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Laser Scanning and Point Cloud Processing

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Message from the Guest Editors

Dear Colleagues,

Accurate 3D digital representations of the natural and built environments play an important role in a wide range of applications. Laser scanning is the principal technology for efficient 3D data capture in the form of point clouds. Point clouds can be generated from laser scanners or derived from image matching techniques, although the focus in this Special Issue is on laser scanner point clouds. However, a point is just a point. It is the context that delivers the information on the object behind the point. Research challenges in the field of laser scanning and point cloud processing range from calibration, fusion, interpretation, and modelling, to efficient information extraction and visualization topics. The scope of this Special Issue is therefore rather broad in the sense that we would like to include indoor, mobile, and airborne laser scanners, in combination with point cloud processing algorithms, for a broad range of applications.

For more information:

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Message from the Editor-in-Chief

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