



Object Detection and Recognition for Intelligent Robotic Systems

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Deadline for manuscript submissions:

closed (20 July 2023)

Message from the Guest Editors

Dear Colleagues,

Effective perception is crucial for the interaction between high-performance robots and their environment. This Special Issue aims to present new ideas and experimental results in the field of high-performance sensing and interpretation, from theory, and the development of sensing devices and recognition algorithms to various civilian, medical, and military applications. Potential applications of the techniques include autonomous driving, smart manufacturing systems, medical 3D imaging for tumor management, unmanned aerial vehicles (UAV), smart missiles, and robots. Advanced techniques, such as acoustic/infrared/tactile imaging, artificial intelligence, machine learning, and deep learning, which are beneficial for achieving highly reliable object detection and recognition are also topics of interest.

Keywords

- scene analysis
- object detection
- object recognition
- visual navigation
- visual servoing
- event-based vision
- robotic manipulation
- unmanned aerial vehicle (UAV)
- acoustic imaging
- tactile imaging





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Message from the Editor-in-Chief

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