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Robot Motion Planning

Guest Editors:

Dr. Adham Atyabi

Department of Computer Science, University of Colorado Springs, Colorado Springs, CO 80918, USA

Dr. Mohd Nadhir Ab Wahab

School of Computer Sciences, Universiti Sains Malaysia, Minden 11800, Malaysia

Dr. Somaiyeh MahmoudZadeh

School of Information Technology, Faculty of Science Engineering & Built Environment, Deakin University, Geelong, VIC 3220, Australia

Deadline for manuscript submissions: closed (30 November 2023)

Message from the Guest Editors

Relevant areas covered in this Special Issue include (but are not limited to):

- Planning and decision making;
- Multi-agent motion planning;
- Path formation (formation planning);
- Modular, hybrid, and reconfigurable systems for motion planning;
- Bioinspired path/route planning;
- Modern artificial intelligence technologies for robot path planning;
- Single- and multi-robot trajectory tracking;
- Vision, sensing, kinematics, and dynamics;
- Novel system design for mapping and navigation;
- Situational awareness and responsiveness.

Applications of interest include:

- Unmanned ground, aerial, and surface vehicles (UGVs, UAVs, USVs);
- Autonomous underwater vehicles (AUVs);
- Industrial and factory robots;
- Healthcare, medical, surgical, and assistive robotics;
- Service robotics;
- Soft robotics;
- Multi-agent systems.





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Editor-in-Chief

Prof. Dr. Flavio Canavero

Department of Electronics and Telecommunications, Politecnico di Torino, 10129 Torino, Italy

Message from the Editor-in-Chief

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