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## 3D Indoor Mapping and Modelling

Guest Editors:

**Dr. Lucía Díaz-Vilariño**

Applied Geotechnologies  
Research Group, Campus  
Universitario de Vigo,  
Universidade de Vigo, CINETEX,  
As Lagoas, Marcosende, 36310  
Vigo, Spain

**Dr. Abdoulaye Abou Diakité**

Geospatial Research Innovation  
and Development (GRID) group,  
Faculty of Built Environment,  
University of New South Wales,  
Sydney, Australia

**Dr. Shayan Nikoohemat**

Department of Earth Observation  
Science, University of Twente,  
7522 NB Enschede, The  
Netherlands

### Message from the Guest Editors

In the last few years, there has been intense research activity towards the mapping and automated modelling of indoor environments. Updated and detailed indoor models are being increasingly demanded for a variety of applications, such as building management, indoor navigation, location-based services, and emergency responses. However, existing interior models are often not up-to-date, and consequently, they do not represent the as-is condition of the scene.

LiDAR scanning and photogrammetry have been revealed to be suitable techniques to collect data at a large scale, especially when dealing with portable and mobile acquisition systems. Nevertheless, point clouds, which constitute massive and unstructured data, need to be efficiently processed in a way that useful information for the applications they intend to serve is extracted.

Deadline for manuscript  
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### Prof. Dr. Wolfgang Kainz

Cartography and Geographic  
Information Science, Department  
of Geography and Regional  
Research, University of Vienna,  
Universitätsstr. 7, A-1010 Vienna,  
Austria

## Message from the Editor-in-Chief

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*ISPRS International Journal of Geo-Information* Editorial Office  
MDPI, Grosspeteranlage 5  
4052 Basel, Switzerland

Tel: +41 61 683 77 34  
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