



Interference, Robustness and Complementary Solutions for GNSS-Based Navigation for Aerial Vehicles

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Deadline for manuscript
submissions:
closed (20 August 2019)

Message from the Guest Editors

Sensors welcomes submissions to this Special Issue on “Interference, Robustness and Complementary Solutions for GNSS-Based Navigation for Aerial Vehicles”.

The main themes and keywords to guide potential authors are as follows:

1. Interference detection, classification, mitigation, and localization in GNSS
2. Authentication mechanisms in GNSS
3. Novel navigation solutions for aerial vehicles

Keywords

- GNSS interferences
- Spoofing
- Meaconing
- Interference detection
- Interference mitigation
- Interference localization
- Interference classification
- Authentication mechanisms in GNSS
- Alternative/complementary tracking and navigation methods for aviation
- Drones
- Aviation
- UAV





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