



Control Theory and Applications in Marine Autonomous Vehicles

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Message from the Guest Editors

Dear Colleagues,

The control of marine autonomous vehicles has been an exciting subfield of marine science and engineering. Some significant theoretical designs and applications continue to be developed by numerous researchers and industrial engineers, e.g., path-following control, dynamic positioning control, obstacle avoidance guidance, formation control, etc. This work has generated significant progress to facilitate the application of related theoretical design in engineering practice. This Special Issue of the *Journal of Marine Science and Engineering* aims to present meaningful results concerning the topic “Control Theory and Applications of Marine Autonomous Vehicles”.

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Message from the Editor-in-Chief

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