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Recent Advances in Modelling, Control and Navigation of Ground and Aerial Robots

Guest Editors:

**Prof. Dr. Andon Venelinov
Topalov**

Control Systems Department,
Faculty of Electronics and
Automation, Technical University
of Sofia, Plovdiv Branch, 4000
Plovdiv, Bulgaria

Dr. Sevil Ahmed

Control Systems Department,
Faculty of Electronics and
Automation, Technical University
of Sofia, Plovdiv Branch, 4000
Plovdiv, Bulgaria

Deadline for manuscript
submissions:

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Message from the Guest Editors

Papers presenting different approaches from nonlinear control theory applied to trajectory tracking control and navigation of robots, as well as various robot control systems, are welcome.

- robotics, robot manipulators
- mobile robots
- mobile manipulators
- unmanned aerial vehicles
- collective robotics
- robot control and navigation
- backstepping control
- sliding mode control
- computed torque control
- Lyapunov-based nonlinear feedback control
- intelligent control

I/We look forward to receiving your contributions.



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Special Issue



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Editor-in-Chief

Prof. Dr. Flavio Canavero

Department of Electronics and
Telecommunications,
Politecnico di Torino, 10129
Torino, Italy

Message from the Editor-in-Chief

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Electronics Editorial Office
MDPI, Grosspeteranlage 5
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