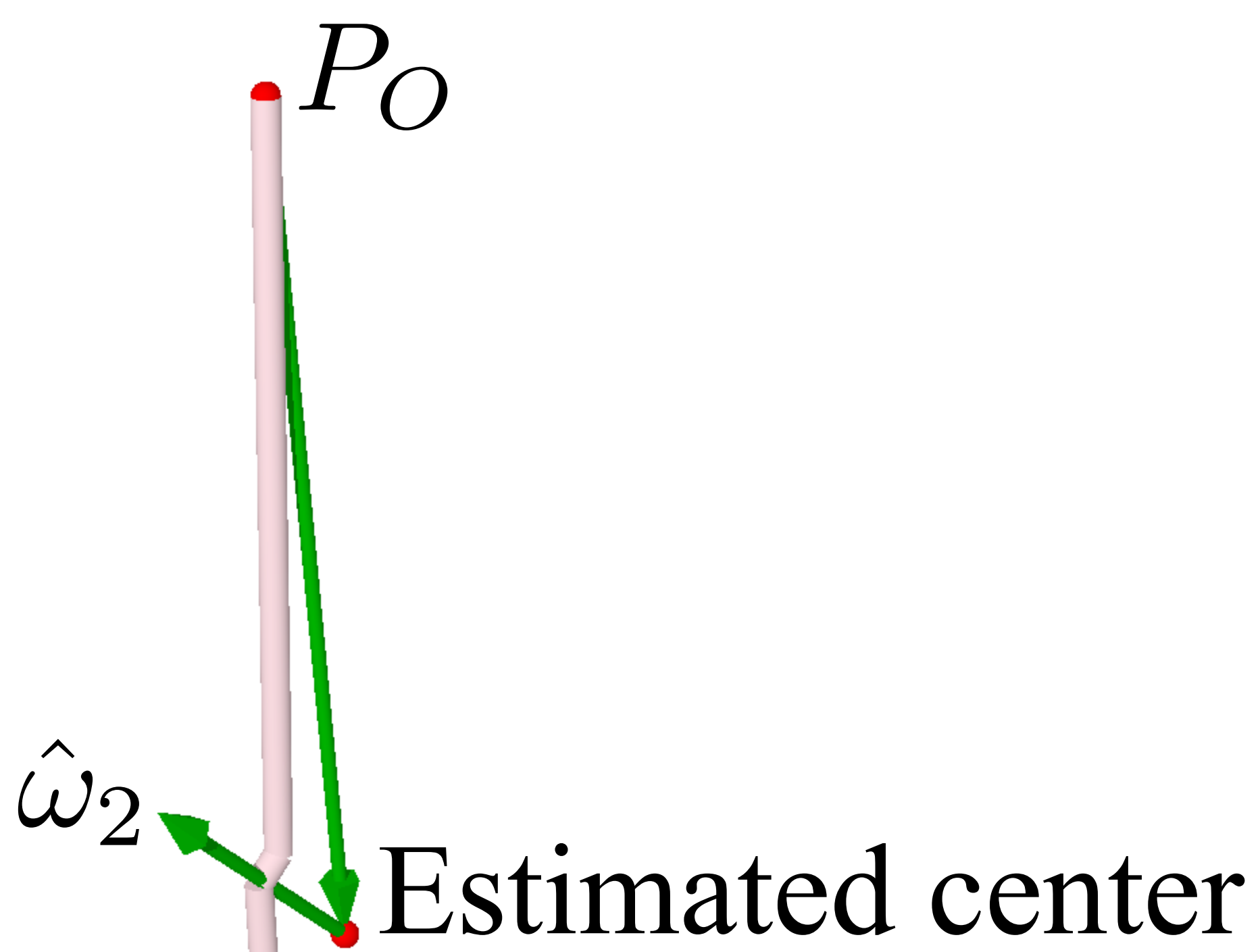


Rotated trajectory

Circle center•



Trajectory

PM_0

C_0