



Article Optimizing Design Parameters of PLA 3D-Printed Scaffolds for Bone Defect Repair

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Abstract: Current materials used to fill bone defects (ceramics, cement) either lack strength or do not induce bone repair. The use of biodegradable polymers such as PLA may promote patient healing by stimulating the production of new bone in parallel with a controlled degradation of the scaffold. This project aims to determine the design parameters maximising scaffold mechanical performance in such materials. Starting from a base cylindrical model of 10 mm height and of outer and inner diameters of 10 and 4 mm, respectively, 27 scaffolds were designed. Three design parameters were investigated: pore distribution (crosswise, lengthwise, and eccentric), pore shape (triangular, circular, and square), and pore size (surface area of 0.25 mm², 0.5625 mm², and 1 mm²). Using the finite element approach, a compressive displacement (0.05 mm/s up to 15% strain) was simulated on the models and the resulting scaffold stiffnesses (N/mm²) were compared. The models presenting good mechanical behaviors were further printed along two orientations: 0° (cylinder sitting on its base) and 90° (cylinder laying on its side). A total of n = 5 specimens were printed with PLA for each of the retained models and experimentally tested using a mechanical testing machine with the same compression parameters. Rigidity and yield strength were evaluated from the experimental curves. Both numerically and experimentally, the highest rigidity was found in the model with circular pore shape, crosswise pore distribution, small pore size (surface area of 0.25 mm^2), and a 90° printing orientation. Its average rigidity reached 961 \pm 32 MPa from the mechanical testing and 797 MPa from the simulation, with a yield strength of 42 ± 1.5 MPa. The same model with a printing orientation of 0° resulted in an average rigidity of 515 \pm 7 MPa with a yield strength of 32 \pm 1.6 MPa. Printing orientation and pore size were found to be the most influential design parameters on rigidity. The developed design methodology should accelerate the identification of effective scaffolds for future in vitro and in vivo studies.

Keywords: scaffolds; 3D-printing; scaffolds design; bone resection; bone replacement; PLA

1. Introduction

Several conditions such as infection, trauma, or cancer can result in large surgical bone defects that present many challenges for reconstructive orthopedic surgery [1]. Current treatments include autologous and allogenic bone grafting as well as acrylic and ceramic bone cements [1,2]. There are several drawbacks to these types of treatments. Autografts result in donor site morbidity, and present an availability problem [3,4]. Acrylic bone cements provide mechanical support without regenerative properties, while ceramic cements can promote bone repair yet lack mechanical strength [1,5]. There is an unmet



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Copyright: © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). clinical need for better bone substitutes, which can provide both mechanical support and tissue regenerative properties. In this regard, research has been focusing on scaffolds made of polymers and composite materials [3]. Tissue engineering (TE) is a growing area of interest in bone repair, whereby scaffolds are combined with cells and biologics to be used as temporary implants promoting bone regeneration and tissue ingrowth [6,7]. TE aims to restore, maintain, or improve tissue functionality [2], with the long-term goal of replacing damaged tissues and organs [8]. It is presented as an alternative approach to eliminate the drawbacks of autologous and allogeneic bone grafts [3,9].

Several types of scaffolds have been developed over the years for use in bone repair. Seeing as bone tissue is a heterogenous material composed of hydroxyapatite mineral [10] and organic components such as collagen, scaffolds should be designed as a combination of materials to achieve structural biomimicry [11]. Indeed, combining materials, such as PLA (polylactic acid) and cHA (carbonatite hydroxyapatite) to produce composite or hybrid scaffolds has been proven to improve bioactivity [5,11]. The PLA/HA combination attracts many researchers since it is more similar to natural bone tissue (in structure and composition) than ceramic or polymer materials alone [12]. Composite scaffolds made of TCL (terephthaloyl chloride) combined with magnesium can promote bone healing [9], and composite scaffolds made of PCL (polycaprolactone) combined with a hydrogel infused with small molecules (resveratrol and strontium ranelate) can significantly promote bone formation in critical-sized mandibular bone defects [13]. Furthermore, several studies have pointed to the osteogenic impact of composite polymeric scaffolds combined with nano-hydroxyapatite [14]. Metal-based scaffolds have also provided great results. Several clinical studies have shown that porous titanium scaffolds provided satisfactory results in large bone defects [7].

Additive manufacturing in the form of 3D printing has rapidly gained traction for bone repair applications. In fact, a FDA-approved, 3D-printed scaffold for bone repair is available commercially/clinically for spine fusions [15]. Major advantages of using 3D printing for scaffolds are that an enormous range of geometries, pore sizes, and materials can be used to control mechanics, degradation rates, and biological impact of the scaffold [16]. Many polymeric materials present great rigidities and are bioresorbable, meaning that following implantation and bone regeneration support, they will be gradually replaced by new tissue [17]. For example, PLA is a commonly used material for bone tissue replacement, mainly due to its high mechanical properties [18,19] and its great biocompatibility and biodegradability [1,2,18,19]. It has been proven to be effective for trabecular bone replacement [2,18]. It is also an inexpensive and commonly available material. In line with what other groups have found, we have shown that low-cost 3D printers can generate scaffolds of various pore sizes to control stem cell differentiation [1,16,20,21] and that composite scaffolds containing beta-tricalcium phosphate or hydroxyapatite can also drive stem cell differentiation and promote bone repair in animal models [22–24].

In terms of scaffold design, several parameters are crucial, namely *porosity*, pore size, and pore configuration. *Porosity* allows cell migration and improves surface area, promoting osteogenesis [7]. For example, porosities higher than 50% promote vascularization [25]. However, high *porosity* can hardly respect the need for the high mechanical strength required for bone usage, suggesting that a compromise must be made among *porosity*, strength, and osseointegration [7]. Indeed, Zhang et al. showed that *scaffold rigidity* decreases linearly with increasing scaffold *porosity* [26]. Previous studies have also shown that pore size and pore density have an impact on cellular growth and attachment [27,28], indicating that scaffolds must be engineered in a way which favors the type of cells and tissues they intend to supplant [11]. Here, we set out to examine various configurations of pore geometry, pore size, and pore configuration to determine the combination providing the highest mechanical properties, while keeping in mind that there is a need for adequate cell proliferation and osteogenesis. We also compared two printing orientations (fiber alignment) and evaluated their impact on *scaffold rigidity*. This parameter was also tested by Zhang et al., who found that when the filaments are aligned with the direction of

the compressive loading, they can better sustain the mechanical load than when they are perpendicular [26]. The design parameters were chosen following a literature review focusing on scaffold design on rigidity and cell differentiation. In that review, we found a recurrence of square pore shapes of size ranging from 0.4 cm to 1.0 cm, with a *porosity* varying from 20% to 84% [1,20,25,26,29–32]. A bone graft substitute in combination with drug carriers can locally deliver anti-cancer therapeutics [33], which could prevent cancer recurrence. Therefore, our base scaffold model is a hollow-centered cylinder, allowing the addition of a drug-infused material.

2. Materials and Methods

The methodology includes five main steps: (1) CAD design of multiple scaffold models; (2) finite element simulations of compressive testing on the models, which allowed discriminating models to print; (3) 3D printing of retained models; (4) experimental compression testing of printed models; (5) data analysis to retrieve *scaffold rigidity* and determine the "best model" for bone replacement.

2.1. CAD Design

A total of 27 scaffolds were designed starting from a cylindrical base model of 10 mm in height, with outer and inner diameters of 10 mm and 4 mm, respectively. Three design parameters were investigated: pore distribution (crosswise, lengthwise, and eccentric), pore shape (circular, square, and triangular), and pore size (equivalent surface areas of 0.25, 0.56, and 1 mm²). The pores' diameters/sizes were adjusted so that each shape corresponded to the same surface area. Figure 1 shows multiple views of the three different pore distributions for a scaffold with large circular pores. The design was made using CATIA V5 (Dassault Systèmes, SolidWorks Corporation; Waltham, MA, USA) while considering the resolution of the FDM printer used (Monoprice MP Select Mini v2 (Monoprice Inc; Brea, CA, USA)). Hence, the space between pores and between the outer edge of a pore and the base of the scaffold was set to a minimum of 0.5 mm to ensure proper printing. The CAD models were converted to STL files and sliced using an Ultimaker Cura 4.6.1 (Ultimaker B.V.; Utrecht, The Netherlands) to prepare the G-code necessary for printing.



Figure 1. Top view (left column), cross sectional view (middle column), and isometric view (right column) of scaffolds with different pore distributions. Pore distributions are identified in yellow in the corresponding line.

Table 1 details the resulting *porosity* of each scaffold model. The *porosity* was calculated following Equation (1). To do so, we used the Measuring Inertia command in CATIA to get the scaffold's volume and the *volume of the cylinder* without any pores.

$$Porosity (\%) = \frac{(Volume of the cylinder - Volume of the scaffold) (cm3)}{Volume of the scaffold (cm3)} \times 100 \%$$
(1)

Pore Size (Surface Area)	Pore Shape	Crosswise	Lengthwise	Eccentric
Small (0.25 mm ²)	Square	15	21	16
	Circular	15	21	16
	Triangular	16	21	16
Medium (0.56 mm ²)	Square	24	26	29
	Circular	25	26	30
	Triangular	25	26	31
Large (1 mm ²)	Square	36	37	49
	Circular	35	37	47
	Triangular	35	36	52

Table 1. The *porosity* in percentage (%) for each scaffold model.

2.2. Finite Element Simulations of Compression Testing

Simulated mechanical testing of a compressive load was performed on each model using a finite element analysis (FEA) software, ANSYS Workbench 2019 R2 (ANSYS; Canonsburg, PA, USA). To do so, adequate meshing of the 3D models was required. However, not all pore distributions with a triangular pore shape could be meshed because some had sharp edges. A convergence study was done to determine the optimal meshing sizes for each scaffold size (small, medium, and large) using the square crosswise model, to give fast yet precise calculations. Scaffolds were meshed according to 4 different sections: inner/outer edge of the base, base surface area, inside the pores, and everything else. The mesh sizes were tested from coarse to fine, calculating a maximum normal *stress*. A mesh size was chosen when the next iteration took a significantly longer time to compute, while having little difference in resulting *stress*. For the simulation, the scaffold material was PLA modeled as linear elastic with a density of 1.24 g/cm³ and a material rigidity of 1000 MPa, which was established by the calibration of previously tested sample data. The resulting *scaffold rigidity*, which is different from material rigidity, was obtained from simulations of a compressive loading to 15% *strain* at a 0.05 mm/s *displacement* rate.

2.3. Printing and Experimental Compression Testing

As already specified, printing was carried out using the Monoprice MP Select Mini v2. Following the finite element results, the models resulting in high scaffold rigidities were 3D printed (n = 5/model) in 1.75 mm PLA (MakerGeeks; Springfield, MO, USA) along two orientations: 0° (the cylinder is sitting on its base) and 90° (the cylinder is laying on its side, flat on the print bed, with enabled support in the Cura slicer settings). Printing orientation is therefore the 4th investigated parameter. At this point, all models with a triangular pore shape were excluded because convergence studies were not conclusive. A total of 120 scaffolds were printed with a 0.3 mm nozzle diameter, 0.2 mm layer height, and 100% infill—60 specimens with a 0° orientation and 60 with a 90° orientation, each group composed of 12 different models printed 5 times. The 12 models can be separated in 2 subgroups, crosswise and lengthwise pore orientations. In each of those groups, we can find square and circular pores in 3 sizes (surface area), that is, small (0.25 mm²), medium (0.56 mm²), and large (1 mm²). The scaffolds were printed one by one on a 50 °C bed with

a 210 °C printing temperature at a 15 mm/s speed. Printed scaffolds were further tested along the vertical cylinder axis on MTS Insight Electromechanical Testing Systems (MTS; 14,000 Technology Dr. Eden Prairie, MN, USA). The machine was programmed to perform the exact same test as the simulations, which was a compressive load at a *displacement* of 0.05 mm/s for a 15% *strain*.

2.4. Analysis

2.4.1. Simulations

To extract the data to obtain the *scaffold rigidity* of each model, the f and *force* (N) were respectively normalized to *strain* (%) and *stress* (MPa) with respect to their sample *initial height* (mm) and base area (mm²), using Equations (2) and (3):

$$Strain (\%) = \frac{Displacement (mm)}{Initial height (mm)} \times 100 \%$$
(2)

$$Stress (MPa) = \frac{Force (N)}{Area of the base (mm2)}$$
(3)

The *area of the base* is 65.97 mm² for each model. It corresponds to the surface area of the top view of the cylinder (resembling a donut shape) and it excludes the pores, which we considered negligible for this measure. The *scaffold rigidity* was then obtained from the corresponding *stress-strain* graph, following Equation (4):

$$Scaffold \ rigidity \ (MPa) = \frac{Stress(MPa)}{Strain \ (mm/mm)}$$
(4)

2.4.2. Experimental Testing

Prior to mechanical compression testing, the *initial height* and diameter of each sample was first measured with a micrometer (precision of 0.05 mm) to define the exact *strain*, and the same process as for the simulations was done using Equations (1) and (2). Then, a *stress-strain* graph was produced using Microsoft Excel. A visual analysis made it possible to deduce the points associated with the beginning and the end of the slope corresponding to the elastic *strain*.

2.4.3. Statistical Analyses

T-tests were performed to determine the statistical significance of the mean rigidities of scaffolds for different configurations retrieved from experimental testing. Four statistical tests were carried out. For scaffolds with square pores, crosswise pore orientation was tested against lengthwise pore orientation for all pore sizes and both printing orientations (test 1). The same analysis was done for scaffolds with circular pores (test 2). Square and circular pores were tested against each other with a crosswise pore orientation, for every pore size and printing orientation (test 3). The same was done with lengthwise pore orientation (test 4).

3. Results

3.1. Results from Simulations

The following Table 2 compares the scaffold rigidities for each model using finite element simulations.

Pore Size (Surface Area)	Pore Shape	Crosswise	Lengthwise	Eccentric	
Small (0.25 mm ²)	Square	802 MPa	800 MPa	768 MPa	
	Circular	797 MPa	808 MPa	763 MPa	
	Triangular	641 MPa	Not converging	Not converging	
Medium (0.56 mm ²)	Square	758 MPa	799 MPa	710 MPa	
	Circular	773 MPa	804 MPa	694 MPa	
	Triangular	606 MPa	675 MPa	Not converging	
Large (1 mm ²)	Square	725 MPa	782 MPa	618 MPa	
	Circular	726 MPa	786 MPa	618 MPa	
	Triangular	558 MPa	653 MPa	Not converging	

Table 2. Rigidities in MPa for each model with their simulated compression load (FEA).

The square and circular pore shapes gave similar results for both crosswise and lengthwise configuration, with slightly higher rigidities for the circular pore shape and lengthwise pore distribution. The rigidities with the eccentric distribution were smaller than the two others, but also similar for square and circular pore shapes. The triangular pore shape gave results 19% to 23% smaller than its counterparts. Additionally, these models could not converge for four out of nine simulations. Therefore, models with a triangular pore shape and eccentric configuration were excluded for the remaining of the study. Regarding pore size, scaffolds with smaller pores—and smaller *porosity*, as seen in Table 1—resulted in higher rigidities than the ones with medium pores and larger pores. Table 2 indicates the simulated rigidity for each geometry, size and orientation. Triangular shaped pores could not be calculated and were hence removed from the remainder of the study.

3.2. *Results from Experimental Testing* 3.2.1. Printing

Figure 2 shows the two printing orientations along with two printed scaffolds.



Figure 2. (a) Printing orientations (represented by the small crosswise model with circular pores); (b) printed scaffolds printed with 0° (left) and 90° (right) orientation.

3.2.2. Experimental Testing

We can observe in Figure 3 that the curves of models printed with a 0° orientation are similar to typical PLA *stress-strain* curves [34], whereas a 90° orientation is not. The 90° sample slope starts to get steeper much later than the 0° sample slope, which could be explained by faults induced by the printing orientation: the base surface is less smooth when printed sideways (90°), as we can observe on Figure 2b. Therefore, there are some physical adjustments at the interface between the compressive device and the scaffold, which may induce some surface imperfections, explaining the prominent toe region of the

curve. Mean scaffold rigidities for each printed configuration are presented in Figure 4. Scaffolds printed with a 90° orientation provided much higher rigidities than the ones printed with a 0° orientation, all models combined. As expected from the simulations, scaffolds with smaller pores and smaller *porosity* presented higher rigidities. However, experimental testing showed that crosswise models had higher rigidities than lengthwise models, which can be confirmed with the statistical analysis. The complete experimental data can be found in Supplementary Materials.



Figure 3. Representative *stress-strain* curves obtained by experimental testing for each model and printing orientation. Experiments were performed, n = 5.





The mean yield strength for each printed configuration is presented in Figure 5. Yield strength corresponds to the *stress* at which the deformation is no longer considered reversible. This *stress* value should never be exceeded. We can see from Figure 5 that those values are much higher for scaffolds printed with a 90° orientation, allowing for higher stresses.



Figure 5. (a) Mean yield strength of square pore scaffolds; (b) mean yield strength of circular pore scaffolds. Error bars represent \pm standard deviation, n = 5.

Table 3 summarizes every result obtained for square and circular pore shapes, from finite element to experimental testing.

Table 3. Summary table (in MPa) of mean rigidities from FEA, mean rigidities from experimental testing, and yield strengths from experimental testing.

		Crosswise					Lengthwise				
Pore Size (Surface Area)	Pore Shape										
			Exp.	Exp.	Yield	Yield		Exp.	Exp.	Yield	Yield
		FEA	Res.	Res.	Str 00°	Str.	FEA	Res.	Res.	Str.	Str.
			90 °	0 °	511. 90	0 °		90 °	0 °	90 °	0 °
Small	Square	802	949	519	44	30	800	743	367	39	20
(0.25 mm ²)	Circular	797	961	515	42	32	808	749	376	36	21
Medium	Square	758	783	424	34	26	799	748	378	35	23
(0.56 mm ²)	Circular	773	810	501	33	24	804	772	525	35	22
Large	Square	725	659	480	27	21	782	753	449	33	19
(1 mm^2)	Circular	726	654	464	24	19	786	649	465	28	19

3.3. Comparative Analysis of Rigidity and Yield Strength

The complete statistical analyses can be found in Supplementary Materials. For the square pore models, we found the mean rigidities to be statistically significant (p < 0.05) between crosswise and lengthwise pore orientations for small pores (for both printing orientations), medium pores (for 0° printing orientation), and large pores (for 90° printing orientation). This means that the square pore scaffold with the highest rigidity is the one with small pores and a crosswise pore orientation. For the circular pore scaffolds, we found the mean rigidities to be statistically significant (p < 0.05) between the two pore orientations only for small pores (for both printing orientations). This means that the

circular pore scaffold with the highest rigidity is the one with small pores and a crosswise pore orientation. When testing the two pore shapes against each other with a crosswise pore orientation, and then with a lengthwise pore orientation, we only found a significant

pore orientation, and then with a lengthwise pore orientation, we only found a significant (p < 0.05) difference between mean rigidities for medium scaffolds with lengthwise pore orientation for a 0° printing orientation (meaning that circular pore scaffolds have higher rigidity for this model).

Differences between mean yield strengths were significant. For the square pore shape, when comparing crosswise against lengthwise pore distribution, we found the mean yield strength to be statistically significant (p < 0.05) for all models except for medium–90° scaffolds. This means that crosswise models permit a much higher *strain* before plastic deformation than their lengthwise counterparts. The results are similar for scaffolds with circular pores; only the large–0° and large–90° models had yield strengths that were not statistically significant. When testing the two pore shapes against each other with a crosswise pore orientation, we found that circular-pore-shaped models exhibited higher yield strengths for medium–90° and large–0° scaffolds than models with square pores (p < 0.05). A similar situation was observed with the lengthwise pore orientation, for small–0°, medium–0°, and large–90° models.

4. Discussion

In this study, different parameters, namely pore shape, pore size, and distribution as well as printing fiber orientation (raster angle), were assessed for the design of 3D-printed scaffolds to be used as bone substitutes. The most optimal model was then determined in terms of highest *scaffold rigidity* and highest yield strength. Based on these criteria, the small circular pore sized scaffold arranged in a crosswise orientation and printed with a 90° fiber orientation was found to yield the best results.

Printing orientation is the most influential parameter in terms of mechanical properties. Indeed, Figure 4 and Table 3 show that, for both crosswise and lengthwise pore distributions, scaffolds printed with a 90° orientation provided almost twice the rigidity of their 0° counterparts. This result was also observed in other studies. When the filaments of the printed scaffold are aligned with the direction of the compressive load, the scaffold provides better mechanical support [26]. The same was shown for scaffolds under tensile loadings, where rigidities were found to be much higher when the filaments were aligned with the applied tension than when the raster angle was of 0° or 45° [35]. Many studies aim at assessing the relationship between raster angle and isotropic and anisotropic behaviors of scaffolds to provide optimal mechanics [26,30,31]. Aligned pores provide higher rigidities than pores with varying raster angle patterns [36], and designs with orthogonal pores provide higher rigidities than designs with isometric pores (which correspond to triangular pores in our experiment) [37,38]. These studies support our findings, where rigidities obtained from the finite element analysis (FEA) were almost identical for circular and square pore shapes, whereas triangular pore shapes gave lower mechanical results and proved problematic in terms of convergence. A comparison of experimental mechanical results also showed no significant difference in terms of rigidity between circular and square pore shapes. This could be explained by the fact that pore sizes of different shapes were chosen to provide equivalent surface area, hence reducing the impact of pore shapes. There is, however, a significant difference when it comes to yield strength: scaffolds with circular pores allowed higher deformation before becoming permanent than scaffolds with square pores. For a bone replacement scaffold, a high yield strength value is desired [11].

Pore sizes have a notable effect on mechanical properties. Indeed, FEA predicted that smaller pore sizes would yield higher rigidities compared to their medium and large counterparts, and the experimental results clearly support this finding. *Scaffold rigidity* was found to be inversely proportional to *porosity*, as shown in Table 1. For example, for the crosswise model with circular pores, the *porosity* was 15%, 25%, and 35%, respectively, for small, medium, and large sizes. This indicates that scaffolds with smaller pores have more material deposited by the printer, and therefore, higher rigidity, as expected [1,20,26]. This

result was also corroborated by the experimental testing. However, we did not measure the *porosity* of the experimental printed scaffolds. It has been demonstrated that *porosity* is often much lower than expected, due to excess material extrusion during printing [25]; it is expected that the 3D printing process produces pores smaller than designed [18]. While other studies showed that scaffolds made with polymers such as PCL or PPF (polypropylene fumarate) provided adequate rigidities [26,39,40], our data are in line with several other studies indicating that PLA provides higher mechanical properties and could therefore be suitable for bone replacement [2,20,29].

Finite element analysis (FEA) can be used to quickly and accurately compare the mechanical strength of various scaffold models. In this study, mechanical parameters obtained from FEA closely matched experimental results for scaffolds printed with a 90° printing orientation. While the corresponding rigidities did not exactly match, they were comparable against other designs and provide a quick and reliable comparison. However, the simulated models were limited by a few factors, namely the definition of the material properties and the required calibration. Indeed, the PLA material was defined as linear elastic and its rigidity was found from a prior calibration with results from our lab. FE simulations can allow relative comparisons of scaffold models, integrating multiple design iterations with little to no costs [2].

Although our designs provide good mechanical properties, it does not mean that they provide great biocompatibility as well. Previous studies have shown that smaller pore sizes produce higher rigidities [1,20,26,31], while medium to large pore sizes encourage bioactivity [1,20]. It was previously mentioned that our 3D-printed scaffolds should not only display high rigidity (approaching that of bone), but also an adequate capacity of promoting vascularization, osteoinduction, osteoconduction, and general tissue repair. In fact, 3D-printed scaffolds poorly promote bone regeneration alone [13]. Growth factors have also been frequently used (BMP2, TGFß, etc.) in that matter with promising pre-clinical and clinical results [41,42]. They can improve osteogenesis and vascularization [21,43] as well as bioactivity [2]. However, caution is often exercised since growth factor delivery can promote cancer and even cause death in some cases [44]. There is also a risk of bone formation inside soft tissues [11]. Mesenchymal stem cell delivery has also been used to treat bone defects, with ample data pointing to their anti-inflammatory properties rather than their regenerative capacity [45]. To circumvent this issue, many researchers are focused on developing advanced materials (composites of polymer, ceramics, metals, etc.), which can alone promote bone repair. Yan et al. found that deferoxamine-loaded PCL scaffolds presented greater vascularization and new bone integration in rat models than pure or aminated PCL [30]. Jeong et al. have found that HA/ß-TCP composite scaffolds revealed superior cell proliferation than their control models in in vitro assays 28 June 2022 11:26:00 AM. Previous studies have shown that composite polymer-mineral, 3D-printed scaffolds do integrate well and promote bone regeneration in bone defects in vivo [1,9,42,46,47]. Using our approach of optimizing pore size and geometry, perhaps a further improvement in tissue regeneration can be achieved. In this sense, further investigations should be done to define the most promising combination of materials (and geometrical parameters).

While several previous studies, including many of our own, have shown compelling data toward the use of 3D-printed polymeric/composite scaffolds for improved bone defect repair, there remain several limitations to this approach. Firstly, biocompatibility remains a concern. Regardless of the type of scaffold generated through 3D printing (metallic, polymeric, ceramic), fibrous capsule formation remains a challenge toward osteogenic integration [48]. Another key challenge and limitation, particularly important for this study, is the resolution of thermoplastic 3D-printers. Due to their nature of heating and liquifying the polymers, accurately and reproducibly generating a small pore size is difficult below 50 μ m. Indeed, scaffolds can be modelled using CAD software to have quite a small pore size; however, these cannot be translated to reality using our current methods. Metal and stereolithography 3D-printers can make smaller pore sizes, but issues with high costs or

biocompatibility are limiting. Future work should focus on lowering the cost of metal printers or generating improved bioprinted scaffolds with increased mechanical strength.

In conclusion, this study explored printing orientation and pore size, which were found to be the most influential design parameters on rigidity from both our FE mechanical strength analysis and our experimental data obtained for the printed and tested 3D-printed scaffolds. Since the highest rigidity is desired for bone repair applications, further investigation could be done considering more variations of these parameters to further optimize the designs. Our experiment also showed that finite element analysis can be used to reliably estimate compressive mechanical behaviors of scaffolds printed with a 90° orientation. The developed design methodology should accelerate the identification of effective scaffolds for future in vitro and in vivo studies.

Supplementary Materials: The following supporting information can be downloaded at: https: //www.mdpi.com/article/10.3390/surgeries3030018/s1, Table S1: Rigidity in MPa for each combination; Table S2: Yield strength (MPa) for each combination; Table S3: Statistical analyses comparing rigidities between models; Table S4: Statistical analyses comparing yield strengths between models.

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