

Indexed in: PubMed



an Open Access Journal by MDPI

Medical Micro/Nanorobots

Guest Editors:

Prof. Dr. Tianlong Li

State Key Laboratory of Robotics and System, Harbin Institute of Technology, Harbin 150001, China

Prof. Dr. Zhiguang Wu

School of Medicine and Health, Harbin Institute of Technology, Harbin 150001, China

Deadline for manuscript submissions:

closed (30 June 2023)

Message from the Guest Editors

Dear Colleagues,

Medical micro/nanorobots that can be navigated into hard-to-reach tissues are promising candidates for the application in biomedicine and micromanipulation. Considerable efforts have been devoted to various aspects of medical micro/nanorobots, including fabrication, propulsion, cargo loading, transportation, and targeted release to achieve therapeutic functions. Various functionalized medical micro/nanorobots have been developed for biological tasks or work in superficial tissues and locations with relatively easier access routes (e.g., the gastrointestinal tract and peritoneal cavity). Minimally invasive administration and deployment of medical microrobots to tissues in deeper locations in the body remain grand challenges toward practical medical applications. Accordingly, this Special Issue seeks to showcase research papers, short communications, and review articles that focus on novel methodological developments in medical microrobots, i.e., novel fabrication technology, functional performance and the breakthrough of biological barriers.

We look forward to receiving your submissions!

Prof. Dr. Tianlong Li Dr. Zhiguang Wu Guest Editors













an Open Access Journal by MDPI

Editor-in-Chief

Prof. Dr. Ai-Qun Liu

1. Department of Electrical and Electronic Engineering, The Hong Kong Polytechnic University, Hong Kong, China 2. School of Electrical and Electronic Engineering, Nanyang Technological University, Singapore 639798, Singapore

Message from the Editor-in-Chief

You are invited to contribute research articles or comprehensive reviews for consideration and publication in *Micromachines* (ISSN 2072-666X). *Micromachines* is published in the open access format. Research articles, reviews and other contents are released on the internet immediately after acceptance. The scientific community and the general public have unlimited free access to the content as soon as it is published. As an open access journal, *Micromachines* is supported by the authors or their institutes by payment of article processing charges (APC) for accepted papers. We are pleased to welcome you as our authors.

Author Benefits

Open Access: free for readers, with article processing charges (APC) paid by authors or their institutions.

 $\textbf{High Visibility:} \ indexed \ within \ Scopus, \ SCIE \ (Web \ of \ Science), \ PubMed,$

PMC, Ei Compendex, dblp, and other databases.

Journal Rank: JCR - Q2 (Physics, Applied) / CiteScore - Q2 (Mechanical Engineering)

Contact Us