



Force and Tactile Sensing for Robots

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Message from the Guest Editors

This Special Issue gives an opportunity to researchers from robotics as well as from the discipline of material and technology development to get an insight into the excellent work done in the respective fields. The topics of interest include, but are not limited to the following:

- Tactile Sensing Technologies
- Tactile Objects' Perception
- Tactile Objects' Interaction, Grasp, and Manipulation
- Tactile-based Human–Robot Interaction
- Tactile-Based Human–Robot Communication

Welcome to contribute.

Deadline for manuscript submissions:

closed (30 June 2021)





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Message from the Editor-in-Chief

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