



Sensing and Perception in Human-Robot Interaction

Guest Editor:

Dr. Rocco Antonio Romeo

Istituto Italiano di Tecnologia,
Center for Robotics and
Intelligent Systems, Via San
Quirico19d, 16163 Genoa, Italy

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Message from the Guest Editor

Dear Colleagues,

The combination of human cognition with the high effectiveness and precision of collaborative robots, namely cobots, leads HRI to outperform traditional robot behavior. A key feature boosting the success of HRI is the instrumentation of cobots with various types of sensors, such as force, torque, tactile, motion, proximity, and vision sensors. The integration of sensors in collaborative robotics setups, together with robust algorithms that make use of different sensory inputs, will constantly increase the cognitive capabilities of cobots, resulting in a significant improvement in HRIs.

The present Special Issue aims to collect articles showing new sensing modalities and algorithms in the execution of HRI. Particular attention is given to how sensors are integrated into a collaborative robotic setup, as well as to perception modalities, data processing methods, and consequent decision-making processes. The topics of interest include (without being limited to) the following:

- Sensor integration in HRI;
- Sensing applications in HRI;
- Safety in HRI;
- Hardware design of cobots;
- Instrumented end effectors of cobots;
- Control of cobots.





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Prof. Dr. Marco Ceccarelli

LARM2: Laboratory of Robot
Mechatronics, Department of
Industrial Engineering, University
of Rome Tor Vergata, Via del
Politecnico 1, 00133 Roma, Italy

Message from the Editor-in-Chief

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It is great fun to create intelligent robots and imagine their practical applications. *Robotics* is now ready to serve you in the long journey towards such a goal.

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Robotics Editorial Office
MDPI, Grosspeteranlage 5
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