



Article Metric Relations in the Fuzzy Right Triangle

Ronald Manríquez D

Laboratorio de Investigación Lab[e]saM, Departamento de Matemática, Física y Computación, Universidad de Playa Ancha, Valparaíso 2340000, Chile; ronald.manriquez@upla.cl

Abstract: The study of fuzzy geometry and its different components has grown in recent years, establishing the formal foundations for its development. This paper is devoted to addressing some metric relations in the fuzzy right triangle; in particular, a version of the Pythagorean theorem and geometric mean theorem are provided in analytical fuzzy geometry. The main results show, under certain conditions of the fuzzy vertices, a subset relation between the fuzzy distances associated with the fuzzy right triangle, which is very similar to the classical statements of the Pythagorean theorem and the geometric mean in Euclidean geometry.

Keywords: fuzzy set; fuzzy geometry; metric relations; Pythagorean theorem; geometric mean theorem

MSC: 94D05; 03E72

1. Introduction

The aim of this paper is to study some metric relations in a fuzzy right triangle following the ideas from [1,2]. Particularly, we provide a version of the altitude and Pythagorean theorems in analytical fuzzy plane geometry.

Set theory was born, as a separate mathematical discipline, with the work developed by Georg Cantor in 1874 [3]. The elegance of this theory led current mathematics to consider it an essential pillar of the foundations of this science. The idea of using sets to formalize mathematics is to define all mathematical objects as sets: numbers, functions, algebras, geometric figures, etc. However, the strict dichotomy of belonging or not belonging to a set can make certain tasks or decisions complicated. In particular, determining what belongs or does not belong to a set that uses unclear, fuzzy, or vague terms, such as determining the objects in the set of beautiful colors, can be difficult. Sometimes, drastic decisions are made based on these classifications, which are not always easy to make.

In the mid-1960s, Lotfi A. Zadeh introduced the notions of fuzzy sets in his famous paper, entitled "Fuzzy sets" [4]. His aim was to represent, in a mathematical way, the uncertainty generated by the vague definition of some sets, using values between 0 and 1 to represent how much an object belongs to a set (with 1 meaning that it certainly belongs, 0 meaning that it certainly does not belong, and intermediate values meaning that it partially belongs). Formally, a fuzzy set \tilde{A} consists of ordered pairs such that

$$\widetilde{A} = \{(x, \mu_{\widetilde{A}}(x)) : x \in X, \ \mu_{\widetilde{A}}(x) \in [0, 1]\},\$$

where $\mu_{\widetilde{A}}$ is the membership function of the set and $X \subseteq \mathbb{R}^n$ (see [4,5]).

Fuzzy set theory has advanced in various ways and across many disciplines. Applications of this theory are found, for example, in artificial intelligence, computer science, decision theory, control theory, logic, management science, and robotics. See, for instance [6–11].

Ideas about fuzzy geometric notions have been proposed by many researchers, providing notions of point, line, angle, plane, area, perimeter, and shapes; see, for example, the



Citation: Manríquez, R. Metric Relations in the Fuzzy Right Triangle. *Mathematics* **2023**, *11*, 4056. https:// doi.org/10.3390/math11194056

Academic Editors: Vishal Gupta and Pooja Dhawan

Received: 16 August 2023 Revised: 8 September 2023 Accepted: 11 September 2023 Published: 25 September 2023



Copyright: © 2023 by the author. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). references [12–19]. However, only Buckley and Eslami, in the papers [1,2], gave some ideas on the construction and representation of basic fuzzy geometric entities in a mathematical framework. Subsequently, Ghosh and Chakraborty, based on the works [1,2], provided different contributions to analytical fuzzy plane geometry (see, for instance, [20,21]). Moreover, Ghosh et al. also contributed to analytical fuzzy space geometry (see [22,23]), as did Qiu and Zhang in [24].

The aim of this paper is to study some metric relations in a fuzzy right triangle following the ideas from [1,2]. Particularly, we use the definitions of fuzzy distance, fuzzy point, and fuzzy triangle provided in the paper [1]. Since the fuzzy distance between two fuzzy points is a fuzzy number (see Section 2.2), the metric relations that are stated are naturally inclusion relations. Specifically, we provide a version of the altitude and Pythagorean theorems considering fuzzy points that define cones with circular bases in fuzzy geometry. It is worth noting that the sense of the inclusion relation changes, as it depends on the radii associated with the circular bases (see Theorems 1 and 2), or there may not even be a relation of inclusion (see Example 3). In the case where all radii are congruent, inclusion is only possible in each statement; more accurately, we state that $\widetilde{C^2} \subseteq \widetilde{A^2} + \widetilde{B^2}$, and $\widetilde{H^2} \subseteq \widetilde{P} \cdot \widetilde{Q}$, where $\widetilde{A}, \widetilde{B}, \widetilde{C}, \widetilde{P}, \widetilde{H}$, and \widetilde{Q} are the fuzzy distances associated to a fuzzy right triangle (see Corollaries 1 and 2, respectively).

To achieve the aforementioned objective, we present a general characterization of the α -cut set of fuzzy distance denoted by \widetilde{D} between two fuzzy points. Furthermore, we show that if two fuzzy points, \widetilde{P}_1 and \widetilde{P}_2 , define a cone with circular bases of radii r_1 and r_2 , respectively, then $\widetilde{D}(\widetilde{P}_1, \widetilde{P}_2)(\alpha) = [a - (r_1(\alpha) + r_2(\alpha)), a + (r_1(\alpha) + r_2(\alpha))]$, where *a* is the Euclidean distance between the points in \mathbb{R}^2 that have membership function equal to 1 (for more details, see Section 3). We utilize some definitions and results of convex sets, since the α -cut set of a fuzzy point is a compact and convex subset of \mathbb{R}^2 (Definition 7).

The paper is organized as follows: Section 2.1 contains generalities about fuzzy sets, fuzzy numbers, and the α -cut set. Section 2.2 recalls the basic definitions of fuzzy geometry, which are fuzzy point, fuzzy line segment, fuzzy distance, and fuzzy triangle.

Section 3 provides, in a general way, the α -cut set of fuzzy distance *D*. In Section 4, we deal with two metric relations in the fuzzy right triangle. Specifically, a version of the geometric mean and Pythagorean theorems is provided in fuzzy geometry. To state the geometric mean theorem, it is necessary to introduce the altitude definition of a fuzzy triangle. Section 5 is devoted to illustrating some examples from Section 4. Finally, in Section 6, some comments and conclusions are presented.

2. Preliminaries

In this section, some definitions and results that come from [1,2,4,5] are reviewed.

2.1. Fuzzy Set and Fuzzy Number

The following are definitions of fuzzy sets and fuzzy numbers.

Definition 1 (Fuzzy set [4]). Let X be a classical set. Then, the set of order pairs

$$\widehat{A} = \{(x, \mu_{\widetilde{A}}(x)) : x \in X, \ \mu_{\widetilde{A}}(x) \in [0, 1]\}$$

is called a fuzzy set on X. *The evaluation function* $\mu_{\widetilde{A}}(x)$ *is called membership function or grade of membership of* x *in* \widetilde{A} .

Definition 2 (α -Cut set [25]). For a fuzzy set A, its α -cut is denoted by $A(\alpha)$ and is defined by

$$\widetilde{A}(\alpha) = \begin{cases} \{x \in X : \ \mu_{\widetilde{A}}(x) \ge \alpha\} & \text{if } 0 < \alpha \le 1\\ closure\{x \in X : \ \mu_{\widetilde{A}}(x) > \alpha\} & \text{if } \alpha = 0 \end{cases}$$

Notice that the α -cut set is not a fuzzy set.

To represent the construction of the membership function of a fuzzy set \widetilde{A} , we adopt the notation $\bigvee \{ x : x \in \widetilde{A}(0) \}$, which means $\mu_{\widetilde{A}}(x) = \sup \{ \alpha : x \in \widetilde{A}(\alpha) \}$.

Proposition 1. *For all* $\alpha \in [0, 1]$ *, the following apply:*

- 1. $\widetilde{A} \subseteq \widetilde{B}$ if and only if $\widetilde{A}(\alpha) \subseteq \widetilde{B}(\alpha)$.
- 2. $\widetilde{A} = \widetilde{B}$ if and only if $\widetilde{A}(\alpha) = \widetilde{B}(\alpha)$.

The proof of the above proposition can be found in [21].

Definition 3. The support of a fuzzy set \widetilde{A} , denoted by $supp(\widetilde{A})$, is defined as $supp(\widetilde{A}) = \{x \in X : \mu_{\widetilde{A}}(x) > 0\}.$

Definition 4 (Core [5]). *The core of a fuzzy set* \widetilde{A} *, denoted by core* (\widetilde{A}) *, is defined as core* $(\widetilde{A}) = \{x \in X : \mu_{\widetilde{A}}(x) = 1\}$. When the core has at least one element, we have a normal fuzzy set.

Definition 5 (Convex fuzzy set [5]). A fuzzy set \widetilde{A} is convex if all its α -cuts are convex.

Definition 6 (Fuzzy number [5]). A fuzzy set \widetilde{A} is a fuzzy number if and only if \widetilde{A} is convex, is normalized, and has bounded support, and its α -cuts are closed intervals for $\alpha > 0$.

Since the α -cuts of fuzzy numbers are always closed and bounded intervals, the arithmetic of fuzzy numbers is defined in terms of their α -cuts (for more details, see [5]).

Let us consider intervals $A = [a_1, a_3]$ and $B = [b_1, b_3]$, subsets of \mathbb{R} . Then, the following apply:

1. Addition

$$[a_1, a_2](+)[b_1, b_2] = [a_1 + b_1, a_2 + b_2].$$

2. Multiplication

$$[a_1, a_2] \cdot [b_1, b_2] = [a_1 \cdot b_1 \wedge a_1 \cdot b_2 \wedge a_2 \cdot b_1 \wedge a_2 \cdot b_2, a_1 \cdot b_1 \vee a_1 \cdot b_2 \vee a_2 \cdot b_1 \vee a_2 \cdot b_2],$$

where $a \wedge b = \min\{a, b\}$ and $a \vee b = \max\{a, b\}$.

2.2. Fuzzy Geometry

The following are definitions of fuzzy geometry and come from [1,2].

Definition 7 (Fuzzy point [1]). A fuzzy point at $(a, b) \in \mathbb{R}^2$, denoted by $\tilde{P}(a, b)$, is defined by its membership function, which satisfies the following conditions:

- 1. $\vec{P}(a,b)$ is upper semi-continuous;
- 2. $\mu_{\widetilde{P}}(x,y) = 1 \Leftrightarrow (x,y) = (a,b);$

3. $\forall \alpha \in [0,1], \widetilde{P}(\alpha)$ is a compact and convex subset of \mathbb{R}^2 .

If there is no confusion, fuzzy point $\tilde{P}(a, b)$ is simply denoted by \tilde{P} .

From the above definition, we can see that $\tilde{P}(a, b)$ can be considered a surface on \mathbb{R}^3 , which is the graph of $z = \mu_{\tilde{P}}(x, y)$ (see Example 1).

Example 1. A fuzzy point P at (1,1) can be taken with the membership function defined by

$$\mu_{\widetilde{P}}(x,y) = \begin{cases} 1 - \sqrt{(x-1)^2 + (y-1)^2} & \text{if } (x-1)^2 + (y-1)^2 \le 1 \\ 0 & \text{elsewhere.} \end{cases}$$

See Figure 1.



Figure 1. Fuzzy point \tilde{P} at (1, 1).

We denote by dist(\cdot , \cdot) the usual Euclidean distance metric on \mathbb{R}^2 .

Definition 8 (Fuzzy distance [1]). Fuzzy distance \tilde{D} between two fuzzy points $\tilde{P}_1(a_1, b_1)$ and $\tilde{P}_2(a_2, b_2)$ is defined by its membership function

$$\mu_{\widetilde{D}}(d) = \sup \Big\{ \alpha : d = dist(u, v), \ u \in \widetilde{P}_1(0), \ v \in \widetilde{P}_2(0), \ and \ \mu_{\widetilde{P}_1}(u) = \mu_{\widetilde{P}_2}(v) = \alpha \Big\}.$$

The authors in [1] show that \widetilde{D} is a fuzzy number in \mathbb{R} .

Remark 1. The previous definition of fuzzy distance is different from the one in [20]. The support of the fuzzy distance proposed in [20] must always be a subset of the fuzzy distance introduced by Bluckley and Eslami in [1]. However, their cores are identical.

In order to define a fuzzy line segment, we denote by \overline{XY} the line segment defined by points *X* and *Y* belonging to \mathbb{R}^2 .

Definition 9 (Fuzzy line segment [1]). *Fuzzy line segment* $\tilde{L}_{\tilde{P}\tilde{Q}}$ *between two fuzzy points* \tilde{P} *and* \tilde{Q} *is defined by its membership function*

$$\mu_{\widetilde{L}_{\widetilde{P}\widetilde{Q}}}(x,y) = \sup \Big\{ \alpha : (x,y) \in \overline{XY}, X \in \widetilde{P}(\alpha) \text{ and } Y \in \widetilde{Q}(\alpha) \Big\}.$$

If there is no confusion, fuzzy line segment $\widetilde{L}_{\widetilde{P}\widetilde{O}}$ is simply denoted by \widetilde{L} .

Let v_1 , v_2 , v_3 be three distinct points in \mathbb{R}^2 that define a triangle, and let \tilde{P}_i be a fuzzy point at v_i , with i = 1, 2, 3.

Definition 10 (Fuzzy triangle [1]). Let \tilde{L}_1 , \tilde{L}_2 , \tilde{L}_3 be fuzzy segments between \tilde{P}_1 and \tilde{P}_2 , \tilde{P}_2 and \tilde{P}_3 , \tilde{P}_3 and \tilde{P}_1 , respectively. Then, the fuzzy set

$$\widetilde{\mathcal{T}} = \bigcup_{i=1}^{3} \widetilde{L}_i$$

is a fuzzy triangle, and it is defined by its membership function

$$\mu_{\widetilde{\mathcal{T}}}(x,y) = \max_{1 \le i \le n} \Big\{ \mu_{\widetilde{L}_i}(x,y) \Big\}.$$

Moreover, we say that the fuzzy triangle is strongly non-degenerate if $\tilde{P}_i(0)$, $1 \le i \le 3$, are pairwise disjoint. Finally, we say that \tilde{T} is a fuzzy right triangle at \tilde{P}_i if and only if $core(\tilde{T})$ is a right triangle at $\tilde{P}_i(1)$.

Throughout this paper, the phrase *fuzzy right triangle* always means "strongly non-degenerate fuzzy right triangle".

Example 2. Let $\tilde{P}_1(2,2)$, $\tilde{P}_2(5,2)$, and $\tilde{P}_3(5,11)$ be three fuzzy points defined by their membership functions

$$\begin{split} \mu_{\widetilde{P}_{1}}(x,y) &= \begin{cases} 1 - \sqrt{(x-2)^{2} + (y-2)^{2}} & \text{if } (x-2)^{2} + (y-2)^{2} \leq 1 \\ 0 & \text{elsewhere.} \end{cases}, \\ \mu_{\widetilde{P}_{2}}(x,y) &= \begin{cases} 1 - \frac{\sqrt{(x-5)^{2} + (y-2)^{2}}}{2} & \text{if } (x-5)^{2} + (y-2)^{2} \leq 4 \\ 0 & \text{elsewhere.} \end{cases}, \\ \mu_{\widetilde{P}_{3}}(x,y) &= \begin{cases} 1 - \frac{\sqrt{(x-5)^{2} + (y-11)^{2}}}{3} & \text{if } (x-5)^{2} + (y-11)^{2} \leq 9 \\ 0 & \text{elsewhere.} \end{cases} \end{split}$$

respectively. Then, fuzzy triangle $\tilde{\mathcal{T}} = \tilde{L}_{\tilde{P}_1\tilde{P}_2} \bigcup \tilde{L}_{\tilde{P}_2\tilde{P}_3} \bigcup \tilde{L}_{\tilde{P}_3\tilde{P}_1}$ is a fuzzy right triangle at \tilde{P}_2 . We can see the graph of $\tilde{\mathcal{T}}$ in Figure 2.



Figure 2. On the left and at the center, two views of the fuzzy triangle. On the right side, a level set of $\tilde{\mathcal{T}}$.

3. α -Cut Set of Fuzzy Distance \widetilde{D}

In this section, we will define the α -cut set of fuzzy distance \widetilde{D} between two fuzzy points. For the latter, we will set some notations, and since each α -cut set of a fuzzy point is a compact and convex subset of \mathbb{R}^2 (Definition 7), we will recall a few elements about convex sets. The description of \widetilde{D} will be helpful in Section 4, where the main results are presented.

We consider \mathbb{R}^2 endowed with the classical Euclidean distance, denoted by dist(\cdot, \cdot). The distance, denoted by d, between a point y and a set $X \subset \mathbb{R}^2$ is defined as $d(y, X) = \inf_{a \in X} \operatorname{dist}(y, a)$. Furthermore, the distance between two sets X and Y, denoted by $\widehat{d}(X, Y)$, is defined as $\widehat{d}(X, Y) = \inf{\operatorname{dist}(x, y) : x \in X \text{ and } y \in Y}$. Finally, the boundary of a subset $X \subseteq \mathbb{R}^2$ is denoted by ∂X .

Remark 2. In general, \hat{d} does not satisfy the positiveness property, and it does not satisfy the triangle inequality property either; hence, \hat{d} is not really a distance function; however, it is usually called distance. For more details, see [26].

The following propositions can be found in [27] or [28].

Proposition 2. Let X be a closed non-empty and convex subset of \mathbb{R}^2 . For each $y \in \mathbb{R}^2$, there exists a unique point $x \in X$ that minimizes the distance from y, i.e., dist(y, x) = d(y, X).

Proposition 3. Let X be a closed non-empty and convex subset of \mathbb{R}^2 . If $y \in \mathbb{R}^2 \setminus X$, then $x \in \partial X$.

From the previous propositions, $\hat{d}(X, Y) = \inf\{\operatorname{dist}(x, y) : x \in \partial X \text{ and } y \in \partial Y\}.$

Let v_1, v_2 be two distinct points in \mathbb{R}^2 , and let \tilde{P}_1 and \tilde{P}_2 be two fuzzy points at v_1 and v_2 , respectively, such that $\tilde{P}_1(0)$ and $\tilde{P}_2(0)$ are pairwise disjoint and $a = \text{dist}(v_1, v_2)$.

Let us remember that Definition 8 determines the fuzzy distance between fuzzy points \tilde{P}_1 and \tilde{P}_2 as

$$\bigvee_{\alpha\in[0,1]} [\delta^{\alpha}_m, \delta^{\alpha}_M],$$

where

$$\delta_m^{\alpha} = \min_{\substack{x_1 \in \partial \tilde{P}_1(\alpha), \, x_2 \in \partial \tilde{P}_2(\alpha) \\ x_1 \in \partial \tilde{P}_1(\alpha), \, x_2 \in \partial \tilde{P}_2(\alpha)}} \operatorname{dist}(x_1, x_2) \text{ and}$$

where $\partial \widetilde{P}_i(\alpha)$ denotes the boundary of $\widetilde{P}_i(\alpha)$, with i = 1, 2.

In what follows, we will show that δ_m^{α} and δ_M^{α} can be expressed in terms of $a = \text{dist}(v_1, v_2)$.

We denote by x_a^1 and x_a^2 the points belonging to $\partial \tilde{P}_1(\alpha)$ and $\partial \tilde{P}_2(\alpha)$, respectively, such that dist $(x_a^1, x_a^2) = \hat{d}(\tilde{P}_1(\alpha), \tilde{P}_2(\alpha))$, and by F_a^1 and F_a^2 the points of intersection between line segment $\overline{v_1v_2}$ and the boundaries of $\tilde{P}_1(\alpha)$ and $\tilde{P}_2(\alpha)$, respectively, that is,

$$\partial \widetilde{P}_1(\alpha) \cap \overline{v_1 v_2} = \left\{ F_a^1 \right\} \text{ and } \partial \widetilde{P}_2(\alpha) \cap \overline{v_1 v_2} = \left\{ F_a^2 \right\}.$$

Finally, we set

$$r_a^1 = \operatorname{dist}(v_1, F_a^1), \ r_a^2 = \operatorname{dist}(v_2, F_a^2), \ \operatorname{and} \ \widehat{a} = \operatorname{dist}(F_a^1, F_a^2).$$

For all of the above, see Figure 3.



Figure 3. Minimum distance between the α -cut sets of fuzzy points \widetilde{P}_1 and \widetilde{P}_2 .

Remark 3. It is clear that x_a^1 , x_a^2 , F_a^1 , F_a^2 , r_a^1 , and r_a^2 depend on α . However, to simplify the notation, we simply denote them without the α reference.

Since x_a^1 and x_a^2 are the points that define the distance between $\widetilde{P}_1(\alpha)$ and $\widetilde{P}_2(\alpha)$, $\operatorname{dist}(x_a^1, x_a^2) \leq \widehat{a}$; hence, we can identify two points, denoted by p_a^1 and p_a^2 , between F_a^1 and F_a^2 onto $\overline{v_1v_2}$, such that $\operatorname{dist}(p_a^1, p_a^2) = \operatorname{dist}(x_a^1, x_a^2)$ (see Figure 4). We set $h_a^1 = \operatorname{dist}(p_a^1, F_a^1)$ and $h_a^2 = \operatorname{dist}(p_a^2, F_a^2)$. Then, we have

$$\widehat{a} = \operatorname{dist}\left(x_a^1, x_a^2\right) + h_a^1 + h_a^2 \quad \text{and} \quad a = \widehat{a} + r_a^1 + r_a^2,$$

hence, we obtain

$$\delta_m^{\alpha} = \operatorname{dist}\left(x_a^1, x_a^2\right) = a - \left(r_a^1 + r_a^2\right) - \left(h_a^1 + h_a^2\right). \tag{1}$$



Figure 4. Projection of x_a^1 and x_a^2 onto $\overline{v_1v_2}$.

On the other hand, we denote by m_a^1 and m_a^2 the points that define the maximum distance between $\tilde{P}_1(\alpha)$ and $\tilde{P}_2(\alpha)$. Since dist $(m_a^1, m_a^2) \ge a$, we can identify two points, denoted by q_a^1 and q_a^2 , between m_a^1 and m_a^2 such that dist $(q_a^1, q_a^2) = a$. We set $H_a^1 = \text{dist}(m_a^1, q_a^1)$ and $H_a^2 = \text{dist}(m_a^2, q_a^2)$ (see Figure 5). Then,

$$\delta_M^{\alpha} = \operatorname{dist}\left(m_a^1, m_a^2\right) = a + H_a^1 + H_a^2. \tag{2}$$

Therefore, by Equations (1) and (2), we have

$$\widetilde{D}\left(\widetilde{P}_{1},\widetilde{P}_{2}\right)(\alpha) = \left[a - \left(r_{a}^{1} + r_{a}^{2}\right) - \left(h_{a}^{1} + h_{a}^{2}\right), a + H_{a}^{1} + H_{a}^{2}\right].$$
(3)



Figure 5. Projection of v_1 and v_2 onto the segment defined by m_a^1 and m_a^2 .

Remark 4. In general, identifying x_a^1 , x_a^2 or m_a^1 , m_a^2 is a very interesting subject, but it is outside the scope of this paper. However, when the fuzzy points define cones of circular bases, these elements are easy to identify, as we will show in the next section.

4. Some Metric Relations

In this section, we address two metric relations in the fuzzy right triangle, which are the Pythagorean theorem and the geometric mean theorem (also known as Euclidean theorem). From the above section, it is clear that many different and complicated cases can occur with respect to the form of a 0-cut set of a fuzzy point, so it is necessary to limit ourselves to a few cases. Hereinafter, we consider the following statements: Let v_1, v_2, v_3 be three distinct points in \mathbb{R}^2 such that dist $(v_1, v_2) = a$, dist $(v_2, v_3) = b$, and dist $(v_1, v_3) = c$. Without losing generality, we assume that $0 < a \le b < c$.

Let \tilde{P}_i be a fuzzy point at v_i , with i = 1, 2, 3, such that they define a fuzzy right triangle \tilde{T} at \tilde{P}_2 . Moreover, let $\tilde{A} = \tilde{D}(\tilde{P}_1, \tilde{P}_2)$, $\tilde{B} = \tilde{D}(\tilde{P}_2, \tilde{P}_3)$, and $\tilde{C} = \tilde{D}(\tilde{P}_1, \tilde{P}_3)$, i.e., the fuzzy distances associated to each pair of fuzzy points.

We also assume that \tilde{P}_i defines a cone of circular base of radius r_i , with i = 1, 2, 3. The membership function for each i = 1, 2, 3 is given by

$$\mu_{\widetilde{P}_{i}}(x,y) = \begin{cases} 1 - \frac{\sqrt{(x - v_{i}^{1})^{2} + (y - v_{i}^{2})^{2}}}{r_{i}} & \text{if } (x - v_{i}^{1})^{2} + (y - v_{i}^{2})^{2} \le r_{i}^{2}, \\ 0 & elsewhere. \end{cases}$$

with $v_i = (v_i^1, v_i^2)$. Moreover,

$$\partial \widetilde{P}_i(\alpha) = \left\{ (x, y) \in \mathbb{R}^2 : \ (x - v_i^1)^2 + (y - v_i^2)^2 = (r_i(1 - \alpha))^2 \right\},$$

that is, the boundary of the α -cut for P_i is a circle around the core with radius $r_i(1 - \alpha)$.

Remark 5.

- 1. Since \tilde{T} is a fuzzy right triangle, $\tilde{P}_i(0)$, $1 \le i \le 3$ are pairwise disjoint; this implies that $r_1 + r_2 < a$, $r_2 + r_3 < b$, and $r_1 + r_3 < c$.
- 2. Note that for \widetilde{P}_i and \widetilde{P}_j , with $i \neq j$, Equation (3) is

$$\widetilde{D}\left(\widetilde{P}_{i},\widetilde{P}_{j}\right)(\alpha) = [dist(v_{i},v_{j}) - (r_{i}+r_{j})\alpha'), dist(v_{i},v_{j}) + (r_{i}+r_{j})\alpha')],$$
(4)

where $\alpha' = 1 - \alpha$.

4.1. Fuzzy Pythagorean Theorem

The famous Pythagorean theorem remembered by the majority of students has been extended in different ways and in different geometries. In a very simple way, the law of cosines is one of them. Other versions on different spaces and geometries can be found, for example, in [29–32].

The above shows that this mathematical result has attracted and still attracts the attention of many researchers who try to generalize or extend the ideas to different geometries or spaces. In this section, we study a version of the Pythagorean theorem in fuzzy geometry considering the conditions of the previous section; that is, we consider fuzzy points defining cones of circular base.

Proposition 4 (Necessary condition). *With the previous notation, we have the following:*

- 1. If $\widetilde{C^2} \subseteq \widetilde{A^2} + \widetilde{B^2}$, then $a(r_1 + r_2) + b(r_2 + r_3) c(r_1 + r_3) > 0$.
- 2. If $\widetilde{A^2} + \widetilde{B^2} \subseteq \widetilde{C^2}$, then $a(r_1 + r_2) + b(r_2 + r_3) c(r_1 + r_3) < 0$.

Proof. From Equation (4), we have

$$\begin{split} \widetilde{A}(\alpha) &= \widetilde{D}\left(\widetilde{P}_1, \widetilde{P}_2\right)(\alpha) = [a - (r_1 + r_2)\alpha', a + (r_1 + r_2)\alpha'], \\ \widetilde{B}(\alpha) &= \widetilde{D}\left(\widetilde{P}_2, \widetilde{P}_3\right)(\alpha) = [b - (r_2 + r_3)\alpha', b + (r_2 + r_3)\alpha'], \\ \widetilde{C}(\alpha) &= \widetilde{D}\left(\widetilde{P}_1, \widetilde{P}_3\right)(\alpha) = [c - (r_1 + r_3)\alpha', c + (r_1 + r_3)\alpha'], \end{split}$$

where $\alpha' = 1 - \alpha$. Then,

$$\widetilde{A^{2}}(\alpha) = [(a - (r_{1} + r_{2})\alpha')^{2}, (a + (r_{1} + r_{2})\alpha')^{2}],$$

$$\widetilde{B^{2}}(\alpha) = [(b - (r_{2} + r_{3})\alpha')^{2}, (b + (r_{2} + r_{3})\alpha')^{2}], \text{ and}$$

$$\widetilde{C^{2}}(\alpha) = [(c - (r_{1} + r_{3})\alpha')^{2}, (c + (r_{1} + r_{2})\alpha')^{2}].$$

Hence,

$$\widetilde{A^2}(\alpha) + \widetilde{B^2}(\alpha) = \left[\left(a - (r_1 + r_2)\alpha' \right)^2 + \left(b - (r_2 + r_3)\alpha' \right)^2, \left(a + (r_1 + r_2)\alpha' \right)^2 + \left(b + (r_2 + r_3)\alpha' \right)^2 \right].$$

By Proposition 1 item 2, $\widetilde{C^2} \subseteq \widetilde{A^2} + \widetilde{B^2}$ if and only if

$$(a + (r_1 + r_2)\alpha')^2 + (b + (r_2 + r_3)\alpha')^2 \ge (c + (r_1 + r_3)\alpha')^2$$
(5)

and

$$(a - (r_1 + r_2)\alpha')^2 + (b - (r_2 + r_3)\alpha')^2 \le (c - (r_1 + r_3)\alpha')^2.$$
(6)

From inequalities (5) and (6), we obtain

$$a(r_1 + r_2) + b(r_2 + r_3) - c(r_1 + r_3) + \alpha'(r_2(r_1 + r_2 + r_3) - r_1r_3) \ge 0$$
(7)

and

$$-a(r_1+r_2) - b(r_2+r_3) + c(r_1+r_3) + \alpha'(r_2(r_1+r_2+r_3) - r_1r_3) \le 0$$
(8)

respectively. Finally, from inequalities (8) and (7), we obtain $a(r_1 + r_2) + b(r_2 + r_3) - c(r_1 + r_3) > 0$. This proves item 1. To prove item 2, we proceed in an analogous way considering $\widetilde{A^2} + \widetilde{B^2} \subseteq \widetilde{C^2}$. \Box

From Proposition 4, we have two necessary conditions for two possible inclusions. Then, we can state the following result.

Theorem 1. With the previous notation, we have the following:

1. $\widetilde{C^2} \subseteq \widetilde{A^2} + \widetilde{B^2}$ if and only if

$$|r_2(r_1 + r_2 + r_3) - r_1r_3| < a(r_1 + r_2) + b(r_2 + r_3) - c(r_1 + r_3)$$

2. $\widetilde{A^2} + \widetilde{B^2} \subseteq \widetilde{C^2}$ if and only if

$$|r_2(r_1 + r_2 + r_3) - r_1r_3| < c(r_1 + r_3) - a(r_1 + r_2) - b(r_2 + r_3)$$

Proof.

1. (Necessary condition). By Proposition 1 item 2, $\widetilde{C^2} \subseteq \widetilde{A^2} + \widetilde{B^2}$ if and only if

$$a(r_1 + r_2) + b(r_2 + r_3) - c(r_1 + r_3) + \alpha'(r_2(r_1 + r_2 + r_3) - r_1r_3) \ge 0$$
(9)

and

$$-a(r_1+r_2) - b(r_2+r_3) + c(r_1+r_3) + \alpha'(r_2(r_1+r_2+r_3) - r_1r_3) \le 0,$$
(10)

where $\alpha' = 1 - \alpha$. Moreover, by Proposition 4, $a(r_1 + r_2) + b(r_2 + r_3) - c(r_1 + r_3) > 0$; hence, inequalities (9) and (10) are equivalent to $\alpha' |r_2(r_1 + r_2 + r_3) - r_1r_3| < a(r_1 + r_2) + b(r_2 + r_3) - c(r_1 + r_3)$. The first step of this proof is finished, because the above inequality is true for all $\alpha \in [0, 1]$. The sufficient condition is direct.

2. We can prove item 2 in the same way.

Notice that if $r_1 = r_2 = r_3 = r$, then it can only be stated that $\widehat{C^2} \subseteq \widehat{A^2} + \widehat{B^2}$, since $r_1 = r_2 = r_3 = r$ implies a + b - c > 0, and this is always true in any triangle.

In the case where $r_1 = r_2 = r_3 = r$, we obtain the following result.

Corollary 1. Let \tilde{P}_1 , \tilde{P}_2 , and \tilde{P}_3 be three fuzzy points defining a fuzzy right triangle at \tilde{P}_2 such that $\tilde{A} = \tilde{D}(\tilde{P}_1, \tilde{P}_2)$, $\tilde{B} = \tilde{D}(\tilde{P}_2, \tilde{P}_3)$, and $\tilde{C} = \tilde{D}(\tilde{P}_1, \tilde{P}_3)$. If each \tilde{P}_i is a cone of circular base of radius r > 0, then

$$C^2 \subseteq A^2 + B^2$$

Proof. If each \widetilde{P}_i is a cone of circular base of radius r > 0 and they define a fuzzy right triangle, then $\widetilde{P}_i(0)$ are pairwise disjoint; this implies that $r < \frac{a}{2}$ (see Remark 5). On the other hand, by Theorem 1 item 1, $\widetilde{C^2} \subseteq \widetilde{A^2} + \widetilde{B^2}$ if and only if r < a + b - c. The latter inequality is always true. The following Lemma is useful to prove it.

Lemma 1. Let $\triangle ABC$ be a right triangle in *C*, and let *a*, *b*, and *c* be the lengths of the legs and the hypotenuse, respectively, with a $\leq b < c$. If k = a + b - c, then $k > \frac{a}{2}$.

Proof of Lemma 1. We assume that $k \le \frac{a}{2}$. Since k = a + b - c, we obtain that $\left(b + \frac{a}{2}\right)^2 \le c^2$. Considering $c^2 = a^2 + b^2$, we obtain $b \le \frac{3a}{4}$. But $b \ge a$. In consequence, $k > \frac{a}{2}$. \Box

Then, by Lemma 1,
$$a + b - c > \frac{a}{2}$$
, and since $r < \frac{a}{2}$, we conclude that $r < a + b - c$. \Box

4.2. Altitude Theorem or Geometric Mean Theorem

The following metric relation we address is the altitude theorem or geometric mean theorem, also known as Euclidean theorem. For that, it is necessary to define the altitude of a fuzzy triangle. This secondary element of the fuzzy triangle must be a fuzzy segment with one end at one vertex and the other on one side of the triangle. In particular, the ends are vertex \tilde{P}_2 and a point on the fuzzy hypotenuse, that is, fuzzy line segment $\tilde{L}_{\tilde{P}_1\tilde{P}_3}$. The following definition is about the containment of a fuzzy point on a fuzzy line segment.

Definition 11 (Containment of a fuzzy point on a fuzzy line segment [1]). We will say that a fuzzy point \tilde{P} is contained on a fuzzy line segment \tilde{L} if and only if $\mu_{\tilde{P}}(x,y) \leq \mu_{\tilde{L}}(x,y)$ for all $(x,y) \in \mathbb{R}^2$.

In [20], a measurement of the degree to which \tilde{P} belongs to \tilde{L} only when $\operatorname{core}(\tilde{P}) \in \operatorname{core}(\tilde{L})$ was proposed. Of course, Definition 11 implies the above condition. In Section 6, we provide some comments about the proposal given in [20].

Let \tilde{E} be a fuzzy point contained in $\tilde{L}_{\tilde{P}_1\tilde{P}_3}$ such that $\tilde{E}(0)$ and $\tilde{P}_i(0)$ are disjoint, with i = 1, 3. We denote by $\tilde{H}_{\tilde{P}_2}$ the fuzzy line segment defined by fuzzy points \tilde{P}_2 and \tilde{E} .

Definition 12. We will say that $\widetilde{H}_{\widetilde{P}_2}$ is the altitude of fuzzy right triangle $\widetilde{\mathcal{T}}$ from \widetilde{P}_2 if and only if $\operatorname{core}\left(\widetilde{H}_{\widetilde{P}_2}\right)$ is perpendicular to $\operatorname{core}\left(\widetilde{L}_{\widetilde{P}_1\widetilde{P}_3}\right)$.

Other ways of defining altitude can be obtained by following the ideas proposed in [33].

Let v_4 be points in \mathbb{R}^2 such that dist $(v_1, v_4) = p$, dist $(v_3, v_4) = q$, and dist $(v_2, v_4) = h$. Let \tilde{E} be a fuzzy point at v_4 contained in $\tilde{L}_{\tilde{P}_1\tilde{P}_3}$ such that \tilde{E} defines a cone of circular base of radius r_4 ; $\tilde{E}(0)$ and $\tilde{P}_i(0)$ are disjoint, with i = 1, 3. Let $\tilde{H}_{\tilde{P}_2}$ be the altitude of fuzzy right triangle \tilde{T} from \tilde{P}_2 , that is, the fuzzy line segment defined by fuzzy points \tilde{P}_2 and \tilde{E} . Finally, we denote by \tilde{H} , \tilde{P} , and \tilde{Q} the fuzzy distances between fuzzy points \tilde{P}_2 and \tilde{E} , \tilde{P}_1 and \tilde{E} , and \tilde{P}_3 and \tilde{E} , respectively.

Proposition 5 (Necessary condition). *With the previous notation, we have the following:*

1. If
$$H^2 \subseteq P \cdot Q$$
, then $p(r_3 + r_4) + q(r_1 + r_4) - 2h(r_2 + r_4) > 0$.
2. If $\tilde{P} \cdot \tilde{Q} \subseteq \tilde{H}^2$, then $p(r_3 + r_4) + q(r_1 + r_4) - 2h(r_2 + r_4) < 0$.

Proof. In the same way as in the proof of Proposition 4. \Box

Another metric relation that relates to the altitude theorem is that the squared measure of a leg is the product between the measure of the leg projection and the hypotenuse measure, i.e., $a^2 = pc$ and $b^2 = qc$. We also provide a necessary condition about these relations.

Proposition 6 (Necessary condition). *With the previous notation, we have the following:*

- 1. If $\widetilde{A^2} \subseteq \widetilde{P} \cdot \widetilde{C}$, then $c(r_1 + r_4) + p(r_1 + r_3) 2a(r_1 + r_2) > 0$.
- 2. If $\tilde{P} \cdot \tilde{C} \subseteq \tilde{A}^2$, then $c(r_1 + r_4) + p(r_1 + r_3) 2a(r_1 + r_2) < 0$.
- 3. If $\widetilde{B^2} \subseteq \widetilde{Q} \cdot \widetilde{C}$, then $c(r_3 + r_4) + q(r_1 + r_3) 2b(r_2 + r_3) > 0$.
- 4. If $\tilde{Q} \cdot \tilde{C} \subseteq \tilde{B}^2$, then $c(r_3 + r_4) + q(r_1 + r_3) 2b(r_2 + r_3) < 0$.

Proof. In the same way as in the proof of Proposition 4. \Box

As in the previous subsection, the subset relation may vary, giving rise to two cases in each statement. The following result summarizes this fact.

Theorem 2. With the previous notation, we have the following:

1. $\widetilde{H^2} \subseteq \widetilde{P} \cdot \widetilde{Q}$ if and only if

 \sim

~~~.

$$\left|r_4(r_1+r_3-2r_2)+r_1r_3-r_2^2\right| < p(r_3+r_4)+q(r_1+r_4)-2h(r_2+r_4).$$

2.  $\widetilde{P} \cdot \widetilde{Q} \subseteq \widetilde{H^2}$  if and only if

$$\left|r_4(r_1+r_3-2r_2)+r_1r_3-r_2^2\right| < 2h(r_2+r_4)-p(r_3+r_4)-q(r_1+r_4).$$

3.  $\widetilde{A^2} \subseteq \widetilde{P} \cdot \widetilde{C}$  if and only if

$$\left|r_1(r_3+r_4-2r_2)+r_3r_4-r_2^2\right| < c(r_1+r_4)+p(r_1+r_3)-2a(r_1+r_2).$$

4.  $\widetilde{P} \cdot \widetilde{C} \subseteq \widetilde{A^2}$  if and only if

$$\left|r_1(r_3+r_4-2r_2)+r_3r_4-r_2^2\right| < 2a(r_1+r_2)-c(r_1+r_4)-p(r_1+r_3).$$

5.  $\widetilde{B^2} \subseteq \widetilde{Q} \cdot \widetilde{C}$  if and only if

$$\left| r_3(r_1 + r_4 - 2r_2) + r_1r_4 - r_2^2 \right| < c(r_3 + r_4) + q(r_1 + r_3) - 2b(r_2 + r_3).$$

6.  $\widetilde{Q} \cdot \widetilde{C} \subseteq \widetilde{B^2}$  if and only if

$$\left|r_3(r_1+r_4-2r_2)+r_1r_4-r_2^2\right| < 2b(r_2+r_3)-c(r_3+r_4)-q(r_1+r_3).$$

**Proof.** In the same way as in the proof of Theorem 1, but using Proposition 5 or Proposition 6.  $\Box$ 

Let us notice that if  $r_1 = r_2 = r_3 = r_4$ , then we only have a possibility of inclusion in each classical statement. The following result summarizes this fact.

**Corollary 2.** Let  $\tilde{P}_1$ ,  $\tilde{P}_2$ , and  $\tilde{P}_3$  be three fuzzy points defining a fuzzy right triangle  $\tilde{T}$  at  $\tilde{P}_2$ , and let  $\tilde{H}_{P_2E}$  be the altitude of  $\tilde{T}$  from  $\tilde{P}_2$  to  $\tilde{L}_{\tilde{P}_1\tilde{P}_3}$ , such that  $\tilde{A} = \tilde{D}(\tilde{P}_1, \tilde{P}_2)$ ,  $\tilde{B} = \tilde{D}(\tilde{P}_2, \tilde{P}_3)$ ,  $\tilde{C} = \tilde{D}(\tilde{P}_1, \tilde{P}_3)$ ,  $\tilde{H} = \tilde{D}(\tilde{P}_2, \tilde{E})$ ,  $\tilde{P} = \tilde{D}(\tilde{E}, \tilde{P}_1)$ , and  $\tilde{Q} = \tilde{D}(\tilde{P}_3, \tilde{E})$ .

If each  $\tilde{P}_i$  is a cone of circular base of radius r > 0 and so is  $\tilde{E}$ , then the following apply:

- 1.  $\widetilde{H^2} \subseteq \widetilde{P} \cdot \widetilde{Q}$ .
- 2.  $\widetilde{A^2} \subset \widetilde{P} \cdot \widetilde{C}$ .
- 3.  $\widetilde{B^2} \subset \widetilde{O} \cdot \widetilde{C}$ .

**Proof.** By Theorem 2 item 1,  $\widetilde{H^2} \subseteq \widetilde{P} \cdot \widetilde{Q}$  if and only if

$$\left| r_4(r_1 + r_3 - 2r_2) + r_1r_3 - r_2^2 \right| < p(r_3 + r_4) + q(r_1 + r_4) - 2h(r_2 + r_4).$$
(11)

If  $r_1 = r_2 = r_3 = r_4$ , then inequality (11) is equivalent to  $0 . The latter is always true, because <math>p + q - 2h = (\sqrt{p} - \sqrt{q})^2 \ge 0$ .

Items 2 and 3 are proved in the same way, considering that  $c + p - 2a = \frac{(c-a)^2}{c}$  and  $c + q - 2b = \frac{(c-b)^2}{c}$  for each item, respectively.  $\Box$ 

# 5. Examples

In this section, we provide three examples. The first and second ones show the necessary condition of Proposition 4 and Proposition 6, respectively. To finish, Example 5 shows a fuzzy right triangle satisfying Theorem 2.

**Example 3.** Let  $\tilde{P}_1(2,2)$ ,  $\tilde{P}_2(5,2)$ , and  $\tilde{P}_3(5,6)$  be three fuzzy points defined by their membership functions

$$\begin{split} \mu_{\widetilde{P}_{1}}(x,y) &= \begin{cases} 1 - \frac{\sqrt{(x-2)^{2} + (y-2)^{2}}}{1.5} & \text{if } (x-2)^{2} + (y-2)^{2} \leq 1.5^{2}, \\ 0 & \text{elsewhere.} \end{cases} \\ \mu_{\widetilde{P}_{2}}(x,y) &= \begin{cases} 1 - \frac{\sqrt{(x-5)^{2} + (y-2)^{2}}}{0.9} & \text{if } (x-5)^{2} + (y-2)^{2} \leq 0.9^{2}, \\ 0 & \text{elsewhere.} \end{cases} \\ \mu_{\widetilde{P}_{3}}(x,y) &= \begin{cases} 1 - \frac{\sqrt{(x-5)^{2} + (y-6)^{2}}}{2.9} & \text{if } (x-5)^{2} + (y-6)^{2} \leq 2.9^{2} \\ 0 & \text{elsewhere.} \end{cases} \end{split}$$

respectively, and defining a fuzzy right triangle at  $\widetilde{P}_2$ , with a = 3, b = 4, c = 5,  $r_1 = 1.5$ ,  $r_2 = 0.9$ , and  $r_3 = 2.9$ . Hence,  $a(r_1 + r_2) + b(r_2 + r_3) - c(r_1 + r_3) = 3 \cdot 2.4 + 4 \cdot 3.8 - 5 \cdot 4.4 = 0.4 > 0$ . However,  $\widetilde{C}^2 \not\subseteq \widetilde{A}^2 + \widetilde{B}^2$ , because  $\widetilde{C}^2(0) = \left[ (5 - 4.4)^2, (5 + 4.4)^2 \right] = [0.36, 88.36]$ 

and  $\left(\widetilde{A^2} + \widetilde{B^2}\right)(0) = \left[(3 - 2.4)^2 + (4 - 3.8)^2, (3 + 2.4)^2 + (4 + 3.8)^2\right] = [0.4, 90]$ . This illustrates that the condition  $a(r_1 + r_2) + b(r_2 + r_3) - c(r_1 + r_3) > 0$  of Proposition 4 is not sufficient. Furthermore, notice that  $|r_2(r_1 + r_2 + r_3) - r_1r_3| = 0.42$ ; then,  $|r_2(r_1 + r_2 + r_3) - r_1r_3| > a(r_1 + r_2) + b(r_2 + r_3) - c(r_1 + r_3)$ ; then, Theorem 1 is not satisfied.

**Example 4.** Let us consider fuzzy points  $\tilde{P}_1(12,3)$ ,  $\tilde{P}_2(13,3)$ , and  $\tilde{P}_3(3,10)$  defining a fuzzy right triangle, denoted by  $\tilde{T}$ , at  $\tilde{P}_2$ . The membership functions of each fuzzy point are defined by

$$\begin{split} \mu_{\widetilde{P}_{1}}(x,y) &= \begin{cases} 1 - \sqrt{(x-12)^{2} + (y-3)^{2}} & \text{if } (x-3)^{2} + (y-3)^{2} \leq 1 \\ 0 & \text{elsewhere.} \end{cases}, \\ \mu_{\widetilde{P}_{2}}(x,y) &= \begin{cases} 1 - \sqrt{(x-3)^{2} + (y-3)^{2}} & \text{if } (x-12)^{2} + (y-3)^{2} \leq 1 \\ 0 & \text{elsewhere.} \end{cases}, \\ \mu_{\widetilde{P}_{3}}(x,y) &= \begin{cases} 1 - \frac{\sqrt{(x-3)^{2} + (y-10)^{2}}}{3} & \text{if } (x-3)^{2} + (y-10)^{2} \leq 3^{2} \\ 0 & \text{elsewhere.} \end{cases} \end{split}$$

respectively. Let  $\tilde{E}$  be the fuzzy point contained in  $\tilde{L}_{\tilde{P}_1\tilde{P}_2}$  with membership function

$$\mu_{\widetilde{E}}(x,y) = \begin{cases} 1 - \frac{\sqrt{(x-8)^2 + (y-8)^2}}{2} & \text{if } (x-8)^2 + (y-8)^2 \le 2^2 \\ 0 & \text{elsewhere.} \end{cases}$$

Let  $\widetilde{H}_{\widetilde{P}_2}$  be the altitude of  $\widetilde{T}$  from  $\widetilde{P}_2$ . In this case, we have a = 10, b = 10,  $c = 10\sqrt{2}$ ,  $p = q = h = 5\sqrt{2}$ ,  $r_1 = 1$ ,  $r_2 = 1$ ,  $r_3 = 3$ , and  $r_4 = 2$ . From straightforward computations, we obtain that  $\widetilde{H}^2(0) = \left[59 - 30\sqrt{2}, 59 + 30\sqrt{2}\right]$  and  $\left(\widetilde{P} \cdot \widetilde{Q}\right)(0) = \left[65 - 40\sqrt{2}, 65 + 40\sqrt{2}\right]$ , this implies that  $\widetilde{H}^2 \subseteq \widetilde{P} \cdot \widetilde{Q}$ . According to Proposition 6,  $p(r_3 + r_4) + q(r_1 + r_4) - 2h(r_2 + r_4) > 0$ . Indeed,  $p(r_3 + r_4) + q(r_1 + r_4) - 2h(r_2 + r_4) = 5\sqrt{2} \cdot 5 + 5\sqrt{2} \cdot 3 - 2 \cdot 5\sqrt{2} \cdot 3 = 10\sqrt{2}$ .

**Example 5.** Let us consider the fuzzy points of Example 4. We know from the previous example that  $\widetilde{H^2} \subseteq \widetilde{P} \cdot \widetilde{Q}$ . Notice that the necessary and sufficient condition of Theorem 2 item 1 is satisfied, that is,  $|r_4(r_1 + r_3 - 2r_2) + r_1r_3 - r_2^2| < p(r_3 + r_4) + q(r_1 + r_4) - 2h(r_2 + r_4)$ . Indeed,  $|r_4(r_1 + r_3 - 2r_2) + r_1r_3 - r_2^2| = 6$ , and from Example 4,  $p(r_3 + r_4) + q(r_1 + r_4) - 2h(r_2 + r_4) = 10\sqrt{2}$ . See Figure 6.



Figure 6. Fuzzy points of Example 5.

# 6. Conclusions and Comments

In this paper, two metric relations of the right triangle were extended from Euclidean geometry to fuzzy geometry. More precisely, a version of the Pythagorean theorem and a version of the altitude theorem were provided in analytical fuzzy geometry. For this, the membership function for each fuzzy point was considered to be a right circular cone. The stated metric relations are inclusion relations that depend on the cone radii, which have a very similar form to the classical statements (or the crisp statements) in Euclidean geometry.

This condition imposed on the fuzzy points is due to the complexity of establishing a simple condition that implies some inclusion relation; for instance, in a general way,  $\widetilde{C^2} \subseteq \widetilde{A^2} + \widetilde{B^2}$  if and only if  $(\delta_{m,c}^{\alpha})^2 \ge (\delta_{m,a}^{\alpha})^2 + (\delta_{m,b}^{\alpha})^2$  and  $(\delta_{M,c}^{\alpha})^2 \le (\delta_{M,a}^{\alpha})^2 + (\delta_{M,b}^{\alpha})^2$ , for all  $\alpha \in [0, 1]$ , where

$$\begin{split} \delta^{\alpha}_{m,a} &= \min_{\substack{x_1 \in \partial \widetilde{P}_1(\alpha), \ x_2 \in \partial \widetilde{P}_2(\alpha)}} \operatorname{dist}(x_1, x_2), \quad \delta^{\alpha}_{m,b} &= \min_{\substack{x_1 \in \partial \widetilde{P}_2(\alpha), \ x_2 \in \partial \widetilde{P}_3(\alpha)}} \operatorname{dist}(x_1, x_2), \\ \delta^{\alpha}_{m,c} &= \min_{\substack{x_1 \in \partial \widetilde{P}_1(\alpha), \ x_2 \in \partial \widetilde{P}_3(\alpha)}} \operatorname{dist}(x_1, x_2), \quad \delta^{\alpha}_{M,a} &= \max_{\substack{x_1 \in \partial \widetilde{P}_1(\alpha), \ x_2 \in \partial \widetilde{P}_2(\alpha)}} \operatorname{dist}(x_1, x_2), \\ \delta^{\alpha}_{M,b} &= \max_{\substack{x_1 \in \partial \widetilde{P}_2(\alpha), \ x_2 \in \partial \widetilde{P}_3(\alpha)}} \operatorname{dist}(x_1, x_2), \quad \delta^{\alpha}_{M,c} &= \max_{\substack{x_1 \in \partial \widetilde{P}_1(\alpha), \ x_2 \in \partial \widetilde{P}_3(\alpha)}} \operatorname{dist}(x_1, x_2). \end{split}$$

More accurately, from Section 3, Equation (3),  $\widetilde{C^2} \subseteq \widetilde{A^2} + \widetilde{B^2}$  if and only if

$$\left(c - \left(r_c^1(\alpha) + r_c^3(\alpha)\right) - \left(h_c^1 + h_c^3\right)\right)^2 \ge \left(a - \left(r_a^1(\alpha) + r_a^2(\alpha)\right) - \left(h_a^1 + h_a^2\right)\right)^2 + \left(b - \left(r_b^1(\alpha) + r_b^2(\alpha)\right) - \left(h_b^1 + h_b^2\right)\right)^2,$$

and  $(c + H_c^3 + H_c^1)^2 \le (a + H_a^1 + H_a^2)^2 + (b + H_b^2 + H_b^3)^2$ . Then, imposing the condition on the fuzzy points such that their membership functions are right circular cones helps us to reduce some variables in the above inequalities.

As we mentioned in Section 4.2, Ghosh and Chakraborty proposed in [20] a measure of the degree to which a fuzzy point  $\tilde{P}$  belongs to a fuzzy line segment  $\tilde{L}$  only when  $\operatorname{core}(\tilde{P}) \in \operatorname{core}(\tilde{L})$ . Although this containment proposal is more accurate than the one given by Buckley and Eslami in [1], we did not consider it, since assuming one or the other definition to compute the fuzzy distance between two fuzzy points, where one of them is contained in a fuzzy line segment and the other is a fuzzy point defining the fuzzy line segment, is the same. For instance, we see Figure 7. Let  $\tilde{L}$  be a fuzzy line segment defined by fuzzy points  $\tilde{P}_1$  and  $\tilde{P}_2$ . According to [20], fuzzy point  $\tilde{E}$  is fuzzily contained in  $\tilde{L}$  with the membership value of  $0 < \beta < 1$ , because  $\tilde{E}(0) \not\subset \tilde{L}(0)$ . Then,  $\tilde{D}(\tilde{E}, \tilde{P}_2)(\alpha) = [p - (r_3 + r_2)(1 - \alpha), p + (r_3 + r_2)(1 - \alpha)]$  for all  $\alpha \in [0, 1]$ . The latter is the same if  $\tilde{E}(0) \subset \tilde{L}(0)$ .



**Figure 7.** Fuzzy point  $\tilde{E}$  is fuzzily contained in  $\tilde{L}$ .

In future research, we want to compare our results with those obtained by considering the definitions of fuzzy distance and fuzzy line segment that depend on the definitions of inverse points and same points with respect to continuous fuzzy points given in [20]. Moreover, we plan to define other secondary elements of a fuzzy triangle and study their properties or how to extend them from Euclidian geometry to analytical fuzzy geometry.

**Funding:** This research was funded by Universidad de Playa Ancha de Ciencias de la Educación, regular research grant 2021–2022, key project CNE 07-2223 and UPLA Foundation Projects within the framework of Execution of Diplomado Bases de la Investigación Científica.

Data Availability Statement: Not applicable.

Conflicts of Interest: The author declares no conflict of interest.

# References

- 1. Buckley, J.; Eslami, E. Fuzzy Plane Geometry. 1. Points and Lines. Fuzzy Sets Syst. 1997, 86, 179–187. [CrossRef]
- 2. Buckley, J.; Eslami, E. Fuzzy Plane Geometry. 2. Circles and Polygons. Fuzzy Sets Syst. 1997, 87, 79–85. [CrossRef]
- 3. Cantor, G. On a property of the class of all real algebraic numbers. *Crelle'S J. Math.* 1874, 77, 258–262. [CrossRef]
- 4. Zadeh, L. Fuzzy Sets. Inf. Control 1965, 8, 338–353. [CrossRef]
- 5. Lee, K. *First Course on Fuzzy Theory and Applications;* Advances in Intelligent and Soft Computing; Springer: Berlin/Heidelberg, Germany, 2005; Volume 27.
- Ahuja; Davis; Milgram; Rosenfeld. Piecewise Approximation of Pictures Using Maximal Neighborhoods. *IEEE Trans. Comput.* 1978, C-27, 375–379. [CrossRef]
- Clark, T.; Larson, J.; Mordeson, J.; Potter, J.; Wierman, M. Applying Fuzzy Mathematics to Formal Models in Comparative Politics; Studies in Fuzziness and Soft Computing; Springer: Berlin/Heidelberg, Germany, 2008; Volume 225.
- Egusa, Y.; Akahori, H.; Morimura, A.; Wakami, N. An Application of Fuzzy Set Theory for an Electronic Video Camera Image Stabilizer. *IEEE Trans. Fuzzy Syst.* 1995, 3, 351–356. [CrossRef]
- 9. Lingala, M.; Joe Stanley, R.; Rader, R.; Hagerty, J.; Rabinovitz, H.; Oliviero, M.; Choudhry, I.; Stoecker, W. Fuzzy Logic Color Detection: Blue Areas in Melanoma Dermoscopy Images. *Comput. Med. Imaging Graph.* **2014**, *38*, 403–410. [CrossRef] [PubMed]
- 10. Yoshimura, S.; Mochizuki, Y.; Yagawa, G. Automated Structural Design Based on Knowledge Engineering and Fuzzy Control. *Eng. Comput.* **1995**, *12*, 593–608. [CrossRef]
- 11. Zimmermann, H. Fuzzy Control. In *Fuzzy Set Theory and Its Applications*; Springer: Berlin/Heidelberg, Germany, 2001; pp. 223–264.
- 12. Bogomolny, A. On the Perimeter and Area of Fuzzy Sets. Fuzzy Sets Syst. 1987, 23, 257–269. [CrossRef]
- Guha, D.; Chakraborty, D. A New Approach to Fuzzy Distance Measure and Similarity Measure between Two Generalized Fuzzy Numbers. *Appl. Soft Comput.* 2010, 10, 90–99. [CrossRef]
- 14. Gupta, K.; Ray, S. Fuzzy Plane Projective Geometry. Fuzzy Sets Syst. 1993, 54, 191–206. [CrossRef]
- 15. Li, Q.; Guo, S. Fuzzy Geometric Object Modelling. In *Proceedings of the Fuzzy Information and Engineering*; Cao, B., Ed.; Springer: Berlin/Heidelberg, Germany, 2007; pp. 551–563.
- Löffler, M.; Kreveld, M. Geometry with Imprecise Lines. In Proceedings of the 24th European Workshop on Computational Geometry, Nancy, France, 18–20 March 2008; Volume 40, pp. 133–136.
- 17. Rosenfeld, A. The Diameter of a Fuzzy Set. Fuzzy Sets Syst. 1984, 13, 241–246. [CrossRef]
- 18. Rosenfeld, A. Fuzzy Plane Geometry: Triangles. Pattern Recognit. Lett. 1994, 15, 1261–1264. [CrossRef]
- 19. Rosenfeld, A. Fuzzy Geometry: An Updated Overview. Inf. Sci. 1998, 110, 127–133. [CrossRef]
- 20. Ghosh, D.; Chakraborty, D. Analytical Fuzzy Plane Geometry I. Fuzzy Sets Syst. 2012, 209, 66. [CrossRef]
- 21. Ghosh, D.; Chakraborty, D. An Introduction to Analytical Fuzzy Plane Geometry; Springer: Berlin/Heidelberg, Germany, 2019.
- 22. Ghosh, D.; Gupta, D.; Som, T. Analytical Fuzzy Space Geometry I. Fuzzy Sets Syst. 2021, 421, 77–110. [CrossRef]
- 23. Ghosh, D.; Gupta, D.; Som, T. Analytical Fuzzy Space Geometry II. Fuzzy Sets Syst. 2022, 459, 144–181. [CrossRef]
- 24. Qiu, J.; Zhang, M. Fuzzy Space Analytic Geometry. In Proceedings of the 2006 International Conference on Machine Learning and Cybernetics, Dalian, China, 13–26 August 2006; pp. 1751–1755. [CrossRef]
- 25. Dubois, D.; Prade, H. Fuzzy Sets and Systems: Theory and Applications; Academic Press: New York, NY, USA, 1980; Volume 144.
- 26. Conci, A.; Kubrusly, C. Distances between Sets. Sci. Appl. 2017, 26, 1–18.
- 27. Gardner, R. Geometric Tomography; Cambridge University Press: Cambridge, UK, 1995; Volume 6.
- Schneider, R. Convex Bodies: The Brunn–Minkowski Theory; Number 151 in Encyclopedia of Mathematics and Its Applications; Cambridge University Press: Cambridge, UK, 2014.
- 29. Alber, Y. Generalized Projections, Decompositions, and the Pythagorean-type Theorem in Banach Spaces. *Appl. Math. Lett.* **1998**, *11*, 115–121. [CrossRef]
- Amari, S. Information Geometry and Its Applications: Convex Function and Dually Flat Manifold. In *Emerging Trends in Visual Computing*. *ETVC 2008*; Lecture Notes in Computer Science; Nielsen, F., Ed.; Springer: Berlin/Heidelberg, Germany, 2009; Volume 5416, pp. 75–102. [CrossRef]

- 31. Conant, D.; Beyer, W. Generalized Pythagorean Theorem. Am. Math. Mon. 1974, 81, 262–265. [CrossRef]
- 32. Ungar, A. The Hyperbolic Pythagorean Theorem in the Poincaré Disc Model of Hyperbolic Geometry. *Am. Math. Mon.* **1999**, 106, 759–763. [CrossRef]
- 33. Chakraborty, D.; Das, S. Fuzzy Geometry: Perpendicular to Fuzzy Line Segment. Inf. Sci. 2018, 468, 213–225. [CrossRef]

**Disclaimer/Publisher's Note:** The statements, opinions and data contained in all publications are solely those of the individual author(s) and contributor(s) and not of MDPI and/or the editor(s). MDPI and/or the editor(s) disclaim responsibility for any injury to people or property resulting from any ideas, methods, instructions or products referred to in the content.