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Collective Mobile Robotics: From Theory to Real-World Applications

Guest Editor:

Prof. Dr. Frédéric Guinand

1. LITIS Laboratory, Normandy University of Le Havre, Le Havre, Normandy, France
2. Faculty of Mathematics and Natural Sciences, Cardinal Stefan Wyszyński University, 01-815 Warsaw, Poland

Deadline for manuscript submissions:

closed (30 September 2024)

Message from the Guest Editor

Dear Colleagues,

From theoretical models to deployment of real robots, Collective Mobile Robotics (CMR) have witnessed a growing interest last two decades. In the context of this special issue, a swarm is considered as a set of autonomous machines presenting a collective behavior without relying on any centralized mechanism. This special issue aims at offering a venue for specialists of any domain related to robot swarming, from theoretical foundations to real-world applications including robotic platforms and testbeds. Measuring the distance that may exist between theory and practical experiments, and raising open questions related to swarm robotics is one of the objectives of this SI. Contributions of mature works as well as emerging new ideas from theoretical models to existing hardware solutions enabling robots to behave as swarms are welcome.



mdpi.com/si/137234

Special Issue



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Editor-in-Chief

Prof. Dr. Vittorio M. N. Passaro

Dipartimento di Ingegneria
Elettrica e dell'Informazione
(Department of Electrical and
Information Engineering),
Politecnico di Bari, Via Edoardo
Orabona n. 4, 70125 Bari, Italy

Message from the Editor-in-Chief

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Sensors Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland

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