



## Autonomous Navigation of Unmanned Maritime Vehicles

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### Message from the Guest Editors

Dear Colleagues,

This Special Issue aims to address issues involved in the analysis, design, and implementation of Autonomous Navigation of Unmanned Maritime Vehicles. This includes:

1. Intelligent agents and multi-agent systems;
2. Intelligent control of ships and ocean vehicles;
3. Intelligent perception and autonomous control of unmanned systems;
4. Multi-agent systems and intelligent transportation network control;
5. Intelligent control and detection technology;
6. Autonomous navigation control of surface or underwater vehicles;
7. Nonlinear control;
8. Unmanned systems;
9. Autonomous control of robots;
10. Information collection of ships or unmanned craft;
11. Ship or unmanned craft control technology;
12. Image processing techniques;
13. Field verification of unmanned systems;
14. Development trend of unmanned systems in the future.





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## Editor-in-Chief

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## Message from the Editor-in-Chief

*Electronics* is a multidisciplinary journal designed to appeal to a diverse audience of research scientists, practitioners, and developers in academia and industry. The journal is devoted to fast publication of latest technological breakthroughs, cutting-edge developments, and timely reviews of current and emerging technologies related to the broad field of electronics. Experimental and theoretical results are published as regular peer-reviewed articles or as articles within Special Issues guest-edited by leading experts in selected topics of interest.

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