



Heterogeneity in Intelligent Mobile Robots and Systems

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Message from the Guest Editors

Dear Colleagues,

This Special Issue will present recent advances in intelligent systems and mobile robots with a specific focus on the heterogeneity aspects in the system. Some of the areas of interest include biological systems exploiting heterogeneity, nature-inspired methods in heterogeneous mobile robots, cooperative communication, collaborative control, mission planning for heterogeneous systems, object manipulation using heterogeneity, combined learning from heterogeneous agents, and heterogeneous multirobot systems.





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Message from the Editor-in-Chief

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There are, in addition, unique features of this journal: Manuscripts regarding research proposals and research ideas will be particularly welcomed; Electronic files or software regarding the full details of the calculation and experimental procedure - if unable to be published in a normal way can be deposited as supplementary material.

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