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Learning Technology Based on Navigation Sensors

Guest Editor:

Prof. Dr. Taikjin Lee

Sensor System Research Center, Korea Institute of Science and Technology (KIST), Seoul, Korea

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Message from the Guest Editor

Dear Colleagues,

Location is one of the most important aspects of modern life, specifically recognizing one's location and trajectory. Map applications such as Google Maps are used on a daily basis. However, since such programs are based on GNSS, limitations are inevitable in GNSS-denied environments such as indoor or urban spaces. Recently, research that easily combines various navigation sensors using technologies such as machine learning and deep learning and overcoming the limitations of sensors through pattern recognition is evolving. In particular, these technologies are serving as solutions to the "seamless" problem.

This Special Issue includes maximizing the performance of navigation sensors through pattern recognition technology. Thus, we look forward to your proposals on new localization and pattern recognition technologies that are more accurate, highly available, and seamless. We encourage authors to submit new research results about technological innovations and novel applications for pattern recognition and localization.

For more information, please access the website at: https://www.mdpi.com/journal/sensors/special_issues/PRLBNS



Specialsue





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Message from the Editor-in-Chief

Prof. Dr. Vittorio M. N. Passaro Dipartimento di Ingegneria Elettrica e dell'Informazione (Department of Electrical and Information Engineering), Politecnico di Bari, Via Edoardo Orabona n. 4, 70125 Bari, Italy Sensors is a leading journal devoted to fast publication of the latest achievements of technological developments and scientific research in the huge area of physical, chemical and biochemical sensors, including remote sensing and sensor networks. Both experimental and theoretical papers are published, including all aspects of sensor design, technology, proof of concept and application. *Sensors* organizes Special Issues devoted to specific sensing areas and applications each year.

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Sensors Editorial Office MDPI, Grosspeteranlage 5 4052 Basel, Switzerland Tel: +41 61 683 77 34 www.mdpi.com mdpi.com/journal/sensors sensors@mdpi.com X@Sensors_MDPI