



Robotics and Vibration Mechanics

Guest Editors:

**Prof. Dr. Alessandro
Gasparetto**

Polytechnic Department of
Engineering and Architecture,
University of Udine, 33100 Udine,
Italy

Dr. Lorenzo Scalera

Polytechnic Department of
Engineering and Architecture,
University of Udine, Udine, Italy

Dr. Ilaria Palomba

Faculty of Science and
Technology, Free University of
Bozen-Bolzano, 39100 Bolzano,
Italy

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Message from the Guest Editors

The growing interest and development of collaborative and lightweight robots and mechanisms have led to the study and investigation of several aspects of both robotic systems and mechanical vibrations strictly related between them. Indeed, compliance and flexibility may lead to undesired mechanical vibrations, especially when lightweight systems performing high-speed operations are considered. Therefore, a proper structural design, trajectory planning, and control architecture are required to correctly steer the system during operation.

This Special Issue will bring researchers together to present recent advances and technologies in the fields of robotics and vibration mechanics. Suitable topics include, but are not limited to, the following:

- Robotics and autonomous systems
- Mechanical vibrations and noise
- Kinematic and dynamic modeling of robotic systems
- Path and trajectory planning
- Automatic control systems
- Flexible multibody systems
- Collaborative robotics
- Design and optimization of robotic and mechatronic systems
- Mechanisms design
- Manufacturing systems





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Editor-in-Chief

Prof. Dr. Giulio Nicola Cerullo
Dipartimento di Fisica,
Politecnico di Milano, Piazza L.
da Vinci 32, 20133 Milano, Italy

Message from the Editor-in-Chief

As the world of science becomes ever more specialized, researchers may lose themselves in the deep forest of the ever increasing number of subfields being created. This open access journal Applied Sciences has been started to link these subfields, so researchers can cut through the forest and see the surrounding, or quite distant fields and subfields to help develop his/her own research even further with the aid of this multi-dimensional network.

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MDPI, Grosspeteranlage 5
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