



Article Research into the Impact of Spindle Speed and Feed Rate Changes on the Life of a Deep-Drilling Technology Tool

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Abstract: The drilling process in real production places ever-increasing demands on the length and accuracy of the holes made. The drilling of holes beyond a length-to-diameter ratio of 5–10 is called deep drilling. The aim of the research was to determine in detail the deep-drilling process input conditions, their impact on the stability of the cutting process and the degree to which the output requirements were achieved. The focus of the analysis was on how the monitored technological and physical impacts translate into achieving the required gun-drill life and the quality and dimensional accuracy of deep holes, as well as their overall impact on tool life. Based on the analysis, tests were conducted to verify the impact of individual parameters on tool life. The obtained results were then statistically evaluated and optimized. Drawing on the evaluated experimental results, solutions and procedures were proposed and implemented in the environment of a real operation. This research obtained the optimal values of the frequency of rotation and displacement to ensure maximum tool life while maintaining the efficiency of the production of drilled parts. At the same time, based on the research, a methodology and recommendations for deep-drilling technology were developed.

Keywords: gun drill tool; deep-drilling technology; optimization; tool life

1. Introduction

The rapid development of new technologies and growing consumer demands mean that companies are trying to find new and more efficient ways of developing and researching their products and, thus, receive the retroactive economic benefits of production. Current technical progress and the application of specific solutions and innovations, thanks to which manufacturing companies can promptly improve established procedures and techniques, is expected to ensure high production efficiency. One such major technological operation is the drilling process [1].

The drilling of deep holes can be carried out in several ways: with a rotating workpiece or with a rotating tool, or with a tool rotating simultaneously with the rotating workpiece. Regardless of the drilling method, the basic principles of drilling and, moreover, the correct choice of cutting speed and feed rate, remain unchanged [2,3]. Successful chip formation and its removal from the cutting edge without damaging the tool and workpiece are, in principle, the most important factors influencing the quality of drilled holes [4]. Small-diameter holes are created using the technology of deep (gun-drill tool) drilling with the STS (single-tube system). An alternative to STS technology in cases where the drilling of a smaller production series is carried out and a specialized machine is not available is the ejector system [5,6]. Due to the state-of-the-art development of carbide monolithic tools, it is currently possible to make holes with smaller diameters with carbide screw augers featuring length-to-diameter ratios of up to 30 mm [7].



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Copyright: © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). Both the design and the materials and coating used in deep-drilling technology have evolved [8]. The most recent solution is the design of gun-drill tool bodies with interchangeable cutting plates and interchangeable guide surfaces that provide the additional adjustment of dimensions using different washer widths [9]. Nevertheless, even with the use of the latest auger design, one of the most important conditions for maintaining a stable process is still relevant, namely the application of sufficient cutting fluid pressure to dissipate heat, to remove chips and to provide the cutting process with lubrication [10–12]. Other influences, such as the stability and accuracy of the machine, the properties of the machined material, the technological parameters and the use of a suitable tool also enter the process. All these factors affect the resulting process, which must, first and foremost, take into account the economic viability of production [13–15].

Several important authors from the worldwide scientific community address the issue of deep drilling. Hong J. et al. discuss a new method of data monitoring to estimate tool wear when making holes with the application of deep-drilling technology. The proposed monitoring method is a Gaussian regression process (GRS) based on a combination of force, torque and vibration signals that are extracted from a predefined segment. The results show that the accuracy of the tool wear estimate can be improved by the method proposed, which significantly outperforms other methods. Examples include linear regression and support vector regression [16]. In their publications, focusing on the force system and performance of the AlSi 1045 cutting steel drilling rig, Wang Y. et al. describe a drilling-force system created by integrating the forces on the main cutting edge by wear and outer diameter (OD) and mechanical equilibrium equations using a specific energy model, which consists of geometric parameters, machining parameters and material properties [17]. The researchers Zhang X. et al. are engaged in similar research and the development of high-quality augers with precisely controllable tool geometry. Through planned experiments, they experiment with the effects of changes in apex deviations on deviations in hole flatness. Through a series of FEM analyses and further measurements of the internal rolling of the machined holes, it was concluded that unbalanced cutting force components, applied to previously drilled holes due to inconsistent apex displacement, cause newly formed holes to deviate from the thin wall due to the greater material strain on the thin-walled side relative to the side with thick walls [18]. Studies of precision and surface roughness after deep drilling have been carried out by Kirsanov, S.V. and Babaev A.S., particularly on sintered carbide and water-resistant coating, which have higher wear resistance and ensure the lower surface roughness of drilled holes [19]. Based on their experimental results, Mann J.B. et al. conducted research in the field of drilling effects with overlapping controlled lowfrequency modulation (MAM) and on the surface structures created after deep drilling [20]. With development of science and technology, the precision of the individual-component manufacturing process by deep-drilling technology increases together with the demand and constantly growing requirements for the tools and equipment needed for these operations. Therefore, Zhang K.L. researched the improvement in the accuracy and efficiency of these devices for real use in practice [21]. Schnabel D. et al. deal with deep-drilling processes resulting in small holes and openings, addressing especially the cooling and lubrication of the machined zone, which translates into longer tool life. In their publication, they model the movement of the cooling lubricant during the drilling process using the finite volume and the hydrodynamics of cooled particles. The results prove that changing the coolant close to the cut guarantees the desired cooling effect. The coolant is modeled by the smooth-pin hydrodynamics method and the end-point method is used to describe the points. This study also provides transient simulations of the hydrodynamics of the smooth particles, which show insufficient weight, and recommends replacing the cutting edges corresponding to the steady state and the results of the simulation of the final volume with a complete bore filled with coolant [22]. In their studies on point formation and wear behavior during the drilling process of titanium-coated forged steel S 48CS1V, Wang Y. et al. point out the complex wear of the hard carbide tool in the chip-forming tests performed on this steel. They claim that high alternative stress resulted in plastic strain, and that

for atomic absorption, cold welding caused the carbide substrate grains to detach from the cobalt bond, thus causing the wear and tear of the tool [23]. In addition to turning and milling, drilling holes with augers is the most commonly used method in machining technology. A great number of machined holes is naturally reflected in the significant consumption of augers not only by individual companies, but also on a global scale. The choice of suitable types and auger design solutions therefore has a significant impact on the accuracy, efficiency and productivity of drilling, as well as on its economical use and consumption [24].

Drilling is a technological process resulting in circular cross-section holes. Their length depends on the design requirements and it is often necessary to drill holes with depths of up to five times their diameter [25]. This type of operation is referred to as deep drilling. Deep-drilling technology places greater emphasis on the cutting process than standard-hole (\leq 5D) drilling. To ensure a stable cutting process, as well as dimensional accuracy and quality standards, the following requirements must be met [26,27]:

- (a) The design of the tool must ensure good guidance of the tool in the hole and the geometry of the cutting part of the tool must ensure the formation of chips that can be easily removed from the hole area.
- (b) The tool must be sufficiently rigid to be able to drill efficiently in order to ensure that the drilling process runs smoothly.
- (c) The design of the tool must allow smooth chip removal from the hole area to ensure the smooth running of the drilling process and to prevent damage to the tool.
- (d) The technology must ensure a favorable relationship between cutting productivity and production economy through the appropriate choice of machine and other working conditions while adhering to all the required technical conditions for the accuracy of the drilled part.
- (e) The tool design must provide the prescribed dimensional accuracy, geometric shape and surface quality.

Monolithic long screw augers STS22 1130 and STS 22 1150 or augers with internal cooling STS 22 1154, manufactured with cutting fluid supply conduits, are used for drilling deep holes. Because the auger grooves fill quickly with chips, the augers need to be pulled out of the hole often to cool and remove the chips. This type of drilling is called intermittent drilling [28]. To avoid auger overload, the work cycle for augers ranging between 10 to 30 mm in diameter is selected according to the following established rules: the first bore is drilled to a depth of 2.5 to 4D; for subsequent bores, the hole is deepened gradually by 2D, 1.5D, 1D; and every subsequent attempt deepens the bore by 0.5D. Drills with an automatic work cycle operate in such a way that the auger spindle returns to its initial position at rapid traverse upon reaching a certain depth. After the chips have been emptied, it returns to the bottom of the hole at rapid traverse and continues drilling [29,30].

Due to difficult working conditions, the cutting ratios are reduced compared to those in short-hole drilling. Taking these values as a basis, for a hole depth of L = 3 to 15D, the cutting speed is reduced to 0.9 or further down, to 0.4, while the feed rates are reduced to 0.3–0.6 times of the basic values.

Carbide augers work similarly to HSS. They are manufactured up to a length of 30xD and they always feature internal cooling, thanks to which they do not require an intermittent work cycle. A precondition is a pilot hole, which must meet the hole accuracy requirements, usually in IT8. The depth of the pilot hole is given by at least 2D. Compared to HSS drills, TK drills can be used for drilling at higher speeds. The feed rate for TK drills can be set min. 5 times higher and set spindle speed min. 3 times higher compared to HSS, which depends on the manufacturer's recommendations. The drills can also be cooled with oil mist (MQL), which is capable of ensuring good conditions for the stable cutting process [31].

The gun-drill tool is a single-wedge tool with internal flushing and external chip removal. It consists of three basic parts—the drill head, the drill tube, and the clamping shank. The tool has an outer straight V-shaped path and an inner conduit for the coolant and lubricant. The liquid flows through the tool axis, bypasses the cutting edge, carries away the emerging chips and washes them out of the hole through the external path. The drill head is typically carved from carbide, but in cases involving larger diameters, it can be made of steel with carbide elements (cutting edge and guide surfaces) bonded to them. The head has guide surfaces ground along the circumference, which are in contact with the drilled material during drilling. For larger diameters, replaceable elements (plates and guide surfaces) are widely used in current work. The forces acting on the tool during drilling strongly press the guide surfaces of the head against the wall of the drilled hole, so that the surface is slightly deformed, resulting in the high machining quality typical of all deep-drilling tools.

The aim of this research was to obtain the optimal values of the two main parameters influencing the tool life of deep-drilling technology, namely the feed rate and the tool rotation frequency. The first series of tests was performed to obtain the optimal spindle speed at a constant feed rate of $0.04 \text{ mm} \cdot \text{min}^{-1}$. The second series of tests was focused on finding the optimal value of the feed rate while maintaining a constant spindle speed of 2600 min^{-1} .

2. Methodology

For the purposes of the experiment, the TBT gun drill $10.5 \times 380 \text{ K15}$ shown in Figure 1 was used. It is a gun drill with a brazed carbide head, 10.5 mm in diameter and with a total length of 380 mm. The effective gun-drill length corresponds to the length of the hole on the test part, which is 280 mm. The carbide head type guide surfaces are of G design, complemented with a longitudinal groove on the main cutting edge, which helps to create chips. The carbide head is coated with TiAlN coating, which increases the auger's life. The smooth clamping shank is 20 mm in diameter and is designed for clamping in a hydraulic clamp. The selected gun-drill tool is clamped in a Schunk hydro clamp of TENDO ES type. Clamping is carried out directly in the connection cone of the clamp.



Figure 1. Gun-drill tool used in the experiment.

To present and analyze the input conditions, an Ishikawa diagram was constructed, as shown in Figure 2. The main axis of the diagram represents the main problem and the individual influences that affect the tool life during the deep-drilling process. Based on the aforementioned factors influencing tool life, the individual effects in this diagram were verified under real engineering operation. The main factors affecting tool life in



deep-drilling are the tool, the workpiece material, the tool geometry, the machine, the clamping and the coolant.

Figure 2. Ishikawa diagram.

Tests of the gun-drill tool life were performed in real production in a plant. The series of tests verified the technological and technical recommendations of the gun-drill manufacturer for a stable cutting process on a given part using deep-drilling technology.

2.1. Experimental Machinery

Testing was carried out under the automotive production conditions at the production line. The machine used for testing in the real production process was a thickness planer and boring center with a portal loader from CZ-Tech Celakovice of the ZAH720 type. Two heads were used on the ZAH720 machine, as shown in Figure 3; the right head was designed for VDI clamping and the other for Bolt-one. The tool holders used were from ALGRA. Electromechanical turrets of the TAN series are designed for installation on CNC lathes. They are used for clamping dovetail toolholders according to VDI 3425 for use in the automatic positioning of toolholders consisting of a solid base and a rotating head made of hardened ground steel. The cooling of the machining center tools is ensured by a system of devices, which consists of a low-pressure pump, a high-pressure pump, a filter, and a small-metal-particle magnetic filter. The coolant pump provides the pressure necessary to cool, lubricate and clean all chips off the tools. A wall-plus pump was used for these needs, supplying a coolant pressure of 18 bar at a flow rate of 10.5 L/min. Its power was sufficient for standard cooling of the turning tools and of the pilot auger. A Grundfos MTS high-pressure pump was used to cool the gun-drill tool.



Figure 3. ZAH720 thickness planer workspace.

2.2. Parameters of the Test-Part Selection

The transmission input shaft shown in Figure 4 was selected as a test part, with a lubrication hole 10.5 mm in diameter and 280 mm long. The deep-drilling tests were performed on the shaft of a six-speed DSG gearbox. Deep-hole drilling consists of drilling a 240 millimeter-long hole 10.5 mm in diameter. This was a lubrication hole, the diameter of which was also chosen with regard to the requirement of relieving the shaft. A vertical lubrication hole with a diameter of 3 mm, located at the end of the shaft, must be smoothened after drilling due to formation of sharp edges up to 10.5 mm in diameter. For this reason, the drilling method was adapted to drill a diameter of 10.5 mm to full extent before drilling a perpendicular hole with a diameter of 3 mm and again applying a drilling cycle to smoothen the D3 hole with the gun-drill. At this point, increased wear on the side edge of the cannon auger occurred, as this was an intermittent cut.



Figure 4. Transmission shaft of the part tested in the experiment.

The material used for the part selected to test the deep-drilling process complied with the company standard. With its composition and properties, the material resembled the 16MnCr5 and EN 10184. The chemical composition, according to the company standard, is presented in Table 1.

Table 1. Chemical composition of the drilled part given in %.

С	Si	Mn	Р	S	Cr	Al	Ν
0.14-0.22	≤ 0.12	1.00-1.50	≤ 0.035	0.02-0.035	0.80-1.30	0.015-0.040	≤ 0.015

The STS 14220 material is a high-grade structural steel for cementation, which is well thermoformable. It is well machinable and weldable after soft and cold annealing. This steel is used for the production of machine parts with the possibility of refining up to diameters of 35 mm for cementation with high core strength, with the use for the production of shafts, gears, camshafts or gear couplings. This semi-finished product is supplied as a form of die forging.

2.3. Pilot-Hole Drilling

When using a gun-drill tool on conventional machines, it is necessary to drill a pilot hole as a guide, the length of which must be between 1 and 1.5 times the gun-drill diameter. For correct guidance, the hole must be within a D8 tolerance. The pilot hole is usually drilled at a greater depth, where the carbide auger has a significantly higher feed rate and, thus, reduces machining time. For a specific part, the gun drill is designed with respect to the given hole profile and the design of the auger is more graded. The pilot gun-drill tool Carbide 10.5/14.5, shown in Figure 5, is made of K40UF carbide from Konrad Friedrichs.



Figure 5. Pilot gun-drill tool Carbide 10.5/14.5 used in the experiment.

3. Statistical Evaluation and Optimization

3.1. Dependence of the Number of Drilled Holes up to the Moment of Tool Damage When Changing the Speed-Constant Feed Rate

The manufacturer-recommended values were used to test the technological parameters of a given part of the transmission shaft, with the cutting speed ranging from 70 to $100 \text{ m} \cdot \text{min}^{-1}$ for the given workpiece material. Figure 6 shows a plotted representation of the course of the number of drilled holes up to the moment the tool was damaged at different speeds and a constant feed rate of 0.04 mm·min⁻¹.



Spindle speed [min *]

Figure 6. Plotted number of holes drilled up to the moment the tool was damaged when the speed changed and the feed rate remained constant.

The cutting speed of 70–100 m·min⁻¹ represents the spindle speed, which ranged from 2100 to 3000 min⁻¹. The selected spindle test range speed was 2400–2900 min⁻¹. The tests were performed on a randomly selected gun-drill tool, while new augers and those that had been re-ground several times were excluded. Figure 7 shows the dependence of the number of drilled holes up to the moment of the tool damage and the length of the drilling time on the tool spindle speed.



Figure 7. Dependence of the number of holes drilled up to the moment of tool damage on the cutting speed.

The resulting values of the number of holes drilled up to the moment the tool was damaged and, thus, the life of the gun-drill tool under different speeds, show a significantly decreasing service life at speeds above 2700 min⁻¹, as shown in Figure 7. The speed of 2700 min^{-1} corresponded to the cutting speed of $90 \text{ m} \cdot \text{min}^{-1}$. This value seems to be the most suitable both in terms of the tool life and in terms of the operation time; at the cutting speed of $90 \text{ m} \cdot \text{min}^{-1}$, the length of the drilling operation was 82 s.

3.2. Dependence of the Number of Drilled Holes up to Moment of Tool Damage When Changing the Feed Rate-Constant Speed

For testing the technological parameters on the selected test part, the speed was also based on the values recommended by the manufacturer, while the feed rate for the given workpiece material was given in the range of $0.03-0.06 \text{ mm}\cdot\text{min}^{-1}$. This range was significantly lower than the range already used at the thickness planer. Feed rate values of $0.065 \text{ mm}\cdot\text{min}^{-1}$ were used as a standard. A test interface of $0.05-0.08 \text{ mm}\cdot\text{min}^{-1}$ was chosen for the testing. A constant value of 2600 min^{-1} was chosen for the speed.

Figures 8 and 9 show plotted dependencies representing the number of holes drilled up to the moment the tool was damaged due to a change in the feed rate, as well as both the dependence of the number of holes drilled up to the moment of tool damage and the duration of the drilling operation on the change in feed rate.

The resulting values of the number of holes drilled up to the moment of damage to the gun-drill tool at different feed rates showed a significantly decreasing tool life at feed rates above 0.07 mm·min⁻¹. The values of the number of holes drilled up to the moment the tool was damaged as a function of the feed are shown in Figure 9. In the tests, the feed rate of 0.55 mm·min⁻¹ resulted in the longest gun-drill tool life, but the drilling time was 98.8 s, which is economically inefficient. In light of the economic efficiency of the deep-drilling operation, a value of 0.07 mm·min⁻¹ appears to be the most suitable feed-rate value, with the operation lasting 82 s in this case.



Figure 8. Plotted number of holes drilled until the tool was damaged, when the feed rate changed and the speed remained constant.



Figure 9. Dependence of the number of drilled holes up to the moment of tool damage and the operation's duration on the change in feed rate.

The reduction in the number of holes drilled by increasing the feed was due to poorer chip removal from the tool and the consequent increase in tool temperature. The heat generation raised the temperature above the melting point of the alloying elements (e.g., Co and W) and the consequent mechanical properties, hardness and chemical wear resistance of the drill bit decreased dramatically due to the peeling of the alloying elements. Heat shock generated vertical or oblique cracks on the blade. These cracks widened and merged and, subsequently, broke the blade.

3.3. Statistical Evaluation and Optimization of the Dependence of the Auger Life at a Constant Feed Rate and Different Spindle Speeds

Figures 10 and 11 show a comparison between the plotted number of holes drilled up to the moment of tool damage and the speed used in the experiment. The results of the comparisons subject to the specified parameters are subsequently presented in Tables 2 and 3, which compare the obtained measurement results based on the number of drilled holes up to the moment of tool damage in terms of the change in experimental speed.



Figure 10. Plotted comparison of the number of drilled holes up to the moment of tool damage and the speed used in the experiment.



Figure 11. Dependence of the number of holes drilled up to the moment of tool damage and drilling time on speed used in the experiment.

Table 2. Results of a comparison of the number of holes drilled up to the moment of tool damage in terms of speed change.

	Kruskal–Wallis ANOVA by Ranks. Number of Drilled Holes (Analysis). Independent (Grouping) Variable: Spindle Speed. Kruskal–Wallis Test: H (5, N = 60) = 21.13129, p = 0.0008						
	Code	Valid N	Sum of Ranks	Mean Rank			
$2400 \mathrm{min}^{-1}$	1	10	376.5000	37.65000			
$2500 { m min}^{-1}$	2	10	410.5000	41.05000			
$2600 { m min}^{-1}$	3	10	360.0000	36.00000			
$2700~\mathrm{min}^{-1}$	4	10	354.5000	35.45000			
$2800 { m min}^{-1}$	5	10	203.5000	20.35000			
$2900 \mathrm{~min^{-1}}$	6	10	125.0000	12.50000			

	Multiple Comparisons of p Values (Two-Tailed). Number of Drilled Holes (Analysis). Independent (Grouping) Variable: Spindle Speed. Kruskal–Wallis Test: H (5, N = 60) = 21.13129, p = 0.0008							
	2400 min ⁻¹ R: 37.650	2500 min ⁻¹ R: 41.050	2600 min ⁻¹ R: 36.000	2700 min ⁻¹ R: 35.450	2800 min ⁻¹ R: 20.350	2900 min ⁻¹ R: 12.500		
$2400 \mathrm{min}^{-1}$		1.000000	1.000000	1.000000	0.401362	0.019220		
$2500 { m min}^{-1}$	1.000000		1.000000	1.000000	0.120608	0.003851		
$2600 { m min}^{-1}$	1.000000	1.000000		1.000000	0.676409	0.039334		
$2700 { m min}^{-1}$	1.000000	1.000000	1.000000		0.797884	0.049479		
$2800 \min^{-1}$	0.401362	0.120608	0.676409	0.797884		1.000000		
$2900 \mathrm{min}^{-1}$	0.019220	0.003851	0.039334	0.049479	1.000000			

Table 3. Results of multiple comparisons of *p* values of the number of drilled holes up to the moment of tool damage in terms of speed.

The value of the achieved level of significance of the Kruskal–Wallis variance analysis (p = 0.0008) makes it possible to state that there was a significant relationship between the speed and the number of drilled holes up to the moment of tool damage, with a significance level of 5%. In other words, speed has a statistically significant effect on tool life. A closer analysis of the multiple comparisons of the p values shows that there was a statistically significant difference between the number of holes drilled up to the moment of tool damage at: 2900 min⁻¹ and 2400 min⁻¹; 2900 min⁻¹ and 2500 min⁻¹; 2900 min⁻¹ and 2600 min⁻¹; and 2900 min⁻¹ and 2700 min⁻¹, respectively. To analyze the dependence of the number of drilled holes up to the moment of tool damage on speed, four different models were considered (Table 4), indicating their basic characteristics.

Table 4. Comparison table of the model for analyzing the dependence of the number of holes drilled up to the moment of tool damage and speed.

Model	AICc	BIC	SSE	RMSE	R-Square
Linear	 58.579379	45.954658	304.02571	8.7181666	0.8377591
Exponential 2P	 59.133867	46.509145	333.46133	9.1304618	0.822051
Quadratic	 75.245678	34.412715	32.944643	3.3138418	0.9824194
Logistic 3P	 78.806526	37.973564	59.638621	4.4586478	0.9681743

A plotted representation of the individual models examining the dependence of the number of holes drilled up to the moment of tool damage on speed, according to Table 4, is shown in Figure 12.

The quadratic model was chosen for the resulting analysis, which is shown in Figure 13, since the highest value of the adjusted determination index demonstrated the ability of the model to describe the data. The resulting general expression of the model is as follows:

$$a + b * v + c * v^2 \tag{1}$$

where *a* is the absolute term, *v* is the speed, *b* is the linear term and c is the quadratic term.

$$-1324.217 + 1.3334511v - 0.000269v^2 \tag{2}$$

The numerical values of the individual terms are given in Table 5. A plotted representation of the quadratic model in the ranges of the speeds used is shown in Figure 14.

In general, we obtain stationary points if we set the first derivation of the dependence function to zero:

$$dv \left(-1324.217 + 1.3334511v - 0.000269v^2 \right) = 0$$
(3)

$$1.3334511 - 0.000538v = 0 \tag{4}$$



Figure 12. Plotted representation of individual models examining the dependence of the number of the holes drilled up to the moment of tool damage on speed change.



Figure 13. Plotted selected quadratic model of the dependence of the number of holes drilled up to the moment of tool damage on speed change.

Table 5. Basic parameters of the quadratic model of dependence of the number of holes drilled up to the moment of tool damage on speed change.

Parameter	Estimate	Std. Error	Lower 95%	Upper 95%
Intercept	-1324.217	379.86959	-2068.748	-579.6862
Slope	1.3334511	0.2875571	0.7698495	1.8970527
Quadratic	-0.000269	-0.000542	-0.000376	-0.000163



Figure 14. The course of dependence of the number of holes drilled up to the moment of tool damage in the range of the speeds used.

A plotted representation of the first derivation of the investigated function is shown in Figure 15, presenting the course of the first derivation of the number of drilled holes up to the moment of tool damage and speed change.



Figure 15. The course of the first derivation of dependence of the number of drilled holes up to the moment of tool damage and speed change.

By solving the following equation (Solve (1.3334511 - 0.000538v = 0, v)) we arrive at the stationary point:

$$\{\{v \to 2478.533643122677\}\}$$
(5)

By inserting the value of the stationary point into the original dependence of the number of drilled holes up to the moment of tool damage depending on the change in speed, we obtain the value of the local function maximum sought (due to the fact that the second derivation of the function <0), that is to say, the number of drilled holes up to the moment of tool damage at a speed of 2478.53 min⁻¹:

$$\{328.2847064044704, \{v \to 2478.5336431226765\}\}$$
(6)

3.4. Statistical Evaluation and Optimization of the Dependence of the Number of Holes Drilled up to the Moment of Tool Damage When Changing the Feed Rate at a Constant Speed

Figures 16 and 17 show a graph illustrating a comparison of the number of holes drilled and the drilling time up to the moment of tool damage under the different feed rates

used in the experiment. The results of the comparisons subject to the specified parameters are subsequently presented in Tables 6 and 7, which compare the measurement results obtained based on the number of holes drilled up to the moment of tool damage in terms of the changed experimental feed rate.



Figure 16. Plotted comparison of the number of holes drilled and the feed rates used in the experiment.



Figure 17. Dependence of the number of drilled holes and drilling time on feed rates used in the experiment.

The value of the achieved level of significance of the Kruskal–Wallis variance analysis (p = 0.0008) makes it possible to state that there was a significant relationship between the speed and the number of holes drilled up to the moment of tool damage, with a significance level of 5%. In other words, feed rate has a statistically significant effect on tool life. A closer analysis of the multiple comparisons of p values shows that there was a statistically significant difference between the number of holes drilled at of the following feed rates: $0.075 \text{ mm} \cdot \text{min}^{-1}$ and $0.05 \text{ mm} \cdot \text{min}^{-1}$; $0.075 \text{ mm} \cdot \text{min}^{-1}$ and $0.055 \text{ mm} \cdot \text{min}^{-1}$; and $0.075 \text{ mm} \cdot \text{min}^{-1}$ and $0.08 \text{ mm} \cdot \text{min}^{-1}$ and $0.05 \text{ mm} \cdot \text{min}^{-1}$ and $0.08 \text{ mm} \cdot \text$

 $0.055 \text{ mm} \cdot \text{min}^{-1}$; $0.08 \text{ mm} \cdot \text{min}^{-1}$ and $0.06 \text{ mm} \cdot \text{min}^{-1}$; $0.08 \text{ mm} \cdot \text{min}^{-1}$ and $0.065 \text{ mm} \cdot \text{min}^{-1}$; and $0.08 \text{ mm} \cdot \text{min}^{-1}$ and $0.07 \text{ mm} \cdot \text{min}^{-1}$, respectively.

Table 6. Results of the comparison of the number of holes drilled up to the moment of tool damage in terms of feed rate.

	Kruskal–Wallis ANOVA by Ranks. Number of Drilled Holes (Analysis). Independent (Grouping) Variable: Feed Rate. Kruskal–Wallis Test: H (6, N = 70) = 44.78770 p = 0.0000							
	Code	Valid N	Sum of Ranks	Mean Rank				
$0.05 ({\rm mm} \cdot {\rm min}^{-1})$	1	10	496.0000	49.6000				
$0.055 ({\rm mm} \cdot {\rm min}^{-1})$	2	10	499.5000	49.9500				
$0.06 \;(mm \cdot min^{-1})$	3	10	468.5000	46.8500				
$0.065 ({\rm mm} \cdot {\rm min}^{-1})$	4	10	400.0000	40.0000				
$0.07 (\text{mm} \cdot \text{min}^{-1})$	5	10	406.0000	40.6000				
$0.075 (\text{mm} \cdot \text{min}^{-1})$	6	10	155.0000	15.5000				
$0.08 \;({\rm mm} \; {\rm min}^{-1})$	7	10	60.0000	6.0000				

Table 7. Results of multiple comparison of *p* values of the number of holes drilled up to the moment of tool damage in terms of change in the feed rate.

	Multiple Comparisons of p Values (Two-Tailed). Number of Drilled Holes (Analysis). Independent (Grouping) Variable: Cut Feed Kruskal–Wallis Test: H (6, N = 70) = 44.78770 p = 0.0000							
	0.05 mm∙min ⁻¹ R: 49.60	0.055 mm∙min ⁻¹ R: 49.950	0.06 mm∙min ⁻¹ R: 46.850	0.065 mm∙min ⁻¹ R: 40.000	0.07 mm∙min ⁻¹ R: 40.600	0.075 mm∙min ⁻¹ R: 15.500	0.08 mm∙min ⁻¹ R: 6.0000	
$0.05 ({\rm mm} \cdot {\rm min}^{-1})$		1.000000	1.000000	1.000000	1.000000	0.003762	0.000035	
$0.055 ({\rm mm} \cdot {\rm min}^{-1})$	1.000000		1.000000	1.000000	1.000000	0.003226	0.000029	
$0.06 ({\rm mm} \cdot {\rm min}^{-1})$	1.000000	1.000000		1.000000	1.000000	0.012011	0.000151	
$0.065 (mm \cdot min^{-1})$	1.000000	1.000000	1.000000		1.000000	0.149184	0.003930	
$0.07 (\text{mm} \cdot \text{min}^{-1})$	1.000000	1.000000	1.000000	1.000000		0.122183	0.003018	
$0.075 (\text{mm} \cdot \text{min}^{-1})$	0.003762	0.003226	0.012011	0.149184	0.122183		1.000000	
$0.08 ({\rm mm} \cdot {\rm min}^{-1})$	0.000035	0.000029	0.000151	0.003930	0.003018	1.000000		

To analyze the dependence of the number of drilled holes on the feed rate, five different models were considered, as presented in Table 8, which provides their basic characteristics.

Table 8. Comparison table of the model for analyzing the number of holes drilled up to the moment of tool damage and feed rate.

Model	AICc	BIC	SSE	RMSE	R-Square
Quadratic	 637.77225	646.15085	32,812.781	22.130138	0.7725013
Cubic	 637.74334	648.04832	31,729.031	21.92585	0.7700151
Quartic	 639.73713	651.89476	31,547.316	22.030509	0.781275
Linear	 672.86817	679.25002	55,944.286	28.682923	0.6121251
Exponential 2P	 679.18499	685.56684	61,227.507	30.006741	0.5754953

A plotted representation of the individual models according to Table 8 is shown in Figure 18.

The quadratic model was chosen for the resulting analysis, since the highest value of the adjusted determination index demonstrated the ability of the model to describe the data. The resulting general expression of the model is as follows:

$$a + b * f + c * f^2$$
 (7)

where *a* is the absolute term, *f* is the feed rate, *b* is the linear term and *c* is the quadratic term.

The numerical values of the individual terms are given in Table 9, which lists the basic parameters of the quadratic model of the dependence of the number of holes drilled up to the moment of tool damage on the feed rate.



Figure 18. Plotted representation of individual models for examining the dependence of the number of holes drilled up to the moment of tool damage on the feed rate.

Table 9. Basic parameters of the quadratic model of the dependence of the number of drilled holes up to the moment of tool damage on the feed rate.

Parameter	Estimate	Std Error	Lower 95%	Upper 95%
Intercept	-376.4143	127.18298	-625.6884	-127.1402
Slope	23,736.19	3979.3245	15,936.858	31,535.523
Quadratic	-209,904.8	30,542.492	-269,766.9	-150,042.6

A plotted representation of the quadratic model in the range of the feed rates used is shown in Figure 19.



Figure 19. Course of dependence of the number of holes drilled up to the moment of tool damage in the range of the feed rates used.

In general, we obtain stationary points if we set the first derivation of the dependence function to zero:

$$df(-376.414 + 23736.19f - 209904.8f^2) = 0$$
(8)

$$23736.19 - 419809.6f = 0 \tag{9}$$

A plotted representation of the first derivation of the investigated function is shown in Figure 20.



Feed rate [mm·min⁻¹]

Figure 20. The course of the first derivation of the dependence of the number of holes drilled up to the moment of tool damage and the feed rate.

By solving the following Equation (10), we arrive at the stationary point:

$$\{\{f \to 0.056540369729515476\}\}$$
(10)

By inserting the value of the stationary point into the original dependence of the number of holes drilled up to the moment of tool damage on the feed rate, the value of the local function maximum sought is obtained (due to the fact that the second derivation of the function <0), that is to say, the number of the holes drilled up to the moment of tool damage at the feed rate of 0.0565 mm·min⁻¹ is:

$$\{294.6121792850139, \{f \to 0.056540369729515476\}\}$$
(11)

4. Recommended Conditions for Drilling with Gun-Drill Tool on a CNC Machine Using a Pilot-Hole Guide

Currently, there is a great demand in the engineering industry for a radical reduction in the preparation time and rationalization of the development process for the rapid application of new methods and techniques. Global competition and increasing demands in the field of product life require not only the modernization of production capacities, but also new, innovative methods ensuring the smooth running of technological means. One such method is the deep-drilling process, which is used when it is necessary to create holes with depths of up to ten times their diameters. Based on long-term tests and the statistical processing of technological and physical parameters, it is possible to establish the following recommendations for deep-drilling technology.

Gun drill of the L10.5 \times 380 DIN 1835A 20 \times 50 CHIP GROOVE type. Procedure for inserting a gun-drill tool:

• Stop the auger before the hole-rapid traverse.

- Slowly insert the auger at a counter-clockwise speed (or without speed, at a maximum of 50 min⁻¹) with cooling.
- Once the auger has been inserted into the pilot hole, switch on full speed and cooling.
- Start the drilling process.
- When the full depth of the hole is reached, switch off the feed rate, stop the spindle speed with a delay and switch off the high-pressure cooling with a small delay.
- Slide the auger out of the hole at rapid traverse.

Testing conditions and recommendations for maximizing service life in terms of the speed and feed-rate settings:

- A feed rate of 0.07 mm·min⁻¹.During the testing of the stable service life at the given feed rate, in the event of a change in input conditions (deviation in the workpiece material), it is recommended to reduce the feed-rate value to 0.06 mm·min⁻¹.
- A speed of 2700 min⁻¹. During the testing of the stable service life at the given speed, in the event of a change in input conditions (deviation in the workpiece material), it is recommended to reduce the speed value to 2600 min⁻¹.

Conditions specified by the manufacturer and verified by testing:

- Coolant pressure >30 bar; the manufacturer recommends that it be above 35 bar.
- Emulsion percentage >9% (the manufacturer recommends over 12%).
- The pilot hole must be 1–1.5xD long.
- The pilot-hole tolerance must be in H8.
- The pilot-hole apex angle should be $>140^{\circ}$.
- The cutting speed varies, depending on the workpiece material used (the tested cutting speed, which showed the highest service life values, was 90 m·min⁻¹).
- The feed rate varies, depending on the workpiece material used (the material tested by us showed the highest tool life at a feed rate of 0.07 mm·min⁻¹).
- The pilot-hole drilling deviation should be <0.02 mm in all axes.
- Gun-drill tool deviation <0.02 mm in all axes.
- The minimum length of the drilling part of the gun-drill tool should be 1.5xD.
- Fixed clamping in the hydraulic clamp.

In order to successfully maximize the service life of gun-drill tools, no limit deviations from the prescribed properties and composition of the material being machined may occur. The service life of the augers is also affected by the functional condition of the machine tools–spindle backlash, machine vibration, guide backlash and leaks in the fluid supply conduit, as well as the consequent loss of pressure.

5. Conclusions

Through measurement, the general recommendations of the manufacturer were verified and proven to be informative in real operation conditions. Based on extensive tests and the resulting statistically processed data, the parameters were correlated with the subsequent methodology for deep-drilling technology. Various technological parameters were tested in a series of tests performed during real engineering production, which were subjected to statistical evaluation. As part of the statistical analysis of the dependences of the monitored input factors, such as the feed rate and speed, a nonlinear regression analysis was performed in order to identify the most suitable optimization function. The quadratic function was chosen as the most suitable function based on the criterion of the best possible description of the experimentally obtained results, while the adjusted determination index was chosen as the criterion for the dependence of the tool life on the feed rate. Based on this dependence, it reached the value of 77.25%. Thus, it can be stated that the chosen model can explain 77.25% of the variability in the measured values. The optimization itself was based on the quadratic optimization function, reaching its local maximum at a feed rate of 0.0565 mm \cdot min⁻¹, with the predicted value of the number of holes drilled up to the moment of tool damage being 294.61. For the analysis of the dependence of the tool life on the speed, the quadratic function was chosen again as a nonlinear regression analysis based

on the criterion of the adjusted determination index as the ability of the model to explain the variability in the measured data. Based on this dependence, the value of the adjusted determination index was 98.24%; therefore, the model could not explain the remaining 1.76% of the measured data. Based on the analysis, the optimization function reached its maximum at a speed of 2478.334 min⁻¹, with the predicted value of the number of holes drilled up to the moment of tool damage being 328.285.

Further research will examine other parameters, such as temperature and pressure of the coolant, with a comparison of the selection of carbide tools for making holes using deep-drilling technology.

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