



Cable-Driven Parallel Robots and Their Applications

Guest Editor:

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Message from the Guest Editor

Dear Colleagues,

Cable-Driven Parallel Robots (CDPR) can work in large spaces and possess relatively high accuracy and stability, providing higher versatility in large spaces without the need for massive support systems. In recent years, numerous CDPRs have been conceived, tested and developed in different sectors and industries such as agriculture, construction and manufacturing. Moreover, novel controlling and positioning algorithms have permitted higher performance capabilities of CDPR, as well as the end-effectors that perform tasks. The Special Issue is seeking articles that outline the latest developments in these areas.

Dr. Kepa Iturralde
Guest Editor

