



Exoskeleton Robots and Human–Robot Interaction Technologies

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Deadline for manuscript
submissions:

closed (28 February 2023)

Message from the Guest Editors

Dear Colleagues,

The main aim of this Special Issue is to focus on exoskeleton robots and human–robot interaction technologies, providing a platform for the discussion of the major research challenges and achievements in this field. Submissions to this Special Issue on “Exoskeleton Robots and Human Robot Interaction Technologies” are solicited to represent a snapshot of the field’s development by covering a range of topics that include, but are not limited to, system and algorithm development, theoretical, engineering, computational simulation, and the experimental and clinical application of robots in the following areas:

- Exoskeleton robots;
- Wearable robot systems;
- Rehabilitation robots;
- Human assistance robots;
- Walking support machines;
- Human–robot interaction;
- Intelligent prosthetics;
- Robotics for the elderly;
- Human gait and balance analysis;
- The diagnosis of gait disorders;
- Neuroscience-based physical diagnosis;
- Augmentative devices;
- Wearable sensors;
- Ergonomics.





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Message from the Editor-in-Chief

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