



## **New Adaptive and Learning Control System Design for Robotic Manipulators**

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Deadline for manuscript submissions:

**closed (30 April 2018)**

### **Message from the Guest Editors**

Dear Colleagues,

Adaptive control for robotic manipulators have been developed in the last decade, and learning control design is still in its early development stages. Control system design is a critical step for robotic manipulator systems and their later development and applications. This Special Issue aims to bring researchers together to present the recent and latest advances and technologies in the field of adaptive and learning control system design for robotic manipulators in order to further summarize and improve the methodologies on this topic. Suitable topics include, but are not limited to, the following:

- Adaptive control design for robotics
- Model reference adaptive control design
- Learning control design for robotics
- Intelligent control system development for robotics
- Advanced control system design for manufacturing
- This call invites both theoretical and empirical studies on this topic.

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*Guest Editors*





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