



## Challenges in the Guidance, Navigation and Control of Autonomous and Transport Vehicles

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### Message from the Guest Editors

Dear Colleagues,

In recent years, transportation systems have considerably evolved in terms of safety, resulting in increased demands on autonomy, performance and energy efficiency. Some of the main research challenges to meet these requirements are rooted in the development of safe and efficient guidance, navigation and control (GNC) systems for different types of transportation vehicles, ranging from mobile robots to automotive and aerospace vehicles. Increasingly autonomous vehicles will require advanced sense-and-avoid technologies and algorithms, the ability to autonomously handle constraints and recover from faults, and an efficient combination of manned and automated control systems. Optimal and robust navigation and control systems are required to meet the challenging performance and energy requirements of the modern day. System identification and adaptive control methods are also needed to allow ground and air vehicles to adapt their control algorithms to changes in model parameters. This Special Issue will bring together papers which describe recent advances in guidance, navigation and control systems for a large range of transportation and autonomous vehicles.





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## Message from the Editor-in-Chief

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