets.

Figure 5 illustrates the SAMIRA downscaling methodology. In simplified terms, the various input datasets were brought to the same coarse resolution and a statistical model was fitted to directly relate the satellite and the proxy data. The model choice was arbitrary and could range from simple linear regression models to more advanced non-linear models such as random forest or similar. Subsequently, the spatial residuals from the model were calculated, downscaled to the fine target resolution using area-to-point kriging [33], and added to the deterministic trend component of the fitted model.



**Figure 5.** General concept of the SAMIRA downscaling methodology. Green boxes indicate input data, white boxes indicate intermediate datasets, blue boxes represent processing steps, and the orange box indicates the final output.

#### 2.5. In Situ $PM_{10}$ Assimilation

For completeness, the SAMIRA pre-operational in situ  $PM_{10}$  air quality data assimilation forecast system should be mentioned. Based on the prototype system developed in the ESA SiAiR project (2014–2015) [59], the WRF-Chem model was setup to run at 5 km horizontal resolution, covering most of Europe. The emission pre-processor was developed by the Central Institute for Meteorology and Geodynamics (ZAMG) in order to prepare data from emission inventories for WRF-Chem. Emissions were taken from the TNO-MACC II emission inventory [60] and the EMEP inventory (<http://www.ceip.at/ceip-reports>, accessed on 30 October 2018) for areas not covered by TNO emissions. This development was a first step towards a full air quality data assimilation system for Romania. It was designed to allow extension to other observational datasets. Thus, adding processor(s) for Sentinel 3, Sentinel 5P, and future missions is desirable.

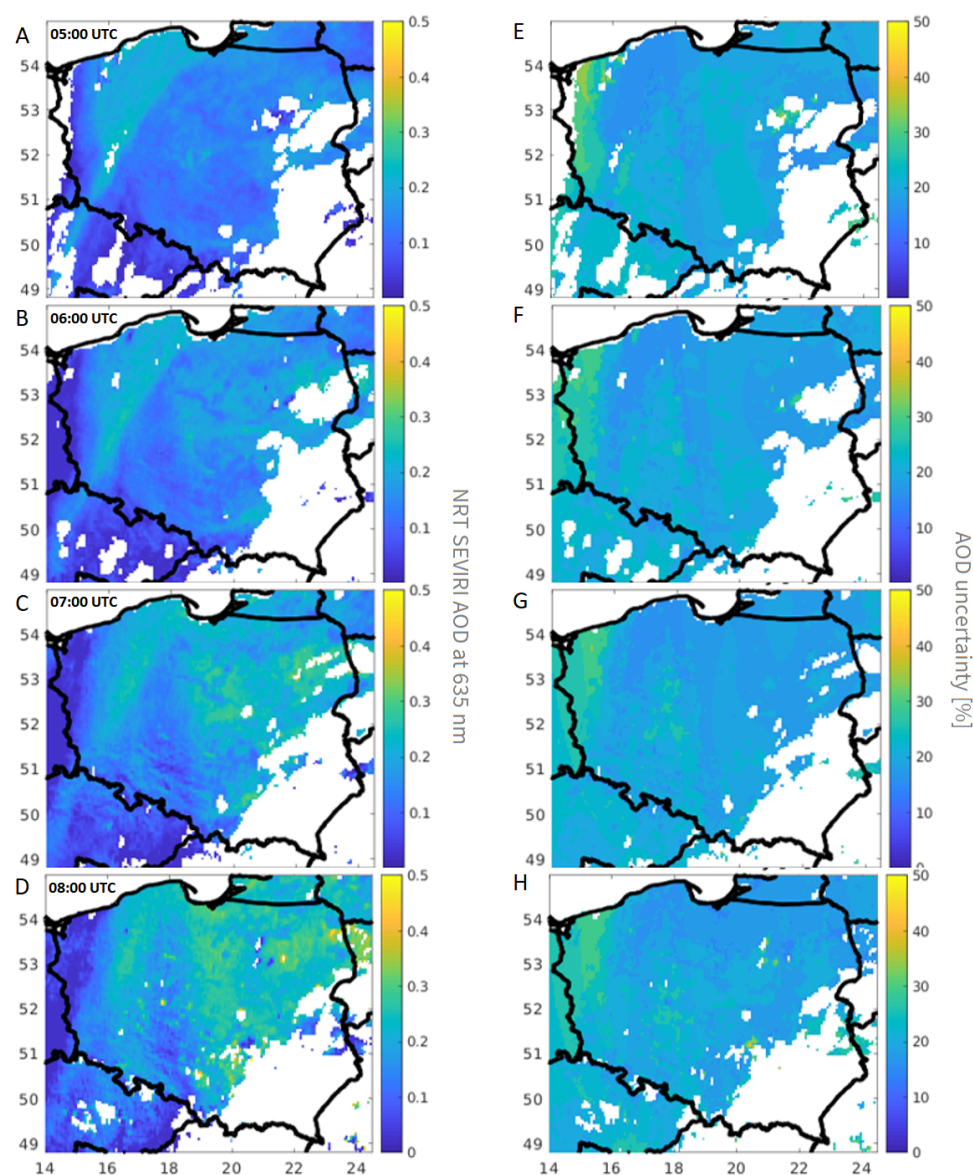
### 3. SAMIRA Product Examples

In the following we show exemplary data products developed during the SAMIRA project.



### 3.1. SEVIRI AOD

As a first example, SEVIRI NRT AOD and AOD uncertainties for Poland for four consecutive retrievals in the morning of 5 June 2019 are shown in Figure 6. During that day an interesting case of strong aerosol loading was observed over Poland. AOD rising by the hour are clearly captured. AOD at 635 nm is increasing starting from below 0.1 at 05:00 UTC to above 0.3 at 08:00 in Central and Eastern Poland. More maps from that day are available via [www.polandaod.pl](http://www.polandaod.pl) (accessed on 5 June 2020).

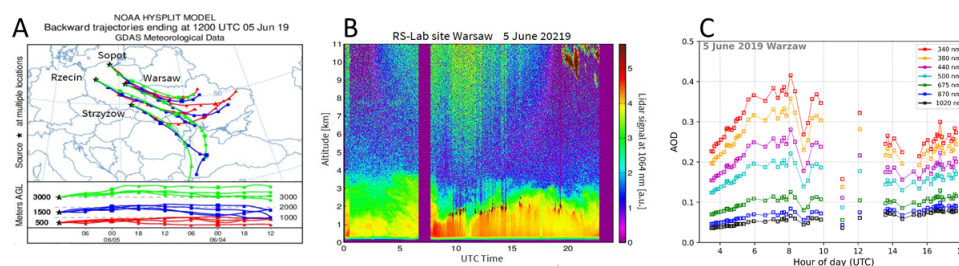


**Figure 6.** SEVIRI NRT AOD (A–D) and AOD uncertainty maps (E,F) over Poland for every fourth retrieval in the morning of 5 June 2019, at 05:00 UTC (A,E), 06:00 UTC (B,F), 07:00 UTC (C,G), and 08:00 UTC (D,H). The pixel resolution is  $5.5 \times 5.5 \text{ km}^2$  and each map represent 15 min.

To better understand the development of the AOD, we looked at complementary data. HySplit trajectories indicate air-mass inflow to Poland from Eastern Europe (see Figure 7A), passing over areas with wildfires (FIRMS Firemaps; <https://firms2.modaps.eosdis.nasa.gov>, accessed on 5 June 2020, not shown for brevity). The PollyXT LIDAR (<http://polly.tropos.de>), which is located at the Remote Sensing Lab in Warsaw, showed high values in the LIDAR signals up to 4 km of altitude, with a clear gradual increase after 5:00 UTC (Figure 7B). The co-located AERONET sun photometer (Level 2.0 Direct Sun and Level 1.5 Version 3



Inversion data; <https://aeronet.gsfc.nasa.gov>, accessed on 5 June 2020, Figure 7C) showed the highest increase in AOD for shorter wavelengths with almost unrecognizable change for the longer ones. It indicates that the observed aerosol was dominated by small particles, resulting in relatively high Ångström exponents (1.8–1.9), typical for biomass burning aerosol. This is consistent with the increase in AOD seen in the calculated SEVIRI AOD maps. The aerosol size distribution derived by AERONET was dominated by the fine mode particles (fine mode fraction >0.8). The situation changed in the afternoon, when size distribution between the modes was more equal (fine mode fraction around 0.6) and precipitable water vapor column decreased, leading to lower AOD. The change in AOD was also captured by the SEVIRI NRT AOD retrieval for the afternoon; although more cloud appeared over Poland area (not shown for brevity).



**Figure 7.** For 5 June 2019, backward trajectories for 12:00 UTC calculated with the HySplit Model (A), the Warsaw PollyXT LIDAR signal (B), and multi-wavelengths AOD for the Warsaw sun-photometer (C).

### 3.2. Satellite-Based $PM_{2.5}$ Retrieval

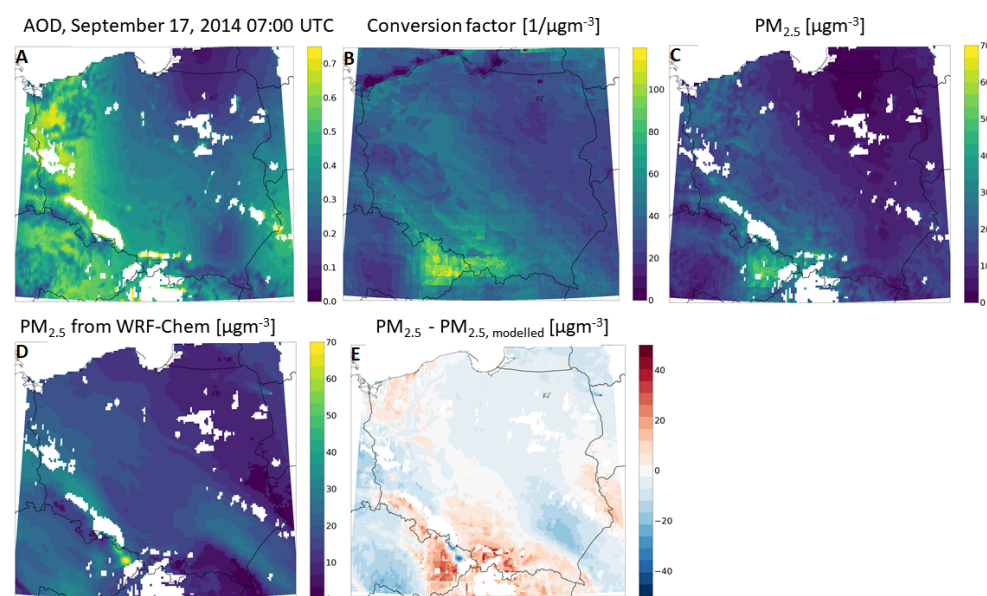
As a second example, the  $PM_{2.5}$  retrieval for September 17, 2014 is shown in Figure 8. Historical data from summer 2014 was used to test and validate our methodology to retrieve ground-based  $PM_{2.5}$  from satellite AOD. The data shown in Figure 8 are the  $PM_{2.5}$  related air pollution in the morning of 17 September 2014, at 07:00 UTC. Besides the aggregated hourly AOD, a map of the AOD-to- $PM_{2.5}$  conversion factor and a map showing the calculated hourly averaged  $PM_{2.5}$  for Poland is shown (Figure 8A–C). The closest in time AOD maps (15-min resolution) were cloud-screened (white areas on the map). The conversion factor map has the resolution of the WRF-Chem output (1-h). The final  $PM_{2.5}$  concentrations map for Poland combines the two. For comparison, the  $PM_{2.5}$  WRF-Chem model output and the difference between the calculated and the modeled  $PM_{2.5}$  is shown (Figure 8D–E).

$PM_{2.5}$  values estimated with the WRF-CHEM model are a good starting point for air quality mapping due to the ability of the model to capture the seasonal or annual variations of aerosols well. The major downside is the fact that it does not represent well random pollution events and only takes into account documented sources. The differences between the WRF-Chem output and our method clearly show that the “smooth” gradients produced by the CTM are far from what the spatial aerosol patterns visible in the AOD shows, which can improve the ground-level  $PM_{2.5}$  estimates. See also Section 4.2 for  $PM_{2.5}$  validation.

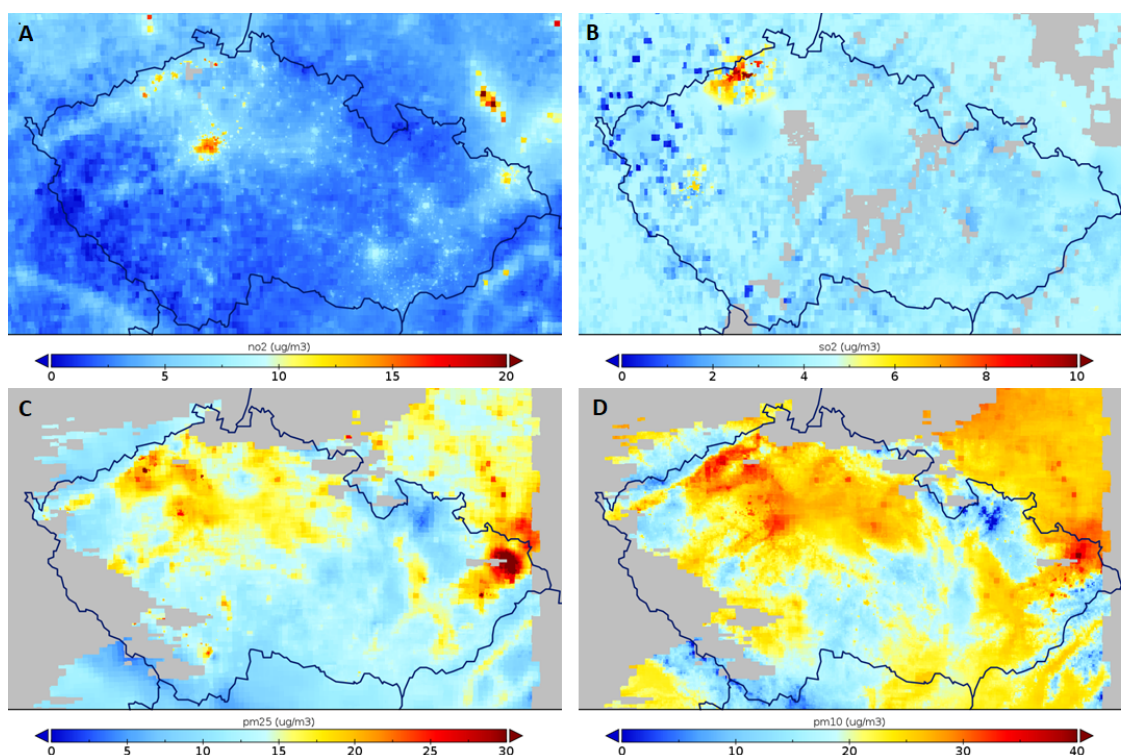
### 3.3. Data Fusion Maps

A third example shows output from the data fusion. The methodology was developed and tested first on historical data, including in situ data, CTM model output (CAMx, WRF-Chem, EMEP), and satellite data (SEVIRI AOD, satellite-based  $PM_{2.5}$ , as well as  $NO_2$ , and  $SO_2$  from OMI and GOME-2) to generate maps for the following pollutants:  $NO_2$ ,  $SO_2$ ,  $PM_{2.5}$ , and  $PM_{10}$ . In a second phase of the SAMIRA project the data fusion was run in near real time to generate up-to-date hourly maps utilizing  $NO_2$  and  $SO_2$  from TROPOMI. Note that for 2019 WRF-Chem data were not available due to technical problems with the UBB high performance computer, therefore, SEVIRI AOD was used as proxy for the data fusion of PM. As an example, in Figure 9 we show NRT air quality maps for the Czech Republic.

Maps of  $\text{NO}_2$ ,  $\text{SO}_2$ ,  $\text{PM}_{2.5}$ , and  $\text{PM}_{10}$  at different temporal slots are shown to illustrate the data fusion results.



**Figure 8.** AOD (panel A), conversion factor (panel B) and  $\text{PM}_{2.5}$  (panel C) map calculated for Poland, 17 September 2014 07:00 UTC. For comparison, in the lower panel  $\text{PM}_{2.5}$  output from WRF-Chem (panel D), and the difference between the calculated and the modeled  $\text{PM}_{2.5}$  is shown (panel E).



**Figure 9.** Hourly NRT air quality maps for the Czech Republic. (A):  $\text{NO}_2$  map for 15 August 2019 15:00 UTC; (B):  $\text{SO}_2$  map for 15 August 2019 15:00 UTC; (C):  $\text{PM}_{2.5}$  for 23 August 2019 07:00 UTC; (D):  $\text{PM}_{10}$  for 23 August 2019 07:00 UTC. Note that grey areas in the Czech Republic show regions with no satellite data due to cloud coverage.

The  $\text{SO}_2$  map shows increased concentrations in the north-eastern Bohemia. In both  $\text{PM}_{10}$  and  $\text{PM}_{2.5}$  maps, elevated concentrations around Prague, in the north-western part of

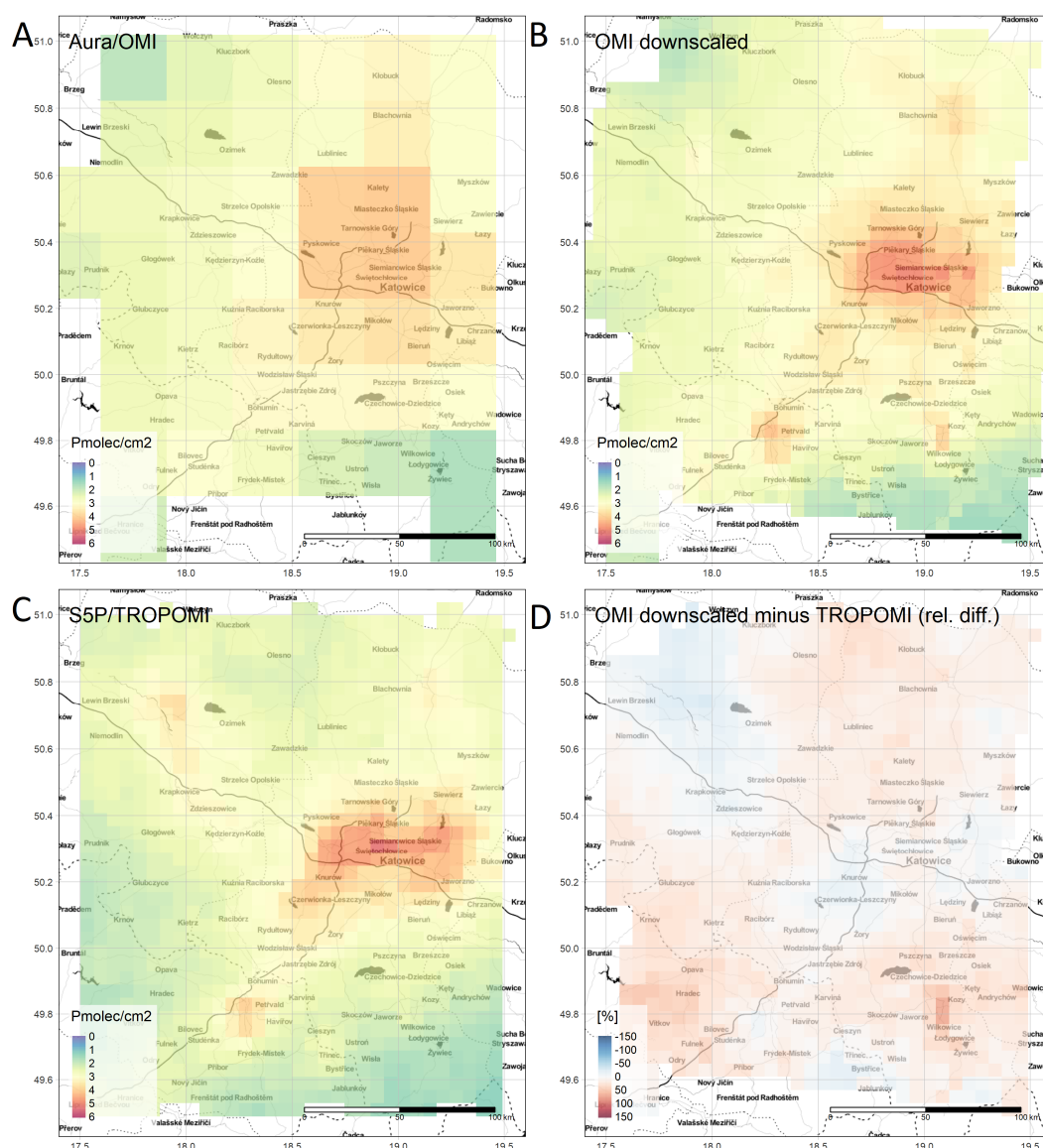
Bohemia and in Ostrava region can be seen. The same areas show also increased NO<sub>2</sub> levels, although the increase is less distinct were compared to PM. The data fusion maps well represent the concentration levels across the given area and correspond to the expected concentrations due to known pollution sources [61]. Both satellite and modeling data provide spatial representation, while the in situ measurement data assures the levels are not biased. The main limitation of these maps is caused by missing satellite data in the clouded areas. This can be overcome by a gap filling, e.g., using data calculated based on the in situ measurement and model data only.

### 3.4. Downscaling

Within the SAMIRA project a downscaling algorithm was developed and tested for several study sites (Oslo, Warsaw, Prague, Bucharest, Ostrava/Katowice), time periods (mostly 2014 and 2018), and pollutants (primarily NO<sub>2</sub> and AOD). As a final example, in Figure 10 we show downscaling results for the area along the border between the Czech Republic and Poland that traditionally have significant problem with air quality. An OMI dataset representing the NO<sub>2</sub> average for July through September 2018 at a spatial resolution of 0.25° by 0.25° was downscaled to the same resolution as TROPOMI (here gridded to 0.05° × 0.05°). This allows for comparing the downscaled OMI dataset with the “true” high-resolution TROPOMI measurements and to both quantitatively and qualitatively evaluate the correspondence between the two datasets, and, thus, the performance of the downscaling algorithm, as well as the used proxy. Qualitatively, Figure 10 indicates that the downscaling technique is able to bring out spatial detail that was not available in the original coarse-resolution OMI dataset. For example the elongated east–west extent of the hotspot in the center of the domain and smaller isolated hotspots related to local pollution. This can be seen for the entire area around Katowice but also for the hotspot in the south-west of the domain south of Bohumin that is visible in both the downscaled OMI dataset, as well as the TROPOMI data. Note that, with levels of  $5\text{--}6 \times 10^{15}$  molecules cm<sup>−2</sup>, the downscaled dataset provides accurate estimates of the actual tropospheric column amounts of NO<sub>2</sub> over the Katowice area that are very close to those actually measured by TROPOMI at high resolution, even though the actual OMI-observed values were significantly lower due to the averaging over the area of coarser pixels. Later on, in Section 4.4, we will show further quantitative results of the same datasets.

There are some limitations of the method which result in patterns that were not observed by TROPOMI. For instance the area in the northwest of the domain north of Krapkowice that shows a clear hotspot in the TROPOMI dataset is somewhat underestimated in the downscaled dataset. The reason for this is not entirely clear because the small hotspot observable in the TROPOMI dataset is large enough that it should also be picked up by the OMI instrument to some extent. It is visible in the downscaled map as a small area of increased tropospheric NO<sub>2</sub> columns, but the values are significantly lower than those in the TROPOMI map. A similar issue can be seen in the area south of Katowice in the Kozy area where the downscaled map show a clear hotspot, but this hotspot is not present in the TROPOMI dataset. The original OMI values in this area are generally higher than TROPOMI.

It is important to note that while the the downscaling technique uses a high-resolution proxy dataset, the downscaled values are entirely constrained by the original satellite measurements, i.e., if the downscaled results are re-aggregated to the coarse resolution, the corresponding values will match exactly the original OMI observations. The use of OMI for downscaling in this example was entirely driven by the possibility to have a high-resolution reference with the TROPOMI data. Although we cannot demonstrate it here, due to the lack of very high resolution reference data, initial experiments with downscaling TROPOMI indicate that the methods has significant potential for also downscaling TROPOMI to even higher spatial resolutions.



**Figure 10.** Real-world validation of the downscaling method using TROPOMI as a high-resolution reference for the area of the Ostrava/Katowice area for July through September 2018. Panel A shows the original OMI data (gridded at  $0.25^\circ \times 0.25^\circ$ ). Panel B shows the result of downscaling the OMI data using the QUARK  $\text{NO}_2$  dataset (<https://ec.europa.eu/environment/air/pdf/NO2%20exposure%20technical%20manual.pdf>, accessed on 30 October 2018) as a proxy. For a direct comparison, panel C shows the original TROPOMI data gridded to a spatial resolution of  $0.05^\circ \times 0.05^\circ$ . Panel D shows the relative difference between the downscaled OMI data and the TROPOMI data.

#### 4. Validation Results

Validation was an essential part of SAMIRA and is essential to understanding the achievements made. It was part of the algorithm developments, as well as done independently. Due to the nature of the different data sets, the validation approach had to be different for the various products. SAMIRA data products, reference data, and approaches used for validation are summarized in Table 1.

##### 4.1. Validation of SEVIRI AOD

For the validation of SEVIRI AOD the historical data from June–September 2014 were used. They were compared with data from AERONET, the Poland-AOD network, and the 3 km AOD product (at 550 nm) from the moderate resolution imaging spectroradiometer (MODIS) [62,63]. The latter was chosen despite its lower accuracy compared to the 10 km



MODIS AOD data, because of its better comparability to the spatial resolution of SEVIRI ( $5.5 \times 5.5 \text{ km}^2$ ). In 2014, AERONET measurements were made at four stations in Romania and at two locations in Poland using the CIMEL Electronique 318A sun photometers (675 nm). The Poland-AOD network measurements were done at three stations with the multifilter rotating shadowband radiometers MFR-7 radiometers (613 and 674 nm). In Table 2, the comparisons between SEVIRI AOD data at 635 nm and AOD from the ground-based sun-photometer are shown for closest matches within 15 min. For the SEVIRI – MODIS comparison one hour was used as a temporal co-location criteria. An AOD value of 0.15, which is the recommended threshold for ‘clean’ reference days, was used as a lower limit for the comparisons [42].

**Table 1.** SAMIRA data products and reference data used for validation.

SAMIRA Products	Datasets Used for Product Development	Datasets Suitable for Validation (Methodology)
SEVIRI AOD	all days: reflectance from SEVIRI reference day: AOD from AERONET, Poland AOD network, and CAMS	AOD from AERONET, the Poland AOD network and MODIS (statistical scores)
PM <sub>2.5</sub> from AOD	SEVIRI AOD from SAMIRA WRF-Chem model output	PM <sub>2.5</sub> from ground-based national air quality networks (correlation)
Data fusion NO <sub>2</sub> , SO <sub>2</sub> , PM <sub>2.5</sub>	AQIS database data for Czech Republic CAMx output, auxiliary data AOD, PM <sub>2.5</sub> from SAMIRA NO <sub>2</sub> , SO <sub>2</sub> from OMI, GOME-2, TROPOMI	Subsets not used in the analysis (cross-validation)
Downscaling NO <sub>2</sub> , SO <sub>2</sub> AOD, PM <sub>2.5</sub>	AOD, PM <sub>2.5</sub> from SAMIRA NO <sub>2</sub> , SO <sub>2</sub> from OMI, TROPOMI Model output (WRF-Chem, WRF-EMEP) QUARK NO <sub>2</sub>	Synthetic data, satellite data with higher spatial resolution (statistical scores)

The country averaged correlation coefficient (R) between AOD from SEVIRI and AOD from the ground-based stations varies between 0.61 and 0.62 with a mean bias between 0.09 and 0.12. The bias differences are only in small proportion influenced by the different wavelengths at which the data were collected ( $10^{-2}$  order of magnitude). We found varying correlations values between individual sites, which can be explained by different reflectance values specific to the land use classes within the satellite pixel. SEVIRI AOD did not correlate as well as with the 3 km AOD product from MODIS, with R and biases between 0.32 and 0.39, and 0.07 and 0.11, respectively. Detailed validation results for the individual AERONET and Poland-AOD sites, as well as map comparisons between SEVIRI and MODIS AOD, are given in [64].

**Table 2.** Validation of SEVIRI AOD using AOD from AERONET, the Poland AOD network, and the 3 km AOD product from MODIS. N: number of co-locations, R: correlation coefficient, RMSE: root mean square error.

Data	Domain	N	R	Bias	RMSE
AERONET	Romania	982	0.62	0.12	0.14
AERONET	Poland	289	0.61	0.10	0.12
POLAND-AOD	Poland	544	0.61	0.09	0.12
MODIS	Romania	90,740	0.32	0.11	0.15
MODIS	Poland	48,912	0.39	0.09	0.14
MODIS	Czech Republic	16,154	0.35	0.07	0.15



#### 4.2. Validation of Satellite-Based $PM_{2.5}$

The reference data for the validation of satellite-based  $PM_{2.5}$  concentrations were  $PM_{2.5}$  observations from the ground-based national air quality networks. When validating satellite derived PM, it was found important to take into consideration details related to the location of the measurement sites. This is illustrated in Figure 11. Sub-pixel variability, e.g., half of the pixel is forested area and the other half is in a urban area, or close-by localized emission sources can have the effect that in situ stations are not being representative for the satellite pixel. Although homogeneous urban areas such as the one shown in Figure 11A were found to be proper validation sites, coastal stations (Figure 11B) were not, because marine aerosol was not included in our model.



**Figure 11.** Illustration of land cover and land-use within a 5 km × 5 km square SEVIRI pixel. (A): urban area, (B): coastal site.

Validation was done separately for the three countries. For Poland and the Czech Republic, 36 and 35 ground stations, respectively, had reported hourly values of  $PM_{2.5}$ . For Romania only daily means of  $PM_{2.5}$  at nine ground stations were available for the time period June–September 2014. After eliminating the non-representative sites, correlation coefficients between the satellite-based  $PM_{2.5}$  and the in situ station are 0.49 and 0.56 for the Czech Republic and Poland, respectively. This is significantly higher than the correlation between the WRF-Chem  $PM_{2.5}$  and the in situ station data (see Table 3). Note that for the correlation between WRF-Chem and the air quality sites there is basically no difference between the entire set of stations and the selected ones. For Romania no hourly  $PM_{2.5}$  station data were available, therefore, daily averages are given in Table 3.

**Table 3.** Correlation (R) between WRF-Chem and satellite-based  $PM_{2.5}$  and  $PM_{2.5}$  measured at ground-based stations.

Country	Temporal Average	WRF-Chem, all / Representative Stations	All Stations (Number of Stations)	Representative Stations (Number of Stations)
Poland	hourly	0.32/0.30	0.40 (36)	0.56 (16)
Czech Republic	hourly	0.25/0.27	0.41 (35)	0.49 (13)
Romania	daily	0.44	0.53 (09)	

#### 4.3. Validation of Data Fusion Mapping Results

The validation of the data fusion mapping results is based on the ‘leave one out’ cross-validation method. It computes the quality of the spatial interpolation of residuals for each measurement point from all available information except from the point in question, i.e., it withholds one data point and then makes a prediction at the spatial location of that point. Data fusion analyses were executed for four pollutants, i.e.,  $NO_2$ ,  $SO_2$ ,  $PM_{2.5}$ , and  $PM_{10}$  for the Czech Republic, based on the 2014 dataset. For all pollutants, daily and hourly time steps were examined, while the annual time step was carried out for  $NO_2$ ,  $SO_2$  only due to the lack of annual PM or AOD satellite data. In Table 4, the root mean square error

and biases are shown for rural and urban background areas separately. The results for annual NO<sub>2</sub> and SO<sub>2</sub> data can be found in Table 5.

**Table 4.** Comparison of different spatial interpolation variants showing cross-validation parameters root mean square error (RMSE) and bias, as annual statistics average, based on the specified pollutants daily and hourly maps across 2014 for the Czech Republic. Numbers are given for without (x|) and with (|x) inclusion of satellite data, and superior results are marked in bold. For PM superscripts indicate which satellite dataset was used. For PM<sub>2.5</sub> three values are shown for without (x|) and with (|x<sub>a</sub>|x<sub>b</sub>) inclusion of satellite data a. with SEVIRI AOD as proxy and b. using SAMIRA PM<sub>2.5</sub> data. Units:  $\mu\text{g m}^{-3}$ .

	Rural Areas		Urban Background Areas	
	RMSE	Bias	RMSE	Bias
NO <sub>2</sub> daily	3.37   <b>3.24</b>	−0.06   <b>−0.04</b>	5.18   <b>5.14</b>	−0.01   0.02
NO <sub>2</sub> hourly	5.46   <b>5.22</b>	−0.01   <b>0.00</b>	<b>8.96</b>   9.04	<b>0.10</b>   0.12
SO <sub>2</sub> daily	3.68   <b>3.61</b>	0.04   0.04	5.56   <b>5.53</b>	−0.11   −0.07
SO <sub>2</sub> hourly	5.75   <b>5.59</b>	0.09   <b>0.03</b>	5.93   <b>5.91</b>	−0.10   −0.04
PM <sub>10</sub> <sup>AOD</sup> daily	4.76   <b>4.57</b>	−0.14   <b>0.00</b>	<b>5.06</b>   5.17	−0.18   −0.12
PM <sub>10</sub> <sup>AOD</sup> hourly	14.00   <b>12.50</b>	1.24   <b>0.01</b>	13.28   <b>8.26</b>	0.77   −0.13
PM <sub>2.5</sub> <sup>AOD,PM<sub>2.5</sub></sup> daily	4.17   <b>3.39</b>   3.65	0.02   <b>0.00</b>   −0.01	4.35   4.60   <b>4.19</b>	<b>0.07</b>   −0.15   −0.10
PM <sub>2.5</sub> <sup>AOD,PM<sub>2.5</sub></sup> hourly	7.26   7.07   <b>6.98</b>	−0.07   <b>0.00</b>   0.01	9.29   <b>8.26</b>   8.67	0.13   −0.13   −0.16

**Table 5.** Comparison of spatial interpolation variants without and with the use of satellite data showing cross-validation parameters RMSE, bias, and R<sup>2</sup>, based on NO<sub>2</sub> and SO<sub>2</sub> annual average map for the Czech Republic for 2014. RMSE and bias are given in  $\mu\text{g m}^{-3}$ .

	Rural Areas			Urban Background Areas		
	RMSE	Bias	R <sup>2</sup>	RMSE	Bias	R <sup>2</sup>
NO <sub>2</sub>	2.83   <b>2.11</b>	0.03   <b>0.00</b>	0.33   <b>0.63</b>	3.52   <b>3.48</b>	0.24   <b>0.15</b>	0.42   <b>0.43</b>
SO <sub>2</sub>	3.11   <b>2.98</b>	−0.13   −0.13	0.25   <b>0.31</b>	2.97   <b>2.75</b>	<b>0.01</b>   −0.30	0.21   <b>0.33</b>

Comparing the data fusion variants without and with the satellite data, we found that the inclusion of the satellite data improves the daily and hourly mapping results of NO<sub>2</sub> in the rural areas. Although for hourly NO<sub>2</sub> data there is an improvement noticed for rural background areas, this does not seem true for the urban environment (see Table 4). Including satellite NO<sub>2</sub> data improved the annual data, both in the rural and in the urban regions (see Table 5). Looking at SO<sub>2</sub>, the inclusion of satellite data slightly improves both, rural and urban mapping results for hourly, daily and annual data. For PM<sub>10</sub>, SEVIRI AOD was used as a proxy, and the original 15-minute data were temporally aggregated into hourly and daily data. For PM<sub>2.5</sub>, two values are shown in Table 4, a. with SEVIRI AOD as proxy and b. using SAMIRA PM<sub>2.5</sub> data. For daily PM<sub>2.5</sub> mapping the results show largest improvement in rural areas when AOD was used and in urban areas when PM<sub>2.5</sub> was included in the data fusion. The inclusion of satellite data (either AOD or PM<sub>2.5</sub>) can improve the results for PM<sub>10</sub> and PM<sub>2.5</sub> for the Czech Republic. However, it is important to note that the results for PM were calculated for a much smaller number of days (June–September 2014) than for NO<sub>2</sub> and SO<sub>2</sub> and did not include winter months.

#### 4.4. Validation of Downscaling Algorithm

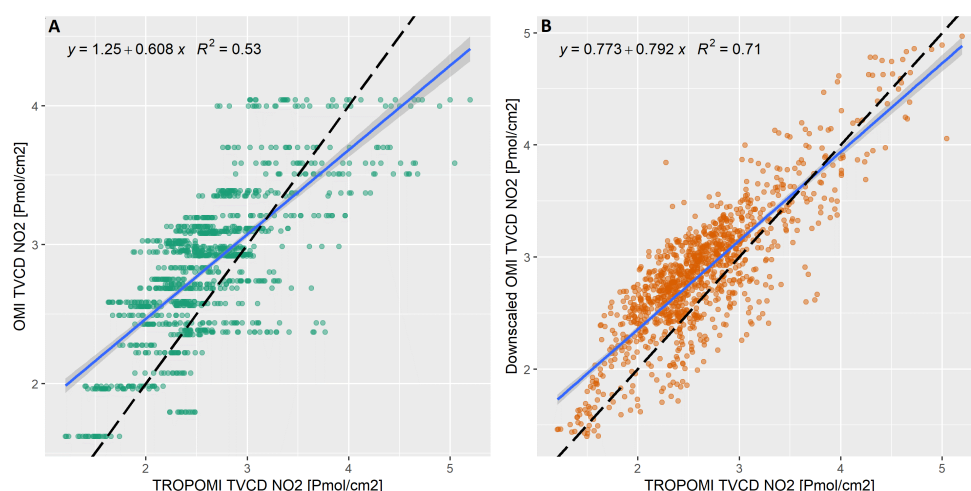
The downscaling algorithm itself was initially validated using synthetic data. Using simulated fields for testing the algorithm has the advantage that the fine-resolution truth is known, and the performance of the downscaling method can be evaluated accurately by comparing against the truth. Table 6 shows the corresponding summary datasets for each method. The SAMIRA method (area-to-point kriging with a covariate) outperforms all the

other methods. In particular, the root mean square error (RMSE) decreases significantly for area-to-point kriging with a covariate.

**Table 6.** Summary statistics of a various downscaling methods for the simulated dataset (A.U.). Marked in bold are the best values for several relevant metrics. SD: standard deviation, MAE: mean absolute error, RMSE: root means square error.

Method	Covariate	Mean Bias	SD	MAE	RMSE	Intercept	Slope	R <sup>2</sup>
Bilinear interpolation	no	0.04	1.42	1.13	1.42	−0.73	1.04	0.91
Area-to-point kriging	no	−0.01	1.32	1.05	1.32	− <b>0.54</b>	<b>1.03</b>	0.93
Simple linear regression	yes	−0.02	1.46	1.15	1.46	0.96	0.95	0.91
Robust linear regression	yes	0.11	1.59	1.26	1.59	−3.11	1.17	0.91
<b>Area-to-point kriging</b>	yes	<b>0.00</b>	<b>0.69</b>	<b>0.54</b>	<b>0.69</b>	0.95	0.95	<b>0.98</b>

In addition, the algorithm was validated using satellite data with higher spatial resolution. Figure 12 shows a comparison of original OMI NO<sub>2</sub> (panel A) and the downscaled OMI NO<sub>2</sub> (panel B) against TROPOMI NO<sub>2</sub>, the latter acting here as a reference. The overall scatter and the alignment with the 1:1 line is significantly improved after downscaling the OMI data. In fact, the R<sup>2</sup> value shows a quite significant increase from 0.53 to 0.71. The results of the comparison are summarized in Table 7. It is evident that six out of seven summary metrics were improved by applying the downscaling algorithm to the coarse-resolution dataset.



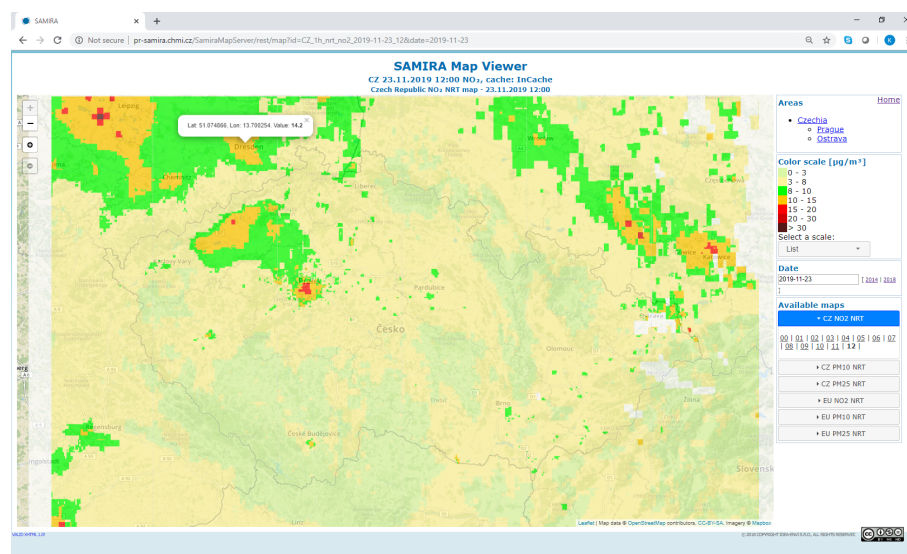
**Figure 12.** Scatterplots showing a comparison of the original OMI NO<sub>2</sub> product (panel A) and the downscaled OMI NO<sub>2</sub> product (panel B) against the TROPOMI NO<sub>2</sub> product [in 10<sup>15</sup> molecules cm<sup>−2</sup>] for the area of the Czech Republic for July through September 2018. Note that due to its coarse resolution a pixel of the original OMI product represents multiple TROPOMI pixels, thus explaining the striped patterns in panel A.

**Table 7.** Summary statistics comparing the original OMI NO<sub>2</sub> data and the downscaled OMI NO<sub>2</sub> data, respectively, against the high-resolution TROPOMI NO<sub>2</sub> data (in 10<sup>15</sup> molecules cm<sup>−2</sup>), shown here for area of the Ostrava/Katowice region. The better metrics are marked in bold. SD: standard deviation, MAE: mean absolute error, RMSE: root means square error.

Dataset	Mean Bias	SD	MAE	RMSE	Intercept	Slope	R <sup>2</sup>
OMI Original	<b>0.22</b>	0.43	0.40	0.48	1.25	0.61	0.53
OMI Downscaled	0.23	<b>0.34</b>	<b>0.34</b>	<b>0.40</b>	<b>0.77</b>	<b>0.79</b>	<b>0.71</b>

## 5. SAMIRA Air Quality Data Mapping Portals

Since March 2019, up-to date hourly maps for NO<sub>2</sub>, SO<sub>2</sub>, PM<sub>2.5</sub> and PM<sub>10</sub> and daily maps for PM<sub>10</sub> and PM<sub>2.5</sub> were created operationally for the Czech Republic and the European domains. These, as well as the historical data from June–September 2014, were visualized with a custom-build responsive mapping portal. As an example, a map showing hourly averaged Czech NO<sub>2</sub> for 23 November 2019 is shown in Figure 13. Furthermore, NRT AOD maps for Poland are shown on the Poland AOD network site (<http://www.polandaod.pl/>; in the Polish language version only). General background information about SAMIRA can be found on the project website <https://samira.nilu.no>.



**Figure 13.** SAMIRA Map Viewer showing hourly averaged NRT NO<sub>2</sub> for 23 November 2019 12:00 over the Czech Republic.

## 6. Conclusions and Outlook

The SAMIRA initiative led to increase in knowledge and better exploitation of synergistic satellite-based air quality products. A distributed NRT system for satellite-based regional air quality was set up, thus successfully demonstrating a complex technical interplay between multiple research and operational institutions located in four European countries. Advances were made in the following research areas:

1. The SEVIRI AOD optimal estimation algorithm was improved and geographically extended from Poland to Romania, the Czech Republic and Southern Norway. Alongside AOD, pixel-level uncertainties were estimated. After testing for historical data (June–September 2014), a NRT retrieval was implemented and is currently operational (for details see [42]). The benefit of using SEVIRI for air quality application is the possibility to obtain data with a high temporal resolution (15 min). The largest limitation of any geostationary AOD algorithm is related to the surface hot-spot effect for scattering angles close to 180° and a small solar zenith angle, limiting the retrieval to day-times up to 10:00 UTC and after 14:00 UTC. The exact range, however, depends on the time of the year and geographical position. A specific issue for the SEVIRI optimal interpolation AOD retrieval is the choice of the reference day (a clean day with low AOD and clear sky) and that the availability of regular ground-based AOD measurements is required. This hinders the retrieval for regions where no photometer data are available, as it was in the case for the Czech Republic. Due to the northern geographic location of Norway scattering geometry is unfavorable and clouds frequently obstruct the scenes, therefore AOD data for Norway are sparse. Validation against ground-based sun-photometers, located in Romania and Poland, using the data from 2014, showed generally good agreements with country mean correlation coefficients (*R*) between 0.61 and 0.62, a bias of 0.09–0.12, and an RMSE of



0.12–0.14, but did not correlate as well with the 3 km AOD product from MODIS. For more details see [64].

2. A retrieval for ground-level concentrations of  $PM_{2.5}$  was implemented using the SEVIRI AOD in a combination with WRF-Chem output. NRT capability for the AOD-to- $PM_{2.5}$  retrieval was demonstrated. The satellite-based  $PM_{2.5}$  data product from our method was validated using ground-based in situ  $PM_{2.5}$  observations from National air quality networks. An important lesson learned is that the representativity of the air quality monitoring stations is a very important factor to take into account when evaluating the methodology. For representative sites in Poland and the Czech Republic correlations between 0.56 and 0.49 were found between satellite-based  $PM_{2.5}$  and  $PM_{2.5}$  measured at air quality sites; this is nearly double the correlation between WRF-Chem  $PM_{2.5}$  and  $PM_{2.5}$  observed at the in situ sites. Uncertainties in the  $PM_{2.5}$  retrieval, as well as AOD and WRF-Chem uncertainties contribute to those from the satellite-based  $PM_{2.5}$ . The boundary layer altitude were found to be an important parameter for a potential future improvement of the  $PM_{2.5}$  retrieval.

3. The added value of including satellite data when creating air quality maps was demonstrated. An operational algorithm for data fusion with the capability of optimally merging and mapping multiple heterogeneous datasets was extended to make use of various satellite-based air quality products ( $NO_2$ ,  $SO_2$ , AOD,  $PM_{2.5}$ , and  $PM_{10}$ ). Validation results showed that in multiple cases the inclusion of satellite data can improve the mapping for the Czech Republic for both, historical as well as NRT data. Moreover, an inclusion of satellite data improves the daily and hourly mapping results of  $NO_2$  in the rural areas and annual data, both in the rural background and in the urban regions. Inclusion of satellite  $SO_2$  slightly improves both rural and urban mapping results for hourly, daily, and annual data. Including AOD or  $PM_{2.5}$  derived from satellite AOD improved the results for  $PM_{2.5}$  and  $PM_{10}$ . The main limitation for the operational use of such data lies in the limited satellite data coverage due to lack of daylight and cloudiness. Gap filling in the cloudy areas, using model and in situ data only, can be considered a suitable way to improve coverage, as long as is properly flagged.

4. A geostatistical downscaling algorithm was developed and tested to bridge the gap between satellite products of air quality (typically provided at spatial resolutions on the order of several kilometres) and urban-scale applications (for which spatial resolution of hundreds of meters are required). Statistical downscaling has been carried out in many disciplines in the past and substantial efforts have also been made in satellite remote sensing. However, so far to our knowledge no studies have used or implemented such approaches for downscaling satellite-based air quality products. In a first step, the SAMIRA downscaling algorithm was validated using synthetic data. Then, we found that it performs well in extracting spatial details that can be seen in the true high-resolution data field. We successfully demonstrated downscaling OMI  $NO_2$  data to the spatial resolution of TROPOMI, with  $NO_2$  data from the latter acting as a true high-resolution reference. It is expected that the advantage provided by the downscaling algorithm will also hold for even finer spatial scales. It is important to note here that—when using a time-invariant proxy—the downscaling on a daily basis (i.e., not for a longer-term average) for a high-resolution instrument, such as TROPOMI, is limited to relatively calm winds in the area and no significant plumes forming. In the case of a substantial plume the downscaling algorithm will spatially redistribute in areas where the original emissions causing the plume have not actually originated, thus leading to erroneous results.

We can conclude that the SAMIRA project was a significant step forward towards a better exploitation of the Earth observation capabilities for air quality monitoring in Europe. Geostationary satellite instruments, like SEVIRI and the upcoming Sentinel 4 mission [65] (launch planned in 2023) are particularly interesting for air quality applications. Setting up a European or international initiative, analogue to, e.g., the Production and Evaluation of Aerosol Climate Data Records from European Satellite Observations (Aerosol\_cci) [66], but with focus on geostationary AOD retrievals, would be an important step forward in



improving satellite-based air quality. This is also true for the estimation of the information content for satellite-based PM<sub>2.5</sub> retrieval. Outcomes from SAMIRA, together with the work performed for the EEA [67], led to the inclusion of satellite data in the EEA air quality mapping in Europe. A geospatial downscaling algorithm was implemented and we could demonstrate its skills. More work is necessary to better understand the uncertainties and limitations associated with the resulting downscaled products. All of the work shown above is about data integration. Linking the NO<sub>2</sub> columnar data with surface concentrations of NO<sub>2</sub>, for which several hundreds of stations are available in Europe, is a natural next step in the development of satellite-based urban-scale air quality monitoring.

**Author Contributions:** The concept for SAMIRA was developed by K.S., D.N., I.S.S., N.A., A.D., J.H., P.S. and C.Z. The manuscript was prepared by K.S. with main input provided by I.S.S., M.B., N.A., J.H., J.M., P.S. and with additional writing—review by O.V. and R.J. Main responsibilities for the SEVIRI AOD retrieval lied with O.Z.-M. (case study analysis: I.S.S.), the PM<sub>2.5</sub> retrieval with M.B. and A.N. (who were supported by V.N. and D.N.), the data fusion with J.H., J.M. and R.J., downscaling with P.S. and the in situ PM<sub>10</sub> data assimilation with A.D. (with support from R.D. and A.I.-B.). R.D., N.A., N.B. and O.V. were responsible for the modeling (supported by A.I.-B.). N.A., H.S., C.B. and K.S. contributed to the independent product validation (supported by I.S.S. and O.Z.-M.). P.N. and L.V. developed the SAMIRA data mapping portal. K.S. was responsible for scientific project management. All authors have read and agreed to the published version of the manuscript.

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