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Underwater Sensor Networks for Communication, Navigation, and Localization

Guest Editor

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Message from the Guest Editor

Around 70% of the Earth is covered by water, with submerged locations remaining to numerous monitored and supervised. Furthermore, there numerous types of undersea environments. Advances in underwater sensors and underwater sensor networks are making these places more accessible since the sensors are less expensive, have greater computing capability, and use less battery power. Every day, the number of applications for which they can be used expands. Moreover, Autonomous underwater vehicles (AUVs) have the potential to remove humans from dangerous underwater duties such as coral planting and underwater research. Despite decades of development, most underwater robots today are still linked by cables and cannot reach full autonomy. Unmanned aerial vehicles, or AUVs in the air, have experienced tremendous research advancement and have become a popular platform for diverse sensing. More research is needed to improve AUV performance in localization, navigation, and communication. This Special Issue will collect articles on the most recent applications, developments, and problems in underwater sensor nodes and underwater sensor networks.













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Message from the Editor-in-Chief

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